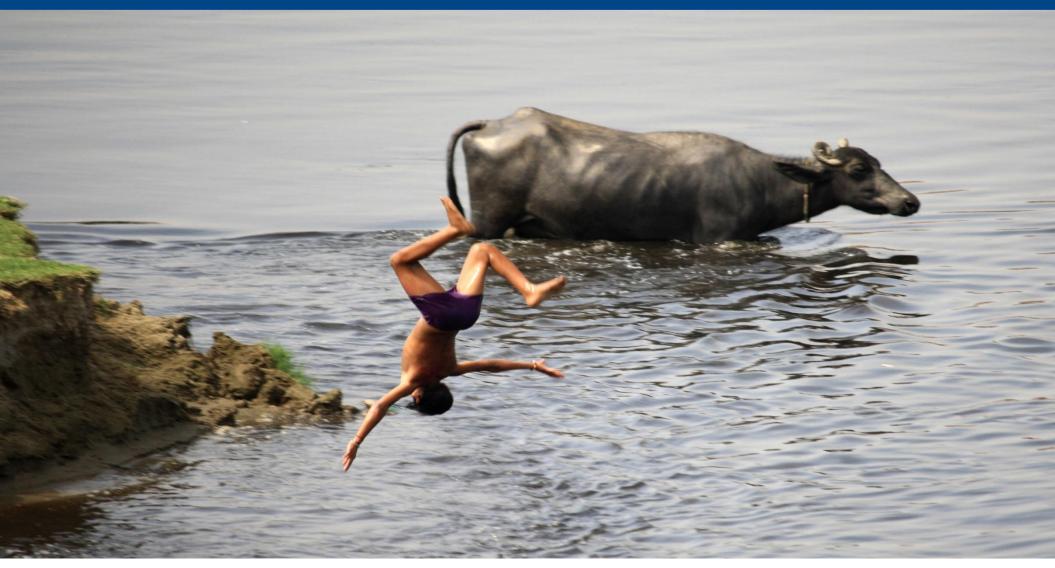
Operating Systems

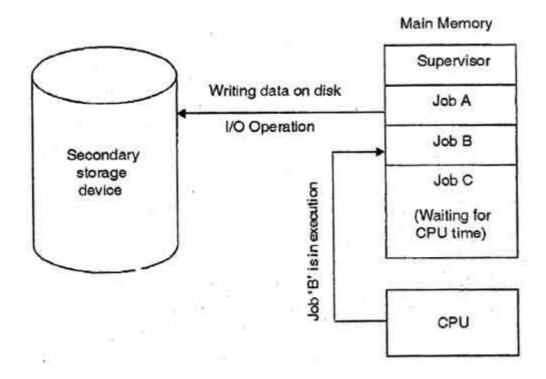


Processor Virtualization via Process Abstraction (Lecture-2)

