

# Operation of Pulse Train FM detector

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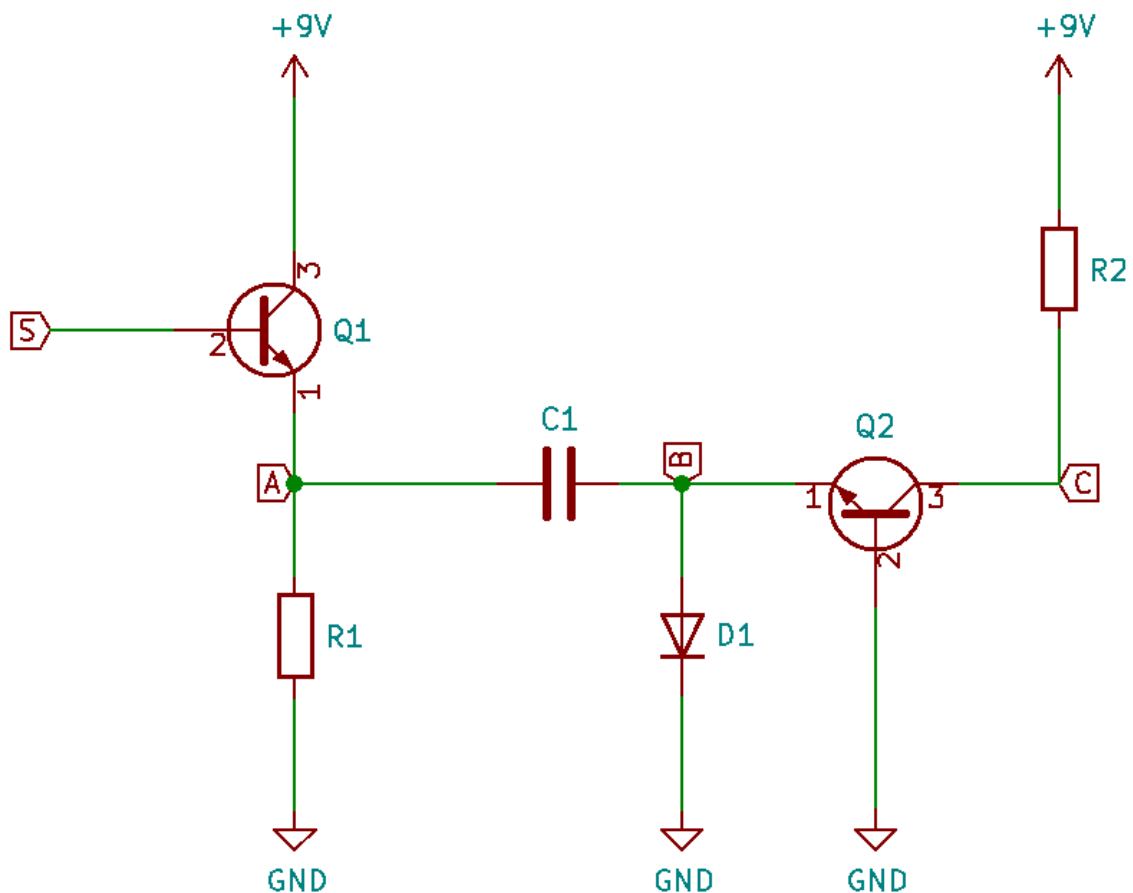
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# 1. Principles of a pulse train FM detector

A pulse train FM detector translates a message which is encoded as a frequency deviation of a carrier into the encoding message. Once every period of the (frequency deviated) carrier a pulse with constant duration is generated. As a result the duty cycle of the resulting pulse train is a direct result of the instantaneous frequency of the input. Low pass filtering the pulse train returns the encoding message.

The pulse width of the output pulses should be constant. ie. independent of the incoming signal.

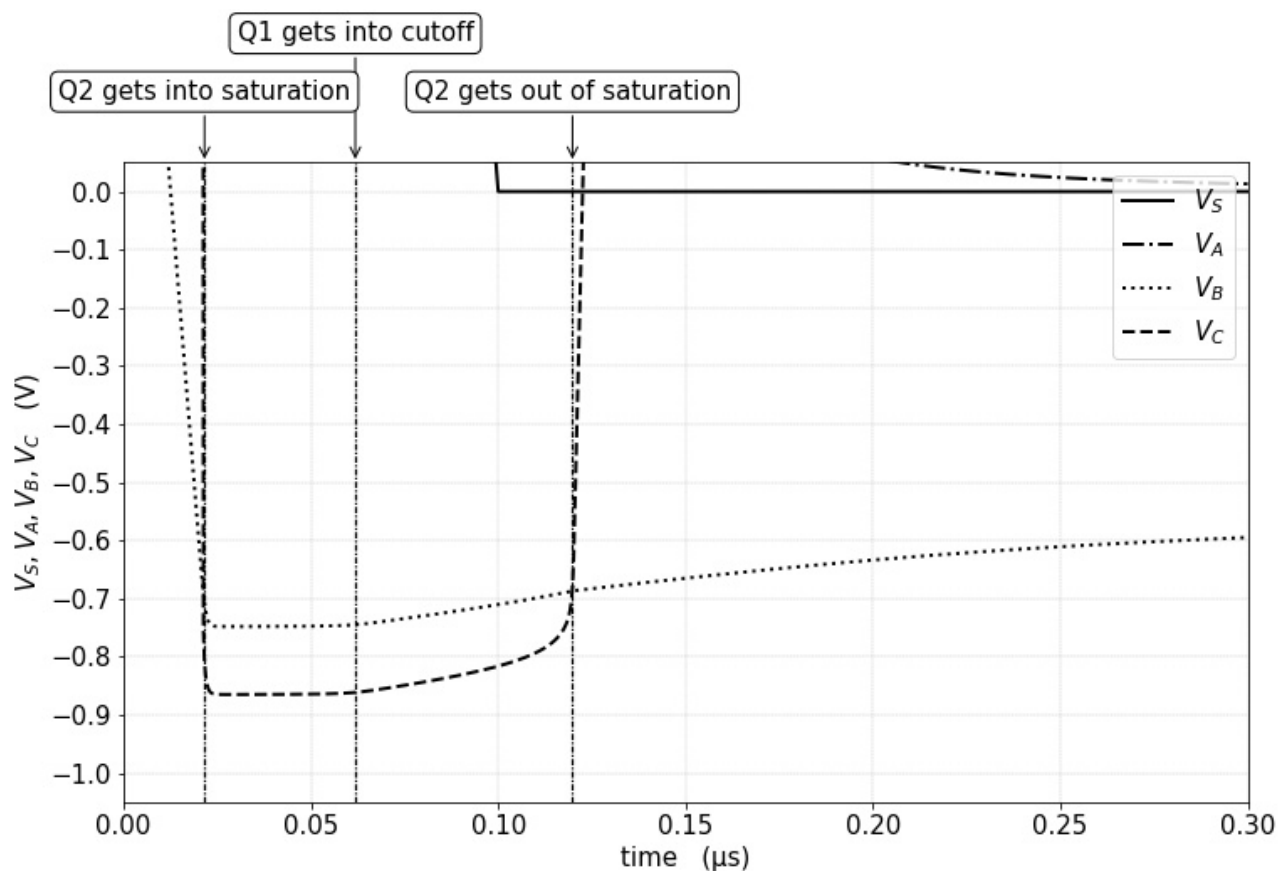
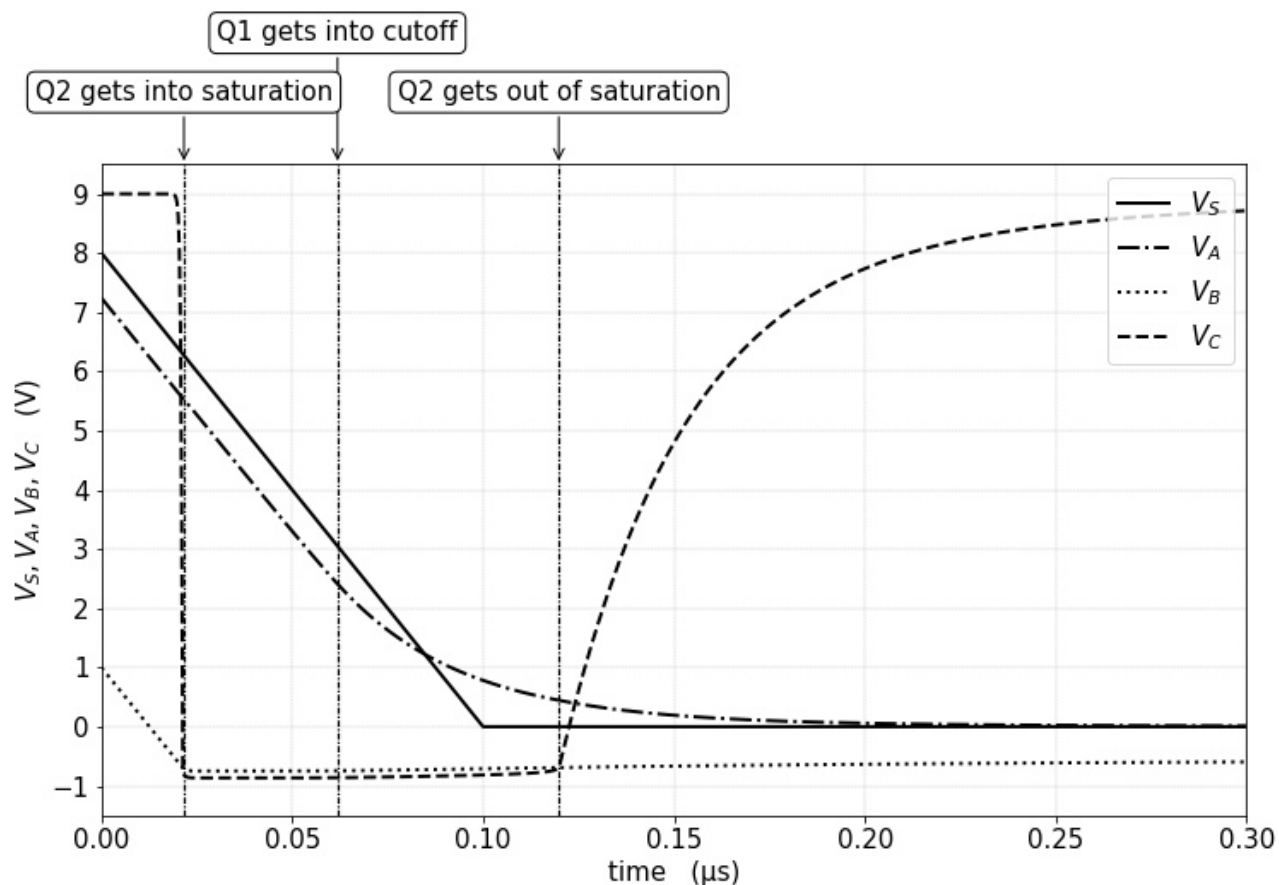
The circuit diagram of a pulse train FM detector looks like this:



The input signal gets into the circuit at S. and the output is taken from C.

In very general terms one could describe operation of the circuit as follows.  $V_B$  will never be higher than a diode drop above because of  $D_1$ . and never lower than a diode drop below ground because of the base-emitter junction of  $Q_2$ . When  $C_1$  is charged.  $V_B$  will be about +0.6V. On a falling input signal  $V_B$  will drop down to about -0.6V. This will get  $Q_2$  into conduction. The  $Q_1$  emitter current will discharge  $C_1$ . This current will pull  $V_C$  down and get  $Q_2$  into saturation. This same current will create a voltage over  $R_1$  which will get  $Q_1$  into cutoff. When  $C_1$  is sufficiently discharged to get  $V_B$  above -0.6V.  $Q_2$  will stop conducting and  $V_C$  will rise to 9V. When  $V_S$  rises again.  $V_A$  will follow and charge  $C_1$ .

This ideal behaviour is shown in figures 1 and 2.



In this document a model is used which describes the pulse generating part of the circuit. Diode  $D_1$  has been removed from the simulation as its only function is prevent  $V_B$  to rise above about +0.6V. Removal of  $D_1$  has been resolved by setting the initial condition for  $V_B$ . see chapter 7.

## 2. General description of operation of pulse train detector

This chapter describes the operation of the pulse train FM detector. The detector operates in four distinct phases. which are separated in the below table by the red rows. The last column in this table mentions certain conclusions which can be drawn from the content in the second and third columns. These four phases can be recognised in figures 1 and 2.

1	Q <sub>1</sub> in conduction. Q <sub>2</sub> in cutoff or active region		
a	V <sub>A</sub> is one diode drop below V <sub>S</sub>	In this phase Q <sub>1</sub> works as an emitter follower.	
b	V <sub>B</sub> drops from initial value to about -0.4V	<p>This negative voltage at V<sub>B</sub> depends on the value of C<sub>1</sub>. When Q<sub>2</sub> gets into its active region <math>i_{Q_2}</math> discharges C<sub>1</sub>. A larger C<sub>1</sub> needs a larger <math>i_{Q_2}</math> to discharge the same amount as a small C<sub>1</sub>. Because V<sub>A</sub> is dictated by V<sub>S</sub> (Q<sub>1</sub> in active region) for a larger C<sub>1</sub>. V<sub>B</sub> needs to drop lower for for more discharge current <math>i_{Q_2}</math> to keep up with V<sub>A</sub>.</p> <p>With a small enough value for C<sub>1</sub>. Q<sub>2</sub> may not even reach saturation. This is a degenerate case.</p>	<p>1. larger C<sub>1</sub> -&gt; lower V<sub>B</sub>  2. very small C<sub>1</sub> -&gt; Q<sub>2</sub> does not saturate</p>
c	i <sub>Q1</sub> drops with falling V <sub>S</sub>	<p>i<sub>Q1</sub> depends on R<sub>1</sub></p> $i_{Q_1} \approx \frac{V_S - 0.6}{R_1} - i_{Q_2}$	
d	i <sub>Q2</sub> rises because of dropping V <sub>B</sub> until Q <sub>2</sub> saturates	<p>Ideally the Ebers-Moll model should be used. but the Shockley diode equation multiplied by <math>\beta</math> is a good approximation:</p> $i_{Q_2} = \beta \cdot I_S \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right)$ <p>As long as Q2 is not saturated <math>i_{R_2} = i_{Q_2}</math></p>	
e	after Q <sub>2</sub> gets into active region i <sub>R2</sub> rises quickly		
f	V <sub>C</sub> drops quickly until it gets Q <sub>2</sub> in saturation > enter 2	$V_C = V_{CC} - i_{R_2}$	
2	Q <sub>1</sub> in active region. Q <sub>2</sub> in saturation		
a	V <sub>B</sub> reaches a minimum at about -0.4V	for the minimum value of V <sub>B</sub> see 1b.	

