

Block coordinate Descent:

$$\min_{\theta_j \in \mathbb{R}^p} \frac{1}{2} \|y - \sum_{j=1}^J Z_j^T \theta_j\|_2^2 + \lambda \sum_{j=1}^J \|\theta_j\|_2$$

$$= \min_{\theta_j \in \mathbb{R}^p} \frac{1}{2} \|y - \sum_{k \neq j} Z_k^T \theta_k - Z_j^T \theta_j\|_2^2 + \lambda \sum_{j=1}^J \|\theta_j\|_2$$

$$\text{def } f(\theta_1, \dots, \theta_J) = \frac{1}{2} \|y - \sum_{j=1}^J Z_j^T \theta_j\|_2^2 + \lambda \sum_{j=1}^J \|\theta_j\|_2$$

$$\text{def } r_j = y - \sum_{k \neq j} Z_k^T \theta_k$$

$$\min_{\theta_j \in \mathbb{R}^p} f(\theta_1, \dots, \theta_J) = \min_{\theta_j \in \mathbb{R}^p} \sum_{j=1}^J f(r_j, \theta_j) = \sum_{j=1}^J$$

\Rightarrow therefore f is separable

\Rightarrow we can apply Block Coordinate Descent

decomposable function:

$$\min_{\theta_j \in \mathbb{R}^{p_j}} \frac{1}{2} \|\Gamma_j - Z_j^T \theta_j\|_2^2 + \lambda \|\theta_j\|_2$$

$$\Gamma_j := y - \sum_{k \neq j} Z_k^T \theta_k$$

convex and differentiable function $g = \frac{1}{2} \|\Gamma_j - Z_j^T \theta_j\|_2^2$

non-differentiable : $h = \lambda \|\theta_j\|_2$

c. proximal Gradient Descent - Gradient step:

$$\nabla g(\theta_{j,k}) = -Z_j^T (\Gamma_j - Z_j^T \theta_{j,k})$$

$$\theta_{j,k} = \theta_{j,k} - t_k \nabla g(\theta_{j,k}) = \theta_{j,k} - t_k (-Z_j^T (\Gamma_j - Z_j^T \theta_{j,k}))$$

t_k : step size

d. proximal function we need to solve:

$$\text{prox}(\theta_{j,k}) = \arg \min_{z} \frac{1}{2t_k} \|\theta_{j,k} - z\|_2^2 + \lambda \|z\|_2$$

$$\text{prox}_\lambda(\theta_{j,k}) = \arg \min_z \frac{1}{2} \|\theta_{j,k} - z\|_2^2 + \lambda t_k$$

problem 2a

$$\textcircled{1} \min_{\beta \in \mathbb{R}^p} \sum_{b=1}^3 \frac{1}{2} \|y_b - X_b \beta_b\|_2^2 + \lambda \|\beta\|_1$$

$$\textcircled{2} \min_{\beta \in \mathbb{R}^{p_b=1}} \sum_{b=1}^3 \left(\frac{1}{2} \beta_b^T X_b^T X_b \beta_b - y_b^T X_b \beta_b \right) + \lambda \|\beta\|_1 + K$$

$$\textcircled{1} \Leftrightarrow \textcircled{2} \Rightarrow \frac{1}{2} \beta_b^T X_b^T X_b \beta_b - y_b^T X_b \beta_b + K$$

$$= \frac{1}{2} \|y_b - X_b \beta_b\|_2^2$$

$$\Leftrightarrow X_b \beta_b \left(\frac{1}{2} \beta_b^T X_b^T - y_b^T \right) + K$$

$$= \frac{1}{2} \|y_b - X_b \beta_b\|_2^2$$

problem 2b:

$$\alpha_p(\beta_b, \theta, u_b) = \sum_{b=1}^3 \left(\frac{1}{2} \beta_b^T X_b^T X_b \beta_b - y_b^T X_b \beta_b \right)$$

$$+ \lambda \|\theta\|_1 + u^T (\beta_b - \theta) + \frac{\rho}{2} \|\beta_b - \theta\|_2^2$$

$$\mathcal{L}_p(\beta_b, \theta, u_b) = \sum_{b=1}^3 \left(\frac{1}{2} \beta_b^T X_b^T X_b \beta_b - y_b^T X_b \beta_b \right) + \lambda \|\theta\|_1 + \frac{\rho}{2} \|\beta_b - \theta + u_b\|_2^2$$

→ For β_b , $b=1, 2, 3$. Since we have quadratic objective
shows.

$$\beta_b^{t+1} = (X_b^T X_b + \rho I)^{-1} (X_b^T y_b + \rho(\theta^t - u_b^t))$$

$$\frac{\partial \mathcal{L}_p(\beta_b, \theta, u_b)}{\partial \beta_b} = \frac{1}{2} (X_b^T X_b + (X_b^T X_b)^T) \beta_b - y_b^T X_b + \rho(\beta_b - \theta + u_b)$$

$$\frac{\partial \mathcal{L}_p(\beta_b, \theta, u_b)}{\partial \beta_b} = 0 \Leftrightarrow$$

$$\frac{1}{2} (X_b^T X_b + (X_b^T X_b)^T) \beta_b - y_b^T X_b + \rho \beta_b - \rho(\theta - u_b) = 0$$

$$\Leftrightarrow \beta_b (X_b^T X_b + \rho I) = y_b^T X_b + \rho(\theta - u_b)$$

$$\Leftrightarrow \beta_b = (X_b^T X_b + \rho I)^{-1} (y_b^T X_b + \rho(\theta - u_b))$$