Monsoon 2014, IIIT-H, Suresh Purini

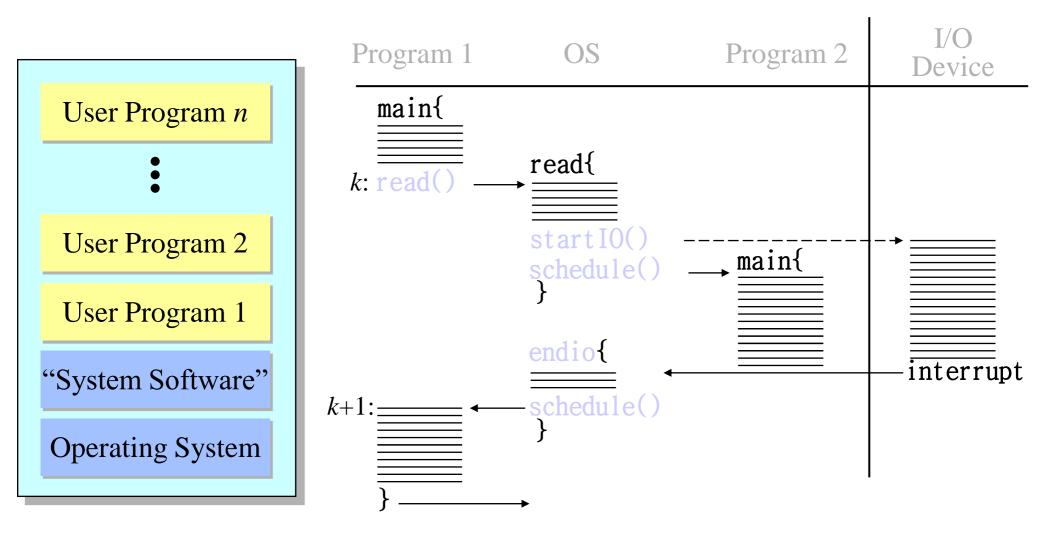
Multiprogrammed Operating Systems

Idea: Switch between multiple jobs based on I/O requests.



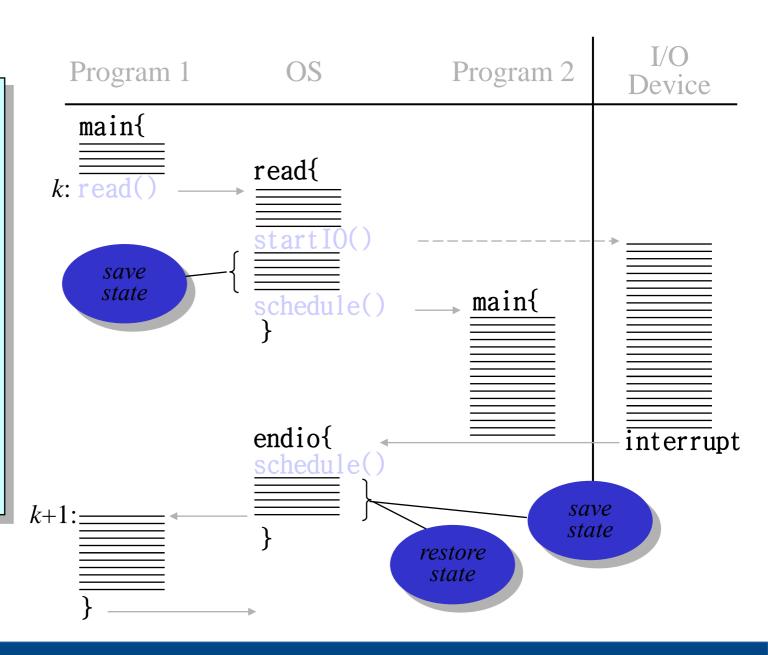
Multiprogramming ('65-'80)

Keep several jobs in memory and multiplex CPU between jobs



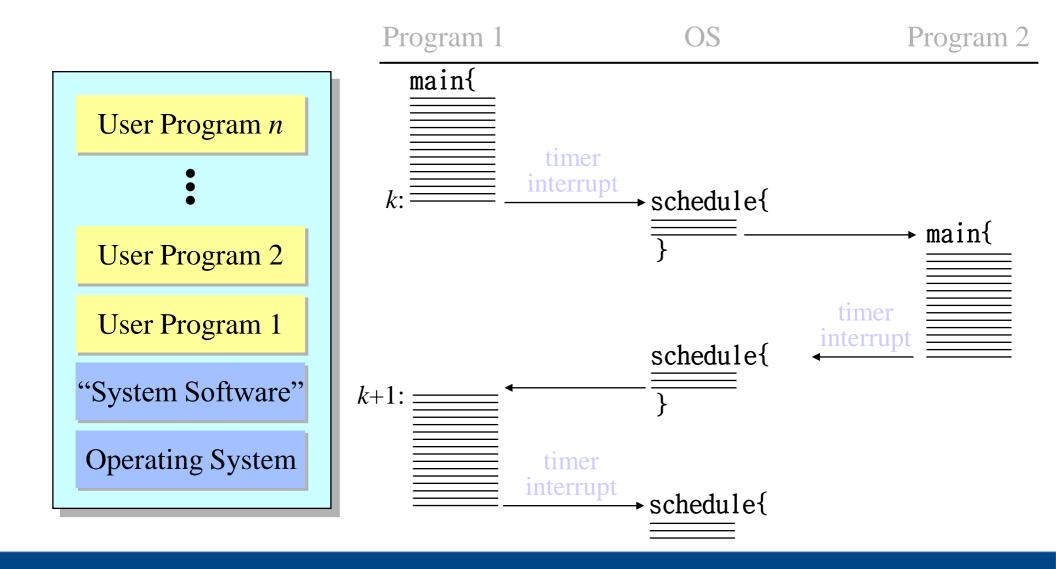
Context Switching

User Program n User Program 2 User Program 1 "System Software" **Operating System** Memory