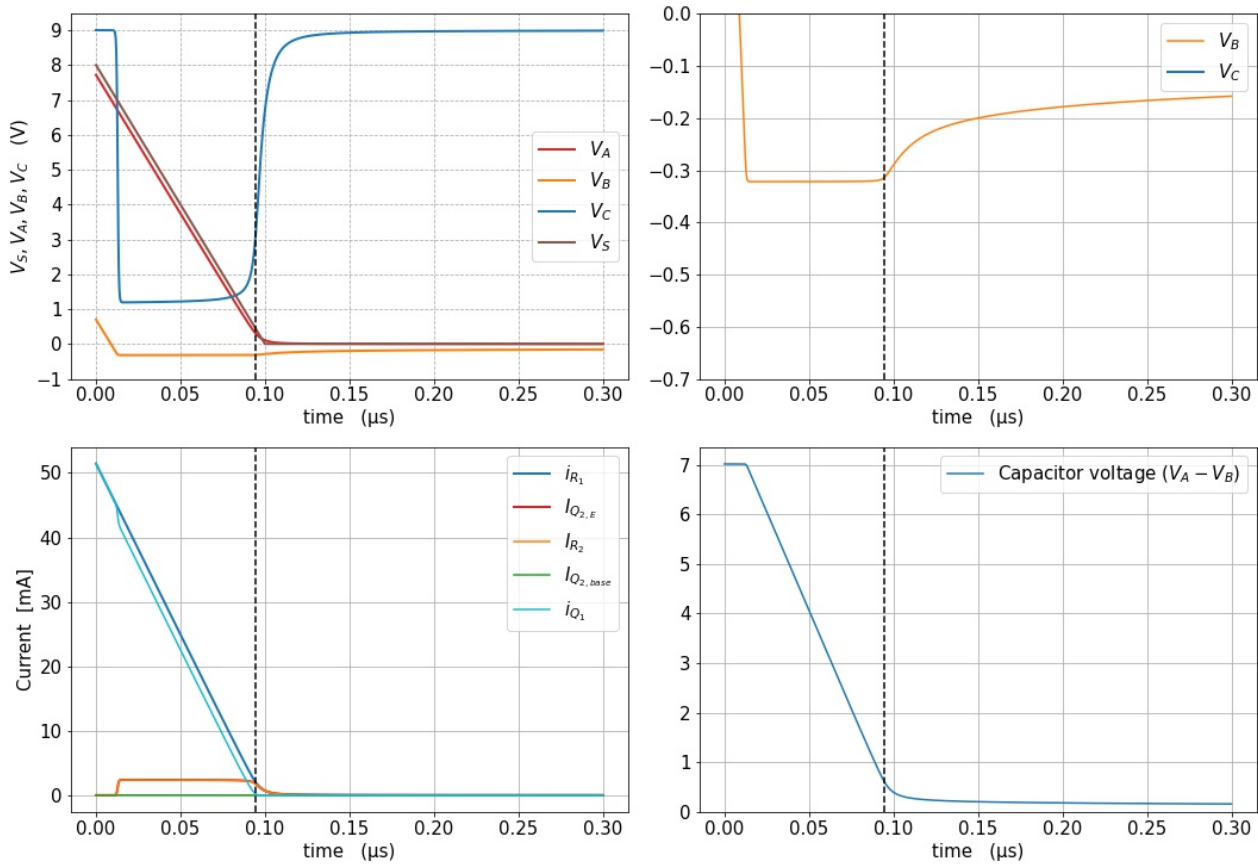
b	any current $i_{Q2}$ which cannot be taken from the collector $i_{Q2,base}$ is taken from the base $i_{Q2,base}$	this can be a substantial amount	
b	$C_1$ discharges because of $i_{Q2}$	$i_{Q2} = C_1 \cdot \frac{d(V_B - V_A)}{dt}$	
c	$i_{Q2}$ does not contribute enough to keep $V_A$ one diode drop below $V_S$ so $Q_1$ stays in active region	<p>In this phase <math>V_A &gt; i_{Q2}R_1</math>. When <math>V_A = i_{Q2}R_1</math> the current <math>i_{Q2}</math> suffices to get <math>V_A</math> on the level as dictated by <math>V_S</math>. At that moment <math>i_{Q1} = 0</math> and <math>Q_1</math> gets into cutoff.</p> <p>At larger <math>R_1</math> the voltage induced at A induced by <math>i_{Q2}</math> will be larger. so <math>Q_1</math> will get into cutoff sooner.</p> <p>And. because <math>V_B</math> depends on the value of <math>C_1</math> (see 1b). and <math>i_{Q2}</math> depends on <math>V_B</math>. the moment at which <math>Q_1</math> gets into cutoff depends on <math>C_1</math>.</p>	3. larger $C_1 \Rightarrow Q_1$ gets into cutoff sooner
d	$V_B$ stays constant at about -0.4V	for the minimum value of $V_B$ see 1b.	
e	when $i_{Q2}$ can supply enough current to maintain $V_A$ . $Q_1$ gets into cutoff > enter 3	$V_A = (i_{Q1} + i_{Q2}) \cdot R_1 = i_{Q2} \cdot R_1$	4. larger $R_1 \Rightarrow Q_1$ gets into cutoff sooner
f	$V_C$ at minimum value. about one diode drop below $V_{Q2,base}$		
3	<b><math>Q_1</math> in cutoff. <math>Q_2</math> in saturation</b>		
a	$i_{Q2}$ is large enough to maintain $V_A$	$V_A = i_{Q2} \cdot R_1$ <p><math>i_{Q1}</math> is not needed to maintain <math>V_A</math>. so <math>Q_1</math> is in cutoff.</p>	
b	$V_A$ is dropping because of $C_1$ discharge by $i_{Q2}$	$i_{Q2} = C_1 \cdot \frac{d(V_B - V_A)}{dt}$	
c	$V_A$ and $V_B$ are determined by the diminishing voltage over the capacitor and the balance equation	$V_A \cdot Z_B = -V_B \cdot R_1$ <p>where</p> $Z_B = -\frac{V_B}{i_{Q2}}$ <p>The larger <math>R_1</math> the more of the voltage over the capacitor is placed over <math>R_1</math>. and thus the higher is <math>V_A</math> and lower <math>V_B</math> (less negative). and so smaller <math>i_{Q2}</math>.</p>	

d	by the diminishing voltage over $C_1$ . and the balance equation $V_B$ slowly rises	see 3c.	
e	$i_{Q2}$ drops		
f	$i_{Q2,base}$ drops as $Q_2$ is still in saturation		
g	$Q_2$ gets slowly out of saturation		
h	$V_C$ slowly rises. until $Q_2$ gets out of saturation > enter 4	<p><math>V_C</math> slowly rises because of rising <math>V_B</math> and thus decreasing <math>i_{Q2}</math>.</p> <p><math>V_B</math> relates to <math>i_{Q2}</math> and <math>V_A</math> with</p> $i_{Q2} = \frac{V_A}{R_1} = I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right)$ <p>(or better even. with the Ebers-Moll equation). But also</p> $i_{Q2} = C_1 \cdot \frac{d(V_B - V_A)}{dt}$ <p>So a larger <math>C_1</math> will discharge slower for the same <math>V_B</math> and <math>i_{Q2}</math>. Slower discharge will cause it to take longer to get out of saturation which will give a longer negative pulse on the collector of <math>Q_2</math>.</p> <p>Larger <math>R_1</math> puts more voltage on <math>V_A</math> than with smaller <math>R_1</math>. This gives a smaller <math>i_{Q2}</math>. so a smaller discharge rate. so a longer output pulse.</p> <p>Because a larger <math>R_1</math> causes <math>Q_1</math> to get into cutoff sooner. <math>V_B</math> will be less deep because of the balance equation. For very large <math>R_1</math> and less deep <math>V_B</math>. <math>Q_2</math> will get out of saturation sooner. so give a shorter output pulse.</p>	<p>5. larger <math>C_1</math> -&gt; longer negative output pulse on <math>Q_2</math>.</p> <p>6. larger <math>R_1</math> -&gt; longer negative output pulse on <math>Q_2</math>.</p> <p>7. even larger <math>R_1</math> -&gt; shorter output pulse on <math>Q_2</math>.</p>
i	$i_{R2}$ slowly decreases		
4	$Q_2$ out of saturation		

a	$i_{Q2}$ still discharges $C_1$	<p>The rate at which <math>C_1</math> discharges is determined by <math>i_{Q2}</math>, which in turns depends on <math>V_B</math>, which depends on the voltage over <math>C_1</math>, the value of <math>C_1</math> by</p> $i_{Q2} = C_1 \cdot \frac{d(V_B - V_A)}{dt}$ <p>and the balance equation:</p> $i_{Q2} = \frac{V_A}{R_1} = I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right)$ <p>The balance equation divides the voltage over the capacitor over <math>V_A</math> and <math>V_B</math>. The larger <math>R_1</math>, the smaller (in magnitude) <math>V_B</math>, the smaller <math>i_{Q2}</math>, the smaller the discharge rate. This translates to a less steep rise in <math>V_C</math> in this phase.</p>	<p>8. larger <math>R_1 \rightarrow</math> less steep rise on output pulse</p> <p>9. larger <math>C_1 \rightarrow</math> less steep rise on output pulse</p>
b	because of $C_1$ discharge and balance equation. $V_B$ rises and $V_A$ drops		
c	$i_{Q2}$ drops		
d	$i_{R2}$ drops		
e	$V_C$ rises	For the rate at which $V_C$ rises see 4a	

### 3. Degenerate cases

$$R_1=150\Omega, R_2=3300\Omega, C_1=30.0\text{pF}, T_1=0.1\mu\text{s}$$

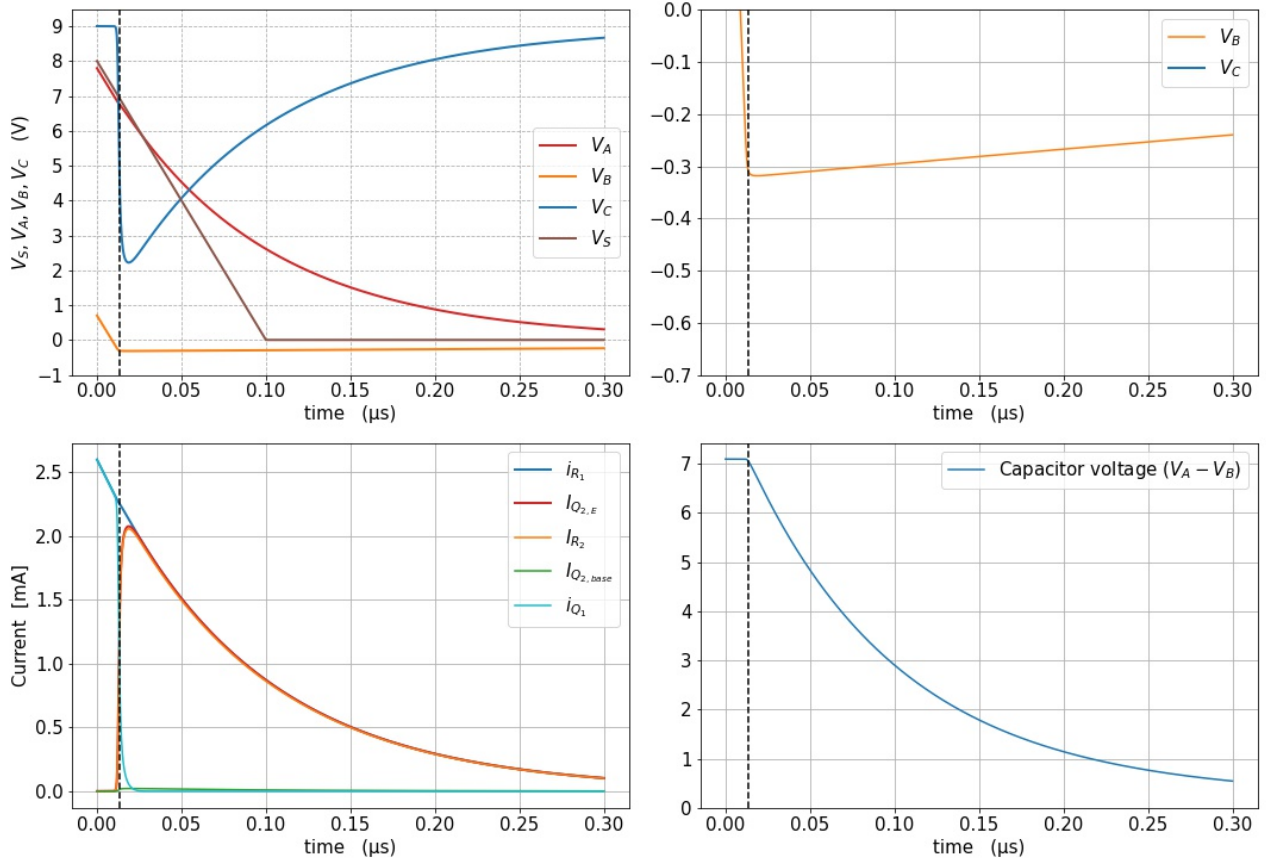


The value of  $C_1$  is too small to get  $Q_2$  into saturation. Lowest value for  $V_B$  depends on the value of  $C_1$  (see chapter 3.); larger  $C_1$  gives more negative  $V_B$ . A more negative  $V_B$  gives a larger current through  $Q_2$ . If the current is too low,  $Q_2$  will not get into saturation.

