

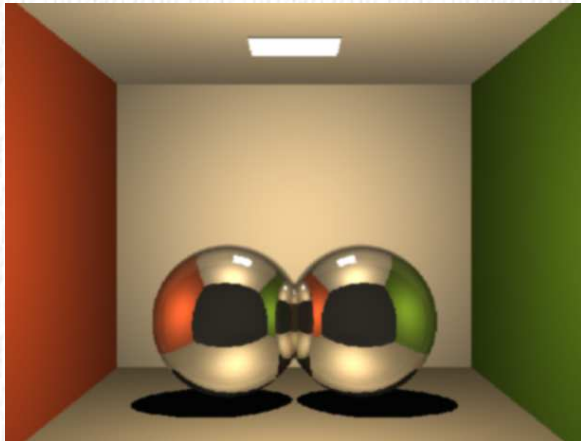
# Lab 2

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<http://graphics.cs.aueb.gr/graphics/people.html>

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Computer Graphics BSc



# Introduction

- Transformations
- GLSL
- GLM

# GLM

- OpenGL Mathematics Library
- Same syntax with GLSL
- Strict type checking
- Use glm namespace
- `glm::translate`, `glm::rotate`, `glm::ortho`, etc.

# GLSL

- OpenGL Shading Language
- C like syntax
- Write vertex, geometry, fragment shaders
- Strict input-output
- Pass variables from CPU side using uniforms
- Swizzling
- Allow for very cool tricks 😊



# GLSL Basic Types

## Scalar values

- bool, int, uint, float, double

## Vector values

- vec2, vec3, vec4, ivec2, ivec3, ivec4, uivec2, etc.

## Matrices

- mat2, mat3, mat4

# Create Uniforms

// Get an index to the variable in the shader

```
GLint uniform_mvp =  
glGetUniformLocation(m_program,  
"uniform_mvp");
```

# Render with shaders

// Set it active

glUseProgram(m\_program);

// pass a matrix uniform

glUniformMatrix4fv(uniform\_mvp, 1, false,  
&mvp\_matrix[0][0]);

// draw!!

e.g. glDrawArrays.....



# GLSL Vertex Shader

```
#version 330
```

```
layout(location = 0) in vec4 position;
```

```
uniform mat4 uniform_mvp;
```

```
void main() {
```

```
    gl_Position = uniform_mvp * position;
```

```
// or gl_Position = uniform_mvp * position.xyzw;
```

```
}
```



# GLSL Fragment Shader

```
#version 330
```

```
layout(location = 0) out vec4 out_color;
```

```
void main() {
```

```
// RGBA color (0-1 values)
```

```
    out_color = vec4(1.0f, 1.0f, 1.0f, 1.0f);
```

```
}
```

# Transformations

- OpenGL uses a right-handed coordinate system (Right is +X, Up is +Y, Back is +Z)
- Matrix multiplication depends on the vector type (i.e. for column vectors multiplication is right to left,, for rows is left to right)

