Dual State Framework

Design Documentation

Yu Chen - C00151352 2015/04/12 21:38:19

Contents

1	Intro	duction		1
2	Fran	nwork D	esign esign	3
	2.1	Archite	ctural Design	3
	2.2	Proced	ural Design	3
	2.3	Interfac	e Design	4
		2.3.1	Namespace	4
		2.3.2	dsf::Runnable	4
		2.3.3	dsf::DualStateFramework	5
		2.3.4	dsf::Synchronisable	5
		2.3.5	dsf::TaskBox	5
		2.3.6	dsf::SynchronizedObject	5
		2.3.7	dsf::Task	6
		2.3.8	dsf::Argument	6
		2.3.9	dsf::TaskFunction	6
		2.3.10	dsf::SynchronizedVar	6
3	Ben	chmark	Program Design	7
	3.1	GUI Fra	amework	7
	3.2	GUI Co	nfiguration	7
	3.3	Output	3	8

1 Introduction

This document gives an overall description of the project, and shows the design of the project that can be easier to figure out the change in design. The project is going to build C++ library, and a benchmark program to profile this library.

- · Framework Design
- · Benchmark Program Design

The Framework Dsign chapter illustrates how the framework works, how to achieve the objective, and how to cooperate with this framework. this chapter has three sections:

- · Architectural Design
- · Procedural Design
- · Interface Design

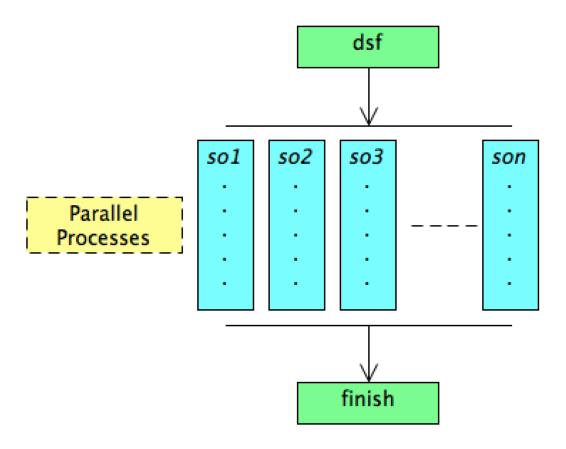
The Benchmark Program Design describes what the user interface looks like, what can be configured by user, and what the result should be.

2 Introduction

2 | Framwork Design

2.1 Architectural Design

The goal of this project is to implement concurrency and parallel. In this framework, each Synchronized Object process simultaneously after Dual State Framework started. The process shows as follow:

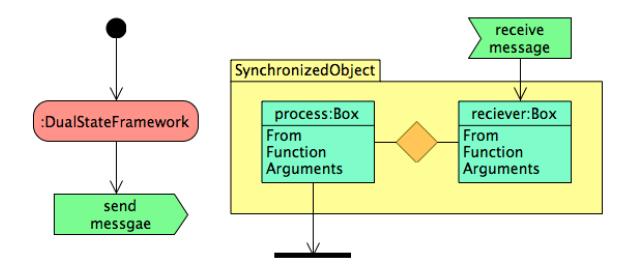


- "dsf" refers to Dual State Framework
- "so" followed by a number refers to Synchronized Object

2.2 Procedural Design

This diagram shows activities and interactions in one success evaluation(one frame in game).

4 Framwork Design



As it shows, the system create a DualStateFramework object. A DualStateFramework object can have many SynchronizedObject objects. Each SynchronizedObject object has two Boxes. One is for processing messages. The other one is for receiving messages. The sequence is like this:

- 1. The DualStateFramework object starts with sending a "start" message.
- 2. Messages from receiver are popped out and then be pushed into processor.
- 3. Processor unpacks messages and evaluates function with arguments in each message sequently.

After step 3, it will go back to step 2. Step 2 and step 3 process alternatively and endlessly until the DualState ← Framework object stopped.

2.3 Interface Design

2.3.1 Namespace

All classes in this framework is under the namespace "dsf", which is abbreviation of the project name "Dual State Framework".

2.3.2 dsf::Runnable

The interface provides a protected pure virtual function run(), which will be called when subclass object starts. For example:

```
class MyDSF : public dsf::DualStateFrameword
{
protected:
    void run()
    {
        // do something here...
    }
}

void main()
{
    MyDSF dsf;
    dsf.start() // It will process MyDSF::run();
```

2.3 Interface Design 5

2.3.3 dsf::DualStateFramework

The starting pointer for the framework is the abstract class dsf::DualStateFramework. It provides essential functions for associating and managing its components (SynchronizedObject objects, function points, and etc.).