The value of  $R_1$  is small enough to give a nice steep rising edge on the output pulse. If the value of  $R_1$  is larger (as shown in the next figure). with the same value for  $C_1$ . The output pulse is further degenerated.



$$R_1=3000\Omega, R_2=3300\Omega, C_1=30.0\text{pF}, T_1=0.1\mu\text{s}$$

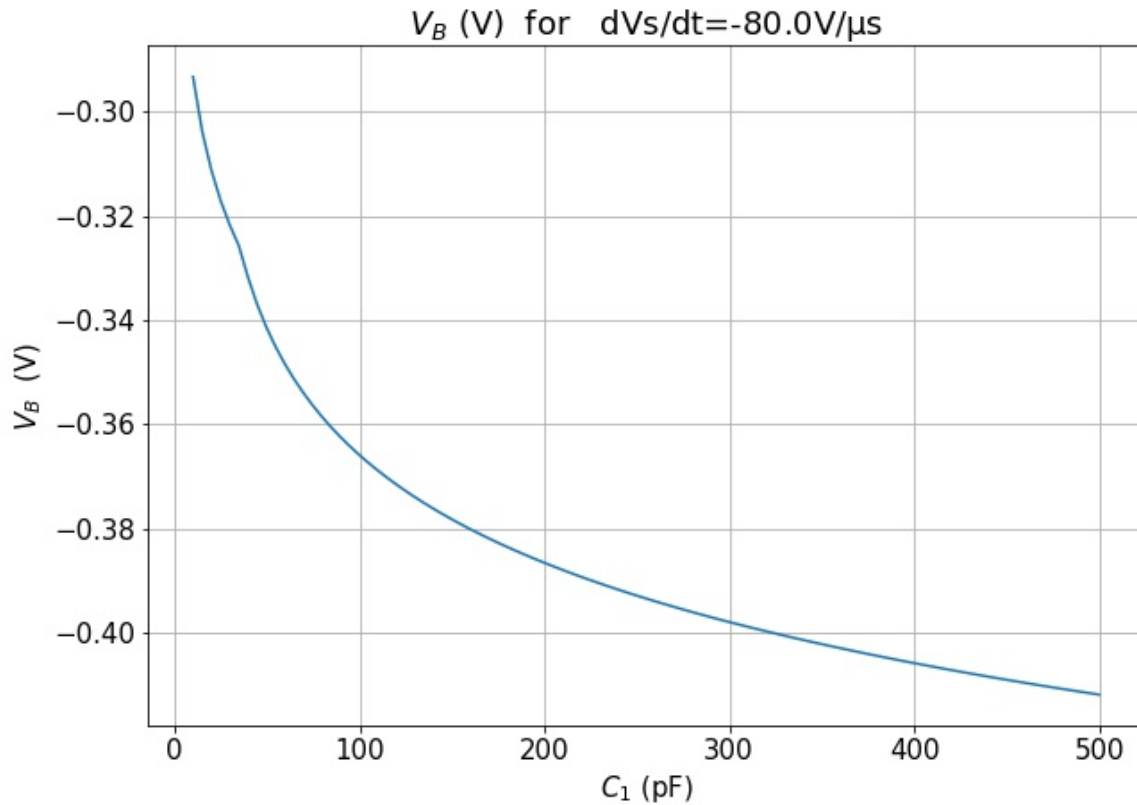


Besides a too low value for  $C_1$ , which will not let  $Q_2$  get into saturation, the value for  $R_1$  is too large. The too large value for  $R_1$  causes a slow discharge of  $C_1$  which shows as a less steep rising edge on the output pulse.

## 4. $V_B$ dependency of $C_1$ , $R_1$ and $dV_S/dt$

### 4.1 $Q_1$ in active region

The graph below shows the steady state value for  $V_B$  when  $Q_1$  is in its active region. It depends on the value of  $C_1$  and the rate at which  $V_S$  is dropping. It is independent of  $R_1$ . This is only valid when  $Q_1$  is in its active region.



The capacitor discharge equation over  $C_1$

$$i_{E,Q_2} = C_1 \left( \frac{dV_B}{dt} - \frac{dV_A}{dt} \right)$$

$V_B$  is more or less constant when  $Q_1$  is in its active region. With  $V_B$  constant

$$i_{E,Q_2} = -C_1 \frac{dV_A}{dt}$$

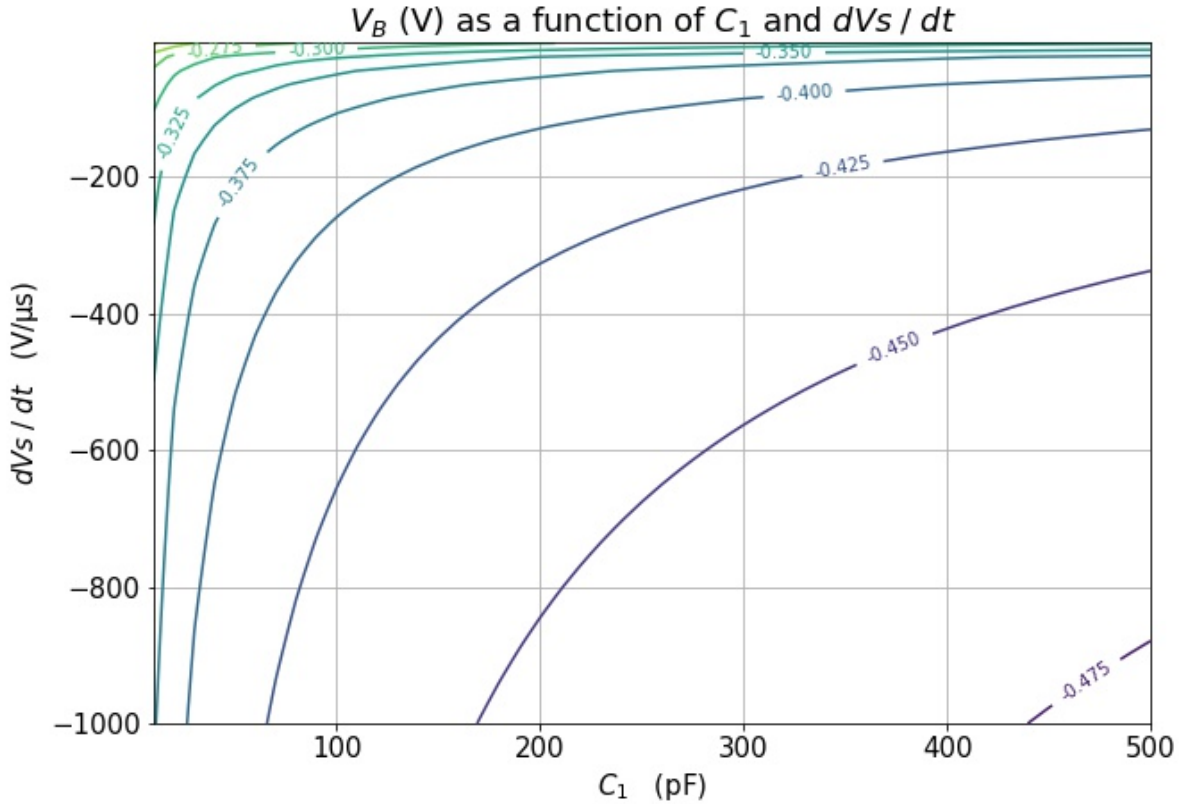
Because  $Q_1$  acts as a voltage follower ( $Q_1$  is in its active region)

$$\begin{aligned} \frac{dV_A}{dt} &= \frac{dV_S}{dt} \\ \Rightarrow i_{E,Q_2} &= -C_1 \frac{dV_S}{dt} \end{aligned}$$

$i_{E,Q_2}$  only depends on  $V_B$  (Ebers-Moll).  $C_1$  is the variable in the above graph. To calculate the above graph a root finder is used to find  $V_B$  (using equations 2 and 3.) to fulfil the equation

$$i_{Q,E_2}(V_B) = -C_1 \frac{dV_S}{dt}$$

It shows that with larger value for  $C_1$ . transistor  $Q_2$  gets deeper in saturation.



The above figure shows that larger values for  $C_1$  will give lower (more negative) values for  $V_B$ . Also larger absolute (more negative) values for  $\frac{dV_S}{dt}$  gives lower (more negative) values for  $V_B$ . Larger absolute values for  $V_B$  (more negative) will get  $Q_2$  into deeper saturation.

The value for  $V_B$  can be calculated by solving the capacitor current equation

$$i_{E,Q_2} = C_1 \frac{dV_{C_1}}{dt}$$

If we assume that  $V_B$  is constant. we know that

$$\frac{dV_{C_1}}{dt} = \frac{d(V_B - V_A)}{dt} = -\frac{dV_A}{dt}$$

When  $Q_1$  is in its active region.  $Q_1$  acts as a voltage follower. and so

$$\frac{dV_A}{dt} = \frac{dV_S}{dt}$$

$$\Rightarrow \frac{dV_{C1}}{dt} = -\frac{dV_S}{dt}$$

Substitute:

$$i_{E,Q2} + C_1 \frac{dV_S}{dt} = 0 \quad (1)$$

$i_{E,Q2}$  can be calculated from  $V_B$  and  $V_C$  with the Ebers-Moll model:

$$i_{E,Q2} = I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right) - \alpha_R \cdot I_{CS} \cdot \left( e^{-\frac{V_C}{V_T}} - 1 \right) \quad (2)$$

When  $V_C$  is known.  $i_{E,Q2}$  can be calculated for any  $V_B$ . Next we will derive an expression for  $V_C$  in terms of  $V_B$ .

For the base current we have the following equation from the Ebers-Moll model

$$I_B = (1 - \alpha_F) \cdot I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right) + (1 - \alpha_R) \cdot I_{CS} \cdot \left( e^{-\frac{V_C}{V_T}} - 1 \right)$$

and for the collector current we have the following equation (Ohm's law over  $R_2$ )

$$I_C = \frac{V_{CC} - V_C}{R_C}$$

Kirchhoff's current law over the transistor is

$$I_E - I_B - I_C = 0$$

where  $I_E = i_{Q2}$ . Substitution of the expressions for  $I_E$ ,  $I_B$  and  $I_C$  into the current law gives

$$I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right) - \alpha_R \cdot I_{CS} \cdot \left( e^{-\frac{V_C}{V_T}} - 1 \right) - (1 - \alpha_F) \cdot I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right) - (1 - \alpha_R) \cdot I_{CS} \cdot \left( e^{-\frac{V_C}{V_T}} - 1 \right) - \frac{V_{CC} - V_C}{R_C} = 0$$

which simplifies to

$$\alpha_F \cdot I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right) - I_{CS} \cdot \left( e^{-\frac{V_C}{V_T}} - 1 \right) - \frac{V_{CC} - V_C}{R_C} = 0$$

From this  $V_C$  can be expressed in terms of  $V_B$  as follows

$$V_C = V_T \cdot W_0 \left( \frac{R_C I_{CS}}{V_T} e^{\frac{A R_C}{V_T}} \right) - A R_C \quad (3)$$

where

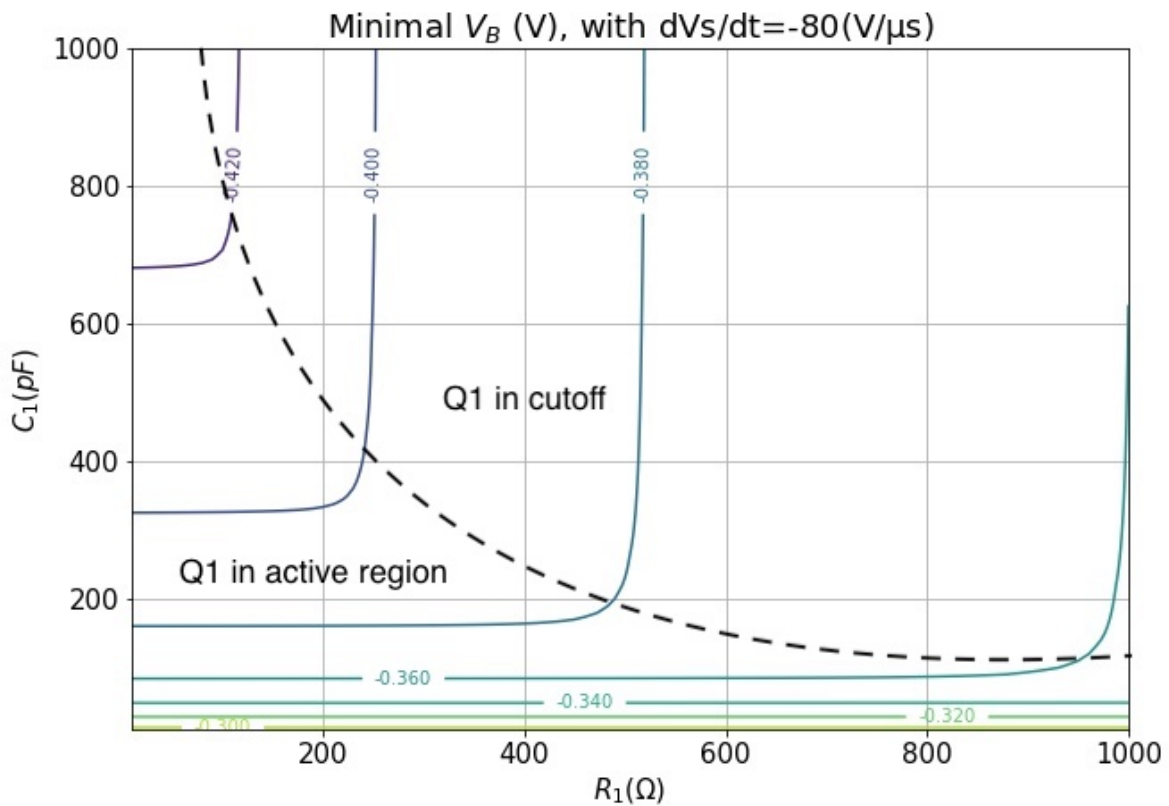
$$A = \alpha_F I_{ES} \left( e^{-\frac{V_B}{V_T}} - 1 \right) + I_{CS} - \frac{V_{CC}}{R_C}$$

and  $W_0$  is the Lambert W function.