Example: for column vectors

$$A = P * V * M$$

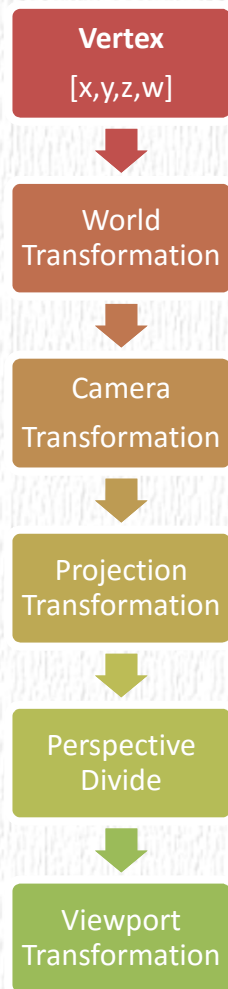
$$v' = A * v$$

Use the inverse to go back

$$A^{-1} = M^{-1} * V^{-1} * P^{-1}$$

$$v = A^{-1} * v'$$

# Transformations

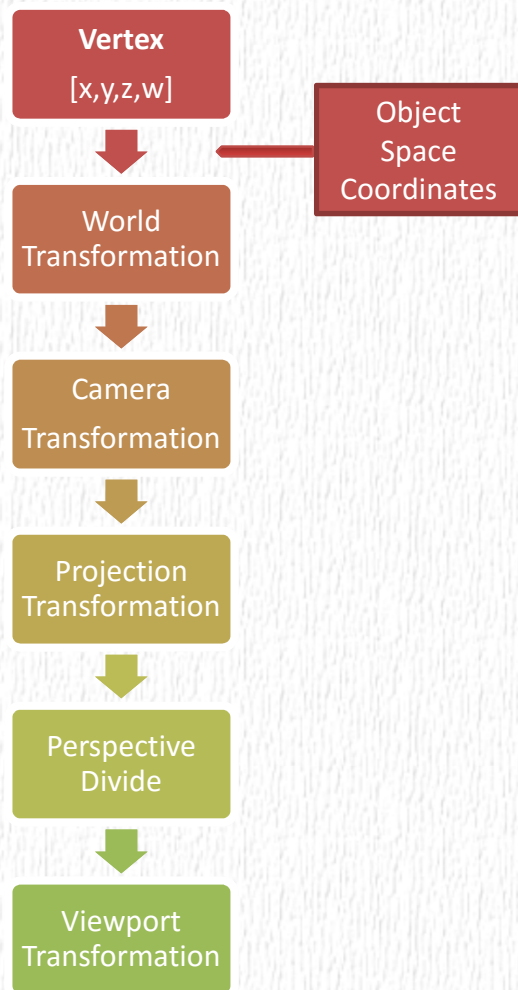


## General idea

- Set the dimensions of your window (viewport)
- Define your world
- Place objects in the world
- Create a “camera” and transform the world so that the camera is at the origin
- Project the world on the screen



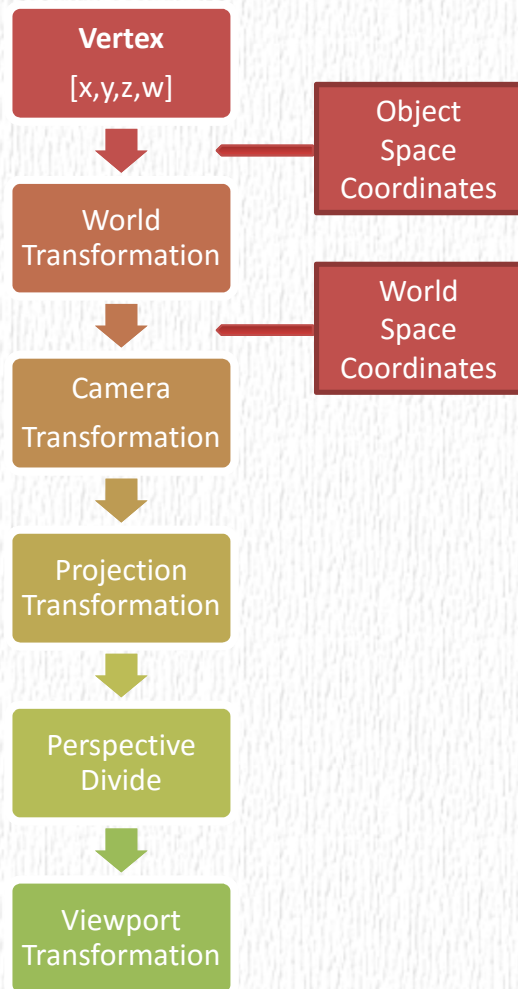
# Transformations



## Object Space Coordinates (OSC)

- What we get from a 3D modelling software (3DS Max, Maya, etc.)
- Usually object is centered at its own origin in OSC
- The coordinates we pass to vertex buffers

