Comparing Measures For The Identification Of Partisan Gerrymandering

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Preliminaries

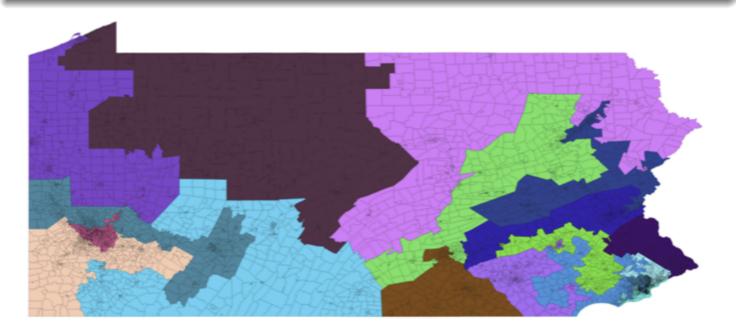
Definition

Every ten years, each state is divided into congressional districts, each of which elects a representative to the House of Representatives biannually. *Partisan gerrymandering* is when the districts are drawn in such a way to purposely favor one party.

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- Given a voting plan, quasi-randomly generate a neutral ensemble for the election.
- ② Use a mathematical metric to determine if the enacted districting is statistically different from the ensemble.

Overview

This project is a survey of the different methods currently in use to identify partisan gerrymandering, using novel methodology (testing methods on real, past elections).

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- Introduction to metrics and algorithms being tested
- Comparison of methods
- Oiscussion of implications

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Definition

Each district in a state is divided into a number of *precincts*. Given some precinct i, let V(i) be the district i is contained in.

Definition

We define a step of the *flip algorithm*:

1 Take a voting plan divided into precincts, and take two precincts A and B such that A and B are geographically adjacent and part of different districts k = V(A) and l = V(B), respectively.

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Example



Definition (DeFord-Duchin-Solomon, 2019)

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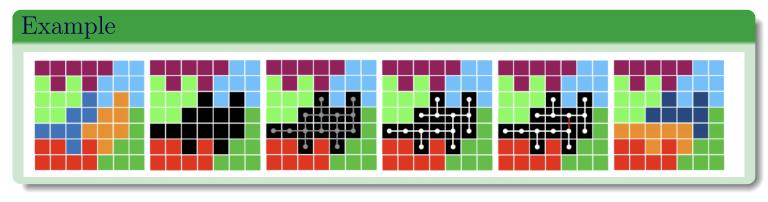
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- If possible, cut an edge of $\tau(A, B)$ that splits it into two trees C and D of equal size. These trees correspond to two new districts of roughly equal population, and thus a new voting plan.
- **5** If no such edge exists, find another spanning tree of G(A, B), or pick two different geographically adjacent districts until such an edge exists.

ReCom Algorithm Example



Efficiency Gap

Definition

Let $V = \{V_1, V_2, \dots, V_n\}$ be the set of districts in the enacted voting plan of a state. For each $1 \le i \le n$, let D_i be the number of Democratic votes in district V_i , and R_i be the number of Republican votes in district V_i .

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A wasted vote in a district is a vote for the losing party or a vote for the winning party above the 50% majority needed to win. In a district V_i for some $1 \le i \le n$, we let WD_i be the number of wasted Democratic votes in the district, and WR_i be the number of wasted Republican votes.

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Definition (Stephanopoulos-McGhee, 2015)

The efficiency gap of an election on districts $V = \{V_1, V_2, \dots, V_n\}$ is defined as

$$E_V = \frac{\sum_{i=1}^{n} (WD_i - WR_i)}{\sum_{i=1}^{n} (D_i + R_i)}.$$

Definition

Let λ be a fixed positive constant. A weighted wasted vote is the same as a wasted vote for the losing party, but is weighted as λ of a vote for the winning party. We let $WWD_i(\lambda)$ be the number of weighted wasted votes for the Democratic party in district V_i with weight λ , and $WWR_i(\lambda)$ be the number of weighted wasted votes for the Republican party in district V_i .

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Definition (Nagle, 2016)

We define the weighted efficiency gap of an election with weight λ on districts $V = \{V_1, V_2, \dots, V_n\}$ as

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Remark

Note that $WE_V(1) = E_V$ for all elections.

