

## Unit - 4

### • Push Down Automata:

→ A PDA consists of 3 components:

- i) Input tape
- ii) Finite control
- iii) Stack Structure.

→ The input tape consists of a linear configuration of cells each of which contains a character from the input Alphabet, the tape can be moved one cell at a time to the left.

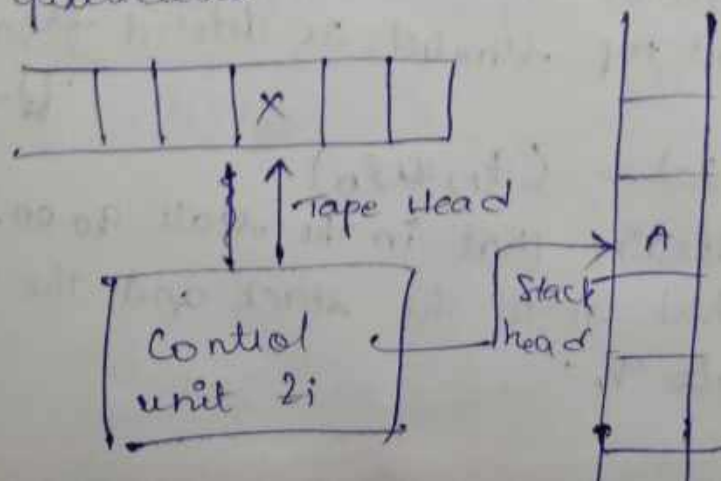
→ A stack is also a sequence structure that has a first element and grows in either directions from the other end.

→ Control unit has some pointer (head) which points the current symbol that is to be read.

→ The head position over the current stack element can read & write special stack characters from that position.

→ The current stack element is always the top element of the stack hence the name is stack.

→ The control unit contains both tape head and stack head and finds itself at any movement in a particular state.



→ A finite state PDA is a 7 tuple machine  $M$  where  $M = \{Q, \Sigma, \delta, \gamma, q_0, z_0, F\}$

$Q$  = finite set of states

$\Sigma$  = finite set of input alphabets

$\gamma$  = finite set of stack alphabets

$q_0$  = start state / initial state

$F$  = set of final states.

$\delta = Q \times (\Sigma \cup \{e\}) \times \gamma \rightarrow Q \times \gamma^*$

$z_0$  = initial stack symbol. ( $z_0 \in \gamma$ )

→ A move on PDA indicates:

- 1) A element maybe added to the stack.
- 2) A element maybe deleted from the stack.
- 3) There may or maynot be change of stack (do nothing operation).

→ Operations:

1)  $\delta(q_0, a, z_0) = (q_0, a z_0)$

→ This indicates that in the state  $q_0$  on seeing  $a$ ,  $a$  is pushed on to the stack and there is no change in the stack.

$$\begin{array}{|c|} \hline a \\ \hline z_0 \\ \hline \end{array} \rightarrow \begin{array}{|c|} \hline a \\ \hline a \\ \hline z_0 \\ \hline \end{array} \text{ (push)}$$

2)  $\delta(q_0, a, z_0) = (q_0, e)$

→ This indicates that in the state  $q_0$  on seeing  $a$ , the current top symbol is deleted from the stack.

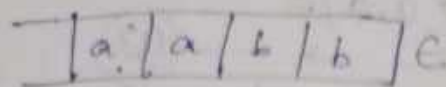
3)  $\delta(q_0, a, z_0) = (q_1, a z_0)$

→ This indicates that in the state  $q_0$  on seeing  $a$ ,  $a$  is pushed on to the stack and the state is changed to  $q_1$ .

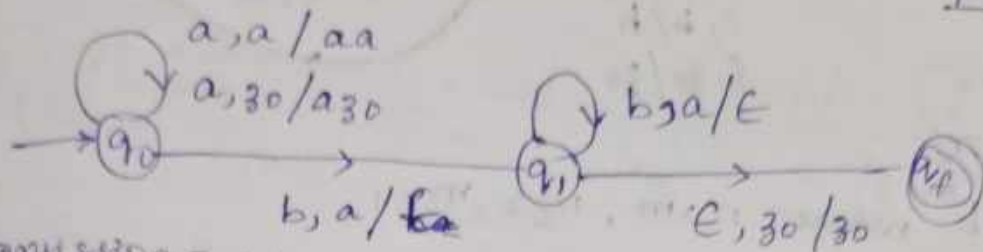
$$\begin{array}{|c|} \hline z_0 \\ \hline \end{array} \rightarrow \begin{array}{|c|} \hline \\ \hline \end{array} \text{ (pop)}$$



