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IMAGE CAPTIONING WITH RECURRENT NEURAL NETWORKS

SEMESTRÁLNÍ PROJEKT
TERM PROJECT

AUTOR PRÁCE
AUTHOR

Bc. JAKUB KVITA

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POPIS FOTOGRAFIÍ POMOCÍ REKURENTNÍCH NEU- RONOVÝCH SÍTÍ

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Abstrakt

Výtah (abstrakt) práce v českém jazyce.

Abstract

Výtah (abstrakt) práce v anglickém jazyce.

Klíčová slova

Klíčová slova v českém jazyce.

Keywords

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Image Captioning with Recurrent Neural Networks

Prohlášení

Prohlašuji, že jsem tento semestrální projekt vypracoval samostatně pod vedením pana Michala Hradiše.

.....

Jakub Kvita
January 4, 2016

Poděkování

Zde je možné uvést poděkování vedoucímu práce a těm, kteří poskytli odbornou pomoc.

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Tato práce vznikla jako školní dílo na Vysokém učení technickém v Brně, Fakultě informačních technologií. Práce je chráněna autorským zákonem a její užití bez udělení oprávnění autorem je nezákonné, s výjimkou zákonem definovaných případů.

Contents

1	Introduction	2
2	Neural networks	3
2.1	Recurrent neural nets	3
2.1.1	LSTM – Long Short-Term Memory	4
2.1.2	GRU – Gated Recurrent Unit	5
2.1.3	Language modeling and word embeddings	6
2.2	Convolutional neural nets	7
3	Experiments	8
3.1	Torch	8
3.1.1	nn, nngraph	8
3.1.2	rnn	8
3.1.3	Other packages	8
3.2	Predicting next character in sequence	8
4	Image caption generation	9
4.1	Related Work	9
4.1.1	Show and Tell: A Neural Image Caption Generator	10
4.1.2	Show, Attend and Tell: Neural Image Caption Generation with Visual Attention	10
4.1.3	From Captions to Visual Concepts and Back	10
4.1.4	Long-term Recurrent Convolutional Networks for Visual Recognition and Description	10
4.2	Datasets	10
4.3	Evaluation	11
4.3.1	Automated metrics	11
5	Model	13
5.1	Architecture	13
5.2	Training details	13
6	Conclusion	14

Chapter 1

Introduction

Klasicky popis toho co se tady bude dit, jak je to dulezite, atd.

Chapter 2

Neural networks

General idea of neural networks was slowly emerging after World War II. Perceptron, as a single neuron unit, was created in 1958 by Frank Rosenblatt¹, but became popular only after creation of backpropagation algorithm in 1975. At that time neural nets have not reached massive popularity, not because they are not working, but due to small computing power of machines back then and lack of datasets. Recently (after 2000) neural nets became popular again, rebranded as ‘Deep Learning’, because researchers realized that it is possible and very useful to stack neural nets on top of each other and create deep architectures, which are more practical than shallow ones. During this reinvention neural nets have been successfully applied in multiple fields like computer vision, speech recognition and natural language processing.

Since then various useful architectures and algorithms are now introduced almost every month. There is vast amount of various architectures and algorithms, in this chapter, I will describe only a couple – those used in this thesis.

2.1 Recurrent neural nets

Feedforward neural nets are extremely powerful models, which can be highly parallelized. Despite that, they can be only applied to problems with inputs and outputs, which have fixed dimensionality (e.g. one-hot encoding vectors). This is a serious drawback, as many of the real-world problems are defined as sequences with lengths that are unknown to us in beforehand. Soon recurrent neural networks were introduced and they proved to be very useful to this kind of task. There is vast amount of recurrent neural networks, many not suitable for sequential tasks like Hopfield network, which are very successful in specific tasks, but nevertheless not useful for us now.

Apart from classification, which can be more precise when using sequences, one of the most important tasks is next value prediction. This core task can be then extended very simply to predict arbitrary number of future values. Prediction problems are all around us, from the weather forecast and stock market prediction to the autocomplete in smartphones or web browsers.

We can understand recurrent neural networks as very deep forward nets with shared weights. It is called RNN unrolling and it is described in figure 1. Layers of this very deep net spread in time, together with the input sequence. This is very innovative idea,

¹The perceptron: A probabilistic model for information storage and organization in the brain. Rosenblatt, F. Psychological Review, Vol 65(6), Nov 1958, 386–408.

