

Team presentation









Andrea Serna Literature review



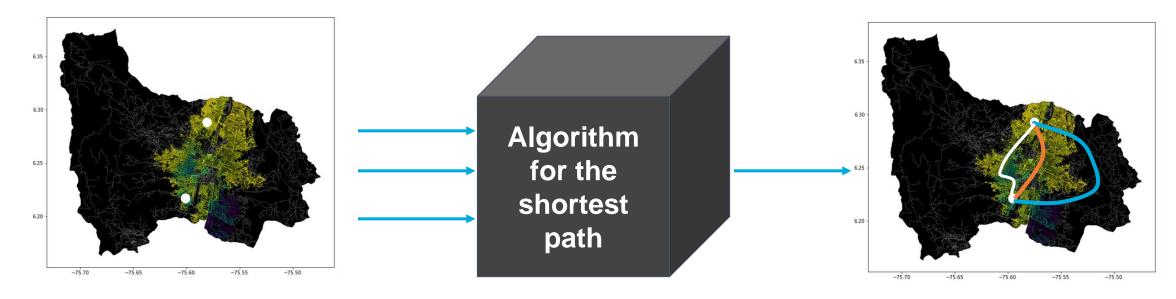
Mauricio ToroData Preparation





Problem Statement





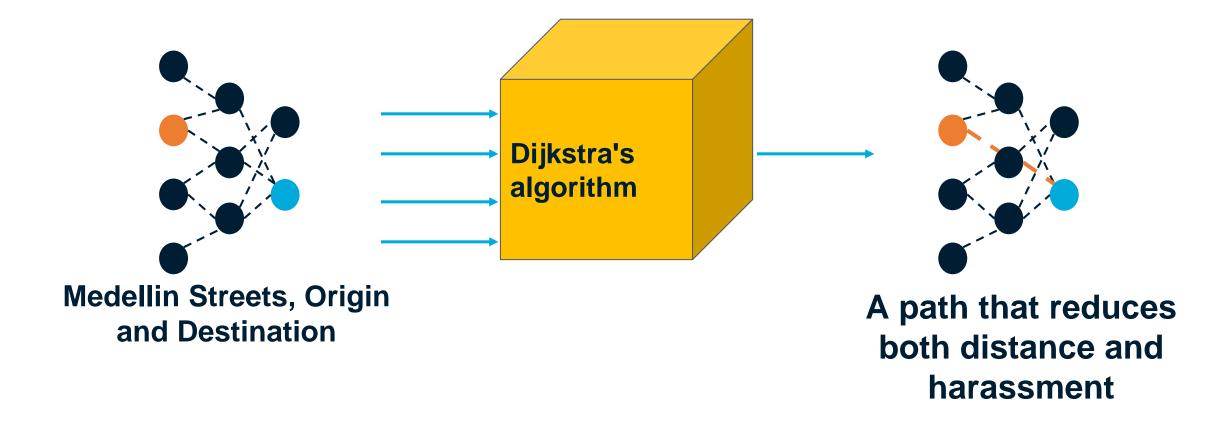
Medellin Streets, Origin and Destination

Three paths that reduce both the risk of harassment and the distance



Solution algorithm



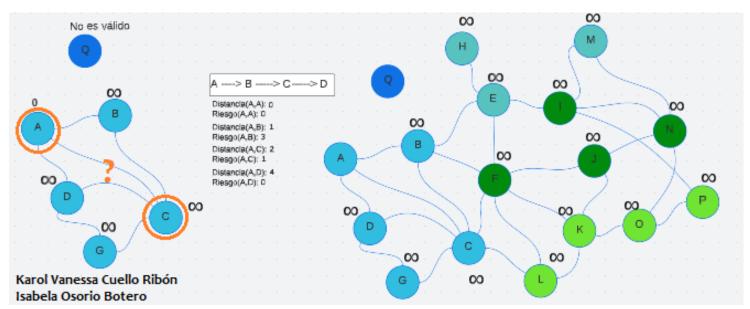




Algorithm explanation



Dijkstra's algorithm, to find the path that reduces both harassment and distance.