\*a) Design a PDA which accepts the language  
 $L = \{a^n b^n, n \geq 1\}$

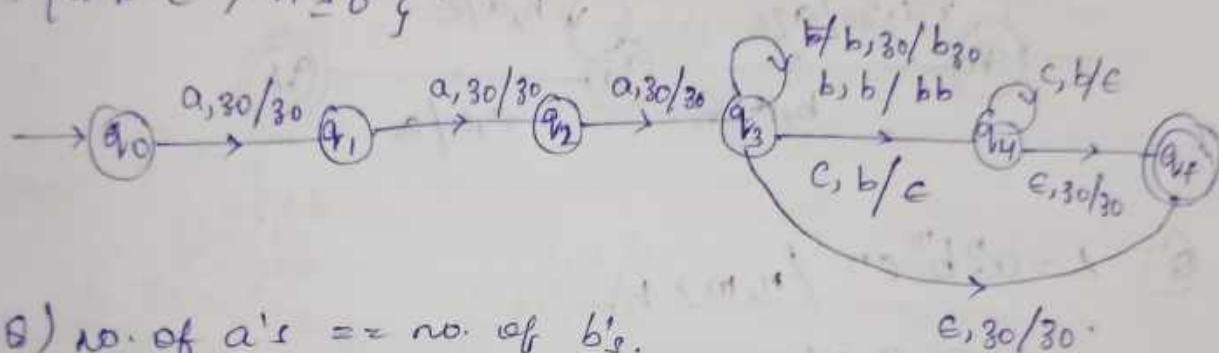


q <sub>0</sub>	a	a	aa
q <sub>1</sub>	b	a	ε
q <sub>2</sub>	ε	z <sub>0</sub>	z <sub>0</sub>



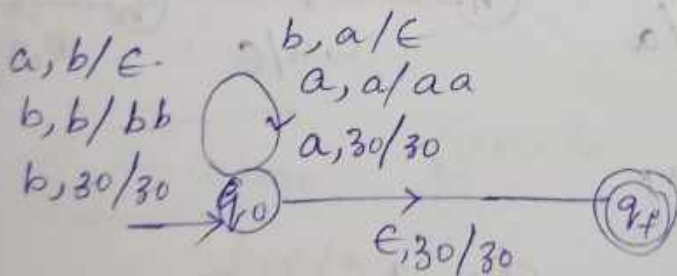
Transition Table.

b)  $\{a^3 b^n c^n / n \geq 0\}$

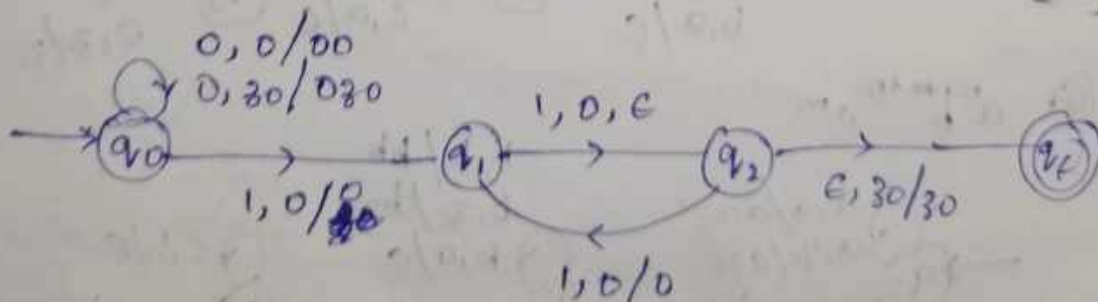


c) no. of a's = no. of b's.

$\{\epsilon, ab, aabb, abab, baba, \dots\}$



d) Design a PDA that accepts  $L = \{0^n 1^n, n \geq 1\}$

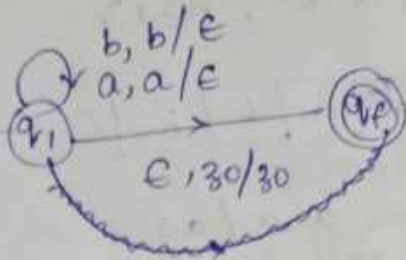


8)

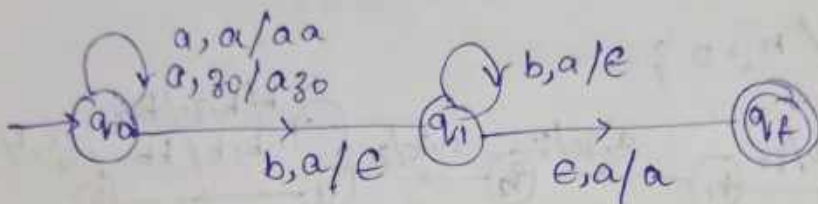
$$L = w c w^R$$

$b, a/ba$   
 $b, b/bb$   
 $b, \epsilon/b\epsilon$

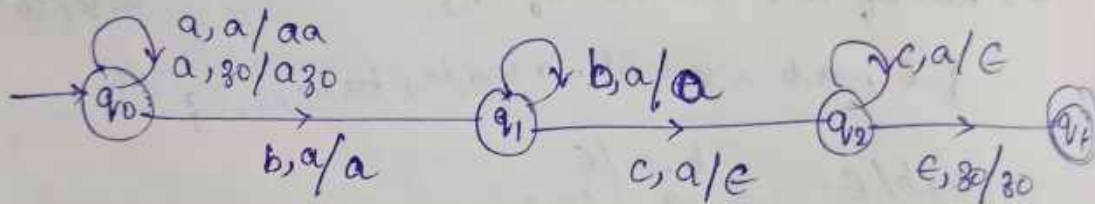
$a, b/ab$   
 $a, a/aa$   
 $a, \epsilon/a\epsilon$



