





## Master Thesis Proposal

# Federated Learning for Object Detection Using 3D Depth Images

## Kevin Patel

Supervised by

Prof. Dr.-Ing. Sebastian Houben

Prof. Dr. Robert Lange

Dr. Markus Hammes

Dr. Nikolaus Mayer

September 2024

## 1 Introduction

## 1.1 Topic of This Thesis

- Provide reasonably detailed description of what you intent to do in your R&D project.
- You may also discuss the challenges that you have to address.
- Reflect on the profile of the reader and PLEAAAASE, tell a story here and refrain from bombarding the readers with details which they may not be able to appreciate.
- TODO: Put a story or a very basic scenario here to make the reader understand the problem.

## 1.2 Relevance of This R&D Project

- Who will benefit from the results of this R&D project?
- What are the benefits? Quantify the benefits with concrete numbers.

## 2 Related Work

## 2.1 Survey of Related Work

- What have other people done to solve the problem?
- You should reference and briefly discuss at least the "top twelve" related works

### 2.2 Limitation and Deficits in the State of the Art

• List the deficits that you have discovered in the related work and explain them such that a person who is not deep into the technical details can still understand them. For each deficit, provide at least two references • You should reference and briefly discuss at least the "top twelve" related works

## 3 Problem Statement

- Which of the deficits are you going to solve?
- What is your intended approach?
- How will you compare you approach with existing approaches?

# 4 Project Plan

## 4.1 Work Packages

WP1 Literature Study

- WP1.1 Conduct a comprehensive literature review of state-of-the-art methods for object detection under adverse weather conditions using multiple modalities
- WP1.2 Analyze and compare various fusion strategies for exploiting the complementary characteristics of different sensors
- WP1.3 Search for suitable public datasets with adverse weather conditions and multimodal sensors data

#### WP2 Data Collection and Preparation

- WP2.1 Acquire the necessary datasets for multimodal object detection under adverse weather conditions, such as K-radar, DENSE, and aiMotive
- WP2.2 Develop tools for pre-processing and augmenting the datasets to enhance the performance of the models
- WP2.3 Perform statistical analysis to identify the main characteristics and challenges of the datasets, including data imbalance and class imbalance

#### WP3 Model Design and Implementation

- WP3.1 Design and implement an existing multimodal object detection architectures that integrates camera, LiDAR, and radar data
- WP3.2 Investigate various fusion strategies, such as concatenation, mixture of experts, attention-based fusion etc, to determine the most effective approach
- WP3.3 Explore deep learning architectures, such as CNNs, RNNs, and Transformers, to improve the performance of the multimodal model
- WP3.4 Optimize the model's hyperparameters and train the model on the acquired datasets

#### WP4 Model Evaluation and Validation

- WP4.1 Evaluate the performance of the developed multimodal object detection model on the acquired datasets under adverse weather conditions
- WP4.3 Compare the proposed model's results to existing state-of-the-art or baseline methods and analyze the strengths and weaknesses of each approach
- WP4.4 Identify the limitations of the proposed model and suggest possible future improvements

#### WP5 Project Report

- WP5.1 Write a detailed report that includes the research problem, objectives, methodology, results, and conclusion
- WP5.2 Present the research findings in a clear and concise manner, highlighting the contributions and limitations of the proposed multimodal object detection model
- WP5.3 Discuss possible future research directions based on the outcomes of the study

#### 4.2 Milestones

M1 Literature review completed and best practice identified

- M2 Data collection and preprocessing completed, including cleaning and augmentation
- M3 Initial model development and testing completed
- M4 Evaluation and optimization of the model completed
- M5 Final model development and testing completed, including comparison with existing state-of-the-art methods and analysis of strengths and weaknesses of each approach.
- M6 Project report completed

