Signals and Systems unit 4

Filters

The simplest ideal filters aim at retaining a portion of the spectrum of the input in some predefined region of the frequency axis and removing the rest.

A LOWPASS FILTER is a filter that passes low frequencies – i.e. around f = 0 and rejects the higher ones, i.e. it multiplies the input spectrum with the following:

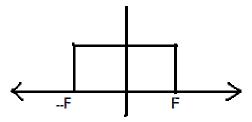


Figure 4.5

A **High pass filter** passes high frequencies and rejects low ones by multiplying the input spectrum by:

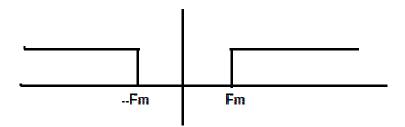


Figure 4.6

A **BANDPASS FILTER** passes a band of frequencies and rejects both higher and lower than those in the band that is passed, thus multiplying the input spectrum by:

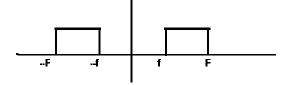


Figure 4.7

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A **BANDSTOP FILTER** stops or rejects a band of frequencies and passes the rest of the spectrum, thus multiplying the input spectrum by:

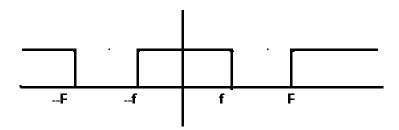


Figure 4.8

How do these filters work? That is, what does multiplication of two signals in the frequency domain imply in the time domain?

If we multiply two Fourier transforms X(f) and H(f), let us see what the Inverse Fourier transform of this product is.

$$\int_{-\infty}^{\infty} X(f) H(f) e^{j2\pi f t} df$$
Consider the integral $-\infty$

Let us replace
$$H(f)$$
 by $-\infty$

$$h(\lambda) e^{-j2\pi f \lambda} d\lambda$$

This makes the integral,
$$-\infty$$

$$\int_{-\infty}^{\infty} X(f) \left\{ \int_{-\infty}^{\infty} h(\lambda) e^{-j2\pi f \lambda} d\lambda \right\} e^{j2\pi f t} df$$

We can interchange the order of integration, so long as the new double integral converges

$$\int_{-\infty}^{\infty} h(\lambda) \left\{ \int_{-\infty}^{\infty} x(f) e^{j2\pi f(t-\lambda)} df \right\} d\lambda$$

we note that the term inside the bracket is just the inverse Fourier transform of X(f) evaluated at $(t-\lambda)$,

Thus the integral simplifies to $-\infty$ $h(\lambda) x(t-\lambda) d\lambda$ which is simply the convolution of h(t) with x(t)!