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We define the relative efficiency gap of an election with weight λ on districts $V = \{V_1, V_2, \dots, V_n\}$ as

$$RE_V(\lambda) = \frac{\sum_{i=1}^n WWD_i(\lambda)}{\sum_{i=1}^n D_i} - \frac{\sum_{i=1}^n WWR_i(\lambda)}{\sum_{i=1}^n R_i}.$$

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Remark

The commonly used variants in the literature are

$$WE_V(1) = E_V, WE_V(2), RE_V(1), RE_V(2)$$
. We will focus on these four.

Definition

The mean-median score of an election on districts $V = \{V_1, V_2, \dots, V_n\}$ is defined as the median of the list $\{\frac{D_1}{D_1 + R_1}, \frac{D_2}{D_2 + R_2}, \dots, \frac{D_n}{D_n + R_n}\}$ minus the mean of this list.

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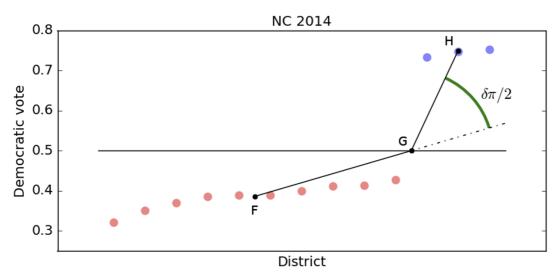
First, uniformly shift the votes in an election so each party gets 50% of the votes. The *partisan bias* is the difference between the Democratic seat share percentage in this hypothetically tied election and 50%.

Definition (Warrington, 2018)

Sort the V_1, V_2, \ldots, V_n in order of increasing D_i , and draw the points $(\frac{2i-1}{2n}, \frac{D_i}{(D_i+R_i)})$ for each $1 \leq i \leq n$. Let F be the center of mass of the points with y-coordinate at least 0.5, H be the center of mass of the points with y-coordinate less than 0.5, and G be the center of mass of all points. The declination is $\frac{2}{\pi}$ times the angle between \overline{FG} and \overline{GH} .

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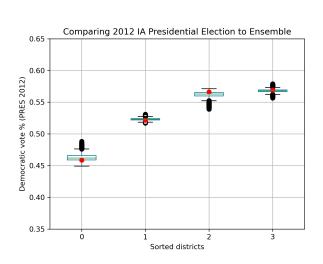
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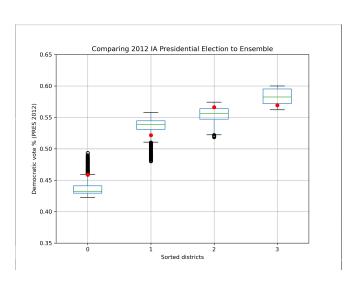
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The left figure shows the Flip algorithm, and the right shows the ReCom algorithm.

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	Flip Algorithm (1,000,000 steps)	ReCom Algorithm (10,000 steps)
6 seats	0	38
7 seats	4601	968
8 seats	221392	4731
9 seats	773998	3466
10 seats	9	744
11 seats	0	53
Mean	8.769	8.407
Standard Deviation	0.432	0.799

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- Track accuracy for different metrics by doing this for different elections.

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Metric	# False Results
Efficiency Gap	3
Mean-Median	4
Partisan Bias	5
Weighted Efficiency Gap (2)	3
Relative Efficiency Gap (1)	3
Relative Efficiency Gap (2)	3
Declination	2

Discussion

• The declination performs the best out of all the metrics, with the least false results; this agrees with the analysis in Warrington's 2019 paper.

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- 2 All variants of the efficiency gap performed the same on this dataset, but the relative efficiency gap is preferred, as in Tapp, 2019.
- 3 The mean-median score and partisan bias are the most unreliable and should not be used in real-world scenarios.

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- 2 If elections have two districts, the mean-median score fails.
- Mean-median score and partisan bias favor elections that are not very competitive.
- 4 Large numbers of independent votes create inaccurate results.

Future Work

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- 2 Take compactness scores into account.
- 3 Create a new metric to identify partisan gerrymandering, using the sources of false results as inspiration.

Acknowledgements

We would like to thank the following people for their support on this project:

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