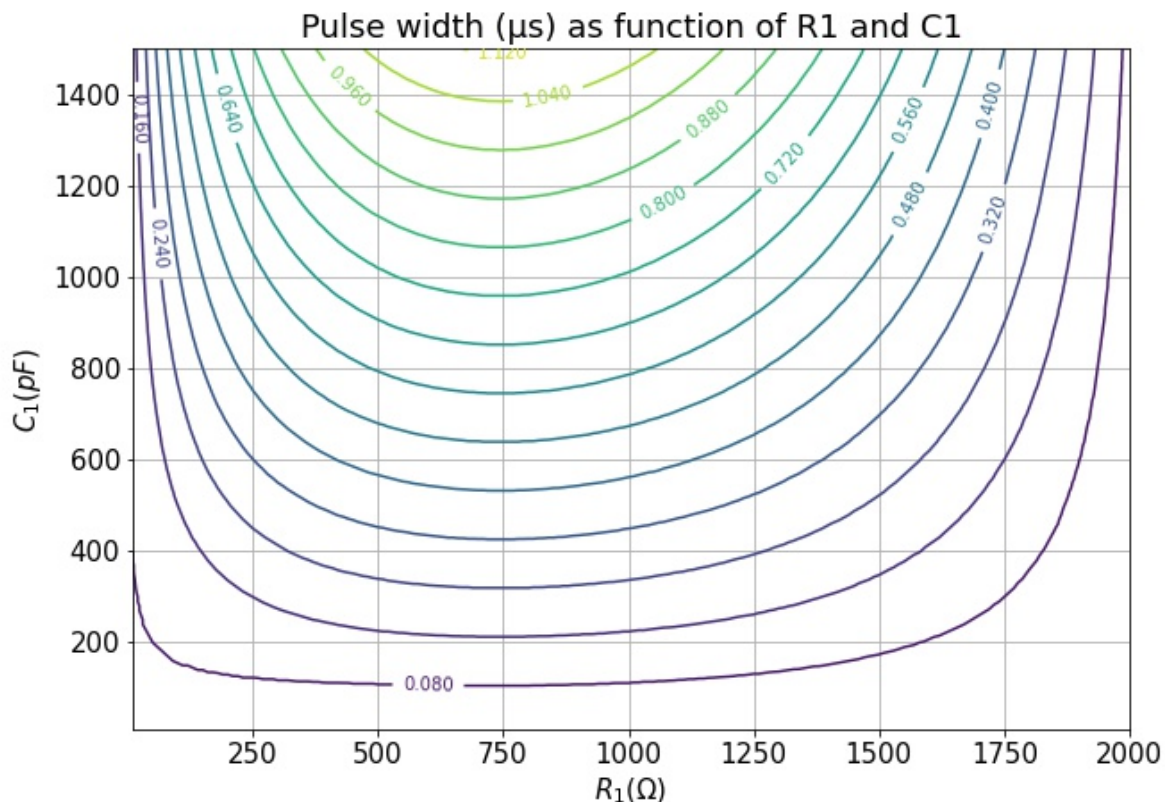
Inserting (3) into (2) allows to calculate  $i_{E,Q2}$ . Using (1) in a root finding algorithm (eq. brentq) and solving for  $V_B$  will return  $V_B$  for any  $\frac{dV_S}{dt}$  and  $C_1$ . Note that this is independent of  $R_1$  and is only valid when  $Q_1$  is in its active region.

## 4.2 $Q_1$ either in active region or cutoff

The graph below shows the dependency of the minimal value of  $V_B$  on  $R_1$  and  $C_1$  when  $Q_1$  is in its active region or in cutoff. The horizontal part of the constant  $V_B$  lines are in the active region of  $Q_1$  where the minimal value of  $V_B$  only depends on  $C_1$ . and is independent of  $R_1$ . The vertical lines are in the cutoff region of  $Q_1$ . the minimal value of  $V_B$  depends on  $R_1$  only.



## 5. Pulse width



The figure above shows lines for constant pulse width. In this context the pulse width is conveniently defined as the time between zero-crossing of the falling and rising edge of the pulse at the collector of  $Q_2$ . It should be noted that pulse width is less clear when the rising edge of the pulse is not steep. Especially in cases with large values  $C_1$  and/or  $R_1$  this definition does not work well.

We see that larger values for  $C_1$  give larger pulse width. There are several counteracting effects of the value of  $C_1$  on the pulse width.

With larger  $C_1$ :

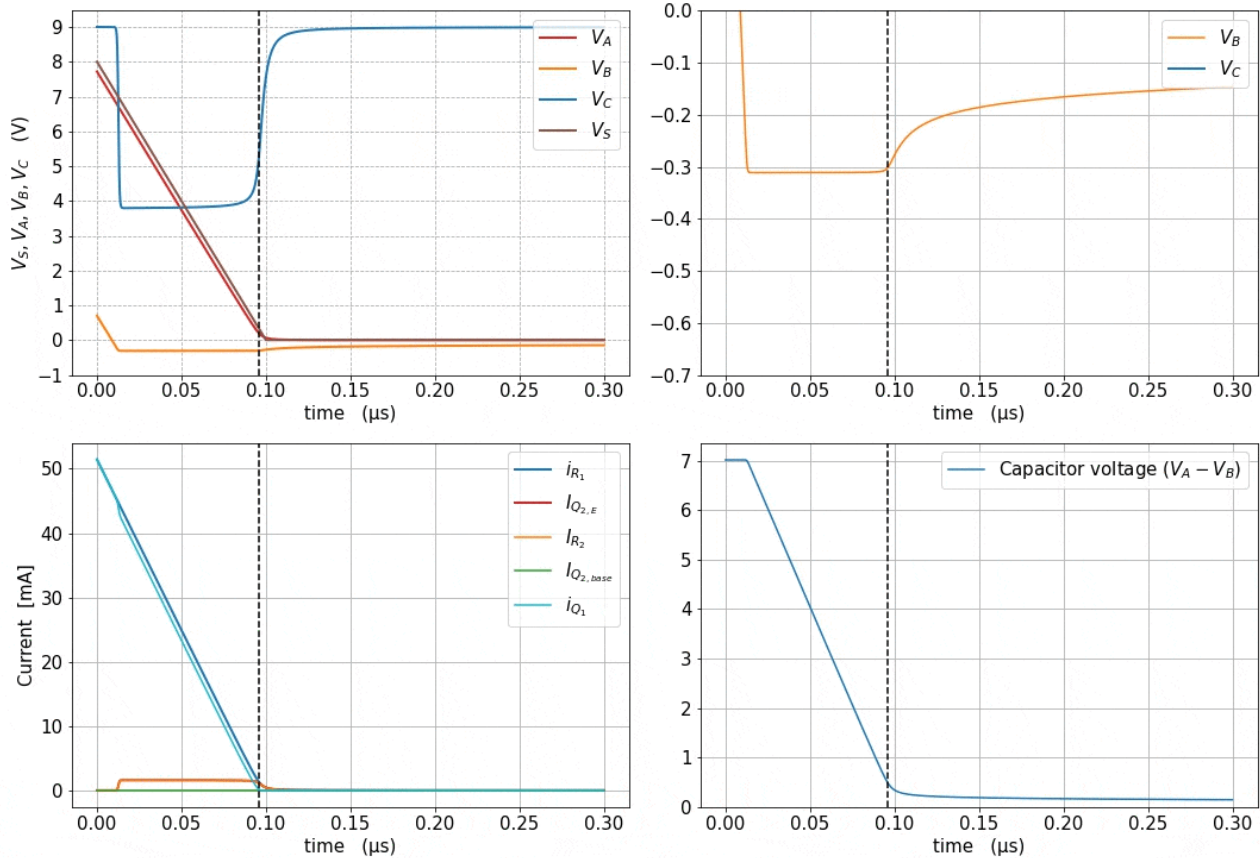
1. the value of  $V_B$  will be more negative (in times of  $Q_1$  active region). so a larger discharge current  $\rightarrow$  shorter output pulse
2.  $Q_1$  gets into cutoff sooner. Cutoff of  $Q_1$  means that  $V_A$  drops slower than  $V_S$ .  $Q_1$  getting into cutoff means that  $C_1$  discharges slower than than if  $Q_1$  would not have been in cutoff  $\rightarrow$  longer output pulse
3. more current is needed to discharge a larger value capacitor. This is especially true when  $Q_1$  is in cutoff.  $\rightarrow$  longer output pulse
4. less steep rising edge on the output pulse. although this does not play a role when using the current definition of pulse width. as this effect mainly takes place when  $V_C > 0$ .

Apparently the effects which cause a longer output pulse with increasing  $C_1$  win.

Note that for  $R_1 \approx 750\Omega$  the pulse width linearly relates to  $C_1$ .

Below is an animation of increasing the value of  $C_1$ .<sup>1</sup>

$$R_1=150\Omega, R_2=3300\Omega, C_1=20\text{pF}, T_1=0.1\mu\text{s}$$



For increasing values of  $R_1$  there is a maximum for the pulse width, which in the figure above seems to be between  $750\Omega < R_1 < 1000\Omega$ . There are several counteracting effects of the value of  $R_1$  on the pulse width.

With larger values of  $R_1$ :

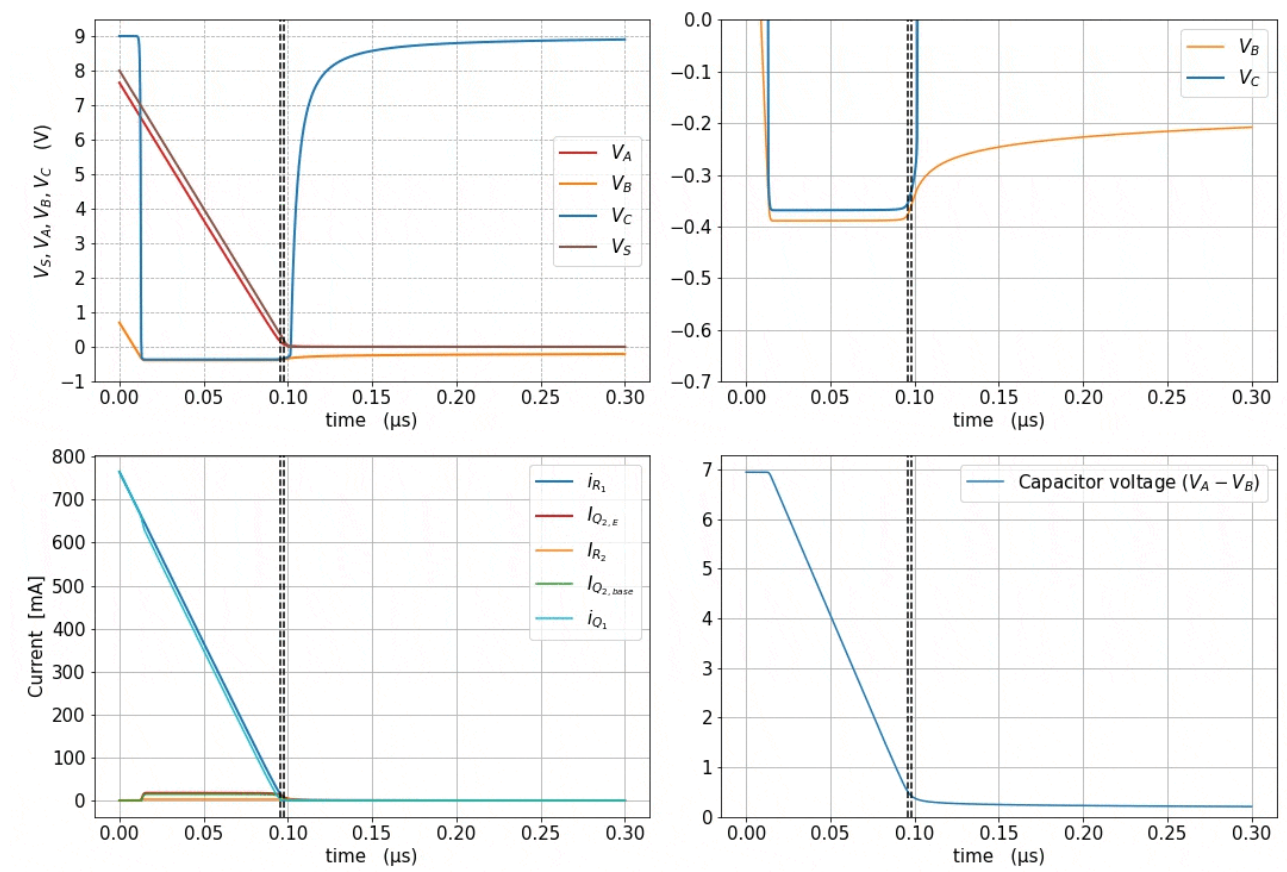
1.  $Q_1$  gets into cutoff sooner. Cutoff of  $Q_1$  means that  $V_A$  drops slower than  $V_S$ .  $Q_1$  getting into cutoff means that  $C_1$  discharges slower than if  $Q_1$  would not have been in cutoff  $\rightarrow$  longer output pulse. This is the same effect as for a larger value of  $C_1$ .
2. with even larger  $R_1$  cutoff of  $Q_1$  will set in nearly immediately. As a result  $V_A$  will be dictated by the balance equation in which  $R_1$  plays an important role. Larger  $R_1$  will put more voltage of the capacitor on  $R_1$  and less on the base-emitter junction of  $Q_2$ .  $Q_2$  will get out of saturation sooner, as it has not been in deep saturation. This will give a shorter pulse width if we define it as the  $V_C$  zero crossing. But total discharging time of the capacitor will take longer. With very large values of  $R_1$  the circuit is getting into the degenerated area. Discharging of  $C_1$  in the saturated state of  $Q_2$  will be shorter, but the overall discharging of  $C_1$  will take longer, with most of the time in the non-saturated state of  $Q_2$ .<sup>2</sup>
3. with even larger values for  $R_1$  the detector gets in a degenerated state in which  $Q_2$  does not saturate at all anymore. This starts happening for values of  $R_1$  at which  $Q_1$  gets into cutoff immediately. At these values for  $R_1$ ,  $V_B$  does not drop as low as when  $Q_1$  is in its active region.

<sup>1</sup> The animation shows only in mac Pages. The animation can be downloaded separately from Github. filename = "C1 series. R1=150.gif".

<sup>2</sup> In fact pulse width cannot be defined as the  $V_C$  zero-crossing for large values of  $R_1$ .

