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Micropilot: automation of fluorescence microscopy-based imaging for systems biology

Christian Conrad, Annelie Wünsche, Tze Heng Tan, Jutta Bulkescher, Frank Sieckmann, Fatima Verissimo, Arthur Edelstein, Thomas Walter, Urban Liebel, Rainer Pepperkok & Jan Ellenberg

Supplementary Figure 1	Classifier training and measurements of HeLa-SEC31 cells.
Supplementary Figure 2	Example images and classification of the live H2B-tubulin HeLa cells (scrambled siRNAi).
Supplementary Figure 3	Classification and normal recovery rate distribution of the automatic FRAP on <i>CBX1-EGFP</i> cells.
Supplementary Table 1	Pseudo code examples for the different microscopic systems.

Note: Supplementary Software and Supplementary Videos 1–4 are available on the Nature Methods website.

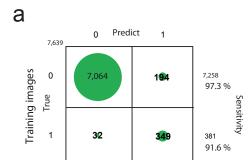
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Supplementary Figure 1

Classifier training and measurements of YFP-SEC31 HeLa cells.

543

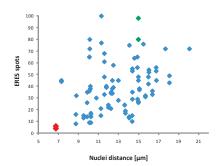
63.3 %



PPV

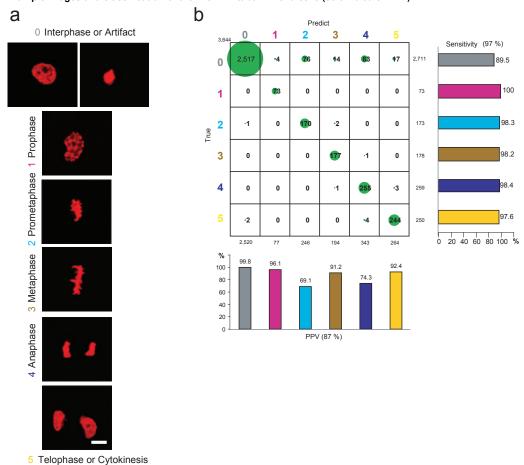
99.5 %

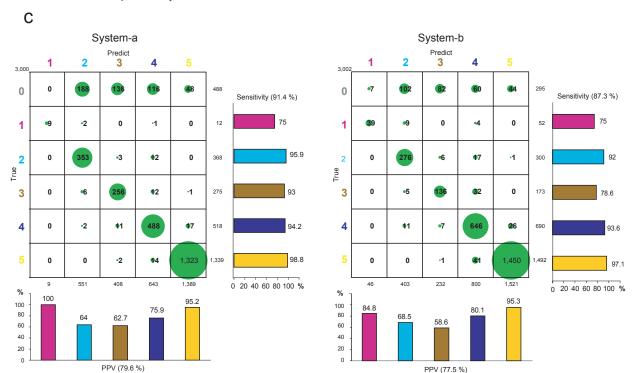
b



(a) Confusion matrix of the trained classifier shows true class assignments by human observer horizontally against the predicted vertically for the two different classes. At edges of the matrix the total numbers of the cell classes are given (overall total number in the left upper corner) corresponding to the PPV = TP / (TP + false positives) and the sensitivity = TP / (TP + false negatives). (b) Number of ERES of 91 high-resolution early anaphases to late telophases are plotted versus distance of nuclei (red rhombs correspond to nuclei in left and green rhombs to nuclei in right image in **Fig 2c**).

Example images and classification of the live H2B-tubulin HeLa cells (scrambled siRNAi).

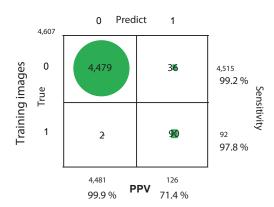


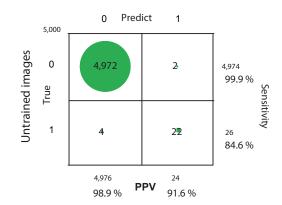


Supplementary Figure 3

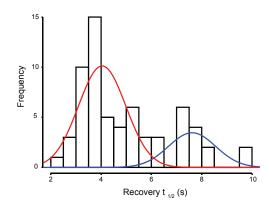
Classification and normal recovery rate distribution of the automatic FRAP on CBX1-EGFP cells.

a





b



(a) Confusion matrix of the classification show true class assignments by human observer horizontally against the predicted vertically for the two different classes. At edges of the matrix the total numbers of the cell classes are given (overall total number in the left upper corner) corresponding to the PPV and the sensitivity. (b) Histogram of the $t_{1/2}$ recovery of *CBX1-EGFP* of all prophase cells and the fitting of normal distribution for late (red) and early (blue) using normal mixture modeling.

Supplementary Table 1 Pseudo code examples for different microscope systems.

Please read the tables step-by-step following the arrows according to the Fig. 1b.

