

## VictorDronhen Language Specifications



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## BNF Description:

<string>	::= "[^"]*"
<number>	::= [-+]?[0-9]*\.[0-9]+
<identifier>	::= [a-zA-Z_]+
<boolean>	::= True   False
<comment>	::= //.*
<comma_seperated_list>	::= ε   <string>   <identifier>   <number>   <boolean>   <number>,<comma_seperated_list>   <identifier>,<comma_seperated_list>   <string>,<comma_seperated_list>   <boolean>,<comma_seperated_list>
<program>	::= <stmt_list>
<stmt_list>	::= <stmt>   <stmt> <stmt_list>   <comment>   <comment>\n<stmt_list>
<stmt>	::= <assignment>;   <loop>   <conditional>   <function_def>   <expression>;
<assignment>	::= <identifier> = <expression>;
<loop>	::= while (<expression>){<stmt_list>}
<conditional>	::= if (<expression>){<stmt_list>}   if (<expression>){<stmt_list>} else{<stmt_list>}
<function_def>	::= function <identifier>(<comma_seperated_list>){<stmt_list>}
<expression>	::= <arithmetic_expression>   <relational_expression>   <boolean_expression>   <function_call>   <identifier>
<function_call>	::= <identifier>(<comma_seperated_list>)
<arithmetic_expression>	::= <term>   <term> + <arithmetic_expression>   <term> - <arithmetic_expression>
<term>	::= <factor>   <factor> * <term>   <factor> / <term>
<factor>	::= <number>   <identifier>   <function_call>   (<arithmetic_expression>)   ε
<relational_expression>	::= <arithmetic_expression> "<" <arithmetic_expression>   <arithmetic_expression> "<=" <arithmetic_expression>   <arithmetic_expression> ">" <arithmetic_expression>   <arithmetic_expression> ">=" <arithmetic_expression>   <arithmetic_expression> "==" <arithmetic_expression>   <arithmetic_expression> "!=" <arithmetic_expression>   <arithmetic_expression>
<boolean_expression>	::= <relational_expression> and <boolean_expression>   <relational_expression> or <boolean_expression>   not <relational_expression>   <relational_expression>

## Primitive Functions:

getHeading()	: Returns a number, [0, 359], indicating the angle between north and heading direction. A return value of 1 indicates 1 degree deviation to the west
getAltitude()	: Returns the altitude in meters
getTime()	: Returns Unix time in seconds
sprayOn()	: Turn the spray on
sprayOff()	: Turn the spray off
climbUp()	: Start climbing up at 0.25 m/s,
dropDown()	: Start dropping at 0.25 m/s
stopVertical()	: Stops vertical movement
stopHorizontal()	: Stops horizontal movement
moveForward()	: Start moving forward at 0.75 m/s
turnLeft()	: Turn left 1 degree
turnRight()	: Turn right 1 degree
print(variable)	: Print to terminal, useful for displaying information. Adds a new line character
input()	: Read input

## Terminals:

<number>	: The number literal represents either a floating point or an integer value. These are used for numerical calculations and arithmetic. They also support relational comparison.
<identifier>	: These are used in naming variables as well as functions in the programming language. The variables can be either a number (an integer or a float), a string or a boolean.
<string>	: String literals are used for representing a sequence of characters. They are used mostly for input / output purposes and are not directly related to the control mechanism of the drone.
<boolean>	: Boolean literal, either True or False. Denotes a boolean value. Used for conditional statements.

## Nontrivial Tokens:

<comment>	: Comments are explanatory notes written in a separate line.
logical reserved	: [ and, or, not ] are used to work with boolean content.
relational reserved	: [ <, >, <=, >=, ==, != ] used for comparison between number types.
arithmetic reserved	: [ +, -, /, *, (, ) ] used for arithmetic between number types.
primitive functions	: See designated section above. We paid attention to readability and writability by giving very clear names.

## Standard Library:

We enhanced the user experience by building a standard library of especially useful functions. This greatly increases the writability criterion of this language by providing essential functions for controlling drones. For the implementation of this library, see below:

## STANDARD LIBRARY: (Every Program Has Access to These Functions)

```
// Turns right at a given angle. Works for negative angles.
function turnRightDegrees(degree){
    if (degree > 0) {
        j = 0;
        while (j < degree) {
            turnRight();
            j = j + 1;
        }
    }
    else{
        j = 0;
        while (j > degree) {
            turnLeft();
            j = j - 1;
        }
    }
}
```

```
// move forwards with the given distance and then stop. Works for negative dist.
function moveForwardDistance(distance) {
    startTime = getTime();
    necessaryTime = distance / 0.75;
    if (distance < 0) {
        necessaryTime = - necessaryTime;
        turnRightDegrees(180);
    }
    moveForward();
    while (getTime() - startTime < necessaryTime) {}
    stopHorizontal();

    // do not change rotation if we move backward.
    if (distance < 0) {
        turnRightDegrees(180);
    }
}
```

```
// moves to the specified height and stops.
function moveToAltitude(height){
    altitude = getAltitude() - height;
    startTime = getTime();
    if (altitude > 0) {
        dropDown();
    }
    else{
        altitude = - altitude;
        climbUp();
    }
    while (getTime() - startTime < altitude * 4) {}
    stopHorizontal();
}
```

```
function turnNorth(){
    turnRightDegrees(getHeading());
}

function turnWest(){
    turnNorth();
    turnRightDegrees(270);
}

function turnEast(){
    turnNorth();
    turnRightDegrees(90);
}

function turnSouth(){
    turnNorth();
    turnRightDegrees(180);
}
```

