# Random Fourier Features for Kernel Ridge Regression

Approximation Bounds and Statistical Guarantees

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# Table of Contents

Motivation

2 Random Fourier Features



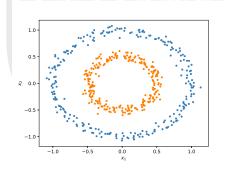


May 3, 2023

# Linear Classification with Non-linear Input

Consider a binary classification problem with non-linear (e.g. polynomial) samples. This is not separable with linear function.

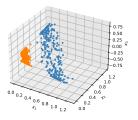
samples. This is not separable with 
$$(\text{e.g. }X = \begin{bmatrix} x_{1,1} \ x_{1,2} \\ x_{2,1} \ x_{2,2} \\ \vdots \\ x_{N,1} \ x_{N,2} \end{bmatrix} \in \mathbb{R}^{N \times 2}.)$$





# Lifting

One idea is to **LIFT** the samples into a higher dimensional space in which the samples are linearly separable.



The Lifting function in this case is  $\phi(X) = \begin{bmatrix} x_{1,1}^2 & x_{1,2}^2 & \sqrt{2}x_{1,1}x_{1,2} \\ x_{2,1}^2 & x_{2,2}^2 & \sqrt{2}x_{2,1}x_{2,2} \\ & \dots \\ x_{N,1}^2 & x_{N,2}^2 & \sqrt{2}x_{N,1}x_{N,2} \end{bmatrix}.$ 



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# Curse of Dimensionality

Consider solving the above problem with *support vector machine* (SVM).

$$\mathcal{L}(\mathbf{w}, \alpha) = \sum_{n=1}^{N} \alpha_n - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} \alpha_n \alpha_m y_n y_m (x_n^{\mathsf{T}} x_m).$$

The  ${\bf w}$  is the linear decision boundary and  $\alpha$  is a vector of Lagrange multipliers.





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We need to use lifting function  $\phi(X)$  to make the samples linearly separable. Specifically, we replace  $(x_n^{\mathsf{T}}x_m)$  with  $(\phi(x_n)^{\mathsf{T}}\phi(x_m))$ .

$$\begin{split} \phi(x_n)^{\mathsf{T}}\phi(x_m) &= \left[ x_{n,1}^2 \ x_{n,2}^2 \ \sqrt{2}x_{n,1}x_{n,2} \right] \left[ x_{m,1}^2 \ x_{m,2}^2 \ \sqrt{2}x_{m,1}x_{m,2} \right]^{\mathsf{T}} \\ &= x_{n,1}^2 x_{m,1}^2 + x_{n,2}^2 x_{m,2}^2 + 2x_{n,1}x_{n,2}x_{m,1}x_{m,2} \end{split}$$



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Calculate the inner product in the  $\mathbb{R}^3$  across all N pairs of samples is acceptable. However, the lifting function  $\phi(X)$  is usually very high dimensional. イロト イ団ト イミト イミト



### Kernel Trick

Consider the following derivation,

$$\begin{split} (x_n^\intercal x_m)^2 &= ([x_{n,1} \ x_{n,2}][x_{m,1} \ x_{m,2}]^\intercal)^2 \\ &= (x_{n,1} x_{m,1} + x_{n,2} x_{m,2})^2 \\ &= x_{n,1}^2 x_{m,1}^2 + x_{n,2}^2 x_{m,2}^2 + 2 x_{n,1} x_{n,2} x_{m,1} x_{m,2} \\ &= \phi(x_n)^\intercal \phi(x_m) \end{split}$$





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$$= (x_{n,1} x_{m,1} + x_{n,2} x_{m,2})^2$$

$$= x_{n,1}^2 x_{m,1}^2 + x_{n,2}^2 x_{m,2}^2 + 2x_{n,1} x_{n,2} x_{m,1} x_{m,2}$$

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Instead of computing inner product in the high dimensional space, we compute the inner product in the original space.





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Instead of computing inner product in the high dimensional space, we compute the inner product in the original space.

The function

$$K(x_n, x_m) = (x_n^{\mathsf{T}} x_m)^2 = \phi(x_n)^{\mathsf{T}} \phi(x_m)$$

is called a kernel function.



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# There must be disadvantages...