The following animation shows a series of increasing  $R_1$  values. leading ultimately into a degenerate pulse on the output. <sup>3</sup>

$$R_1=10\Omega, R_2=3300\Omega, C_1=220.0\text{pF}, T_1=0.1\mu\text{s}$$

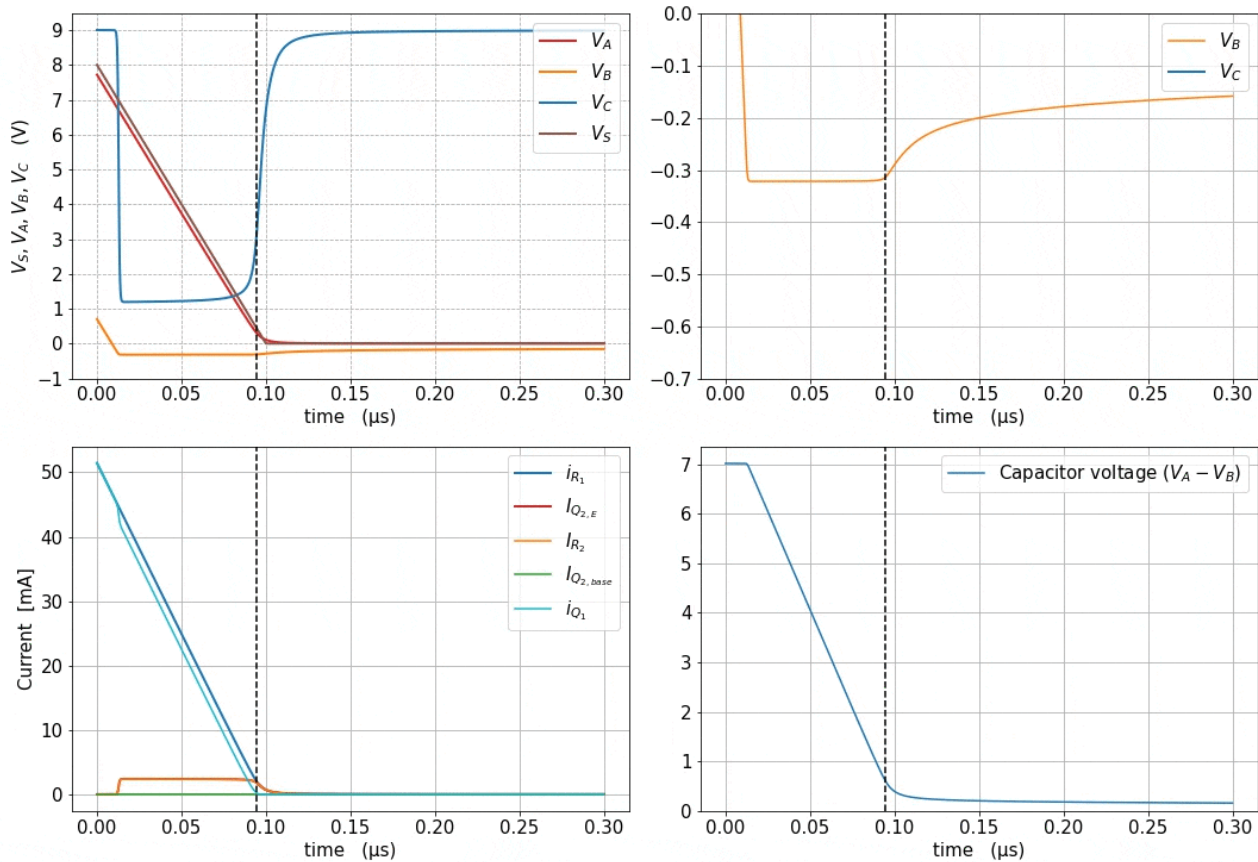


<sup>3</sup> The animation only shows in mac Pages. This animation can be downloaded separately from Github. filename = "R1 Series. C1=220pF.gif"



The next animation shows a degenerate case. with increasing  $R_1$  and  $Q_2$  not getting into saturation <sup>4</sup>.

$$R_1=150\Omega, R_2=3300\Omega, C_1=30\text{pF}, T_1=0.1\mu\text{s}$$



The definition of pulse width as the time between falling zero crossing of  $V_C$  and rising zero crossing can only be used when  $Q_2$  gets well into saturation. If  $Q_2$  does not saturate the zero crossing is less abrupt, and also the rising slope of the output pulse is less steep. In these cases one cannot really speak of a pulse. These are degenerated cases of the pulse train detector.

## 6. What are desired features of a pulse train FM detector?

1. The pulse width of the pulse at the output should be independent of frequency.
2. The pulse width should be as large as possible for maximum dynamic range. Of course the pulse width must be less than the half period of the input signal. Also there should be sufficient margin to allow for highest temporal frequency input signals to be processed well. The maximum frequency deviation in the intermediate frequency signal is equal to the maximum frequency deviation of the original FM signal at FM frequencies. For FM radio the maximum frequency deviation is  $\pm 75\text{kHz}$ . The period of a  $75\text{kHz}$  signal is  $13\mu\text{s}$ . This means that the maximum pulse width can be  $13/2=6.5\mu\text{s}$ .
3. Each pulse in the pulse train should be independent of its predecessor. When  $Q_2$  leaves its saturated state further discharge of  $C_1$  takes place at a much slower rate than when  $Q_2$  is in saturation. When either  $C_1$  and/or  $R_1$  have large values the rising edge on the output pulse is not steep. Before the next falling slope of the input signal, an upward swing pulls  $V_B$  high, so

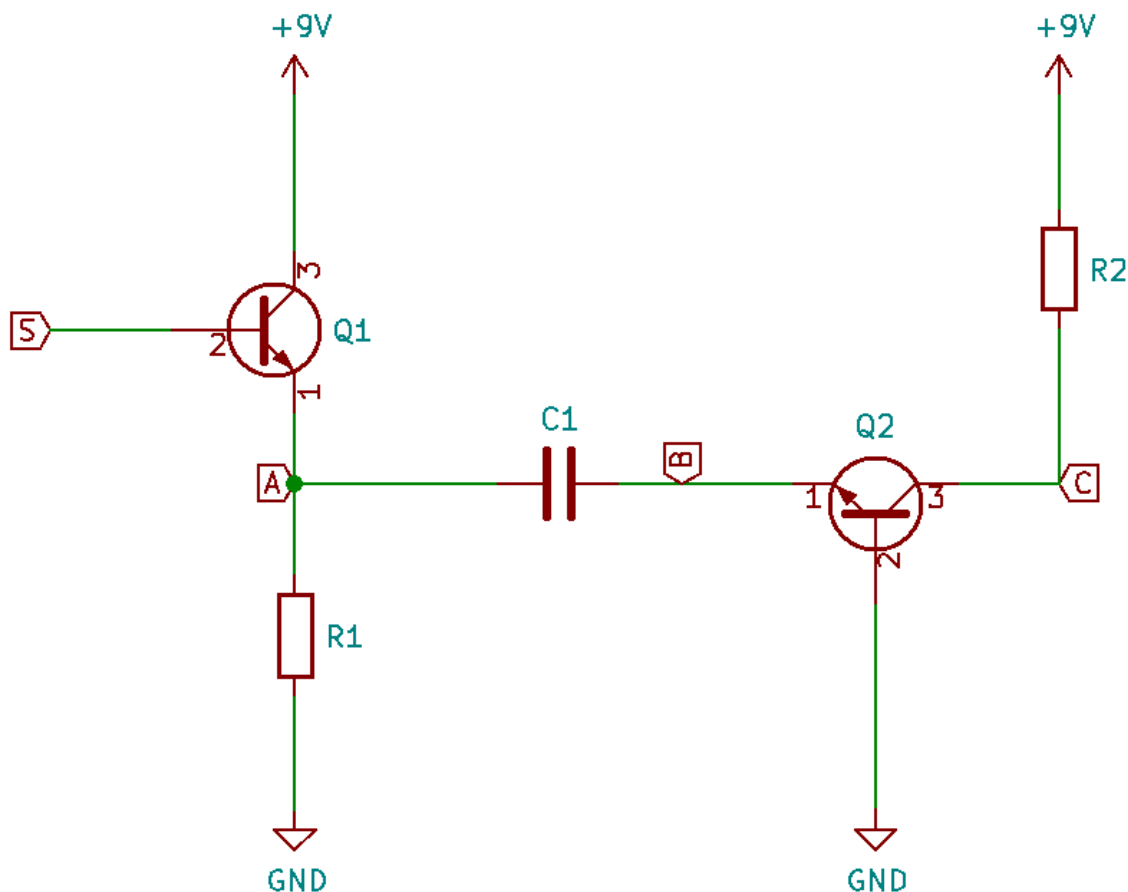
<sup>4</sup> The animation only shows in mac Pages. This animation can be downloaded separately from Github. filename = "R1 Series. C1=30pF.gif"

$Q_2$  will stop conducting, which in turn will pull  $V_C$  high. So, even if  $V_C$  has not reached  $V_{CC}$  before the input signal rises again because of high values of  $R_1$  and/or  $C_1$ ,  $V_C$  will be at  $V_{CC}$  for the next pulse. This makes the pulse independent of the previous pulse.

4. The relation duty cycle vs. the input signals frequency deviation should be linear. Large  $R_1$  and/or  $C_1$  values will cause  $V_C$  to be pulled abruptly high to  $V_{CC}$  as described in the previous point. This will affect the linearity of the detector.
5. Steepest rising edges are obtained when  $R_1$  has a small value. Smaller  $R_1$  implies more power consumption in the emitter follower stage  $Q_1$ . Take care not to exceed the maximum collector current for  $Q_1$  when using a small  $R_1$ .

## 7. How are the plots generated?

The plots in this document are generated with a Jupyter notebook which models the pulse train FM detector. The notebook models the following circuit:



For simplicity  $D_1$  in the original circuit has been removed. In the real circuit  $D_1$  is needed to limit  $V_B$  to about +0.6V. In the simulation this part of the circuit is not needed. Including  $D_1$  in the simulation would only make the model more complicated <sup>5</sup>.

<sup>5</sup> The differential equation describing the voltage at  $V_B$  would be a bit more complicated, although probably not by much. In a next revision of the model it may be implemented.

The Jupyter notebook can be downloaded from Github.

## 7.1 Mathematical model

The circuit is described by

- Ebers-Moll model transistor for  $Q_1$
- Ebers-Moll model transistor for  $Q_2$
- Kirchhoff's current law for  $Q_2$
- Kirchhoff's current law at A
- capacitor current-voltage relation for  $C_1$
- Ohm's law over  $R_1$  and  $R_2$

These simple laws are put into

- one equation to calculate  $V_C$  for any  $V_B$  and  $R_2$
- one differential equation which describes the voltage change over  $C_1$  in time.

These two relations entirely describe the above circuit and will (also) let us calculate the most important aspect of this circuit.  $V_C$  as a function of time.

More equations are implemented in this notebook to test the model. and to implement helper functions. They are not essential to the model however.

## 7.1 Transistor equations

The Ebers-Moll equations for an NPN transistor are as follows. For the  $Q_2$  emitter current  $I_E$  we have the following:

$$I_E = I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right) - \alpha_R \cdot I_{CS} \cdot \left( e^{-\frac{V_C}{V_T}} - 1 \right)$$

For the  $Q_2$  base current  $I_B$  we have the following Ebers-Moll equation

$$I_B = (1 - \alpha_F) \cdot I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right) + (1 - \alpha_R) \cdot I_{CS} \cdot \left( e^{-\frac{V_C}{V_T}} - 1 \right)$$

and for the  $Q_2$  collector current  $I_C$  we use Ohm's law over  $R_2$

$$I_C = \frac{V_{CC} - V_C}{R_2}$$

where  $I_{ES} = \beta_F I_S$  and  $I_{CS} = \beta_R I_S$ , with  $\beta_F = \frac{\alpha_F}{1 - \alpha_F}$  and  $\beta_R = \frac{\alpha_R}{1 - \alpha_R}$ .

Kirchhoff's current law over  $Q_2$  is

$$I_E - I_B - I_C = 0$$

Substitution gives

$$I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right) - \alpha_R \cdot I_{CS} \cdot \left( e^{-\frac{V_C}{V_T}} - 1 \right) - (1 - \alpha_F) \cdot I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right) - (1 - \alpha_R) \cdot I_{CS} \cdot \left( e^{-\frac{V_C}{V_T}} - 1 \right) - \frac{V_{CC} - V_C}{R_2} = 0$$

which simplifies to

$$\alpha_F \cdot I_{ES} \cdot \left( e^{-\frac{V_B}{V_T}} - 1 \right) - I_{CS} \cdot \left( e^{-\frac{V_C}{V_T}} - 1 \right) - \frac{V_{CC} - V_C}{R_2} = 0 \quad (4)$$

With equation (4)  $V_C$  can be solved for any  $V_B$  and  $R_2$  (numerically with a root finder or with the Lambert W function. also see chapter 4.1)

## 7.2 Circuit equations

The Kirchhoff's current law at A tells us that

$$i_{R_1} = i_{E,Q_1} + i_{E,Q_2} \quad (5)$$

where

$$i_{E,Q_1} = I_{ES} \left( e^{\frac{V_S - V_A}{V_T}} - 1 \right) - \alpha_R I_{CS} \left( e^{\frac{V_S - V_{CC}}{V_T}} - 1 \right) \quad (6)$$

and

$$i_{R_1} = \frac{V_A}{R_1} \quad (7)$$

The equation for  $i_{E,Q_2}$  from the Ebers-Moll model is

$$i_{E,Q_2} = I_{ES} \left( e^{-\frac{V_B}{V_T}} - 1 \right) - \alpha_R I_{CS} \left( e^{-\frac{V_C}{V_T}} - 1 \right) \quad (8)$$

Substitution of (6). (7) and (8) into (5) gives

$$\frac{V_A}{R_1} - I_{ES} \left( e^{\frac{V_S - V_A}{V_T}} - 1 \right) + \alpha_R I_{CS} \left( e^{\frac{V_S - V_{CC}}{V_T}} - 1 \right) = I_{ES} \left( e^{-\frac{V_B}{V_T}} - 1 \right) - \alpha_R I_{CS} \left( e^{-\frac{V_C}{V_T}} - 1 \right) \quad (9)$$

This equation will let us calculate  $V_A$  for any given  $V_B$  and  $V_S$  (numerically. with a root finder or with the Lambert W function). Remember that  $V_C$  can be calculated from  $V_B$  with eq. (4).