# Transformations

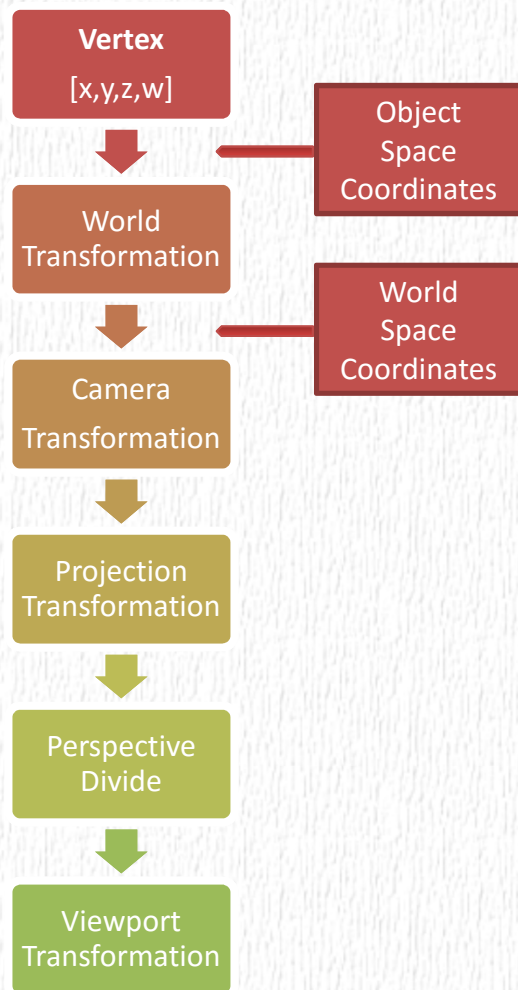


## World Space Coordinates (WSC)

- Place our object in the scene
- Use matrix transformations to move from OSC->WSC
- Translate
- Rotate
- Scale



# Transformations

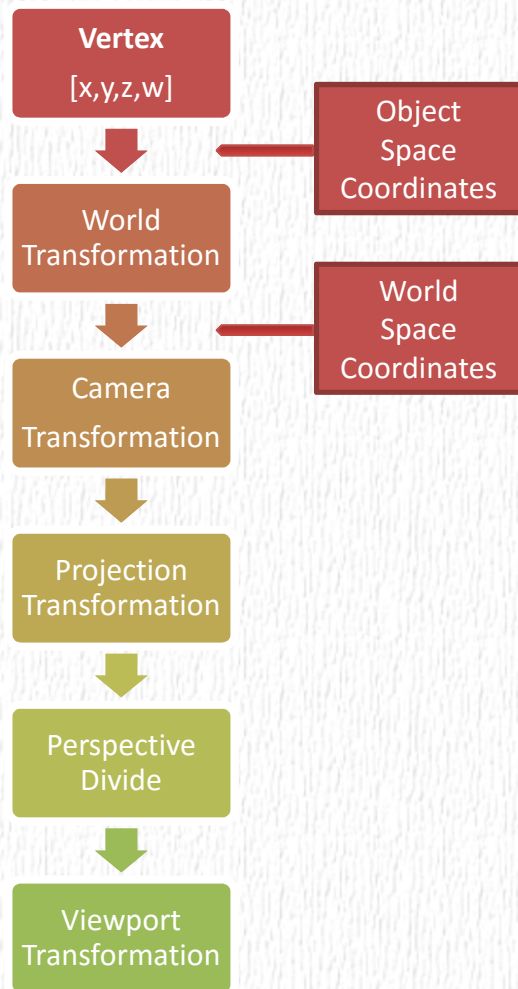


## World Coordinate System

- `glm::translate(x,y,z)`  
// Move an object in the x-axis by 8 units  
`glm::mat4 translation_mat = glm::translate(8.0f, 0.0f, 0.0f);`
- `glm::rotate (angle,x,y,z)`  
// Rotate object around the y-axis by 45 degrees counter-clockwise  
`glm::mat4 rotate_y_axis_mat = glm::rotate(45, 0.0f, 1.0f, 0.0f);`
- `glm::scale(x,y,z)`  
// Scale object uniformly by a factor of 2  
`glm::mat4 scale_mat = glm::scale(2.0f, 2.0f, 2.0f);`