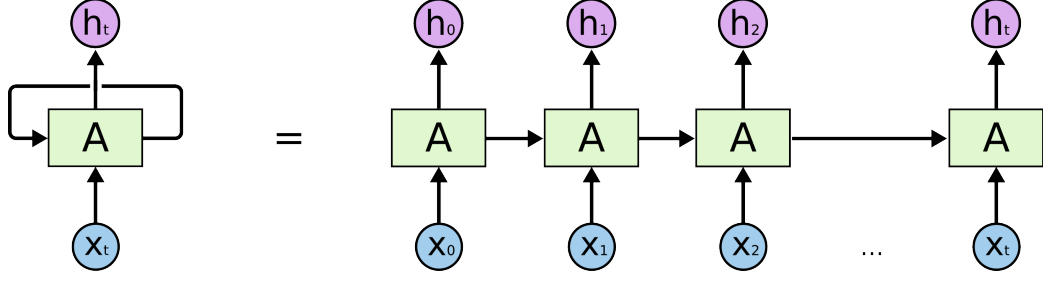


Figure 1: Unrolling of the recurrent neural net. (C. Olah 2015 [13])

which enabled training RNN with backpropagation through time. It also shows that, as very deep networks, they have vanishing or exploding gradient problem, which means that the network is not able to learn long-term dependencies, even though in theory it should. This is a serious issue, which is caused by iterating many times over the weights and the activation function with derivatives > 1 (exploding gradient) or < 1 (vanishing gradient). Gradient then dies out and learning stops for distant dependencies. Among others this problem has been solved by the LSTM unit described in part 2.1.1, which is most popular now and following research resulting in GRU described in part 2.1.2.

2.1.1 LSTM – Long Short-Term Memory

Long Short-Term Memory nets are special kind of recurrent network, capable of learning long-term dependencies. This architecture was introduced by Hochreiter & Schmidhuber (1997) in [7] after prior research of vanishing gradient problem. Later architecture was refined and popularized by other researchers and nowadays LSTM is most used and popular RNN architecture used.

The LSTM unit designed that it can remember a value for an arbitrary length of time. It contains gates that determine when the input is significant enough to remember, when it should keep or forget the value, and when it should output the value. To understand the flow of data, see the diagram of a simplified LSTM unit is on the figure 2.

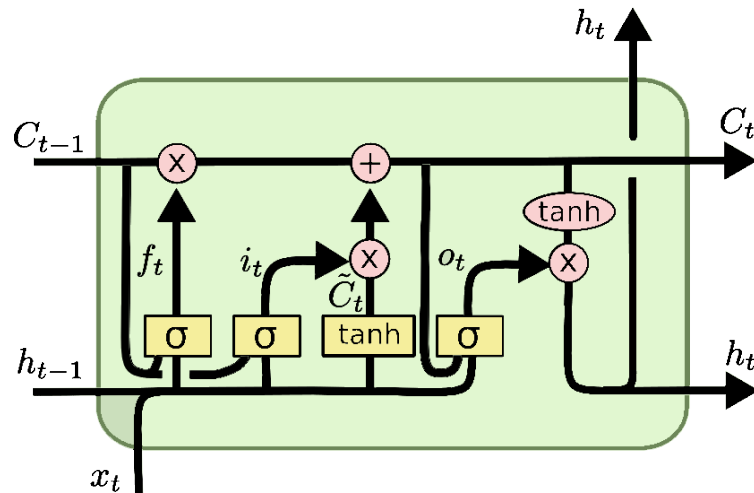


Figure 2: Variation of the LSTM unit. (C. Olah 2015 [13])

All these gates can be described by series of equations (1)→(6). In each time slice the unit is using current input x_t , last stored value c_{t-1} and unit output h_{t-1} to compute next state c_t and output h_t . Variables i_t , f_t , o_t denotes value of input, forget and output gates which are used to control the information flow.

$$i_t = \sigma(W_{xi}x_t + W_{hi}h_{t-1} + W_{ci}c_{t-1} + b_i) \quad (1)$$

$$f_t = \sigma(W_{xf}x_t + W_{hf}h_{t-1} + W_{cf}c_{t-1} + b_f) \quad (2)$$

$$z_t = \tanh(W_{xc}x_t + W_{hc}h_{t-1} + b_c) \quad (3)$$

$$c_t = f_t \odot c_{t-1} + i_t \odot z_t \quad (4)$$

$$o_t = \sigma(W_{xo}x_t + W_{ho}h_{t-1} + W_{co}c_t + b_o) \quad (5)$$

$$h_t = o_t \odot \tanh(c_t) \quad (6)$$

$$\sigma(x) = \frac{1}{1 + e^{-x}} \quad (7)$$

LSTM based on these equations is using total of 11 weight matrices and 4 bias vectors for computations and sigmoid function σ defined in the equation (7) and the operation \odot denotes the element-wise vector product. Equations described in this work are not the only way how to create an LSTM unit, but they will be used later while implementing the proposed model. Some of the versions are omitting ‘peephole connections’, which allows gates to look at stored value C_{t-1} , C_t or include only some of them.