Given training data  $(x_1, y_1), (x_2, y_2), \ldots, (x_N, y_N) \in \mathcal{X} \times \mathcal{Y}$ , where  $\mathcal{X} \subseteq \mathbb{R}^d$  and  $\mathcal{Y} \subseteq \mathbb{R}$ . Consider *Kernel Ridge Regression* (KRR), with  $\phi(\mathcal{X}) \subseteq \mathbb{R}^k$ , where  $k \to \infty$ 

$$\mathcal{L}(\mathbf{w}, \lambda) = \underset{\mathbf{w}}{\operatorname{argmin}} \sum_{n}^{N} (y_n - \mathbf{w}^{\mathsf{T}} \phi(\mathbf{x}_n))^2 + \lambda \mathbf{w}^{\mathsf{T}} \mathbf{w}.$$

Solving it with Lagrange multipliers  $\alpha$ , which is the solution of

$$\mathbf{L} \wedge \mathbf{0} (\mathbf{K} + \lambda \mathbf{I}_k) \alpha = \mathbf{y},$$

requires  $\Theta(k^3)$  time and  $\Theta(k^2)$  memory. Here  $\mathbf{K} \in \mathbb{R}^{k \times k}$  is the kernel matrix or Gram matrix defined by  $\mathbf{K}_{nm} \equiv K(\mathbf{x}_n, \mathbf{x}_m)$ .



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**Intuition:** Can we find a kernel function which lifts  $\mathcal{X}$  to  $\mathbb{R}^s$ , where  $d < s \ll k$ , while not sacrifices model performance?



Kai Rutgers Random Fourier Features May 3, 2023

# Some Prerequisites

## Shift Invariant Kernel (Radial Basis Function (RBF))

A kernel function  $K(\mathbf{x_n}, \mathbf{x_m})$  is called **shift invariant** if it can be written as  $K(\mathbf{x_n}, \mathbf{x_m}) = q(\mathbf{x_n} - \mathbf{x_m})$  for some function  $q(\cdot)$ (e.g.  $K_{Gaussian}(\mathbf{x_n}, \mathbf{x_m}) = \exp(-\gamma ||\mathbf{x_n} - \mathbf{x_m}||_2^2)$ ).

#### Mercer's Theorem

A continuous function  $K(\mathbf{x_n}, \mathbf{x_m})$  is a valid kernel function if and only if the kernel matrix K is positive semi-definite.

#### Bochner's Theorem

A continuous function  $g(\cdot)$  is **positive semi-definite** if and only if it is the Fourier transform of a non-negative measure.





#### Conclusion

A continuous **shift invariant** kernel  $K(\mathbf{x_n}, \mathbf{x_m})$ , which is **positive semi-definite** (Mercer's Theorem), is the Fourier transform of a non-negative measure  $p(\cdot)$ .

$$\phi(\mathbf{x_n})^{\mathsf{T}}\phi(\mathbf{x_m}) = K(\mathbf{x_n}, \mathbf{x_m}) = K(\mathbf{x_n} - \mathbf{x_m})$$
(1)

$$= \int_{\mathbb{R}^d} p(\omega) \exp(i\omega^{\mathsf{T}} (\mathbf{x_n} - \mathbf{x_m})) d\omega$$
 (2)

$$= \mathbb{E}_{\omega}[\xi_{\omega}(\mathbf{x_n})^* \xi_{\omega}(\mathbf{x_m})] \tag{3}$$

Here  $\xi_{\omega}(\mathbf{x}) = \exp(i\omega^{\mathsf{T}}\mathbf{x}) = \begin{bmatrix} \cos(\omega^{\mathsf{T}}\mathbf{x}) \\ \sin(\omega^{\mathsf{T}}\mathbf{x}) \end{bmatrix}$  and hence  $\xi_{\omega}(\mathbf{x_n})^*\xi_{\omega}(\mathbf{x_m})$  is an unbiased estimator of  $K(\mathbf{x_n}, \mathbf{x_m})$  when  $\omega$  is drawn from  $p(\cdot)$ .



Since both the  $p(\cdot)$  and  $K(\Delta)$  are real-valued, we can replace  $\xi(\mathbf{x})$  with  $z_{\omega}(\mathbf{x}) = [\sqrt{2}\cos(\omega^{\mathsf{T}}\mathbf{x} + b)]$  where  $\omega$  is drawn from  $p(\omega)$  and b is uniformly drawn from  $[0, 2\pi]$ . Then eq. (3) becomes  $\mathbb{E}_{\omega}[z(\mathbf{x_n})^{\mathsf{T}}z(\mathbf{x_m})]$ 