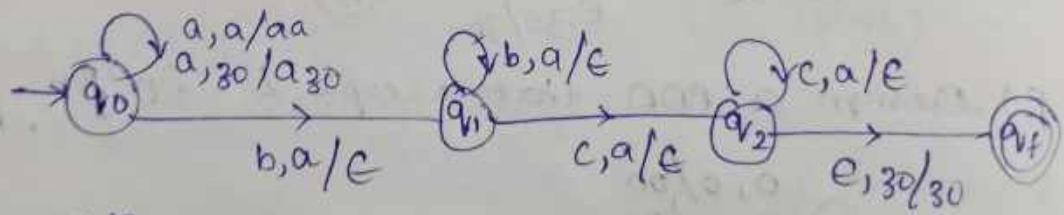
8)  $a^n b^m$  where  $n > m, n \geq 2, m \geq 1$ .



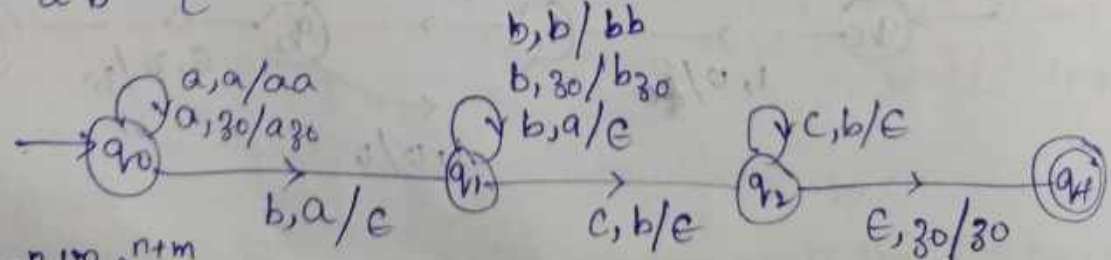
8)  $L = a^n b^m c^n / n, m \geq 1$ .



