NATIONAL TECHNICAL UNIVERSITY OF ATHENS
SCHOOL OF ELECTRICAL & COMPUTER ENGINEERING

SECTOR OF SIGNALS, CONTROL & ROBOTICS

Object-Frame Impedance Control for Dexterous Robotic Grasping

DIPLOMA THESIS

by

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Abstract

This English document is a translation track of the original Greek diploma thesis. The full English translation can be completed incrementally by editing the `*_EN.tex` chapter files.

TODO: translate abstract. You can reuse the existing English abstract text from `diplomatiki_Abstract.tex` (lines "Abstract" / "Key Words") if desired.

Key Words

TODO: translate key words.

Acknowledgements

TODO: translate acknowledgements. This file is the English counterpart of `diplomatiki_euxaristie`

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