2.3.4 dsf::Synchronisable

Class dsf::Synchronisable is a template interface. It has a template member variable "next" and a pure virtual function "synchronise". The variable is a copy of current class. The function synchronises the current state.

```
#include <dsf/Synchronisable.h>

class Vector3D
{
  public:
     float x, y, z;
     Vector3D(float x, float y, float z) : x(x), y(y), z(z){}
};

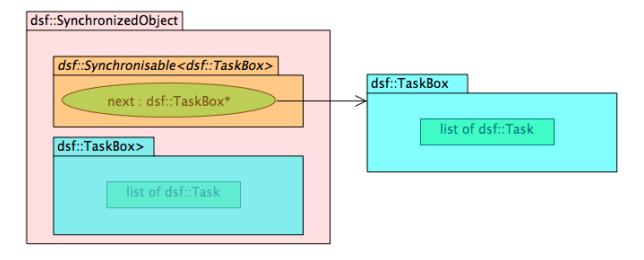
class SyncVector : public dsf::Synchronisable<Vector3D>, public Vector3D
{
  public:
     SyncInt(float x, float y, float z) : Vector3D(x, y, z) {
        this->next = new Vector3D(x, y, z);
    }
    void synchronise() override {
        this->x = this->next->x;
        this->z = this->next->z;
    }
};
```

2.3.5 dsf::TaskBox

The dsf::TaskBox contains a list of dsf::Task objects. It provides essential methods to control the list such as "push", "pop", and "isEmpty".

2.3.6 dsf::SynchronizedObject

The dsf::SynchronizedObject is a subclass of dsf::TaskBox. In this framework, you can regard it as thread. It provides methods for implementing parallelism such as "send", "receive", and etc. Also, it implements interface dsf::Synchronisable<dsf::TaskBox>. Therefore, it has two copies of dsf::TaskBox. One is for receiving messages, and the other one is for executing messages.



6 Framwork Design

2.3.7 dsf::Task

This class have three members: from, function, and arguments, where "from" is a dsf::SynchronizedObject object who sent message to you.

2.3.8 dsf::Argument

A dsf::Argument object can refer to any type of object. The following code is allowed:

```
dsf::Argument i = int(10);
dsf::Argument str = std::string("Hello");
```

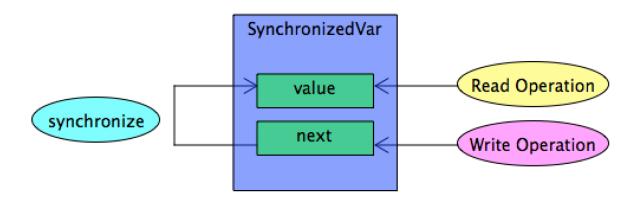
2.3.9 dsf::TaskFunction

The message in a dsf::Task is an object of dsf::TaskFunction. An object of dsf::TaskFunction is a function pointer whose function takes two dsf::SynchronizedObject objects, a dsf::Argument object as arguments. The constructor of dsf::TaskFunction takes a function pointer or a lambda expression as arguments. This is an example that uses lambda expression.

2.3.10 dsf::SynchronizedVar

The purpose of this class is to make thread-safe variables for dsf::SynchronizedObject objects. A dsf::⇔ SynchronizedVar object has two member variables - "value" and "next". The "value" is for read operation, and the "next" is for write operation. The function "synchronize" signs "next" to "value". see example below:

```
dsf::SynchronizedVar myInt;
myInt = int(8); // value == NULL, next == 8
myInt.synchronise(); // value == 8, next == 8
std::cout << myInt.to<int>() << std::endl; // output 8
myInt = int(9); // value == 8, next == 9
std::cout << myInt.to<int>() << std::endl; // output 8
myInt.synchronise(); // value == 9, next == 9
std::cout << myInt.to<int>() << std::endl; // output 9</pre>
```



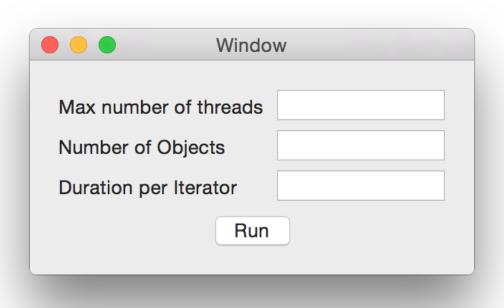
3 Benchmark Program Design

3.1 GUI Framework

To benchmark the framework, I will use SFML to create a graphics application. When running the application, each frame runs many objects. The maximum, minimun, and average FPS(Frame per Second) is what I need for the benchmark. The application allows using different number of threads to run it.

3.2 GUI Configuration

When you start the application, it will show you a configuration form like this:



The application will run by using one thread to the max number of threads that user configured. The maximun, minimun, and average FPS will be recorded each iterator. Number of objects and duration for each iterator can be configured by this form.

3.3 Outputs

The output is a bar graph which shows all information of the benchmark.

- x axis representing number of threads
- y axis representing frames per second(FPS)
- values with the maximum, the minimum, and the average.