Training of the LSTM based network can be performed effectively by standard methods like stochastic gradient descend in the form of backpropagation through time. Major problem with vanishing gradients during training described earlier is not an issue as back-propagated error is fed back to each of the gates.

2.1.2 GRU – Gated Recurrent Unit

Gated Recurrent Unit is slightly more dramatic variation on the LSTM theme from 2014 paper [2]. It combines hidden state of the unit h_t with the saved value C_t , merges input and forget gates into one update gate and removes peephole connections. These changes are simplifying standard LSTM models, but not at the expense of performance, and cause rapid growth in popularity. Diagram of the GRU unit is on the figure 3.

$$r_t = \sigma(W_{xr}x_t + W_{hr}h_{t-1} + b_r) \quad (8)$$

$$z_t = \sigma(W_{xz}x_t + W_{hz}h_{t-1} + b_z) \quad (9)$$

$$\tilde{h}_t = \tanh(W_{xh}x_t + W_{hh}(h_{t-1} \odot r_t) + b_h) \quad (10)$$

$$h_t = (1 - z_t) \odot \tilde{h}_t + z_t \odot h_{t-1} \quad (11)$$

$$\sigma(x) = \frac{1}{1 + e^{-x}} \quad (12)$$

Equations (8)→(11) describe a version of GRU unit used in this work, with sigmoid function σ defined in equation (12). The operation \odot again denotes the element-wise



Figure 3: Variation of a GRU unit. (C. Olah 2015 [13])

vector product. While it is using only 4 weight matrices, 3 biases and just 1 state variable, researchers studied whether this can achieve at least same performance as previous LSTM unit.

Last year, study by Chung [3] was done, where different types of recurrent units were compared on the polyphonic music datasets. In this task LSTM and GRU were significantly better than all the other architectures, with GRU slightly in the lead. Generally, researchers agree that most of the LSTM variations, including GRU, are roughly on the same performance level. In [6] GRU is an average variation, slightly better than vanilla LSTM, with much simpler architecture.

In paper [9], which emphasized variety of tasks and the data, GRU outperformed LSTM unit on all tasks with the exception of language modeling. There are multiple approaches to model languages and in this work I will explore different type than the one mentioned in Jozefowicz’s [9] paper. More will be explained in following chapters. Interestingly they also found that LSTM nearly matched the GRU’s performance, when its forget gate bias was initialized to 1 and not to naive initialization around 0. It is also worth mentioning that Jozefowicz in his paper discovered several architectures similar to GRU, but with slightly better general performance. They were found by evolutionary algorithm working on candidate architectures represented by the computational graph.

2.1.3 Language modeling and word embeddings

With the addition of LSTM units, recurrent neural nets quickly showed good performance in many different types of sequence processing like speech recognition from sound waves, signal prediction and language modeling. These result were further improved when researchers started stacking LSTMs on top of each other like pancakes.

Text is represented by discrete values and is usually presented to network in form of input vectors with one-hot encoding². If we have a task with K classes, class i will be represented by a vector V of length K . All the entries of V will be switched off to 0, except V_i , which will have the value of 1. Vector V is simultaneously a degenerated multinomial

²One-hot encoded vector has exactly one high ('1') value and all the others low ('0').

probability distribution of the current input. If the output has the same shape as input, it can be simply created by softmax function at the output layer. Result will be proper multinomial distribution of next value, given current value.

At this point it is necessary to decide what will classes and defined vectors represent. In most cases, text prediction is performed at the word level. K is hence the number of words in the dictionary. This can cause some problems, as in bigger tasks dictionary often exceeds 100 000 records. This many classes require huge amount of training data to properly cover all the cases and high computational cost of the softmax layer is also an issue. This text representation cannot be used for texts not containing separate words, like multi-digit numbers. Nevertheless, state-of-the-art models have been using word-level representation. One of the advantages is no need to teach the net proper forms of the words. The net does not have to remember, how to spell the words properly and can learn other, more useful, features.

To solve the problem with extremely long input vectors, set of techniques called *word embedding* were developed. They map words from the vocabulary to suitable vectors of real numbers in high dimensional space (around 50–1000 dimensions). Chosen vectors cannot be random, they are meaningful in order of performing some following task. For example Skip-gram model from [12] mapped 783 millions words to vectors of 300 real numbers, while creating reasonable relationships between them.