# 4.3 Project Schedule

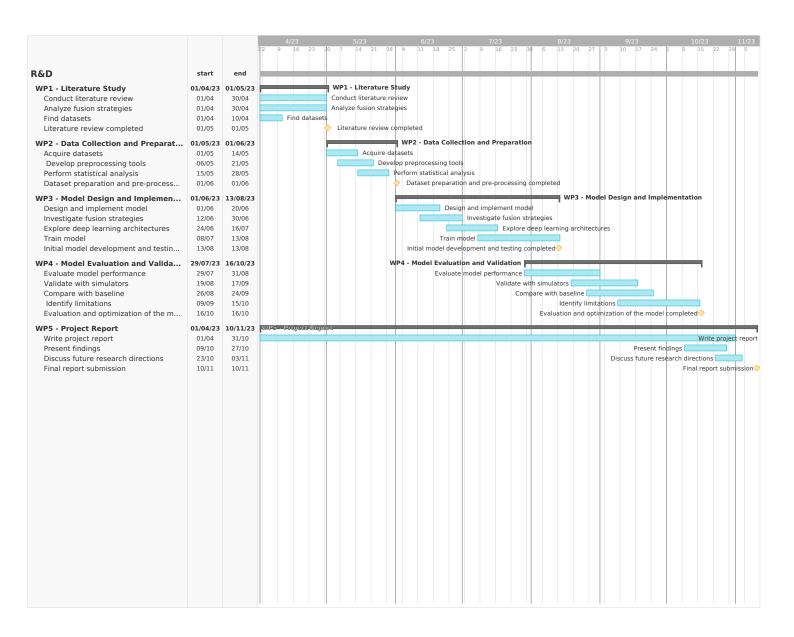


Figure 1: Gantt chart of the project schedule

#### 4.4 Deliverables

#### Minimum Viable

- Conduct a comprehensive literature review on state-of-the-art multimodal object detection methods and their fusion strategies
- Develop and test existing models for object detection
- Perform a comparative analysis of at least two methods on one dataset
- Produce a project report that summarizes the work done and the results obtained

#### Expected

- Compare the performance of more advanced methods with the baseline methods
- Complete the final development and testing of the model, including comparison with existing state-of-the-art methods and analysis of the strengths and weaknesses of each approach.
- Produce a more extensive project report that details the methodology, experimental setup, results, and analysis.

#### Desired

- Compare the developed models' performance on one or more additional datasets.
- Propose improvements to the baseline fusion methods.

# References

[1] Author Name. Book title. Lecture Notes in Autonomous System, 1001:900–921, 2003.

- [2] Paul Voigt and Axel Von dem Bussche. The eu general data protection regulation (gdpr). A Practical Guide, 1st Ed., Cham: Springer International Publishing, 10(3152676):10–5555, 2017.
- [3] Donald Shenaj, Giulia Rizzoli, and Pietro Zanuttigh. Federated learning in computer vision. *IEEE Access*, 2023.
- [4] Brendan McMahan, Eider Moore, Daniel Ramage, Seth Hampson, and Blaise Aguera y Arcas. Communication-efficient learning of deep networks from decentralized data. In *Artificial intelligence and statistics*, pages 1273–1282. PMLR, 2017.
- [5] Bingyan Liu, Nuoyan Lv, Yuanchun Guo, and Yawen Li. Recent advances on federated learning: A systematic survey. *Neurocomputing*, page 128019, 2024.
- [6] Deepthi Jallepalli, Navya Chennagiri Ravikumar, Poojitha Vurtur Badarinath, Shravya Uchil, and Mahima Agumbe Suresh. Federated learning for object detection in autonomous vehicles. In 2021 IEEE Seventh International Conference on Big Data Computing Service and Applications (BigDataService), pages 107–114. IEEE, 2021.
- [7] Vinit Hegiste, Tatjana Legler, and Martin Ruskowski. Federated ensemble yolov5–a better generalized object detection algorithm. In 2023 Eighth International Conference on Fog and Mobile Edge Computing (FMEC), pages 7–14. IEEE, 2023.
- [8] Hao Guan, Pew-Thian Yap, Andrea Bozoki, and Mingxia Liu. Federated learning for medical image analysis: A survey. *Pattern Recognition*, page 110424, 2024.
- [9] Keval Doshi and Yasin Yilmaz. Federated learning-based driver activity recognition for edge devices. In *Proceedings of the IEEE/CVF Conference on computer Vision and Pattern Recognition*, pages 3338–3346, 2022.
- [10] GeeksforGeeks. Collaborative learning federated learning, Mar 2024.