# Transformations



## Order Matters!

- Matrix multiplication is not commutative ( $AB \neq BA$ )
- Common usage is first scale, then rotate and finally translate ( $T \cdot R \cdot S$ )

Example 1:

// Rotate the object by 45 degrees and THEN translate it

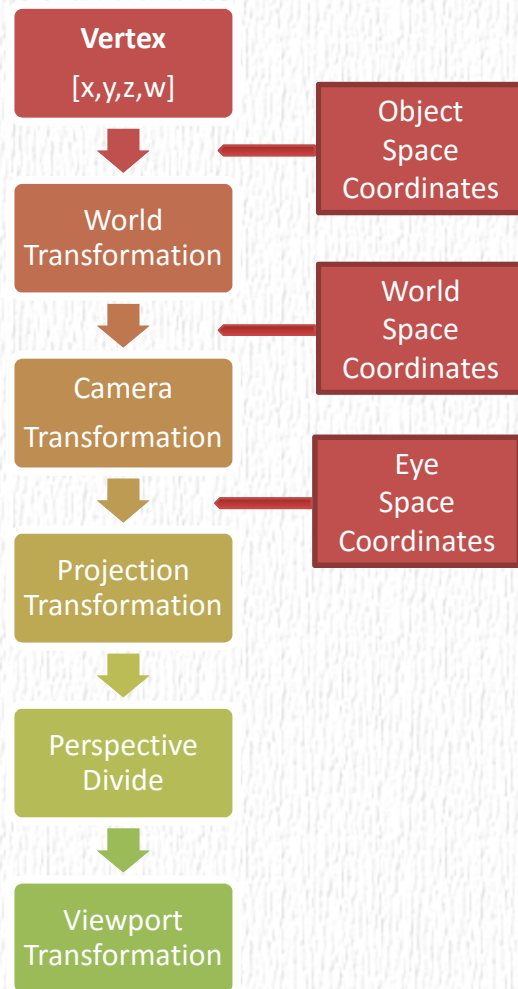
```
glm::ocs_to_wcs_mat =  
translation_mat * rotate_y_axis_mat;
```

Example 2:

// Translate the object by 8 units and then rotate the translated object by 45 degrees

```
glm::ocs_to_wcs_mat =  
rotate_y_axis_mat * translation_mat;
```

# Transformations



## Eye Coordinate System (ECS)

- Need to view the world from our point of view
- Need a camera center, a direction and a new coordinate system
- Use `glm::lookat`



# Transformations

**glm::lookAt**(*vec3 eye, vec3 center, vec3 up*)

- Need only to specify a direction and an up vector (for now 0,1,0)
- $\text{dir} = \text{center} - \text{eye}$
- Coordinate System  $u v n$  (similar to  $x y z$ )
- $n = \text{dir}$
- $v = n \times \text{up}$
- $u = v \times n$

Example:

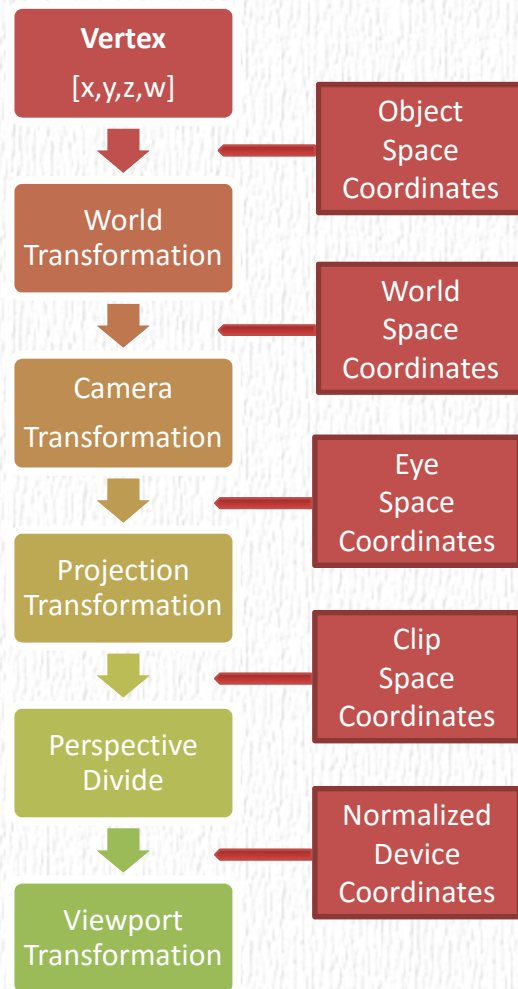
// Create a camera at the origin (0,0,0), looking at  $-Z$