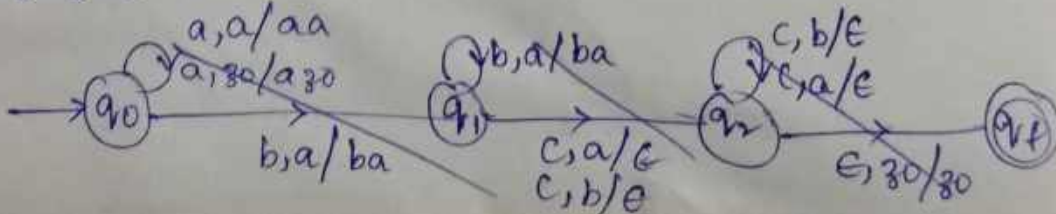
8)  $a^{m+n} b^m c^n / n, m \geq 1$



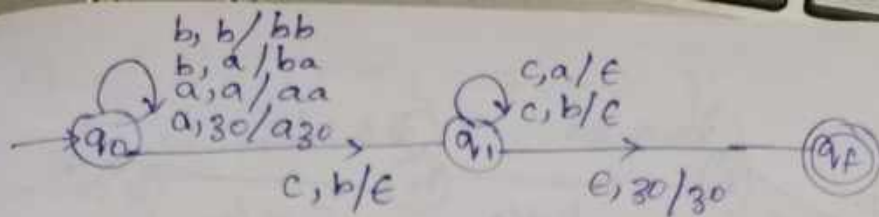
8)  $a^n b^{m+n} c^m$



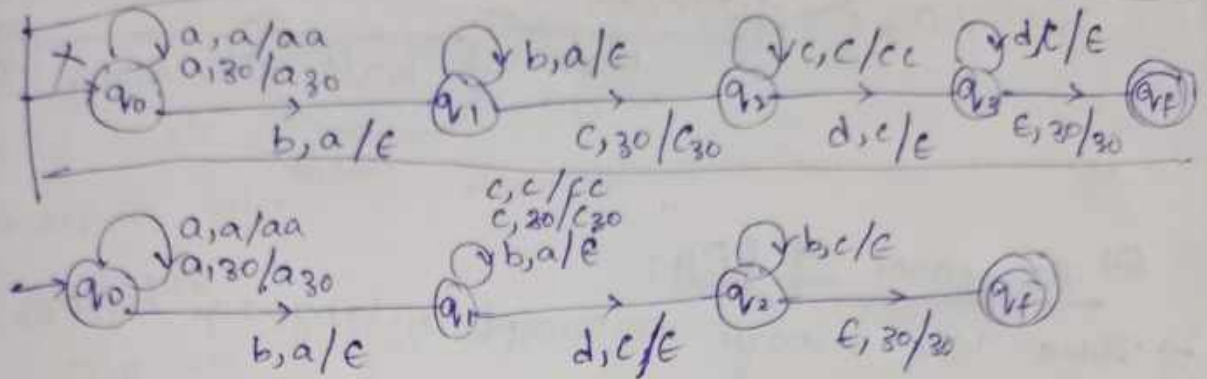
8)  $a^n b^m c^{n+m}$



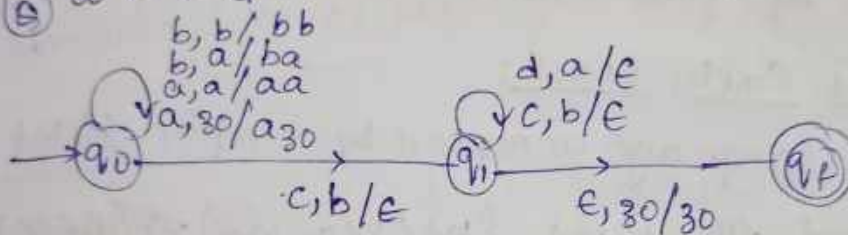




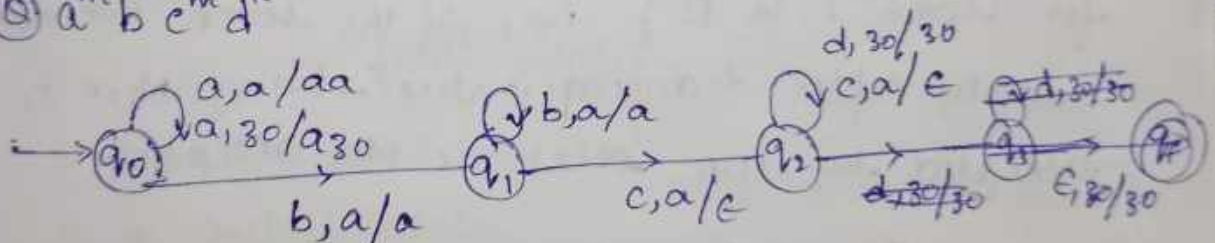
⑧  $a^m b^m c^n d^n$



⑨  $a^m b^n c^n d^m$

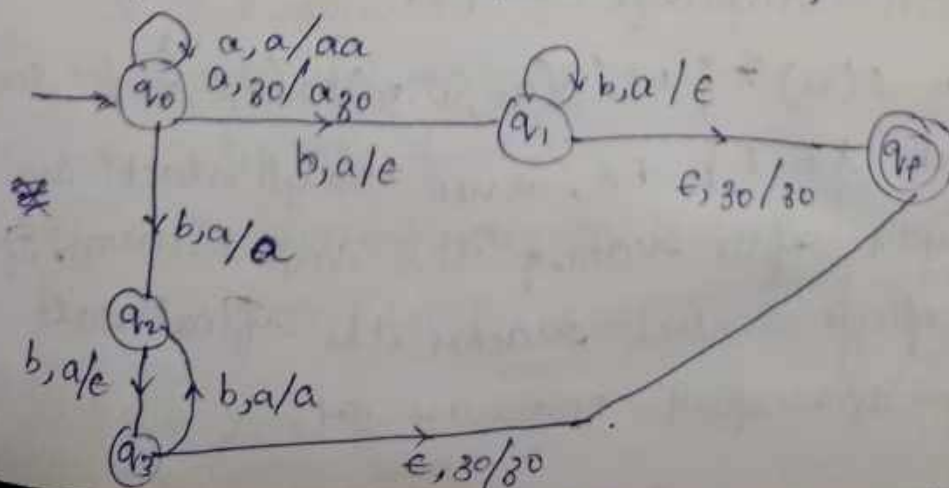


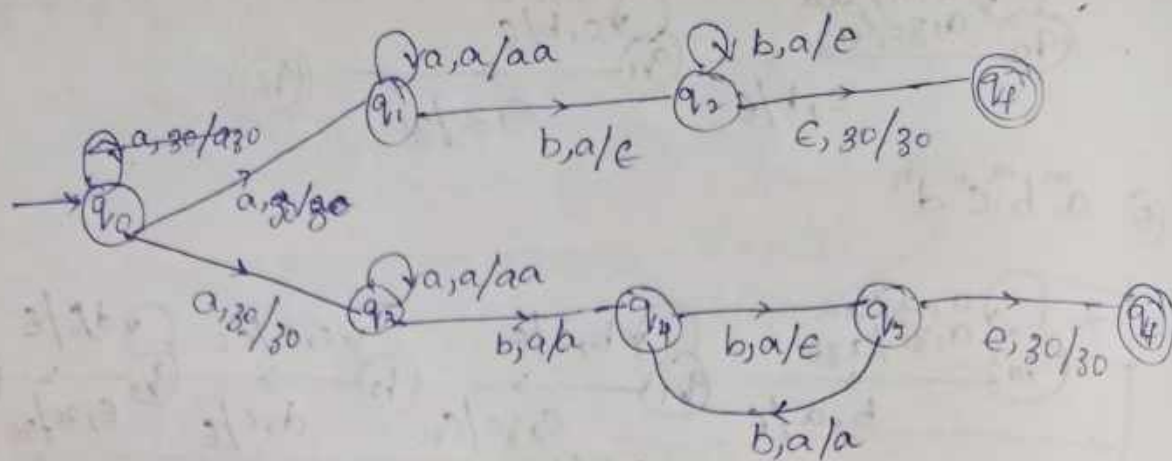
⑩  $a^m b^i c^m d^k$



⑪  $a^m b^m c^m d^n$ ,  $a^n b^n c^n$  can't be designed by PDA.