10 / 14



Since both the  $p(\cdot)$  and  $K(\triangle)$  are real-valued, we can replace  $\xi(\mathbf{x})$  with  $z_{\omega}(\mathbf{x}) = [\sqrt{2}\cos(\omega^{\intercal}\mathbf{x} + b)]$  where  $\omega$  is drawn from  $p(\omega)$  and b is uniformly drawn from  $[0,2\pi]$ . Then eq. (3) becomes  $\mathbb{E}_{\omega}[z(\mathbf{x_n})^{\mathsf{T}}z(\mathbf{x_m})]$ 

**Note:**  $z(\mathbf{x_n})^{\mathsf{T}} z(\mathbf{x_m})$  is an unbiased estimator of  $\phi(\mathbf{x_n})^{\mathsf{T}} \phi(\mathbf{x_m})$ . The  $z(\mathbf{x})$  is not a lifting function.





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**Note:**  $z(\mathbf{x_n})^{\mathsf{T}} z(\mathbf{x_m})$  is an unbiased estimator of  $\phi(\mathbf{x_n})^{\mathsf{T}} \phi(\mathbf{x_m})$ . The  $z(\mathbf{x})$  is not a lifting function.

Note: To further reduce the variance of the estimator, we can randomly draw s samples of  $\omega$  and normalize each corresponding  $z(\mathbf{x})$ by  $\sqrt{s}$ . Then the inner product  $z(\mathbf{x_n})^\intercal z(\mathbf{x_m}) = \frac{1}{s} \sum_{j=1}^s z_{\omega j}(\mathbf{x_n})^\intercal z_{\omega j}(\mathbf{x_m})$ 





## Algorithm

#### **Algorithm 1** Random Fourier Features

**Require:** A shift invariant kernel  $K(\mathbf{x_n}, \mathbf{x_m}) = K(\mathbf{x_n} - \mathbf{x_m})$ .

**Ensure:** A randomized feature map  $z(\mathbf{x}): \mathbb{R}^d \to \mathbb{R}^s$  so that

$$z(\mathbf{x_n})^{\mathsf{T}} z(\mathbf{x_m}) \approx K(\mathbf{x_n}, \mathbf{x_m}).$$

Compute the Fourier transform  $p(\cdot)$  of the kernel  $K: p(\omega) = \frac{1}{2\pi} \int \exp(-i\omega^{\mathsf{T}} \triangle) K(\triangle) \, \mathrm{d} \triangle$ 

Draw s i.i.d. samples  $\omega_1, \omega_2, \dots, \omega_s \in \mathbb{R}^d$  from  $p(\cdot)$  and s i.i.d. samples  $b_1, b_2, \dots, b_s \in [0, 2\pi]$ .

Let 
$$z(\mathbf{x}) \equiv \sqrt{\frac{2}{s}} [\cos(\omega_1^{\mathsf{T}} \mathbf{x} + b_1) \cos(\omega_2^{\mathsf{T}} \mathbf{x} + b_2) \dots \cos(\omega_s^{\mathsf{T}} \mathbf{x} + b_s)]^{\mathsf{T}}$$



## Convergence

# Bound for a fixed pair of points $x_n$ and $x_m$

Given  $z_{\omega}$  is bounded random variable between  $[-\sqrt{2},\sqrt{2}],$  with Hoeffding's Inequality, we have

$$\mathbb{P}(|z(\mathbf{x_n})^{\mathsf{T}}z(\mathbf{x_m}) - K(\mathbf{x_n}, \mathbf{x_m})| \ge \epsilon) \le 2\exp\left(-\frac{s\epsilon^2}{4}\right).$$

Random Fourier Features



12 / 14

## Convergence

## Bound for all pair of points $x_n$ and $x_m$

Let  $\mathcal M$  be a compact sunset of  $\mathbb R^d$  with diameter  $\operatorname{diam}(\mathcal M)$ . Then, for the mapping z defined in Algorithm 1, we have

$$\mathbb{P}\left(\sup_{x,y\in\mathcal{M}}|z(\mathbf{x_n})^{\mathsf{T}}z(\mathbf{x_m}) - K(\mathbf{x_n},\mathbf{x_m})| \ge \epsilon\right)$$

$$\leq 2^8 \bigg(\frac{\sigma_{p(\cdot)}\mathsf{diam}(\mathcal{M})}{\epsilon}\bigg)^2 \exp \bigg(-\frac{s\epsilon^2}{4(d+2)}\bigg).$$



## Two-column slide

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$$E = mc^2$$

First item  $\ell$ Second item This text will be in the second column and on a second thought this is a nice looking layout in some cases.