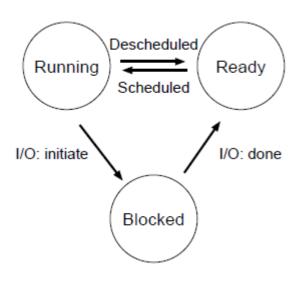


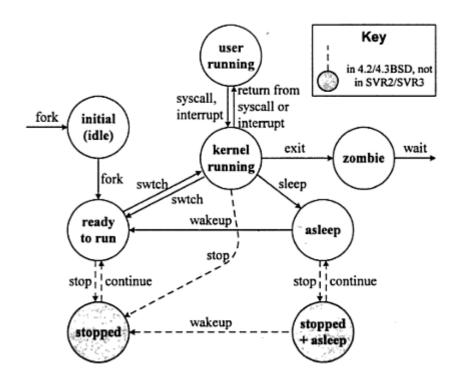
Timesharing Operating Systems ('70-)

A timer interrupt is used to multiplex CPU among jobs



Process State Transitions

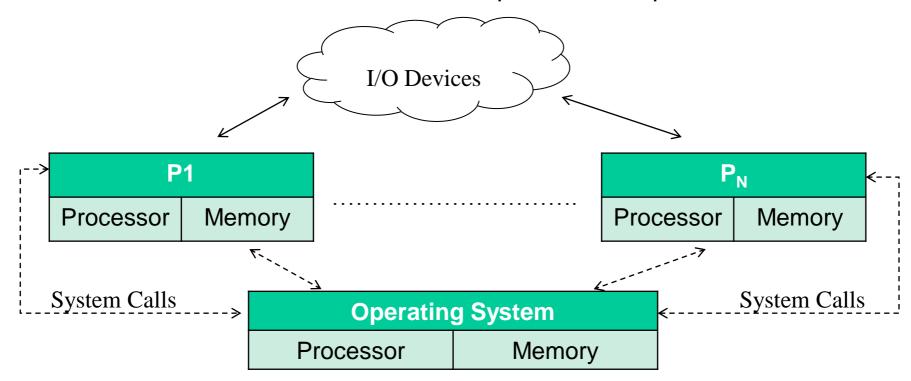




Scheduling Policy: Among the available ready-to-run processes which one should be allocated CPU in the next time slice.

Virtualization 1.0

- Goal: Give every program a virtual PC
- Every process
 - Gets an illusion that it has an entire processor for itself (via multiplexing CPU over time)
 - Complete memory address space available (via Virtual Memory)
- However: Indirect interference between processes is possible



Storage Lay-out of a Program

Code (Procedures are stored here)

Data Segment (Global variables and static variables are stored here)

Heap

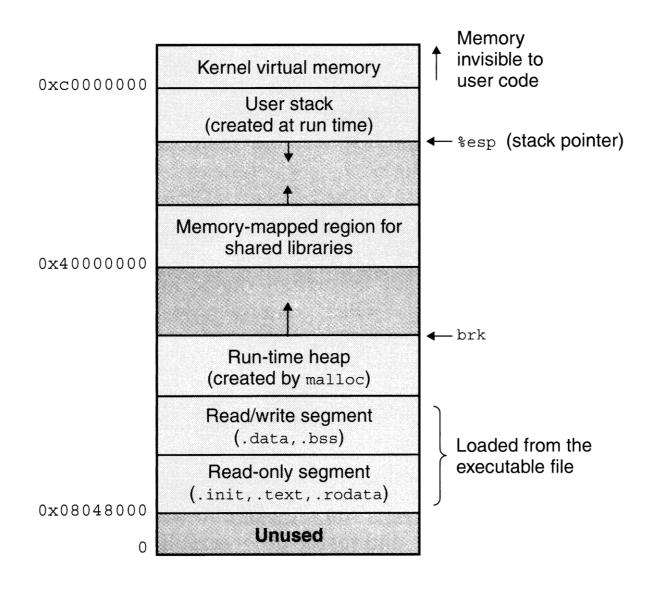
(memory allocated through malloc calls come from here)