8)  $L = \{a^n b^n / n \geq 1\} \cup \{a^n b^{2n} / n \geq 1\}$





### Acceptance of PDA:

→ There are 2 ways to accept a language by PDA:

- i) Accepted by Empty stack.
- ii) Accepted by final state.

#### i) Accepted by Empty stack:

→ The given language accepted by empty stack to be defined as  $L(M) = \{ w / \delta(q_0, w, z_0) \Rightarrow (p, \epsilon, \epsilon) \text{ for some } p \in Q \}$  i.e., if the stack becomes empty after scanning entire string, then it is accepted by PDA otherwise not accepted.

eg:  $L = \{ a^n b^n / n \geq 1 \}$ .

#### ii) Accepted by final state:

→ The given language accepted by final state is defined as  $L(M) = \{ w / \delta(q_0, w, z_0) \Rightarrow (p, \epsilon, \lambda) \text{ for some } p \in F \text{ and } \lambda \in \Gamma^* \}$  i.e., even though stack is not empty after scanning the input string, if the final finite control reaches the final state then it is accepted otherwise not.



eg:  $\{a^n b^m / n \geq m, n \geq 2, m \geq 1\}$

### Types of PDA:

- 1) DPDA (Deterministic Push Down Automata)
- 2) NPDA (Non-Deterministic Push Down Automata)

→ The PDA that has at most one choice of move in any state is called a DPDA.

→ NPDA provides non-deterministic in the moves defined.

→ DPDA are useful in programming languages.

eg: parsers are used in yet another compiler compiler (YACC) are determined in PDA.

### DPDA:

→ A DPDA is a 7-tuple machine.

$$M = \{Q, \Sigma, q_0, \Gamma, z_0, \delta, F\}$$

$Q$  = set of finite states.

$\Sigma$  = set of input alphabets.

$q_0$  = Initial state

$\Gamma$  = finite set of stack alphabets

$z_0$  = Initial stack symbol

$\delta$  = Transition function or mapping function used for mapping current state to next state

$F$  = set of final states.

→ If a transition denotes a unique transition for each input then PDA is said to be a DPDA.

eg:  $L = \{a^n b^n / n \geq 1\}$ ,  $L = \{w c w^R / w = (a+b)^*\}$

## NPDA:

→ A NPDA is a tuple machine,

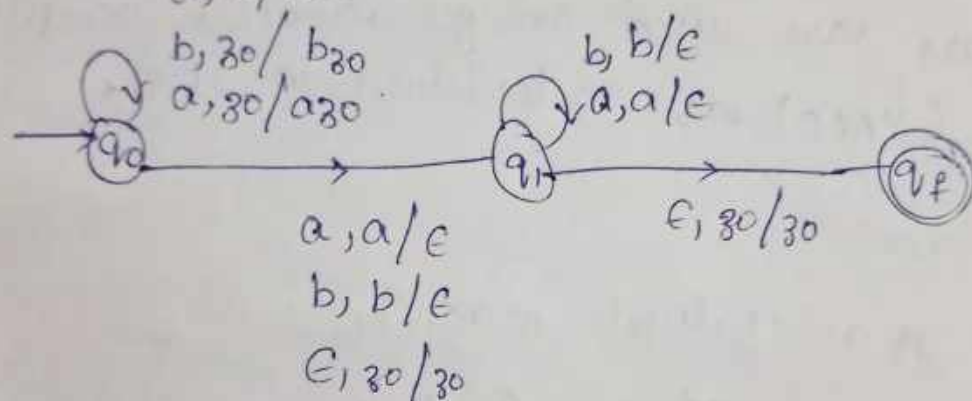
$$M = \{Q, \Sigma, q_0, \Gamma, z_0, \delta, F\}$$

→ If a transition denotes more than one transition for a particular input symbol then the PDA is said to be a NPDA.

\*  $L = (NW^R / w = (a+b)^*)$

a, b / ab  
b, a / ba  
b, b / bb  
a, a / aa

a	a	a
a	b	b
b	a	a
b	b	b



## Equivalence of PDA's & CFG's:

### Conversion of CFG to PDA:

- 1) For constructing a PDA from a given CFG, it is necessary to convert the CFG to some normal forms like GNF.
- 2) For converting a given CFG to PDA, by this method the necessary condition is that the first symbol on Right side of the production rule must be a terminal symbol. This rule that can be used to obtain PDA from CFG.