glm::wcs\_to\_ecs\_mat =

glm::lookat(0.0f, 0.0f, 0.0f, 0.0f, 0.0f, -1.0f, 0.0f, 1.0f, 0.0f);



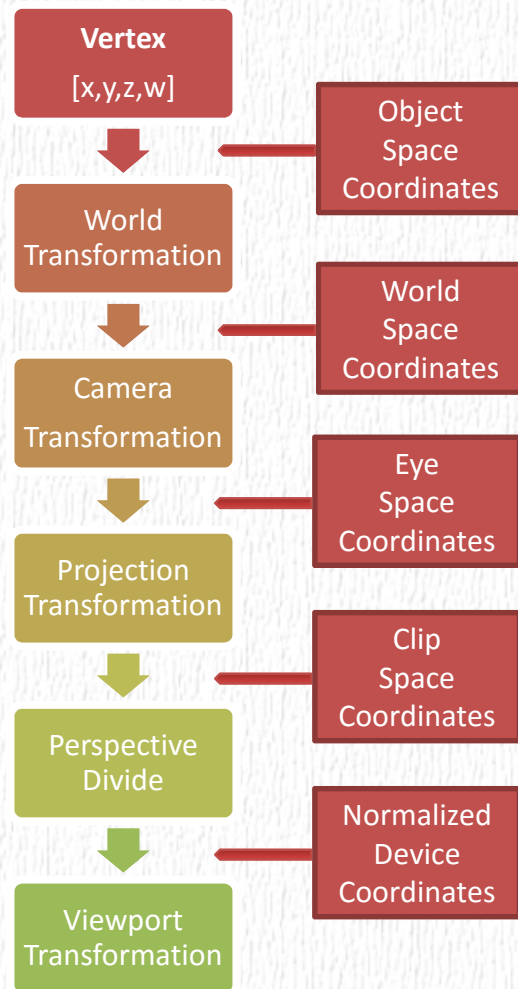
# Transformations



## Projective Space (CSS)

- Orthographic, Perspective
- Transform scene from ECS extents to a cuboid (CSS)
- NDC after perspective divide