Differentiating (9) with respect to time

$$\frac{d}{dt} \left\{ i_{R_1} = i_{E,Q_1} + i_{E,Q_2} \right\}$$

gives

$$\frac{1}{R_1} \frac{dV_A}{dt} = \frac{I_{ES}}{V_T} e^{\frac{V_S - V_A}{V_T}} \frac{d(V_S - V_A)}{dt} - \alpha_R I_{CS} e^{\frac{V_S - V_{CC}}{V_T}} \frac{1}{V_T} \frac{dV_S}{dt} - \frac{I_{ES}}{V_T} e^{-\frac{V_B}{V_T}} \frac{dV_B}{dt} + \frac{\alpha_R I_{CS}}{V_T} e^{-\frac{V_C}{V_T}} \frac{dV_C}{dt} \quad (10)$$

multiplying both sides with  $R_1 V_T$

$$V_T \frac{dV_A}{dt} = R_1 I_{ES} e^{\frac{V_S - V_A}{V_T}} \frac{d(V_S - V_A)}{dt} - \alpha_R R_1 I_{CS} e^{\frac{V_S - V_{CC}}{V_T}} \frac{dV_S}{dt} - R_1 I_{ES} e^{-\frac{V_B}{V_T}} \frac{dV_B}{dt} + R_1 \alpha_R I_{CS} e^{-\frac{V_C}{V_T}} \frac{dV_C}{dt} \quad (11)$$

With

$$\frac{dV_C}{dt} = \frac{dV_C}{dV_B} \cdot \frac{dV_B}{dt}$$

and

$$\frac{d(V_S - V_A)}{dt} = \frac{dV_S}{dt} - \frac{dV_A}{dt}$$

Now define some variables

$$X = \frac{dV_A}{dt}$$

$$\begin{aligned}
Y &= \frac{dV_B}{dt} \\
S_1 &= R_1 I_{ES} e^{\frac{V_S - V_A}{V_T}} \\
S_2 &= \alpha_R R_1 I_{CS} e^{\frac{V_S - V_{CC}}{V_T}} \\
Q &= \alpha_R R_1 I_{CS} e^{-\frac{V_C}{V_T}} \\
B &= R_1 I_{ES} e^{-\frac{V_B}{V_T}}
\end{aligned}$$

Now we express eq. (11) as

$$V_T X = S_1 \left( \frac{dV_S}{dt} - X \right) - S_2 \frac{dV_S}{dt} - R_1 I_{ES} Y e^{-\frac{V_B}{V_T}} + \alpha_R R_1 I_{CS} Y e^{-\frac{V_C}{V_T}} \frac{dV_C}{dV_B} \quad (12)$$

$$\Rightarrow V_T X = S_1 \left( \frac{dV_S}{dt} - X \right) - S_2 \frac{dV_S}{dt} + Y \left( Q \frac{dV_C}{dV_B} - B \right) \quad (13)$$

With the capacitor charging equation

$$i_{E,Q_2} = C_1 \frac{dV_{C_1}}{dt} = C_1 \frac{d(V_B - V_A)}{dt} = C_1 \left( \frac{dV_B}{dt} - \frac{dV_A}{dt} \right) = C(Y - X) \quad (14)$$

So

$$X = Y - \frac{i_{E,Q_2}}{C_1} \quad (15)$$

Substitute (15) into (13)

$$V_T \left( Y - \frac{i_{E,Q_2}}{C_1} \right) = S_1 \left( \frac{dV_S}{dt} - \left( Y - \frac{i_{E,Q_2}}{C_1} \right) \right) - S_2 \frac{dV_S}{dt} + Y \left( Q \frac{dV_C}{dV_B} - B \right)$$

From this extract Y and substitute  $Y = \frac{dV_B}{dt}$

$$\frac{dV_B}{dt} = \frac{i_{E,Q_2} (S_1 + V_T) + (S_1 - S_2) C_1 \frac{dV_S}{dt}}{C_1 \left( S_1 + V_T + B - Q \frac{dV_C}{dV_B} \right)} \quad (16)$$

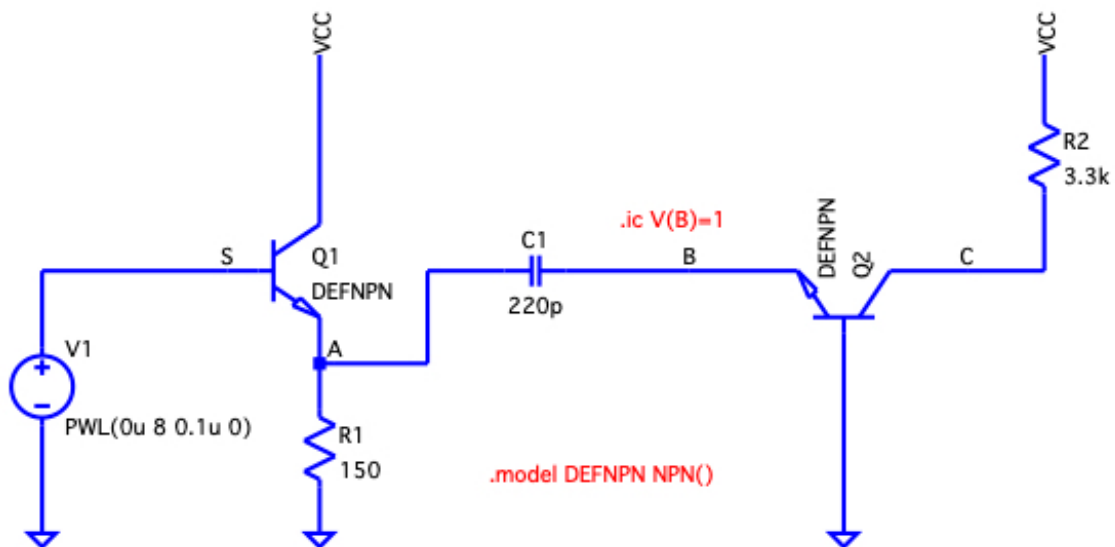
This equation for  $\frac{dV_B}{dt}$  is a first order differential equation described in terms of  $V_A$ ,  $V_B$ ,  $V_C$ ,  $i_{E,Q_2}$  and  $\frac{dV_S}{dt}$  with  $V_B$  the only independent variable.  $V_C$  can be calculated from  $V_B$  using equation (4).  $V_A$  can be calculated from  $V_B$  using equation (9).  $i_{E,Q_2}$  can be calculated from  $V_B$  using equation (8).  $\frac{dV_S}{dt}$  is a known given from the input signal.  $\frac{dV_C}{dV_B}$  can be calculated numerically from equation (4). Solving  $\frac{dV_B}{dt}$  numerically solves the entire circuit.

### 7.3 Jupyter Notebook Implementation details

- using the Lambert W functions allows for simpler code than with a root finder. Care must be taken to prevent numerical overflows. In Python use the mpmath module for increased precision / extended range.

## 8. Accordance with LTSpice model

With a default NPN transistor for  $Q_1$  and  $Q_2$  using SPICE directive `.model DEFNPN NPN()` very similar results are obtained between the Jupyter notebook and the LTSpice model <sup>6</sup>.



Note that in the LTSpice a bare NPN model is used. Apart from the Ebers-Moll model none of the second order parasitic capacitances and Early voltage etc. are implemented <sup>7</sup>.

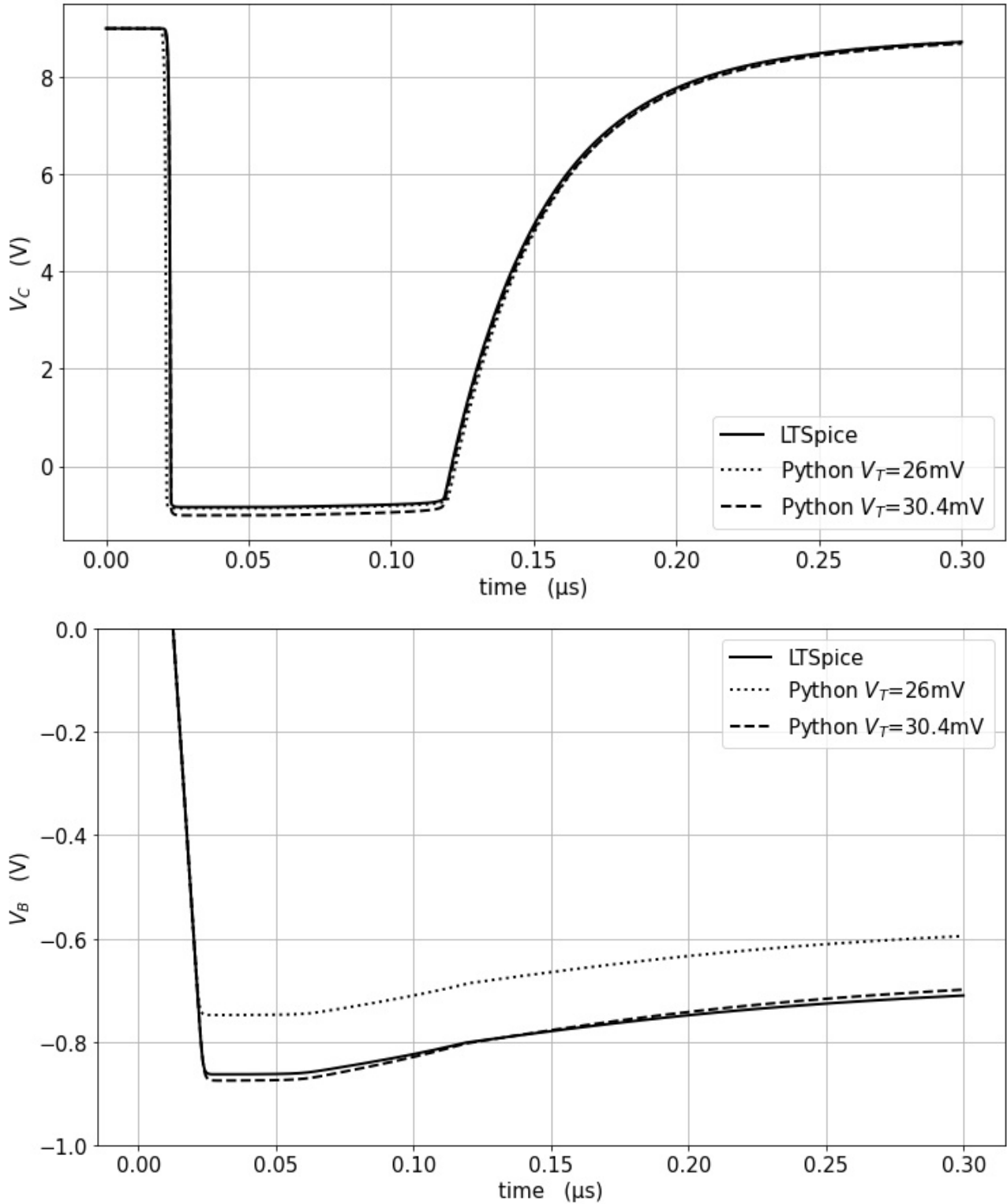
The graphs below show that the model as implemented in the Jupyter notebook agrees fairly well with the LTSpice model. Agreement can be even made more close by adjusting the thermal voltage in the Jupyter notebook. The default model uses 26mV, but agreement is closer when  $V_T=30.4\text{mV}$  is used. A thermal voltage of  $V_T$  corresponds to a temperature of

<sup>6</sup> Differences may be caused by different numerical methods, step sizes etc.

<sup>7</sup> Such a bare model can be used to find the cause of small effects in a real world circuit by adding these effects to the bare model one by one.

$$V_T = \frac{kT}{q} \Rightarrow T = \frac{qV_T}{k} = \frac{1.60 \cdot 10^{-19} \cdot 30.4 \cdot 10^{-3}}{1.38 \cdot 10^{-23}} = 353 \text{ K} = 80 \text{ }^{\circ}\text{C}$$

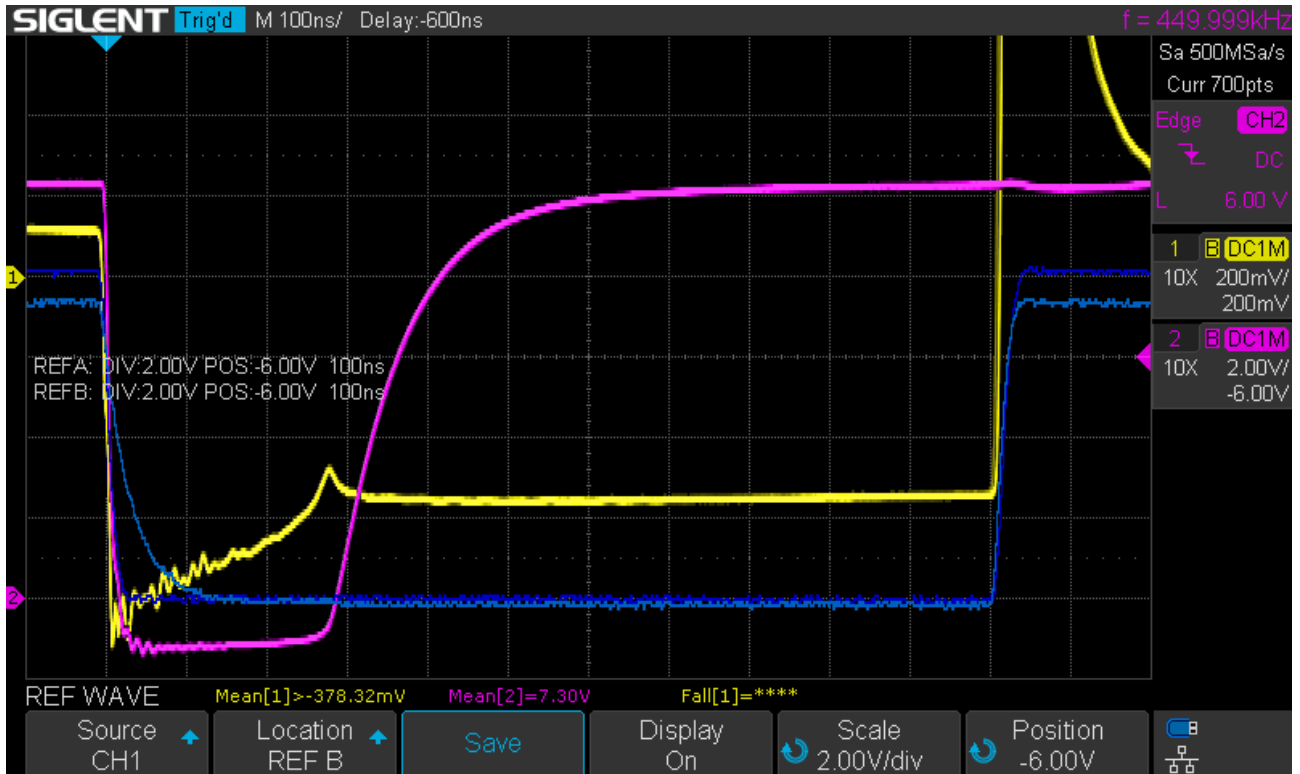
with  $k$  the Boltzmann constant. and  $q$  the elementary electron charge.



