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AN ULTRASONIC NAVIGATION SYSTEM FOR BLIND PEOPL

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ABSTRACT

Ithis paper is to investigate the development of on aid for blind and visually impaired People. It is a microcontroller with synthetic speech is aid is portable and gives information to the urban walking routes to point out what o make. On the other hand, and in order to igation difficulties of the blind, an obstacle ystem using ultrasounds and vibrators is added ice. The proposed system detects the nearest a streoscopic sonar system and sends back le feedback to inform the blind about its n.

words-Handicapped aids, Navigation, Sonar

1. INTRODUCTION

opment and application of technology for and mobility has a long history covering the riod. Although some early endeavors systems that might replace the cane or dog length of the cane, typically one pace ahead of t difficulties detecting overhanging obstacles, and difficulties storing in public places [10].

In this paper, the suggested navigation syst involves a microcontroller with speech output. I contained portable electronic unit. It can supply person with assistance about walking routes by spoken words to point out what decisions to ma

On the other hand, and in order to ove imperfections of existing electronic travel proposed method of measuring distance travel system, is to use the acceleration of a moving b in this case is the blind person. An acce followed by two integrators is used to measure travelled by the blind. This technique is coninertial navigation systems [11] and suffers problems caused by the double integration and the accelerometer which are overcome by the [12]. When this footswitch is closed, the accelerated the velocity are known to be equal to zero and used to apply a correction.

In addition, to help blind or visually impair travellers to navigate safely and quickly among and other hazards faced by blind pedestrians, ar

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