# Transformations



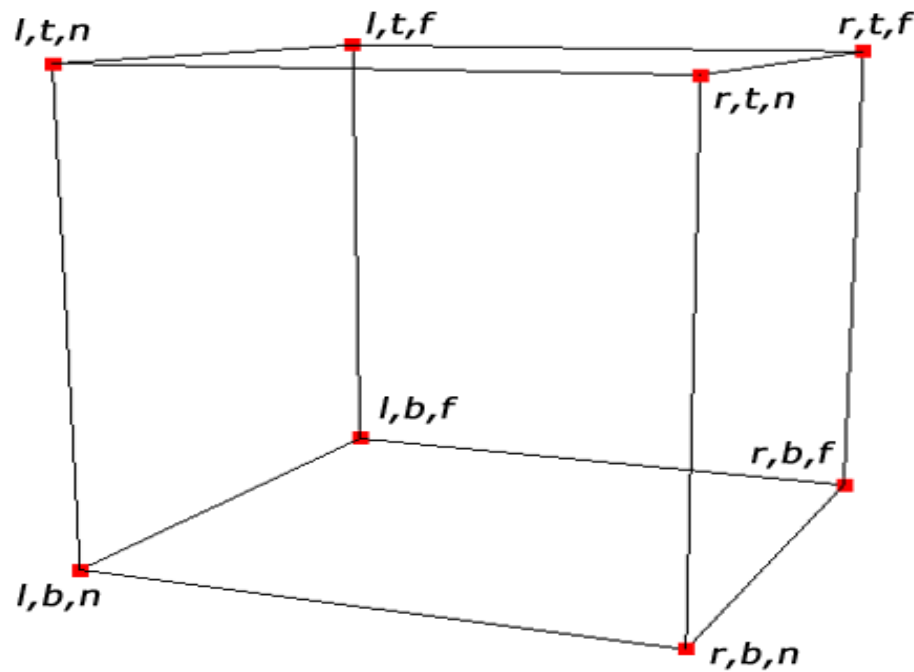
## Orthographic Projection

- Simplest form of projection
- Keeps line parallelism
- Linear relationship between coordinates in eye space and NDC

# Transformations

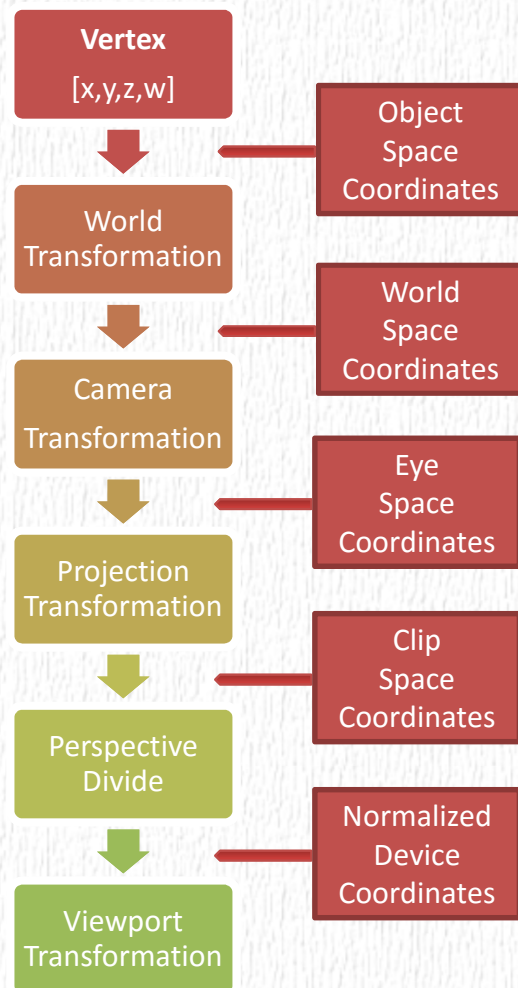
`glm::ortho(left, right, bottom, top, near, far)`

- Parameters are coordinates to clipping planes
- Useful for 2D rendering (text, etc)