Rule-1:

→ for non-terminal symbols,  $\delta(q, \epsilon, A) = (q, \alpha)$   
where the production rule is  $A \rightarrow \alpha$   
( $\alpha$  as non-terminal)

Rule-2:

→ for each terminal symbol,  $\delta(q, a, a) = (q, \epsilon)$   
for every terminal symbol  $a$  as given (CFG)

8) construct a PDA equivalent to the following grammar

$$S \rightarrow 0BB$$

$$B \rightarrow 0S$$

$$B \rightarrow 1S$$

$$B \rightarrow 0$$

9) It is in minimised format.

from Rule-1:  $A \rightarrow \alpha$ ,  $\delta(q, \epsilon, A) = (q, \alpha)$ .

$$\delta(q, \epsilon, S) = (q, 0BB)$$

$$\delta(q, \epsilon, B) = (q, 0S)$$

$$\delta(q, \epsilon, B) = (q, 1S)$$

$$\delta(q, \epsilon, B) = (q, 0)$$

from Rule-2:

$$\delta(q, 0, 0) = (q, \epsilon)$$

$$\delta(q, 1, 1) = (q, \epsilon)$$

(or)

$$\delta(q, 0, S) = (q, BB)$$

$$\delta(q, 0, B) = (q, S)$$

$$\delta(q, 1, B) = (q, S)$$

$$\delta(q, 0, B) = (q, \epsilon)$$

c

Constructing CFG for the given PDA:

→ The construction goes as follows:  
 given PDA<sup>(M)</sup>, we will construct a grammar  $G$   
 such that  $L(G) = L(M)$

Rule-1:

→ The Productions for start symbol  $S$  are given  
 by  $S \rightarrow [q_0, z_0, q]$  for each state  $q$  in  $Q$

Rule-2:

→ Each move that pops a symbol from the stack  
 with transition as  $\delta(q, a, z_i) = (q_1, \epsilon)$   
 includes a production as  $[q, z_i, q_1] \rightarrow a$  for  $q_1$  in  $Q$

Rule-3:

→ Each move that does not pop symbol from stack  
 with transition as  $\delta(q, a, z_0) = (q_1, z_1 z_2 z_3 \dots)$

$[q, z_0, q_m] \rightarrow a [q_1, z_1, q_2] [q_2, z_2, q_3] [q_3, z_3, q_4] \dots [q_{m-1}, z_{m-1}, q_m]$

eg: Give the equivalence CFG for the following

PDA,  $M = \{q_0, q_1\}, \{a, b\}, \{z, z_0\}, \delta, q_0, z_0, \phi\}$

where  $\delta$  is defined by

$\delta(q_0, b, z_0) = (q_0, z_0 z_0)$

$\delta(q_0, \epsilon, z_0) = (q_0, \epsilon)$

$\delta(q_0, b, z) = (q_0, zz)$

$\delta(q_0, a, z) = (q_1, z)$

$\delta(q_1, b, z) = (q_1, \epsilon)$

$\delta(q_1, a, z_0) = (q_0, z_0)$



$$S \rightarrow [q_0, z_0, q_0] / [q_0, z_0, q_1]$$

$$(i) \begin{aligned} [q_0, z_0, q_0] &\rightarrow b [q_0, z, q_0] \quad [q_0, z, q_0] \\ &\quad b [q_0, z, q_1] \quad [q_1, z, q_0] \end{aligned}$$

$$\begin{aligned} [q_0, z_0, q_1] &\rightarrow b [q_0, z_0, q_0] \quad [q_0, z_0, q_1] \\ &\quad b [q_0, z_0, q_1] \quad [q_1, z_0, q_1] \end{aligned}$$

$$(ii) [q_0, z_0, q_0] \rightarrow \epsilon$$

$$(iii) \begin{aligned} [q_0, z, q_0] &\rightarrow b [q_0, z, q_0] \quad [q_0, z, q_0] \\ &\quad b [q_0, z, q_1] \quad [q_1, z, q_0] \end{aligned}$$

$$\begin{aligned} [q_0, z, q_1] &\rightarrow b [q_0, z, q_0] \quad [q_0, z, q_1] \\ &\quad b [q_0, z, q_1] \quad [q_1, z, q_1] \end{aligned}$$

$$(iv) \begin{aligned} [q_0, z, q_0] &\rightarrow a [q_1, z, q_0] \\ [q_0, z, q_1] &\rightarrow a [q_1, z, q_1] \end{aligned}$$

$$(v) [q_1, z, q_1] \rightarrow b$$

$$(vi) \begin{aligned} [q_1, z_0, q_0] &\rightarrow a [q_0, z_0, q_0] \\ [q_1, z_0, q_1] &\rightarrow a [q_0, z_0, q_1] \end{aligned}$$