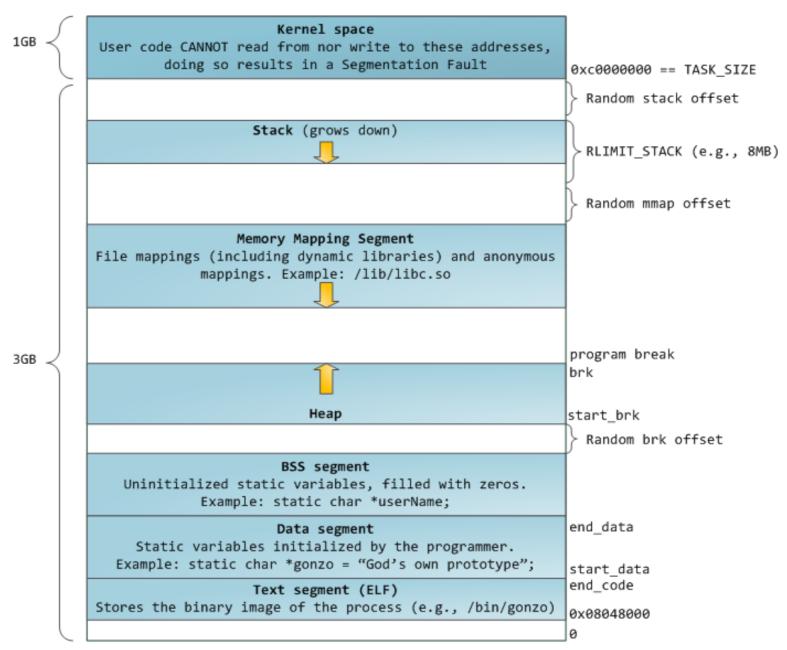
Stack

(Activation records for procedure invocations are stored here)

Virtual Address Space Layout of a Linux Process

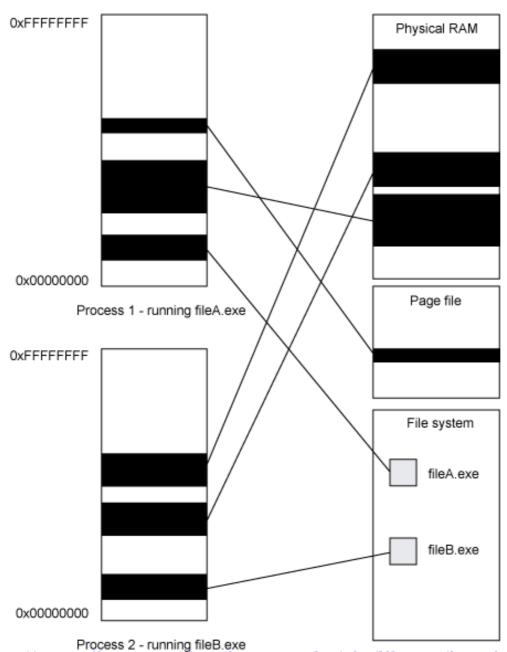


Virtual Address Space Layout of a Linux Process



Taken from: http://duartes.org/gustavo/blog/post/anatomy-of-a-program-in-memory

Virtual Address Space versus Physical Address Space



Taken From: http://www.ibm.com/developerworks/aix/library/j-nativememory-aix/index.html

Virtualizing a Processor

Goal

- We would like to run multiple programs on a single CPU (may be more).
- Each program should get an illusion that it has the entire CPU for itself.
 - In other words, provide each program a separate virtual CPU.
- Possible Tradeoff: Virtual CPU may run a bit slower than the underlying Physical CPU.
- Idea: A program relinquishes the CPU in either of the following two scenarios
 - Has to wait on an I/O request
 - Already used the allocated time slice (time multiplexing)

Process Abstraction

- A process is a dynamic object which can be created and destroyed using an OS API (aka system calls).
- The state of the process and its dynamics (or evolution) are a function of the static program from which it is created.
- Simply Put: A process is a program in execution.
 - A program is a static entity whereas a process is a dynamic entity.
- Process State: text/code, data, bss, stack, heap,
 CPU registers, program counter, ..., anything else!
- As a process executes its state keep evolving.