It starts by giving the "weights" a value of infinity and then begins to evaluate at each node looking for the lowest value to reach the destination, going through the graph moving through each of the nodes (which are taken with respect to the street address).



Complexity of the algorithm



	Temporal complexity	Memory complexity
Dijkstra	O(V ²)	O(V)

Time and memory complexity of Dijkstra's algorithm. V represents the number of vertices or nodes.





First path that minimizes x = d+r



Source	Destiny	Distance (meters)	Harassment risk (between 0 and 1)
Universidad EAFIT	Universidad de Antioquia	11305.436	0.7289

Distance and risk of harassment for the road that minimizes x = distance + risk. Execution time of 68 seconds.



Second path that minimizes $x = d^*r$



Source	Destiny	Distance (meters)	Harassment risk (between 0 and 1)
Universidad EAFIT	Universidad de Antioquia	16846.849	0.4864

Distance and risk of harassment for the road that minimizes x = distance*risk. Execution time of 71 seconds.



Third path that minimizes x = d+(r*1000)



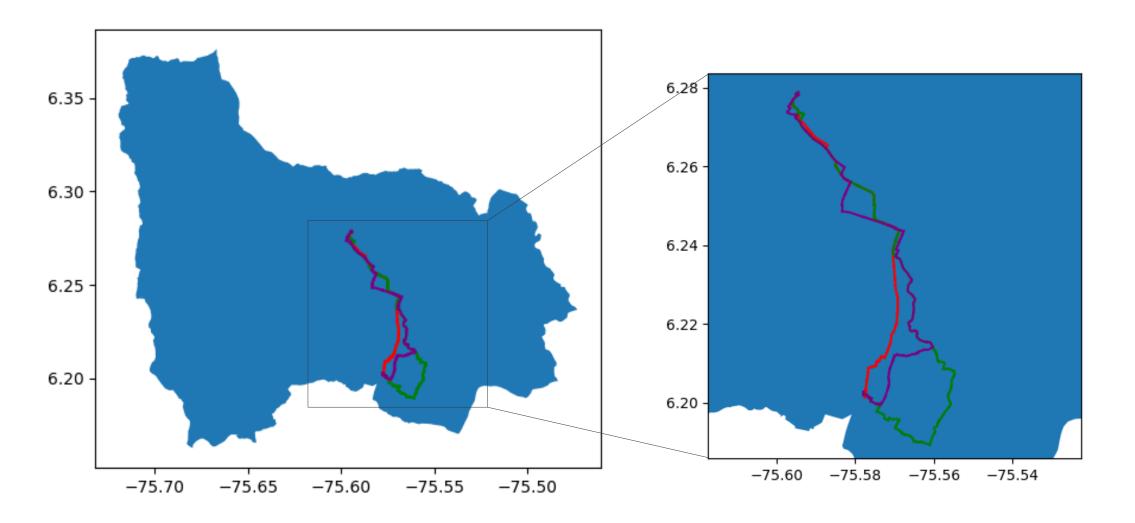
Source	Destiny	Distance (meters)	Harassment risk (between 0 and 1)
Universidad EAFIT	Universidad de Antioquia	14210.585	0.5461

Distance and risk of harassment for the road that minimizes x = distance+(risk*1000). Execution time of 77 seconds.



Visual comparison of the three paths







Future work directions



Proyecto 1

Web Apps: Since it loads on the web server and runs in the browser They are quite useful, works for all phones, no updates needed, they do not take up space unlike mobile apps, and they are also cheaper to develop.

Proyecto 2

VR= the two
environments
communicate and
exchange information
. The interface is a
translator between
the user and the
virtual reality . If the
user applies , the
interface translates
these actions.

Probability Theory

Other risk estimates:
such as weather,
vehicle traffic, time of
day, etc. It helps us to
make a more precise
distribution of
probability, to decide
which risk prevails
over the others.

Optimization 1

Bi objective optimization:
Guarantees assertive decision making, thanks to human input (qualitative vision/knowledge).
Harvest
Organization and analysis
Tracing