3.) Convert the PDA to CFG. PDA is given by  
 $\{ \{P, q\}, \{z_0, \epsilon\}, \{a, b\}, \delta, q_1, z, \phi \}$

$$\checkmark \delta(q, 1, s) = \{ (q, x2) \}$$

$$\checkmark \delta(q, 1, x) = \{ (q, xx) \}$$

$$\checkmark \delta(q, \epsilon, x) = \{ (q, \epsilon) \}$$

$$\checkmark \delta(q, 0, x) = \{ (p, x) \}$$

$$\checkmark \delta(p, 1, x) = \{ (p, \epsilon) \}$$

$$\delta(p, 0, x) = \{ (q, x) \}$$

sol)

$$S \rightarrow [q, z, p] [q, z, q]$$

$$(i) [q, z, p] \rightarrow 1 [q \times q] [q \neq p]$$

$$\text{Eq.} \quad 1 [q \times p] [p \neq p]$$

$$[q, z, q] \rightarrow 1 [q \neq q] [q \neq q]$$

$$1 [q \neq p] [p \neq q]$$

$$(ii) [q, x, q] \rightarrow 1 [q \times q] [q \times q]$$

$$1 [q \times p] [p \times q]$$

$$[q, x, p] \rightarrow 1 [q \times q] [q \times p]$$

$$1 [q \times p] [p \times p]$$

$$(iii) [q, x, q] \rightarrow \epsilon$$

$$(iv) [q, x, q] \rightarrow 0 [p \times q]$$

$$[q, x, p] \rightarrow 0 [p \times p]$$

$$(v) [p, x, p] \rightarrow 1 \text{ ~~p~~ } \text{ ~~p~~ }$$

$$\text{~~1 [p, x, p] \rightarrow 1 [p]~~}$$



$$(vii) [P, 3, 9] \rightarrow 0 [q, 3, 9] [ \text{---} ]$$

$$0 [ \text{---} ] [ \text{---} ]$$

$$[P, 3, P] \rightarrow 0 [q, 3, P] [ \text{---} ]$$

$$0 [ \text{---} ] [ \text{---} ]$$

$$S \rightarrow A/B$$

$$A \rightarrow 1EA / 1FC$$

$$B \rightarrow 1EB / 1FD$$

$$E \rightarrow 1EE / 1FH$$

$$F \rightarrow 1EF / 1FG$$

$$E \rightarrow e / 0H$$

$$F \rightarrow 0G$$

$$G \rightarrow 1$$

$$C \rightarrow 0A$$

$$D \rightarrow 0B$$

Final Grammar:

$$E \rightarrow 1EE$$

$$F \rightarrow 1EF / 1FG$$

$$E \rightarrow e$$

$$F \rightarrow 0G$$

$$G \rightarrow 1$$

### Simplifying the grammar:

In the above grammar 1st identify the non terminals that are not defined and eliminate the productions that refers to these productions. Similarly, use these procedure of eliminating the useless symbols and useless production and then complete grammar is a minimized grammar (By removing useless products)