# Transformations



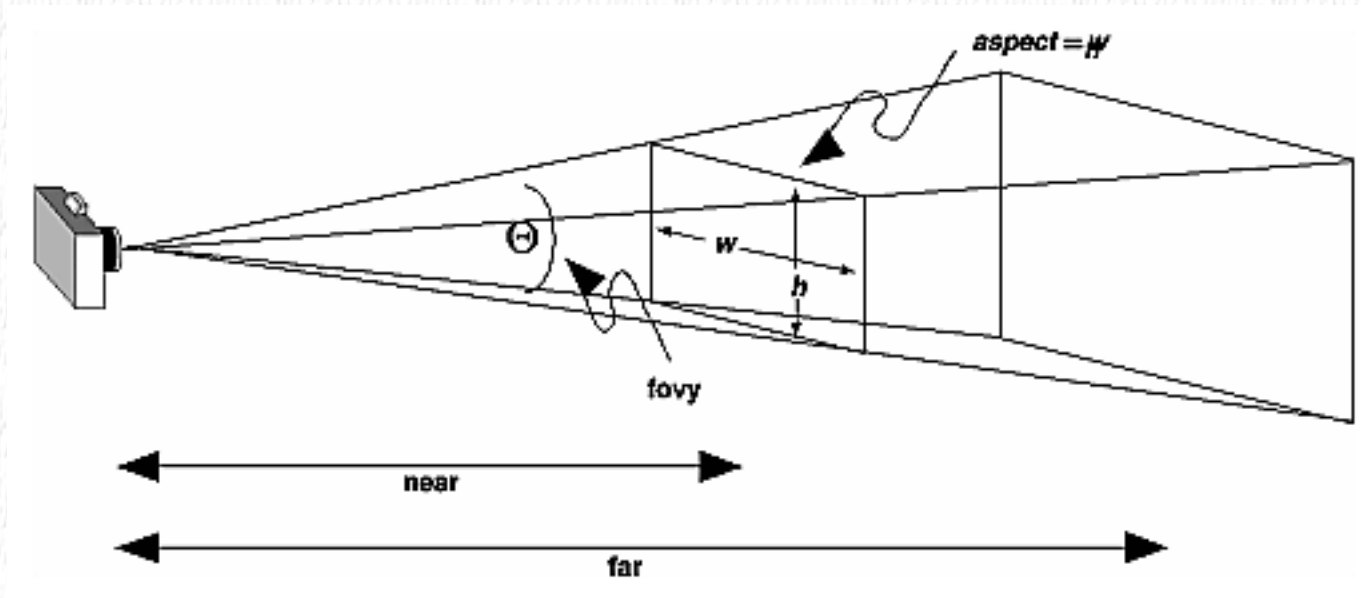
## Perspective Projection

- Mimics way we perceive objects
- Parallel lines may converge at infinity
- Objects appear smaller as they move further away
- Non-linear z relationship between coordinates in eye space and NDC

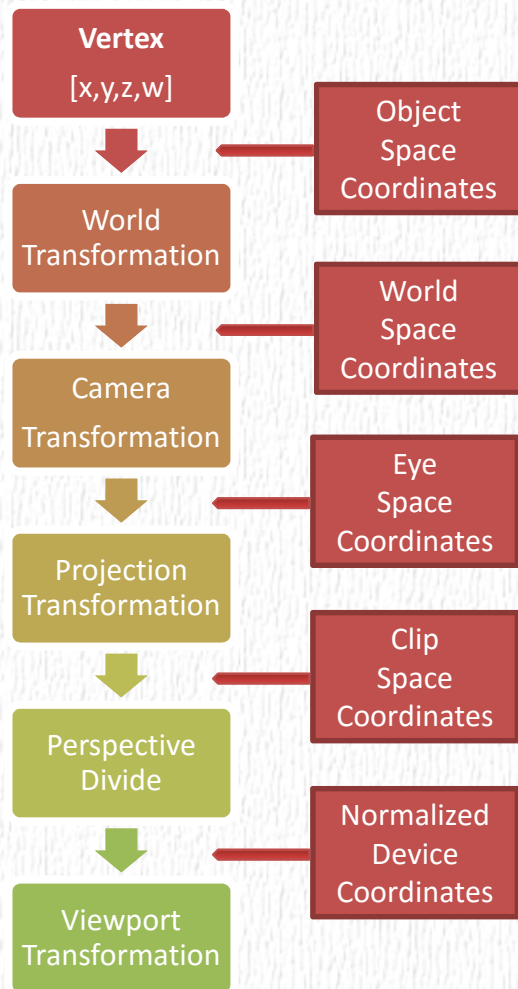
# Transformations

**glm::perspective** (*fov*, *aspect\_ratio*, *near*, *far*)

```
glm::mat4 persp_proj_mat = glm::perspective(30.0f,  
(float)w/(float)h, near_field_value, far_field_value);
```



# Transformations



## Window Space

- Transforms NDC to Window cords
- Happens internally  
***glViewport(x,y,width,height)***



# Recap

- Transform object space to world space
- Transform world space to eye space
- Transform eye space to clip space
- Combine them

```
glm::mat4 mvp_matrix = persp_proj_mat *  
wcs_to_ecs_mat * ocs_to_wcs_mat;
```

- Pass final matrix to shader

# Done!

- Check lab2 project
- Check pdf for more information and online content