Memory Map

BIOS

OS Kernel

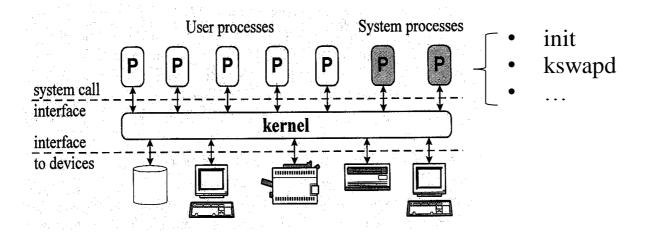
Process (text, data, stack, heap, ...)

Per Process Kernel Data Structures

- u-area (accessible only when the process is currently running)
 - Process control block Stores the hardware context when the process is not running
 - Open file descriptor tables
 - CPU and other resource usage statistics
 - Per kernel stack
 -
- proc structure (accessible at any time)
 - Process id
 - Location of the kernel address map for the u-area of this process
 - Current process state (like READY, STOPPED, BLOCKING, ...)
 - •

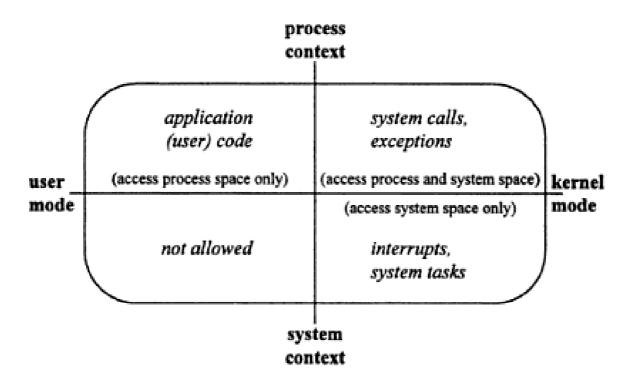
Process Abstraction

- Every process should get
 - a virtual CPU for itself
 - a complete virtual memory address space
- Different processes may run different instances of the same program
 - E.g., Two Firefox processes are fired from the same program.
- Every process gets a unique identifier (pid)



Mode, Space and Context

- User Mode vs Kernel Mode
 - Realized using processor modes
- User Space vs System Space
- Process Context vs System Context



Unresolved Issues

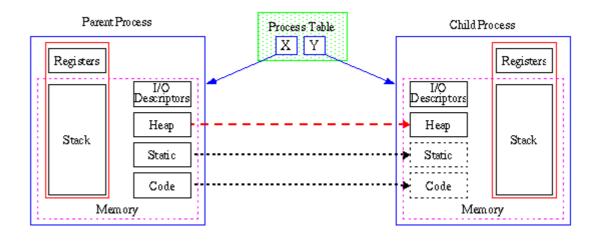
- 1. Kernel isolation
- 2. Process isolation
- 3. Address space isolation

main() pid = 3456 { pid=fork(); if (pid == 0) ChildProcess(); else ParentProcess(); } void ChildProcess() { } void ParentProcess() { }

```
main() pid = 0
{
    pid=fork();
    if (pid == 0)
        ChildProcess();
    else
        ParentProcess();
}

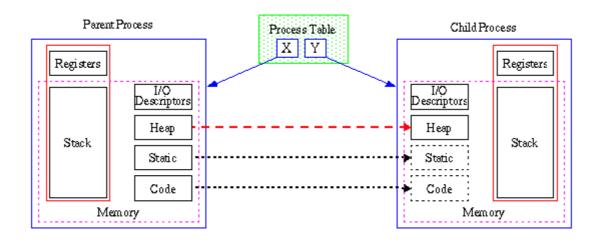
void ChildProcess()
{
    .....
}

void ParentProcess()
{
    .....
}
```

