NUMERICAL METHODS

Course Objectives:

The objective of this course is to familiarize the students with numerical methods of solving the nonlinear equations, interpolation, differentiation, integration, and ordinary differential equations.

Course Outcomes: At the end of the course, the student will be able to:

CO1: calculate a root of algebraic and transcendental equations. Explain the relation between the finite difference operators (**L3**).

CO2: evaluate interpolating polynomial for the given data (L4).

CO3: solve ordinary differential equations numerically using Euler's and RK methods (L3).

CO4: solve numerically the linear system of equations by direct and iterative methods (L3).

COS: discuss eigenvalues and eigenvectors of a matrix using different methods (L2)...

UNIT-I 10 Lectures

Solutions of algebraic and transcendental equations and Finite Differences:

Solutions of algebraic and transcendental equations-Introduction, Bisection Method, Regular Falsi Method, Newton Raphson Method (including error analysis). Finite differences, differences of polynomial (Sections 2.1, 2.2, 2.3, 2.5, 3.3 and 3.5 of the textbook)

Learning Outcomes:

At the end of this unit, the student will be able to

- 1. determine approximate roots of an equation by using different numerical methods (L3)
- 2. evaluate the missing terms in given tabular data (L5)
- 3. explain various discrete operators and find the relation among operators (L2)

UNIT-II 10 Lectures

Interpolation and Numerical Differentiation:

Interpolation: Introduction, Newton's forward difference interpolation, Newton's backward difference interpolation, Lagrange's interpolation and Newton's divided interpolation, Inverse interpolation.

Numerical Differentiation: Introduction, Derivatives using forward difference formula, backward difference formula. (Sections 3.1, 3.6, 3.9.1, 3.10.1, 3.11, 6.2 [excluding 6.2.1 - 6.2.3] of the textbook)

Learning Outcomes:

At the end of this unit, the student will be able

- 1. apply Newton forward and backward formulas for equal and unequal intervals (L3)
- 2. describe how to determine values of derivatives of unknown function at the intermediate points with the given data (L2)
- 3. evaluate an interpolating polynomial for the given tabular data (L5)

UNIT-III 10 Lectures

Numerical Integration and Numerical solution of Ordinary Differential Equations:

Numerical Integration: Introduction, Trapezoidal rule, Simpson's 1/3rd rule, Simpson's 3/8th rules

Numerical solution of ordinary differential equations: Introduction, Euler's method, Modified Euler method, Runge-Kutta method (Sections 6.4.1, 6.4.2, 6.4.3, 8.1, 8.4, 8.5 of the textbook)

Learning Outcomes:

At the end of this unit, the student will be able to

- 1. evaluate the area bounded by non-negative functions by using different numerical Methods (L5)
- 2. determine the solution of an ODE by Euler's method (L3)
- 3. illustrate the solution of an ODE using R-K method (L4)

UNIT-IV 10 Lectures

Numerical Linear Algebra -I

Solution of linear Systems (Iterative Methods) - Gauss elimination, Jacobi Iterative method; Gauss Seidel Iterative Method, LU Factorization- Doolittle's Method, Crout's Method; Cholesky's Method.

(Sections 7.5.1, 7.5.6, 7.6(a),(b) of textbook 1)

Learning Outcomes:

At the end of this unit, the student will be able to

- 1. solve linear simultaneous equations, by using LU Factorization (L3)
- 2. illustrate the solution of the linear simultaneous equations using iterative methods (L4)
- 3. explain Doolittle's, Crout's and Cholesky's Methods (L2)

UNIT-V 10 Lectures

Numerical Linear Algebra -II:

Rayleigh's power method, Gram Schmidt process, QR Factorization of matrices, Singular Value Decomposition, Principal component analysis (Sections 5.8, 6.4, 7.4, 7.5 of textbook 2)

Learning Outcomes:

At the end of this unit, the student will be able to

- 1. determine orthogonal set of vectors from the given linear independent set of vectors(L3)
- 2. evaluate largest eigenvalue and eigenvector using Rayleigh's power method (L5)
- 3. determine singular values and singular vectors (L3)

TEXTBOOKS:

- **1.** S.S. Sastry, "Introductory Methods of Numerical Analysis", 5th edition, Prentice Hall India Pvt. Limited, 2012.
- 2. David C. Lay, "Linear Algebra and Its Applications", 4th edition, Addison-Wesley, 2012

REFERENCE BOOKS:

- **1.** M.K. Jain, S.R.K. Iyengar and R.K.Jain, "Numerical Methods for Scientific and Engineering Computation", 4th edition, New Age International (P) Limited, Publishers, 2004
- 2. Samuel Daniel Conte, Carl W. De Boor, "Elementary Numerical Analysis: An Algorithmic Approach", 3rd edition, McGraw- Hill, 2008.
- 3. Gilbert Strang, "Introduction to Linear Algebra", 5th edition, Wellesely- Cambridge Press, 2016