Comparison of Jupyter Notebook model and LTSpice model. Both with  $C_1=220\text{pF}$  and  $R_1=150\Omega$ . Top plot show  $V_C$ . bottom plot shows  $V_B$ .



## 9. Checking with a real world circuit



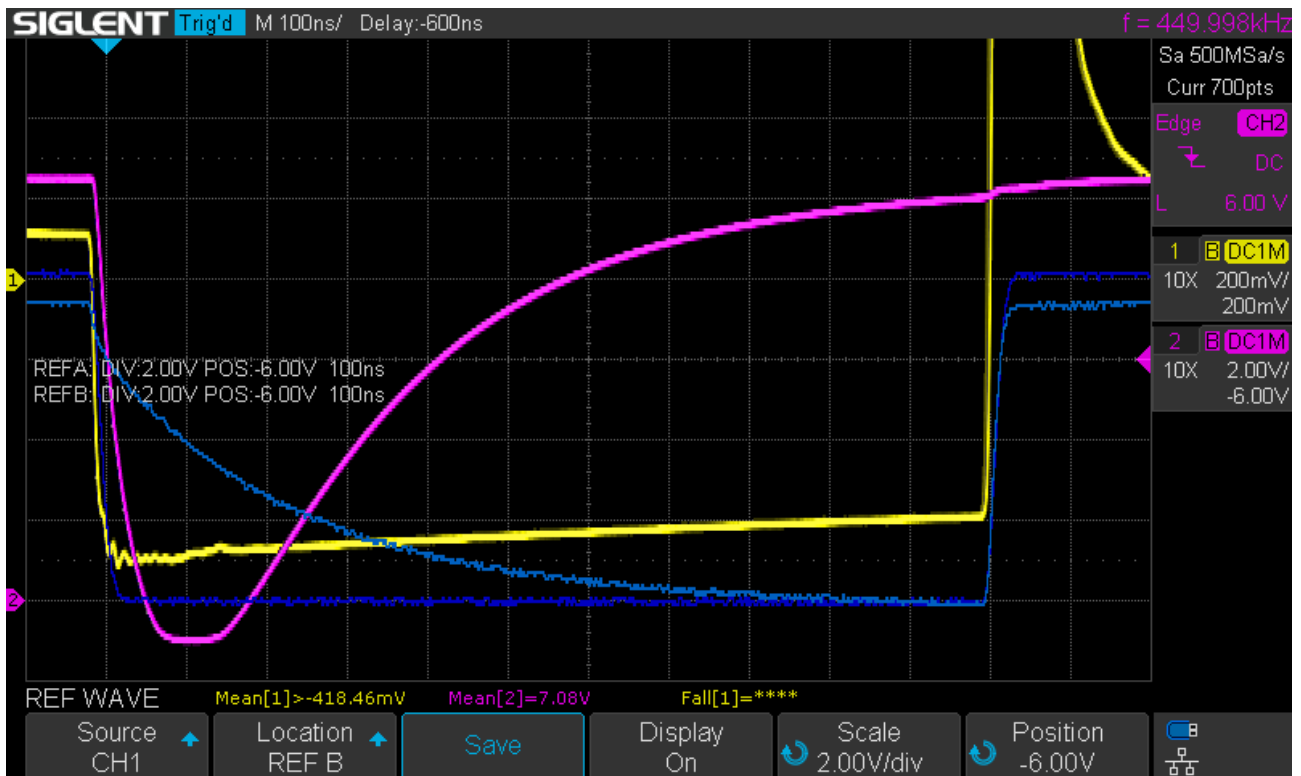
$V_B$ : yellow.  $V_C$ : pink.  $V_A$ : light blue.  $V_S$ : dark blue with  $C_1=220\text{pF}$  and  $R_1=150\Omega$ .

In the above oscilloscope plot we see an output pulse ( $V_C$ ) of about 200ns. This does not agree very well with the Jupyter Notebook model which gives an output pulse of about xxxns. The LTSpice model produces an output pulse of about 350ns when using 2N3904 transistors.

The table below shows the pulse width ( $C_1=220\text{pF}$ ,  $R_1=150\Omega$ )

model	pulse width (ns)
LTSpice MYNPN	95
Jupyter	100
real world circuit	200
LTSpice 2N3904	350

Probably second order effects in the transistors play a big deal in the exact pulse width.



$V_B$ : yellow.  $V_C$ : pink.  $V_A$ : light blue.  $V_S$ : dark blue with  $C_1=220\text{pF}$  and  $R_1=1100\Omega$ .

In the above oscilloscope plot  $R_1$  prevents  $Q_2$  to get well into saturation.  $Q_1$  gets into cutoff too early.  $Q_1$  gets into cutoff before it has had a chance to push  $V_B$  down enough to get  $Q_2$  into saturation. This leads to a badly defined output pulse.

## 10. Duty cycle

Define some variable

$f_c$ : carrier frequency

$f_\Delta$ : frequency deviation

$f_{min} = f_c - f_\Delta$ : minimal instantaneous frequency

$f_{max} = f_c + f_\Delta$ : maximal instantaneous frequency

$p_{max}$ : maximal pulse width

$p_{min}$ : minimal pulse width (=0, but irrelevant)

$d$ : duty cycle of output signal

$d_{max}$ : maximal positive duty cycle of output

$d_{min}$ : minimal positive duty cycle of output

The maximal pulse width  $p_{max} = \frac{1}{2f_{max}}$

By design the minimal positive duty cycle  $d_{min} = 0.5$ .

The duty cycle  $d = \frac{\frac{1}{f} - p}{\frac{1}{f}} = 1 - p \cdot f$

Pulse width  $p$  is fixed by circuit design,  $f$  is variable by nature (frequency modulated signal).

$$f_{min} < f < f_{max}$$

$$f_c - f_{\Delta} < f < f_c + f_{\Delta}$$

$$0 < p < \frac{1}{2f_{max}} = \frac{1}{2(f_c + f_{\Delta})} = p_{max}$$

$$d = 1 - p \cdot f$$

$$d_{max} = 1 - p_{min}f_{min} = 1$$

$$d_{min} = 1 - p_{max}f_{max}$$

$$\Delta d = d_{max} - d_{min} = 2 \cdot p \cdot f_{\Delta}$$

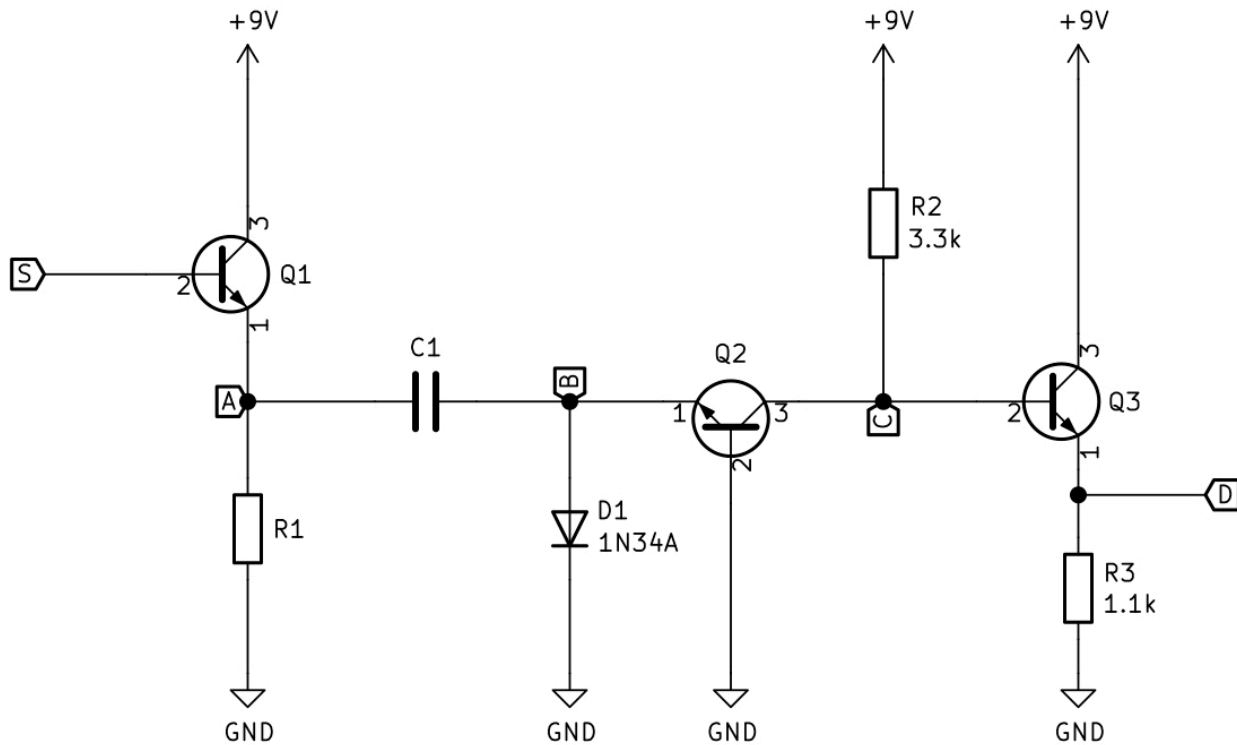
$\Delta d$  is the duty cycle difference between maximal and minimal instantaneous frequency. It should be maximised to get the highest output from the detector.

$f_{\Delta}$  cannot be changed as it is dictated by the frequency modulated input signal. That leaves the pulse width  $p$  to be maximised. With  $p_{max} = \frac{1}{2(f_c + f_{\Delta})}$  only the carrier frequency  $f_c$  can be minimised to maximise  $\Delta d$ . Of course the carrier frequency  $f_c$  should still be higher than the maximal frequency deviation  $f_{\Delta}$ .

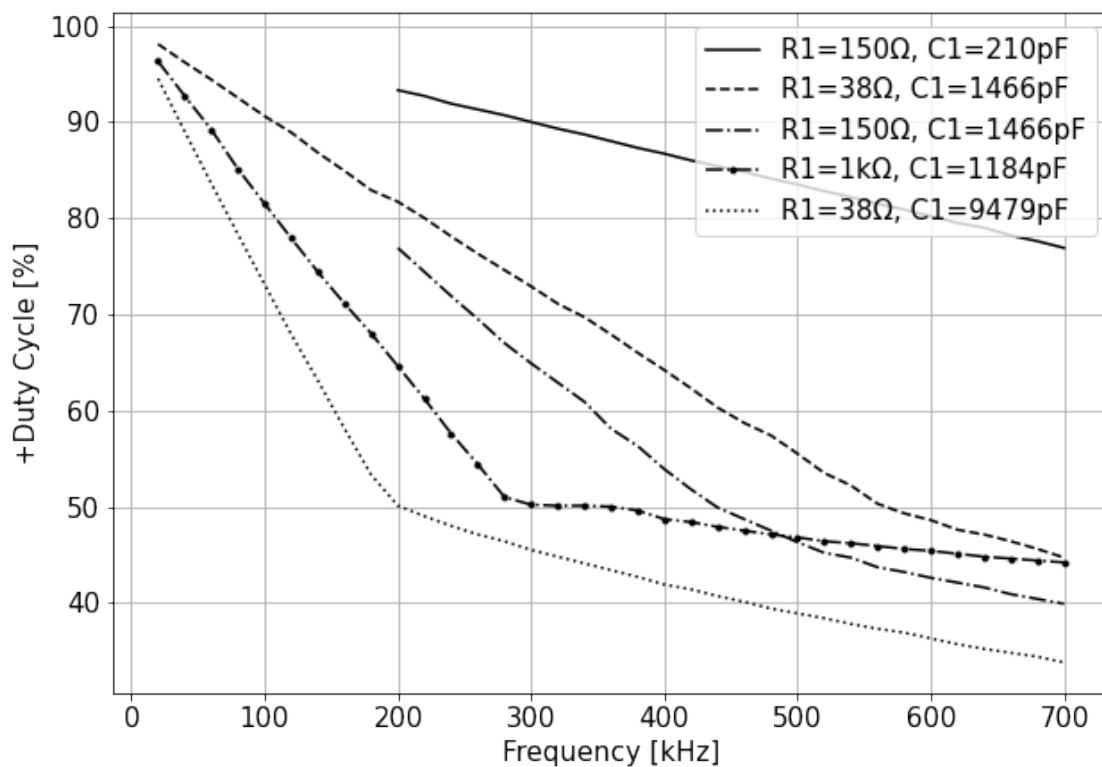
If we choose  $f_c = f_{\Delta}$ , and then choose  $p = p_{max} = \frac{1}{4f_{\Delta}}$ , we will get a maximum output signal with  $\Delta d = 2 \cdot p \cdot f_{\Delta} = 2 \frac{f_{\Delta}}{4f_{\Delta}} = 0.5$ . This is as can be expected. The duty cycle can never be higher than 100% (with  $p = 0$ ), and never be lower than 50% (with  $p = p_{max} = \frac{1}{2(f_c + f_{\Delta})}$ ).

## 11. Measurements

## 11.1 Linearity



Circuit to measure the duty cycle of the pulse train detector. Input signal a 8Vpp square pulse at S. Output measured at D with Siglent SDS1202X-E oscilloscope, +duty cycle measurement. All transistors are 2N3904.