Character level modeling has been considered and used as an alternative to word-level, but so far had slightly worse performance. Regardless, it is still considered as an option, because it has much simpler representation of input and output. Consider roughly 45 characters in English text and over 50000 words created from them. Character level network is also more suited for Czech or Russian and other fusional languages³, which heavily use prefixes and suffixes to create new words. This is also an ability, which cannot be overlooked, as it is not available for word level. Character level models have usually smaller vocabulary size and have to be trained longer, as they need to learn spelling of the words on top of the same features of word level. With the properly trained character level model we can benefit from its much greater generative abilities, than we can achieve with word-level.

2.2 Convolutional neural nets

Kratky uvod do toho, kde se používají, popis jak fungují.

Není potřeba davat subsekcce na vrstvy, staci popsat jak to funguje vsechno dohromady, jednotlivé vrstvy ve větách v jednom odstavci. Obrazek. V diplomce rozpracovat víc.

³Fusional language is a type of language distinguished by its tendency to overlay many morphemes to denote grammatical, syntactic, or semantic change.

Chapter 3

Experiments

Asi kapitola jen na semestrální projekt. V diplomce ji odstranim.

Jak se implementuje deep learning, jaké knihovny se používají - Caffe, Theano, Tensor-Flow, Torch. Popsat ze Torch bude v této kapitole.

Budu popisovat věci co jsem zkoušel implementovat v Torchi.

3.1 Torch

Torch se zrecykluje do diplomky.

Udělat tedy tabulku o různých balících co torch má

Jak fungují rekurentní sítě v Torchi.

Nacítání modelu z Caffe, ukládání v Torchi...

3.1.1 nn, nngraph

Linky na knihovny.

3.1.2 rnn

3.1.3 Other packages

loadcaffe, optim,...

3.2 Predicting next character in sequence

Implementace sekce Language modeling, jak se to konkrétně dělá.

Jak jsem to udělal, co to dělá, ukázky.

Karpathyho char-rnn

[10]

Chapter 4

Image caption generation

Scene understanding is one of the fundamental and most difficult tasks of computer vision. Being able to automatically generate image or video captions in regular text could have great effect. However, it is much more complicated than simple classification or object recognition, because the model also need to understand relations between the recognized objects and capture that correctly in the captions.

In this chapter I will do an overview of approaches to this task and more closely describe latest papers on which is this work based (section 4.1). Following parts cover datasets (4.2) and evaluation procedures (4.3) most commonly used for this task.

4.1 Related Work

Currently, neural networks are most heavily used to generate captions. Before them two main approaches were common. The first one used caption templates, which were filled by detected objects and relations. Second was based on retrieving similar captions from database and modifying them to fit current image. Question of similarity ranking has been addressed by many papers, which are based on the idea of joint embedding vector space for both images and captions. Close captions are located by searching this space.

Both approaches above usually included generalization step to remove information relevant only to current image, for example names. They are quite successful in describing images, but they are heavily hand-designed and their text-generation power is fixed on the database/embedding and is not able to describe previously unseen compositions of objects. Over time these approaches fell out of favor to now dominant neural network methods.

Many of the methods using neural nets are inspired by successful sequence to sequence training of recurrent neural nets for machine translation. One of the reasons is that introduced encoder-decoder architecture can be easily applied for captioning. We can interpret image captioning problem as translation from an image to a sentence. Encoder-decoder is an architecture which first encode image or sequence to a single feature vector, then decode it to produce output. The encoder part of the model is most of the time a convolutional neural network for image classification and decoder is type of a RNN or LSTM, which captioning community took over from machine translation.

One of the most interesting event in this field is MS COCO Captioning Challenge¹ in which many of the state-of-the-art researchers compete directly against each other. Most of the works described further have participated in this challenge.

¹MS COCO Challenge - <http://mscoco.org/dataset/#captions-challenge2015>

4.1.1 Show and Tell: A Neural Image Caption Generator

Clanek z Coco od Googlu.

[17]

Zminit i strojovy preklad (Sequence to Sequence Learning with Neural Networks)

[15]

4.1.2 Show, Attend and Tell: Neural Image Caption Generation with Visual Attention

Clanek z Coco z Montrealu/Toronta

[18]

4.1.3 From Captions to Visual Concepts and Back

Clanek z Coco od Microsoftu, mrknout se i na pokracovani v druhem clanku

[5]

4.1.4 Long-term Recurrent Convolutional Networks for Visual Recognition and Description

Clanek z Coco z berkeley

[4]

4.2 Datasets

Big datasets are necessary requirement in training recurrent neural nets, together with sufficient computing power. As access to machines and hardware suitable for training has been made extremely easy, obtaining enough data become the biggest problem. All the descriptions in the image captioning datasets have to be human generated, which is very expensive. This is one of the reasons, not many specialized datasets are created.