(a)

Synchronous (adhoc) communication using windows registry (similarly implemented for Zeiss 510, Olympus ScanR, or Perkin Elmer Ultraview).

Microscope	Micropilot
Write image path Set windows registry image path parameter after image capture in low-resolution: Software\ Settings\OnlineImageAnalysis\macro\path String Value = C:\repository\experiment_001\image T001Z01C01.tif	
Set the listener: Software\ Settings\OnlineImageAnalysis\macro\code String Value = 1 and wait	Read listener Read every 150ms the windows registry key for new incoming images in: Software\ Settings\OnlineImageAnalysis\macro\code
	Read Image If the listener parameter: Software\ Settings\OnlineImageAnalysis\macro\code String Value = 1 Then read:
	Software\ Settings\OnlineImageAnalysis\macro\path String Value = C:\repository\experiment_001\image T001Z01C01.tif Classification
	Classify image performing segmentation, feature extraction, and class prediction
Continue prescan If listener: Software\ Settings\OnlineImageAnalysis\macro\code String Value = 0 Then capture the next image position and jump back to 'Write image path'	Set listener If no positive cell found, set listener: Software\ Settings\OnlineImageAnalysis\macro\code String Value = 0 to skip position for complex imaging Else: Set xy-position offsets of the object of interest found relative to the image origin: Software\ Settings\OnlineImageAnalysis\macro\xoff String Value = 120 Software\ Settings\OnlineImageAnalysis\macro\yoff String Value = -240 Set listener for complex imaging: Software\ Settings\OnlineImageAnalysis\macro\code String Value = 2
Complex imaging If listener: Software\ Settings\OnlineImageAnalysis\macro\code String Value = 2 Read: Software\ Settings\OnlineImageAnalysis\macro\xoff String Value = 120 Software\ Settings\OnlineImageAnalysis\macro\yoff String Value = -240 Move accordingly to xy values and deploy predefined complex imaging. If finished go back to 'Continue prescan'	7

Asynchronous (list) communication using socket (implemented for Leica SP5).

Leica SP5 (LAS/Matrix Screener)	Micropilot
Send image path CAM server sends image path after new image capture: /relpath:FinalerTest\MitoExperimente 2009_10_22_14_05_20\slideS00\wellU00 V03\fieldX03Y00\imageL0000S00U00V03 J00X03Y00T0000Z00C00.ome.tif	Read image Read CAM command for image path at the specified address and port: /relpath:FinalerTest\MitoExperimente 2009_10_22_14_05_20\slideS00\wellU00V03\field X03Y00\imageL0000S00U00V03J00X03 Y00T0000Z00C00.ome.tif
Continue prescan and go back to 'Send image path'	(eventually filter out command if not applicable, e.g. autofocus images or complex imaging acquisition) Classification Perform segmentation, feature extraction, and class prediction.
Add position to list Listen to CAM add list commands and hold position list meanwhile	Send position If positive cell found send CAM command to add a position: /cli:CConrad /app:matrix /cmd:add /tar:camlist /exp:ips-file /ext:none /slide:0 /wellx:0 /welly:3 /fieldx:3 /fieldy:0 /dxpos:120/dypos:-240
Complex imaging Receive CAM start command and stop prescan to run complex imaging for list positions If finished jump back to 'Continue prescan'	Execute list If maximum number of positive cells is reached Or If timer is down (counting from first positive cell found) Then send CAM start command with timelapse parameters: /cli:CConrad /app:matrix /cmd:startcamscan /runtime:600 /repeattime:60 Clear list of position: cli:CConrad /app:matrix /cmd:deletelist

(**c**)

Synchronous (adhoc) communication using socket (implemented for $\mu Manager$).

Micro-Manager	Micropilot
Prescan image Stop prescanning after image acquisition and wait	Start and stop Start prescan acquisition in the first cycle followed by immediate stop command: gui.acqControlWin_runAcquisition(); acq.setPause(true);
Image path Print to socket: D:\cconrad\MM\Untitled_1\pos1\img_000000000_CFP 000.tif	Invoke image path Invoke image path with beanshell command: print (acq.getLastImageFilePath());
	Read Image D:\cconrad\\MM\\Untitled_1\pos1\img_000000000_CFP_0 00.tif
	Classification Perform segmentation, feature extraction, and class prediction.
Complex imaging Either move to next position for acquisition Or Execute complex imaging defined by dataAcqDlg ("Complex imaging settings")	Send command If no positive cell found: acq.setPause(false); Thread.sleep(100); acq.setPause(true); Jump back to prescan
Print to socket: True, if dataAcq is finished	Else: dataAcqDlg.RunAcquistion(); and invoke every 1000 ms: print(dataAcq.acqFinished_);
	Invoke prescan If dataAcq.acq Finished = True Then: acq.setPause(false); Thread.sleep(100); acq.setPause(true); Jump back to prescan