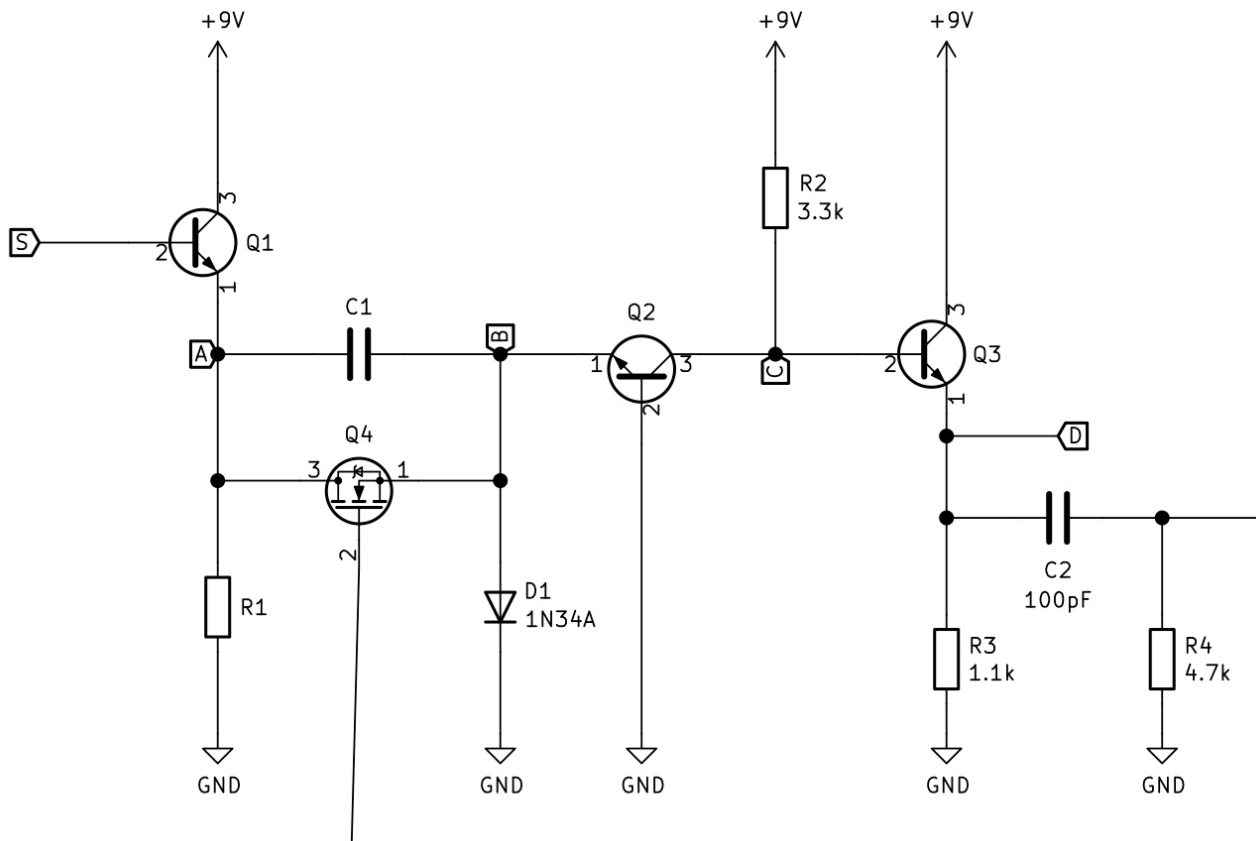
In the above plot it is visible that below a positive duty cycle of 50% we are running into problems (as predicted in chapter 10). Also, a lower intermediate frequency allows for larger values of  $R_1$  and  $C_1$  (with their, in general, larger pulse widths). That will give larger duty cycle swings for the same frequency deviation, and by this a higher output (audio) signal once the pulse train has been lowpass filtered.

## 12. Improvements

### 12.1 Squaring up the output pulse

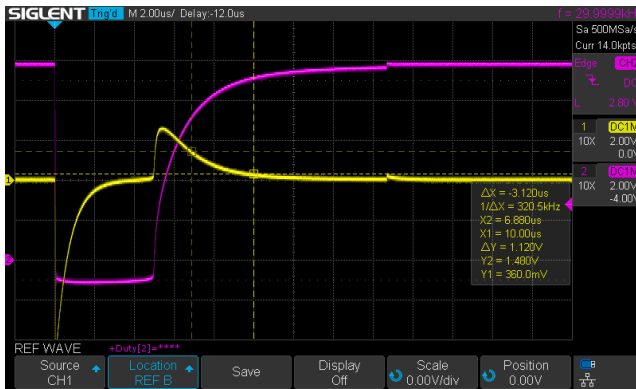
With large values for  $C_1$  and/or  $R_1$  the rising edge of the output pulse is not very steep. This is because at a certain moment  $Q_2$  gets out of saturation, when  $C_1$  has not been discharged a reasonable amount<sup>8</sup>. The remaining charge on  $C_1$  will leak away through  $R_1$ . The voltage over  $C_1$  will be distributed over  $R_1$  and the base-emitter junction of  $Q_2$ . The part over the b-e junction of  $Q_2$  is what decides the collector voltage of  $Q_2$ . For large values of  $R_1$  and/or  $C_1$ , discharge will take place slowly and as such the rising edge of the pulse at the  $Q_2$ 's collector will not be steep.

Several preliminary attempts at steepening up the output pulse have been made. The most promising at this moment seems to be to detect when  $Q_2$  gets out of saturation, and at that moment short the terminals of  $C_1$ . The following circuit is used:

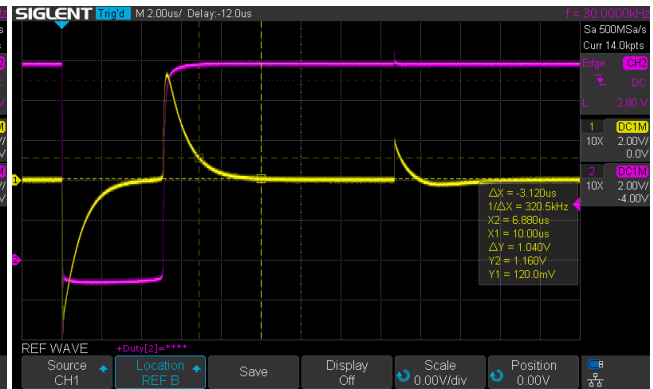


$C_2$ ,  $R_4$  and  $Q_4$  have been added.  $C_2$  and  $R_4$  act as a high pass filter to detect the rising edge of the output pulse. The positive voltage pulse created at that moment opens  $Q_4$ , which shorts  $C_1$  and causes it to discharge at once. This discharge pulls up  $V_B$ , which stops the current through  $Q_2$ , and pulls  $V_C$  to  $V_{CC}$ .

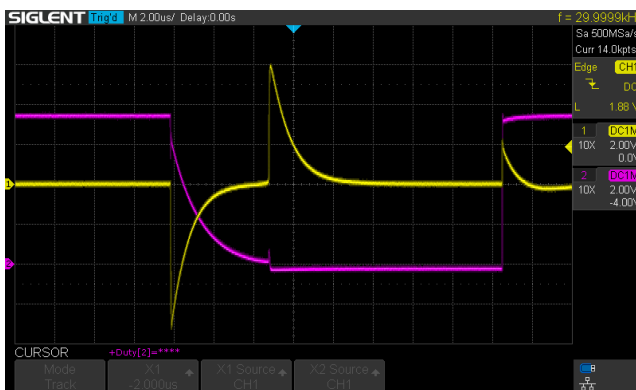
<sup>8</sup> This happens for any value for  $R_1$  and  $C_1$ , only for large values it is more notable.



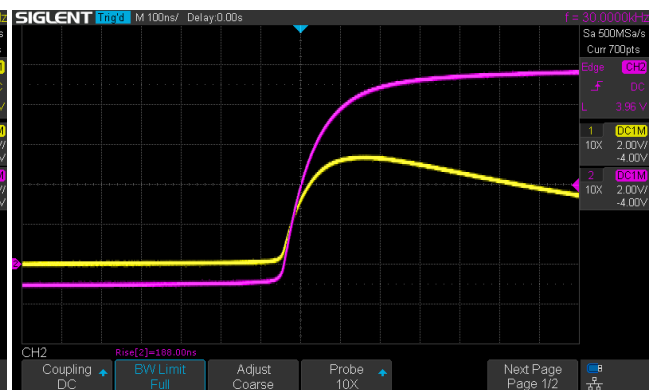
$R_1=150\Omega$ ,  $C_1=10\text{nF}$ , without  $C_2$ ,  $R_4$  and disconnected  $Q_4$ . Violet = output pulse on collector  $Q_3$ , yellow = gate of  $Q_4$ .



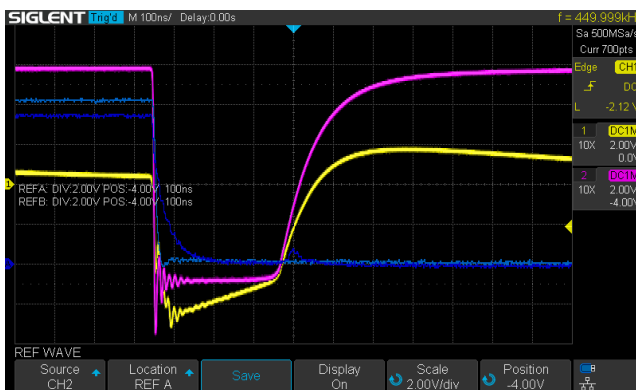
$R_1=150\Omega$ ,  $C_1=10\text{nF}$ , with  $C_2$ ,  $R_4$  and  $Q_4$ . Violet = output pulse on collector  $Q_3$ , yellow = gate of  $Q_4$ .



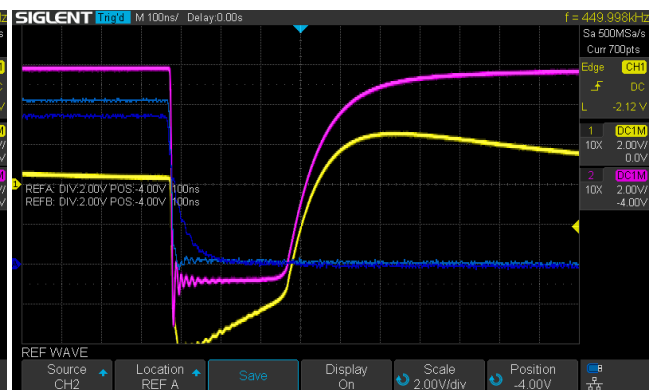
$R_1=150\Omega$ ,  $C_1=10\text{nF}$ , with  $C_2$ ,  $R_4$  and  $Q_4$ . Violet =  $V_A$ , yellow = gate of  $Q_4$ . The violet trace shows the sudden drop in voltage at  $V_A$ , because of the sudden discharge of  $C_1$ .



$R_1=150\Omega$ ,  $C_1=10\text{nF}$ , with  $C_2$ ,  $R_4$  and  $Q_4$ . Violet = output pulse on collector  $Q_3$ , yellow = gate of  $Q_4$ . Compare with the plots below, for  $C_1=220\text{pF}$ . The rise time of the output pulse is the same.



$R_1=150\Omega$ ,  $C_1=220\text{pF}$ , with  $C_2$ ,  $R_4$  and  $Q_4$ . Pink =  $V_C$ , yellow = gate of  $Q_4$ , dark blue =  $V_A$ , light blue =  $V_S$ .



$R_1=150\Omega$ ,  $C_1=220\text{pF}$ , with  $C_2$ ,  $R_4$  and disconnected  $Q_4$ . Pink =  $V_C$ , yellow = gate of  $Q_4$ , dark blue =  $V_A$ , light blue =  $V_S$ .

This is with  $Q_4$  disconnected. For  $C_1=220\text{pF}$  this makes no difference with the speedup circuit installed. Compare with the plot above, for  $C_1=10\text{nF}$ . The rise time of the output pulse is the same.

Not much research has been done yet on this circuit. Several notes:

- $C_2$  and  $R_4$  have been chosen as large as possible, to get phase shift as low as possible
- $C_2$  and  $R_4$  should have an RC time constant times 2.2 less than half the period of the intermediate frequency. If it is larger, it may still keep  $Q_4$  in conduction, which hampers the charging of  $C_1$ . In this case  $2.2R_4C_2 = 2.2 \cdot 4700 \cdot 100e^{-12} = 1\mu s$ . In the above oscilloscope plots the fall time, (90%-10% discharge time of  $C_2$ ) is  $2\mu s$ . This still has to be investigated. With the current 450kHz intermediate frequency of the FM receiver, with a period of  $2.2\mu s$ , a RC discharge time of  $1\mu s$  should suite well. The intermediate frequency used in the above oscilloscope plots is much smaller, 30kHz, for illustration purposes.
- for  $Q_4$ , a BJT has been tried instead of a MOSFET. A BJT needs a lower voltage to trigger into conduction, but it loads the output circuit too much.
- output rise times for  $C_1=10nF$  (with speedup circuit) and  $C_1=220pF$  (with or without speedup circuit) are the same. This shows that the rise time for  $C_1=220pF$  is not influenced by the speedup circuit. It also shows that this rise time is the shortest obtainable with this circuit. The limiting factor is (probably) the parasitic capacitances of  $Q_2$  and  $Q_3$ .
- ideally we want  $C_2$  to be discharged completely before  $Q_2$  gets out of saturation to get the maximum upswing on the gate of  $Q_4$ .

## 12.2 Lowering the intermediate frequency

Lowering the intermediate frequency allows larger values for  $R_1$  and  $C_1$  (see 11.1, Linearity). This in turn will create a larger duty cycle variation (see 11.1, Linearity). A larger variation in duty cycle will create a larger output signal of the pulse train detector once the pulse train has been lowpass filtered. When using larger values for  $R_1$  and  $C_1$ , the rising edge of the output pulse will get less steep. This can be solved by techniques as described in the previous paragraph 12.1.

The following plots show an example.



$R_1=1k\Omega$ ,  $C_1=1nF$ ,  $C_2=100pF$ ,  $R_4=4.7k\Omega$ . Yellow trace shows  $V_A$ , pink trace shows  $V_D$ . The yellow trace clearly shows the discharge of  $C_1$  once  $Q_2$  gets out of saturation and opens  $Q_4$ . This plot is taken from an actual FM modulated input signal of a radio station.

These plots are for larger values of  $R_1$  and  $C_1$  than in the preceding examples. Although the values are large, due to the speedup circuit a steep output pulse is generated with a rise time of only 84ns. The output pulse is about  $1.6\mu s$ . The large value for  $R_1$  implies less current in  $Q_1$  and  $R_1$ , with less power dissipation. In this setup the intermediate frequency

has been lowered from 450kHz to 250kHz. Thus duty cycle variation is much larger now, with a consequently larger audio signal after the pulse train has been lowpass filtered.