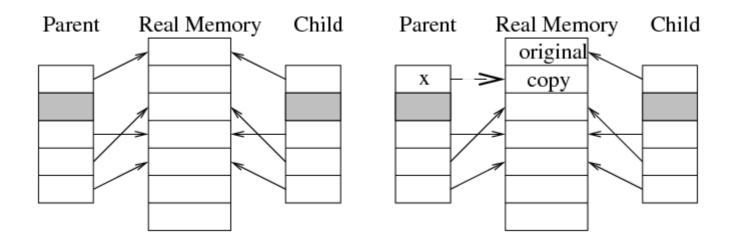


```
Parent
                                        Child
main()
          pid = 3456
                               main()
                                            pid = 0
  pid=fork();
                                  pid=fork();
                                 if (pid == 0)
 ▶ if (pid == 0)
                                     ChildProcess();
      ChildProcess();
   else
                                  else
     ParentProcess();
                                     ParentProcess();
void ChildProcess()
                               void ChildProcess()
void ParentProcess()
                               void ParentProcess()
```

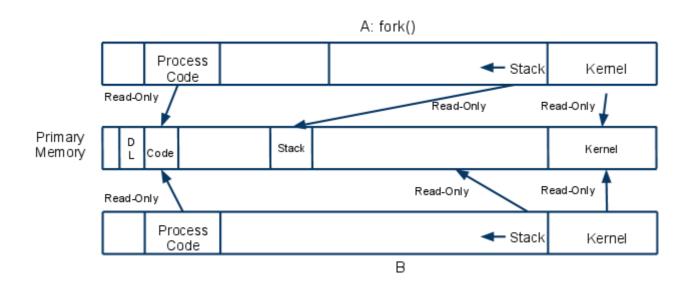
```
Parent
                                         Child
 main()
            pid = 3456
                                main()
                                            pid = 0
    pid=fork();
                                   pid=fork();
    if (pid == 0)
                                   if (pid == 0)
       ChildProcess();
                                      ChildProcess();
    else
                                   else
       ParentProcess();
                                      ParentProcess();
 void ChildProcess()
                               void ChildProcess()
void ParentProcess()
                                void ParentProcess()
```

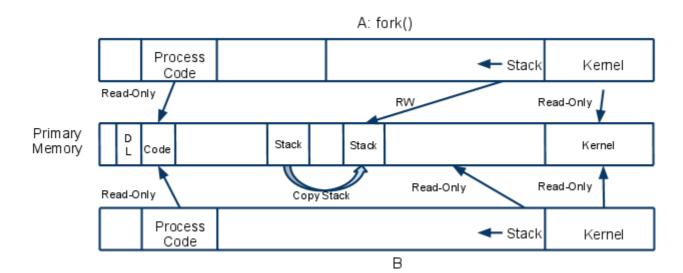


Copy-on-Write

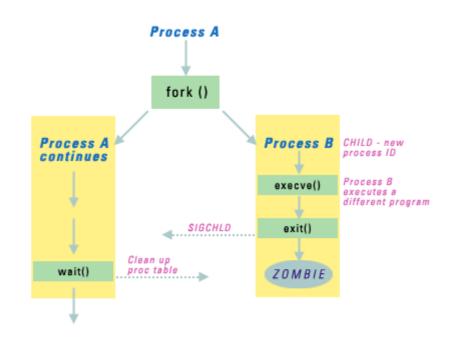


Copy-on-Write

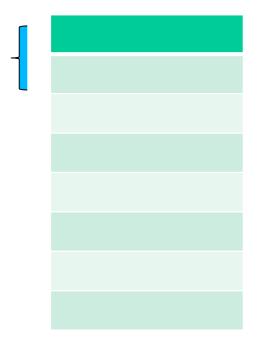


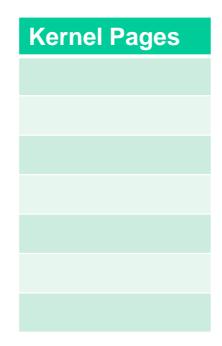


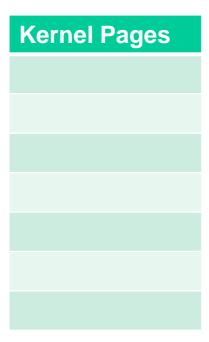
execve



Copy-on-Write







Tying it All Together: The Unix Shell

- Translates (CTRL-C) to the kill() system call with SIGKILL
- Translates (CTRL-Z) to the kill() system call with SIGSTOP
- Allows input-output redirections, pipes, and a lot of other stuff that we will see later