$$w_{i}(t) = \frac{1}{2} P(i)$$

$$w_2(t) = \underbrace{z}_{t+1} P(t)$$

$$w_i(t) = \sum_{i=1}^{k} \frac{iP(i)}{w_i(t)}$$

$$M_{i}(t) = \frac{1}{2} \frac{iP(i)}{Q_{i}(t)}, \quad M_{2}(t) = \frac{3}{2} \frac{iP(i)}{Q_{2}(t)}$$

$$W_{T} = \frac{1}{4\pi i} \frac{(Ri)}{1}$$

$$Q_{2}^{2}(t) = \frac{1}{2} \left[i - M_{2}(t) \right]^{2} \frac{N(i)}{\omega_{2}(t)}$$

$$\mathcal{O}_{T}^{2} = \frac{3}{2} \left[i - \mu_{1}(t) \right]^{2} \frac{P(i)}{\omega_{1}(t) + \omega_{2}(t)}$$

$$d_{b}^{2} = \frac{1}{2} \frac{P(i)}{w_{2}(t)} \left[\frac{\omega_{2}(i - u_{1}tt)^{2} - (i - u_{1}tt)^{2}}{w_{2}(t)} \right] + \frac{1}{2} \frac{P(i)}{w_{2}(t)} \left[\frac{\omega_{2}(i - u_{1}tt)^{2}}{w_{2}(t)} \right] - \frac{1}{2} \frac{P(i)}{w_{2}(t)} \left[\frac{\omega_{2}(i - u_{1}tt)^{2}}{w_{2}(t)} \right] + \frac{1}{2} \frac{P(i)}{w_{2}(t)} \left[\frac{\omega_{2}(i - u_{1}t)^{2}}{w_{2}(t)} \right] + \frac{1}{2} \frac{P(i)}{w_{2}(t)} \left[\frac{\omega_{2}(i - u_{1}t)^{2}}{w_{2$$