### First example simplifying:

$$[q_0, 3_0, q_0] = A$$

$$[q_0, 3_0, q_1] = B$$

$$[q_0, 3, q_0] = C$$

$$[q_0, 2, q_1] = D$$

$$[q_1, 3, q_1] = E$$

$$[q_1, 3_0, q_1] = F$$

$$[q_1, 3_0, q_0] = G$$

$$[q_1, 3, q_0] = H$$

$$S \rightarrow A/B$$

$$A \rightarrow bCA / bDG$$

$$B \rightarrow bCB / bDE$$

$$A \rightarrow e$$

$$C \rightarrow bCC / bDH$$

$$D \rightarrow aC / bD / bDE$$

$$E \rightarrow b$$

$$F \rightarrow aC$$

$$F \rightarrow aB$$

$$G \rightarrow aA$$

$$H \rightarrow aB$$

$$[P, 3, 9] \rightarrow 0[2, 3, 9] [ \text{---} ]$$

$$0[ \text{---} ] [ \text{---} ]$$

$$[P, 3, P] \rightarrow 0[2, 3, P] [ \text{---} ]$$

$$0[ \text{---} ] [ \text{---} ]$$

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$$[q_1, 3, q_1] = F$$

$$[q_1, 3, q_0] = G$$

$$[q_1, 3, q_0] = H$$

$$S \rightarrow A/B$$

$$A \rightarrow bCA / bD G$$

$$B \rightarrow bCB / bDE$$

$$A \rightarrow e$$

$$C \rightarrow bCC / bDH$$

$$D \rightarrow aC / bCD / bDE$$

$$e \rightarrow b$$

$$F \rightarrow aC$$

$$F \rightarrow aB$$

$$G \rightarrow aA$$

$$H \rightarrow aB$$



$$(vii) [P, 3, q] \rightarrow 0 [q, 3, q] [ \text{---} ]$$

$$0 [ \text{---} ] [ \text{---} ]$$

$$[P, 3, P] \rightarrow 0 [q, 3, P] [ \text{---} ]$$

$$0 [ \text{---} ] [ \text{---} ]$$

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$$G \rightarrow 1$$

$$e \rightarrow 0A$$

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$$[q_1, 3, q_1] = E$$

$$[q_1, 3_0, q_1] = F$$

$$[q_1, 3_0, q_0] = G$$

$$[q_1, 3, q_0] = H$$

$$S \rightarrow A/B$$

$$A \rightarrow bCA / bDG$$

$$B \rightarrow bCB / bDE$$

$$A \rightarrow e$$

$$C \rightarrow bCC / bDH$$

$$D \rightarrow aC / bCD / bDE$$

$$e \rightarrow b$$

$$F \rightarrow aC$$

$$F \rightarrow aB$$

$$G \rightarrow aA$$

$$H \rightarrow aB$$

$$b) M = \{ \{q_0, q_1\}, \{0, 1\}, \{0, 1, z_0\}, \delta, q_0, z_0, p \}$$

$$\delta(q_0, \epsilon, z_0) = (q_1, \epsilon)$$

$$\delta(q_0, 0, z_0) = (q_0, 0z_0)$$

$$\delta(q_0, 0, 0) = (q_0, 00)$$

$$\delta(q_0, 1, 0) = (q_0, 10)$$

$$\delta(q_0, 1, 1) = (q_0, 11)$$

$$\delta(q_0, 0, 1) = (q_1, \epsilon)$$

$$\delta(q_1, 0, 1) = (q_1, \epsilon)$$

$$\delta(q_1, 0, 0) = (q_1, \epsilon)$$

$$\delta(q_1, 0, 1) = (q_1, \epsilon)$$

$$\delta(q, \epsilon, z_0) = (q, \epsilon)$$

$$\epsilon \rightarrow [q_0, z_0, q_0] / [q_0, z_0, q_1]$$

$$\rightarrow [q_0, z_0, q_1] \rightarrow \epsilon$$

$$[q_0, z_0, q_0] \rightarrow 0 [q_0, 0, q_0] [q_0, z_0, q_0] /$$

$$0 [q_0, 0, q_1] [q_1, z_0, q_0]$$

$$[q_0, z_0, q_1] \rightarrow 0 [q_0, 0, q_0] [q_0, z_0, q_1] /$$

$$0 [q_0, 0, q_1] [q_1, z_0, q_1]$$

$$[q_0, 0, q_0] \rightarrow 0 [q_0, 0, q_0] [q_0, 0, q_0] /$$

$$0 [q_0, 0, q_1] [q_1, 0, q_0]$$

$$[q_0, 0, q_1] \rightarrow 0 [q_0, 0, q_0] [q_0, 0, q_1]$$

$$0 [q_0, 0, q_1] [q_1, 0, q_1]$$

$$[q_0, 0, q_0] \rightarrow 1 [q_0, 1, q_0] [q_0, 0, q_0] /$$

$$1 [q_0, 1, q_1] [q_1, 0, q_0]$$

$$[q_0, 0, q_1] \rightarrow 1 [q_0, 1, q_0] [q_0, 0, q_1] /$$

$$1 [q_0, 1, q_1] [q_1, 0, q_1]$$

$$[q_0, 1, q_0] \rightarrow 1 [q_0, 1, q_0] [q_0, 1, q_0] /$$

$$1 [q_0, 1, q_1] [q_1, 1, q_0]$$



$$[q_0, 1, q_0] \rightarrow 1 [q_0, 1, q_0] [q_0, 1, q_1] /$$

$$1 [q_0, 1, q_1] [q_1, 1, q_1]$$

$$\rightarrow [q_0, 1, q_1] \rightarrow 0$$

$$[q_1, 1, q_1] \rightarrow 0$$

$$[q_1, 0, q_1] \rightarrow 0$$

$$[q_1, 30, q_1] \rightarrow e$$

$$[q_0, 30, q_0] - A \quad [q_0, 0, q_1] - p$$

$$[q_0, 30, q_1] - B \quad [q_0, 1, q_0] - e$$

$$[q_0, 0, q_0] - C \quad [q_0, 1, q_1] - F$$

$$[q_1, 1, q_1] - G$$

$$[q_1, 0, q_1] - H$$

$$[q_1, 30, q_1] - J$$

$$[q_1, 30, q_0] - J$$

$$[q_1, 0, q_0] - K$$

$$[q_1, 1, q_0] - L$$

$$S \rightarrow A/B$$

$$B \rightarrow e$$

$$A \rightarrow 0CA/0DJ$$

$$B \rightarrow 0CB/0DJ$$

$$C \rightarrow 1eC/1Fk$$

$$D \rightarrow 1eD/1FG$$

$$E \rightarrow 1ee/1FL$$

$$F \rightarrow 1eF/1FG$$

$$- F \rightarrow 0$$

$$- G \rightarrow 0$$

$$- H \rightarrow 0$$

$$- J \rightarrow e$$

$$Q) r = \{ \{q\}, \{i, e\}, \{x, z\}, \delta, q, s, \phi \}$$

$$\delta(q, i, z) = \{ (q, x, z) \}$$

$$\delta(q, e, x) = \{ (q, e) \}$$

$$\delta(q, e, z) = \{ (q, e) \}$$

$$\delta \rightarrow [q, z, q]$$

$$[q, z, q] \rightarrow i [q, x, q], [q, z, q]$$

$$[q, x, q] \rightarrow e$$

$$[q, z, q] \rightarrow e$$

$$S \rightarrow A$$

$$A \rightarrow iBA$$

$$B \rightarrow \epsilon$$

$$A \rightarrow \epsilon$$

All are useful grammar.