## TEST PROGRAM 1:

```
function droneController(heading, distance){
    currentDir = getHeading();
    turnRightDegrees(heading - current_dir);
    moveForwardDistance(distance);
    stopHorizontal();
}
```

## TEST PROGRAM 2:

```
function sprayRectangle(curX, curY, rectX, rectY, rectW, rectH){
    xMove = rectX - curX;
    yMove = rectY - curY;
    moveToAltitude(4);

    turnEast();
    moveForwardDistance(xMove);
    turnNorth();
    moveForwardDistance(yMove);

    sprayOn();
    moveForwardDistance(rectH);

    turnEast();
    moveForwardDistance(rectW);

    turnSouth();
    moveForwardDistance(rectH);

    turnWest();
    moveForwardDistance(rectW);

    sprayOff();
}
```

### TEST PROGRAM 3:

```
// this function creates movements and prints the results
function main(){
    // testing output functionality, printing the drone's heading and altitude.
    print("Heading is : ");
    print(getHeading());
    print("Altitude is: ");
    print(getAltitude());

    // testing the standard library and primitive functions
    moveForwardDistance(25);
    moveToAltitude(20);
    turnEast();
    moveForwardDistance(12);

    // testing a time based operation
    startTime = getTime();
    while (getTime() - startTime < 3) {
        sprayOn();
    }
    sprayOff();

    // testing if current location is indeed correct
    print("Heading is: ");
    print(getHeading());
    print("Altitude is: ");
    print(getAltitude());
}

// Execute the main function
main();
```

#### TEST PROGRAM 4:

```
// this function makes the drone traverse a hilbert curve
// https://medium.com/@nico727272/drawing-hilbert-curves-using-turtle-46f6d628732b
// call with angle = 90 for standard Hilbert Curves
function traverseHilbertCurve(order, angle){
  if(order != 0){
    turnRightDegrees(360 - angle);
    traverseHilbertCurve(order - 1, - angle);
    moveForwardDistance(1);
    turnRightDegrees(angle - 360);
    traverseHilbertCurve(order-1, angle);
    moveForwardDistance(1);
    traverseHilbertCurve(order-1, angle);
    turnRightDegrees(angle - 360);
    moveForwardDistance(1);
    traverseHilbertCurve(order - 1, - angle);
    turnRightDegrees(360 - angle);
  }
}
```

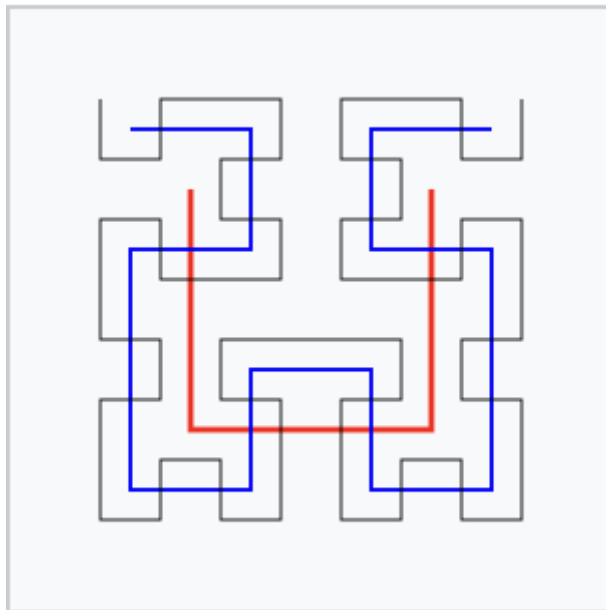


Fig 1. Hilbert Curves of order 1, 2 and 3, image taken from [wikipedia](https://en.wikipedia.org/wiki/Hilbert_curve).



## Lex File:

```
%%
"/".*      { printf("COMMENT"); }
";"        { printf(" SEMICOLON ");}
"("        { printf(" LP ");}
")"        { printf(" RP ");}
"{"        { printf(" LBRACE ");}
"}"        { printf(" RBRACE ");}
","        { printf(" COMMA ");}
"<"        { printf(" LT ");}
">"        { printf(" GT ");}
"<="       { printf(" LT_EQ ");}
">="       { printf(" GT_EQ ");}
"=="       { printf(" EQ ");}
"!="       { printf(" NOT_EQ "); }
"="        { printf(" ASSIGN ");}
"+"        { printf(" PLUS ");}
"-"        { printf(" MINUS ");}
"*"        { printf(" MULT ");}
"/"        { printf(" DIV ");}
"function" { printf(" FUNCTION ");}
"while"    { printf(" WHILE ");}
"if"       { printf(" IF ");}
"else"     { printf(" ELSE ");}
"and"      { printf(" LOGICAL_AND ");}
"or"       { printf(" LOGICAL_OR ");}
"not"      { printf(" LOGICAL_NOT ");}
"True"     { printf(" TRUE_LIT ");}
"False"    { printf(" FALSE_LIT ");}
[+]?[0-9]*\.[0-9]+ { printf(" NUMBER_LIT ");}
[a-zA-Z_]+  { printf(" IDENTIFIER ");}
\"([^\"]|\\.)*\"/> { printf(" STRING_LIT "); }
```

```
%%
int yywrap() {
    return 1;
}
int main(void) {
    yylex();
    return 0;
}
```