## Level set method for cell image segmentation

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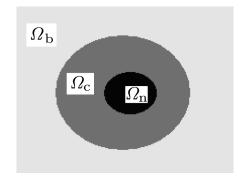


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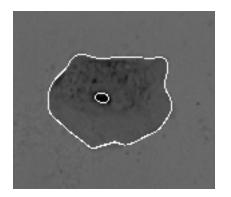
#### Table of contents

- Problem
- Solution
- 3 Implementation
- 4 References

### Cell structure



# Goal



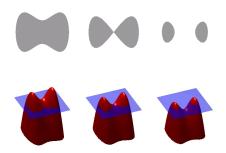
Processed imgage from [1]

### Paper

Solution by Ma Jing-feng et al. [1].

- One level set function
- Proper initialization
- Eliminating factor a priori knowledge
- Improved speed

#### Illustration



Source: Wikimedia Commons Author: Olegalexandrov

## **Evolution equation**

$$\begin{split} \frac{\partial \phi}{\partial t} &= -\delta_{\epsilon}(\phi) (\lambda_{1} e_{1} - \lambda_{2} e_{2}) \\ &+ \upsilon \delta_{\epsilon}(\phi) \operatorname{div} \left( \frac{\nabla \phi}{|\nabla \phi|} \right) \\ &+ \mu \left( \nabla^{2} \phi - \operatorname{div} \left( \frac{\nabla \phi}{|\nabla \phi|} \right) \right) \\ &- \eta \delta_{\epsilon}(\phi) \|I(x) - R_{c}\|^{2} \end{split}$$



## Data fitting

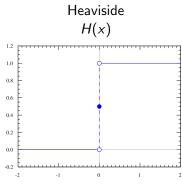
Driving the active countour towards object boundaries

$$e_{i}(x) = \int K_{\sigma}(y - x) |I(x) - f_{i}(y)|^{2} dy, \quad i = 1, 2.$$

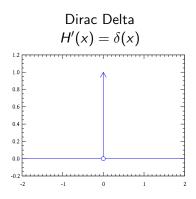
$$f_{i}(x) = \frac{K_{\sigma}(x) * [M_{i}^{\epsilon}(\phi(x))I(x)]}{K_{\sigma}(x) * [M_{i}^{\epsilon}(\phi(x))]}, \quad i = 1, 2.$$

$$M_{1} = H(\phi), \quad M_{2} = 1 - H(\phi)$$

### Heaviside Functions



Source: Wikimedia commons



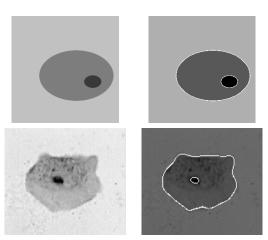
## Intensity distance

$$||I(x) - R_c|| = \begin{cases} I(x) - R_{max}, & \text{if } I(x) > R_{max}, \\ 0, & \text{if } R_{max} > I(x) > R_{min}, \\ R_{min} - I(x), & \text{if } R_{min} > I(x). \end{cases}$$

#### Libraries

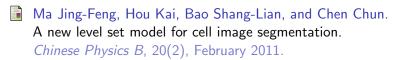
- NumPy http://numpy.scipy.org/
- SciPy http://www.scipy.org/
- Matplotlib http://matplotlib.sourceforge.net/
- Mahotas http://luispedro.org/software/mahotas
- PythODE [2]

### Results



Source of real cell image: [1]

#### References



Andrew Kroshko.

Integrating-factor-based 2-additive Runge-Kutta methods for advection-reaction-diffusion equations.

Master's thesis, University of Saskatchewan, 2011.