There are two main options how to get images and captions. First, using user-generated data from an online service, most commonly Flickr. However, captions are not made specifically for the task and could be prone to error. Second option is to create captions directly for use in the dataset. Amazon Mechanical Turk² is heavily used for this task. All datasets mentioned here are created this way.

Flickr8k [8] was one of the first datasets created for this purpose. It has been later expanded into Flickr30k [19]. MS COCO [1] is dataset created by Microsoft for their captioning challenge. CIDEr [16] datasets PASCAL-50S, ABSTRACT-50S are youngest mentioned, designed specifically for evaluation with the CIDEr metric.

²Amazon Mechanical Turk is crowdsourced Internet marketplace to perform tasks that computers are currently unable to do.

Table 1: Image captioning datasets.

Name	Images	Captions per image	Note
Flickr8k ³	8 092	5	Focused on people or animals (mainly dogs) performing some specific action.
Flickr30k ⁴	31 783	5-6	An extension of Flickr8k dataset.
MS COCO ⁵	120 000	5	Images are divided - 80 000 for training and 40 000 for testing purposes.
PASCAL-50S ⁶	1 000	50	Built upon images from the UIUC Pascal Sentence Dataset.
ABSTRACT-50S ⁷	500	50	Built upon images from the Abstract Scenes Dataset. No photos.

4.3 Evaluation

Recent progress in fields like machine translation, which are very similar to image captioning, caused spike of interest in evaluating regular text output accuracy. Although it is sometimes not clear if a description of an image is best option available, some degree of assessment is possible. The best results can be obtained by asking live raters to give a score on the usefulness of each description. Subjective scores can vary, but it can be averaged by giving same description to multiple raters. However this method consumes tremendous amount of time and usually external raters are necessary. Tools like Amazon Mechanical Turk can be used to great extent, but need for automated tools is evident.

4.3.1 Automated metrics

Assuming that one has access to human generated captions, which is ground truth in our case, completely automated metrics exists. Even though all of them compute how alike are generated to human descriptions, different approaches are used. One metric can use several different settings with slight changes in the algorithm. This raises the question, how can we compare results of different works, despite using the ‘same’ evaluation method. Microsoft group of researchers addresses this issue in [1]. They created an evaluation server⁸ which

³Flickr8k project page: <http://nlp.cs.illinois.edu/HockenmaierGroup/8k-pictures.html>

⁴Flickr30k project page: <http://shannon.cs.illinois.edu/DenotationGraph/>

⁵MS COCO project page: <http://mscoco.org/dataset/>

⁶PASCAL-50S and ABSTRACT-50S page: <http://ramakrishnavedantam928.github.io/cider/>

⁷See footnote 6.

⁸MS COCO evaluation server available through <http://mscoco.org/dataset/#captions-upload>.

have many automated metrics, with several configurations, including all mentioned here. It will serve as a reference point for comparing image captioning models.

The most commonly used metric has been BLEU (Bilingual Evaluation Understudy) [14], which was created in 2002 to evaluate quality of machine translated text from one language to another. Scores are computed on individual segments, usually sentences. BLEU has high correlation with human judgments and is still highly popular even for captioning tasks. However, it is becoming outdated as automatic methods are now outperforming humans. Four different variations of BLEU are used in MS COCO evaluation server.

METEOR (Metric for Evaluation of Translation with Explicit Ordering) [11] is another metric for the evaluation of machine translation from 2007. It was designed to fix some problems of the BLEU metric and it can also look for synonyms and perform stemming on input words.

Last year, metric designed directly to caption evaluation called CIDEr (Consensus-based Image Description Evaluation) [16] was introduced. This is still new metric, but with growing popularity as it correlate well with human judgment. Main idea of this metric is that given enough captions for the same image, metrics perform better. This can be seen in datasets introduced with it (see part 4.2).

Chapter 5

Model

Do semestrálního projektu nebo až na diplomku?

Design modelu, co chci použít, jaké metody chci zkusit.

Položit si principiální otázku a zjistit, jestli to nějak pomůže, jak to funguje.

5.1 Architecture

Architektura modelu, jaké matematické modely jsem použil, bez implementačních detailů.

5.2 Training details

Popis pomocí jakého algoritmu jsme trénovali, s jakými parametry, minibatches, datasety.

Chapter 6

Conclusion

Udelat jeden zaver pro semestralni projekt, pak ho prepsat pro diplomku.

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