

Kevin Black

kevin3.black@gmail.com
(512) 785-1853

kevinblack.dev
github.com/kvabblack

EDUCATION

University of Texas at Austin

Pursuing B. S. in Computer Science and Mathematics

Austin, TX

2018 – 2022

- Turing Scholars, Dean's Scholars honors programs
- Turing Scholars honors thesis in progress, advised by Scott Niekum
- Cumulative GPA: 4.0

RESEARCH EXPERIENCE

Personal Autonomous Robotics Lab (PeARL)

Undergraduate Research Assistant

University of Texas at Austin

February 2021 – Present

- Currently working with a PhD student on a hierarchical reinforcement learning algorithm for robotic manipulation based on object controllability
- Implemented multiple MuJoCo-simulated robot manipulation environments using [robosuite](#)
- Ongoing honors thesis project relating to state representation learning based on contingency awareness and a generalization of bisimulation metrics

Texas Spacecraft Laboratory – Seeker Team

Undergraduate Research Assistant; Team Lead

University of Texas at Austin

January 2019 – February 2021

- Worked on a machine learning-based visual navigation algorithm which was chosen by NASA over competing solutions and flew on an orbital research mission September 2019
- Created a Python library ([Starfish](#)) for generating synthetic training data using Blender
- Helped develop a complex machine learning pipeline for training and evaluating deep computer vision models
- Developed a model that achieved accurate real-time full pose estimation on a low-power, flight-like embedded system
- Served as team lead from August 2019 – February 2021, during which two conference publications were produced

PUBLICATIONS

K. Black, S. Shankar, D. Fonseca, J. Deutsch, A. Dhir, and M. R. Akella, “Real-Time, Flight-Ready, Non-Cooperative Spacecraft Pose Estimation Using Monocular Imagery,” *31st AAS/AIAA Space Flight Mechanics Meeting*, 2021.

C. Schubert, **K. Black**, D. Fonseca, A. Dhir, J. Deutsch, N. Dhamani, G. Martin, and M. R. Akella, “A Pipeline for Vision-Based On-Orbit Proximity Operations Using Deep Learning and Synthetic Imagery,” *2021 IEEE Aerospace Conference*, 2021.

PROFESSIONAL EXPERIENCE

NASA Jet Propulsion Laboratory

Planning and Execution Systems Intern

Pasadena, CA

Summer 2021

- Worked on an activity simulation framework and an AI-based activity scheduler prototype with applications to the Europa Clipper mission

Asana <i>Product Engineering Intern</i>	San Francisco, CA Summer 2020
---	----------------------------------

Bloomberg <i>Data Science Platform Intern</i>	New York, NY Summer 2019
---	-----------------------------

- Added distributed training capabilities via Tensorflow to an internal data science platform
- Benchmarked distributed training throughput for large models (ResNet-50, BERT)
- Gave a talk at the 2019 Kubeflow summit in Sunnyvale, CA on my work and results

Silicon Labs <i>Software Engineering Intern</i>	Austin, TX Summers 2018, 2017, 2016
---	--

VOLUNTEER WORK

HackTX <i>Mentor</i>	2020 – 2021 Austin, TX
--------------------------------	---------------------------

- Assisted undergraduate hackathon teams with their projects during HackTX 2020 and 2021
- Paired directly with one team for 12 weeks during SummerHacks 2020

ATX Science Olympiad <i>Event Proctor</i>	2018 – 2019 Austin, TX
---	---------------------------

- Proctored Science Olympiad events for middle and high school students at various UT-hosted tournaments