

# Kathryn Wantlin

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## Education

### PRINCETON UNIVERSITY

Ph.D., Computer Science

M.S.E., Computer Science

**Relevant Courses:** Machine Learning & Pattern Recognition, Probabilistic Modeling, Robotic Planning, Dynamics and Control of Multi-Agent Systems, Probabilistic Topics in RL, Information Theory, Computer Vision

**Teaching Experience:** Introduction to Machine Learning, Algorithms/Data Structures, Introduction to Computer Science

### HARVARD UNIVERSITY

A.B., Computer Science, Economics Secondary, Chinese Language Citation

May 2021

**Relevant Courses:** Machine Learning, Multi-Robot Systems, Autonomous Robot Systems, Embedded Systems, AI for

Social Impact, Digital Fabrication, Data Visualization, Research Topics in HCI, Abstraction and Design in Computation

**Teaching Experience:** Multi-Robot Systems - Control, Communication, and Security, Mathematics for Computation, Statistics, and Data Science

## Skills

*Programming:* Python, Java, Javascript, ROS, C++, MATLAB, MuJoCo, Sklearn

*Machine Learning Frameworks:* PyTorch, JAX

## Publications

Barnett, S., **Wantlin, K.**, Adams, R.P.

Measuring Cooperation with Counterfactual Planning

*Conference on Game Theory and AI for Security (GameSec) 2025*

Leonard, N.E., Cox, J., Trueman, D., Santos, M., **Wantlin, K.**, Han, I.X., Witzman, S., James, T.

Rhythm Bots

*Neural Information Processing Systems (NeurIPS) 2024, Creative AI Track*

*International Conference on Robotics and Automation (ICRA) 2022, Workshop on Robotics and Art*

## Preprints

**Wantlin, K.**, Zheng, C., Eysenbach, B.E.

Consistent Zero-Shot Imitation with Contrastive Goal Inference

Ghugare, R., Ji, C., **Wantlin, K.**, Schofield, J., Eysenbach, B.E.

BuilderBench — A Benchmark for Generalist Agents

**Wantlin, K.**, Wu, C., Huang, S.C., Banerjee, O., Dadabhoy, F., Mehta, V.V., Han, R.W., Cao, F., Narayan, R.R., Colak, E., Adamson, A. S., Heacock, L., Tison, G.H., Tamkin, A., Rajpurkar, P.

BenchMD: A Benchmark for Universal Learning on Medical Images and Sensors

## Research Experience

### MIT Center for Brains, Minds and Machines

*Summer School Program*

Massachusetts Institute Of Technology

Aug. 2025

- Engineered planning capabilities for token generation in autoregressive LLMs. Compared search capabilities of autoregressive vs. diffusion model architectures and measured alignment. Advised by Dr. Brian Cheung

### Google DeepMind Princeton / Princeton University

*Summer Research w/ Prof. Elad Hazan*

Princeton University

Jun. 2025 – Present

- Apply spectral filtering methods to build world models for long-horizon planning and control

### Princeton RL Lab

*Graduate Research w/ Prof. Ben Eysenbach*

Princeton University

Jan. 2024 – Present

- Developed a theoretically consistent goal-conditioned imitation learning algorithm with temporal contrastive learning and self-directed goal exploration

**Laboratory for Intelligent Probabilistic Systems***Graduate Research w/ Prof. Ryan Adams*

Princeton University

Jun. 2022 – Present

- Utilized spatial point processes and continuous-time MCMC to perform inverse design of emergent shape formation in morphogenetic systems
- Developing causal representation learning methods for solving robotic assembly problems

**Harvard Medical AI Lab***Visiting Graduate Research Fellow w/ Prof. Pranav Rajpurkar*

Harvard Medical School

Nov. 2021 – Jan. 2024

- Combined deep learning Viewmaker networks with hand-generated data augmentations to improve performance for self-supervised learning in VAE models for ECG classification
- First-author Medical AI Benchmark using self-supervised algorithms to investigate generalization of multi-modality models under clinically-relevant distribution shifts (<https://github.com/rajpurkarlab/BenchMD>)

**Leonard Robotics Lab***Graduate Researcher w/ Prof. Naomi Leonard*

Princeton University

Sept. 2021 – May 2023

- Utilized Yolov3 and Deep SORT models to detect/rack humans and define motion of interactive robotic system via nonlinear opinion dynamics models (NeurIPS 2024 Creative AI Track, ICRA 2022 Workshop on Robotics and Art)

**Harvard Economics and Computer Science Research Group***Undergraduate Thesis w/ Prof. David Parkes*

Harvard University

Sept. 2020 – May 2021

- Designed auction-based information exchange policies for robots engaged in cooperative mapping tasks, demonstrating increased robustness to routing failure

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**Professional Experience****MIT Lincoln Laboratory - Advanced Systems and Capabilities Group***Summer Research Intern*

Lexington, MA

Jun. 2021 – Aug. 2021

- Optimized GPS-free autonomous flight algorithms using keypoint identification and matching
- Reduced system memory usage 4x while maintaining navigation performance by experimentally confirming optimal data redundancy in keypoint matching scheme
- Quantified receptive field of utilized neural networks and visualized attention network weights to interpret model performance

**Hewlett Packard Enterprise***AI Engineer Intern*

Seattle, WA

May 2020 – Aug. 2020

- Modularized AutoML tool's data manager to in-memory backend, improving data processing speeds by 60%
- Wrote computer vision data pre-processing node for prebuilt AutoML workflow in Jupyter Notebooks; notebooks served as user tutorials/documentation upon tool's release

**Harvard University Derek Bok Center***Learning Lab Undergraduate Fellow*

Cambridge, MA

Oct. 2019 – Aug. 2020

- Designed Slack analytics dashboard with D3 to help staff gauge project engagement across the Bok Center
- Worked with team of Fellows to create comprehensive tutorials on digital art technologies for classrooms, including Adobe Illustrator/After Effects; reproduced a section of a professional Vox video to demonstrate the creative process

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**Leadership/Volunteer Experience****International Conference on Learning Representations (2025-2026) – Reviewer****Machine Learning for Health Symposium (Collocated with NeurIPS 2022) – Reviewer****Princeton ReMatch Mentoring Program (2021-2022) – Computer Science Mentor**

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**Honors and Awards****Princeton Computer Science Department Tapia Scholarship (2025)****Princeton School of Engineering and Applied Science (SEAS) Travel Grant (2024)****Princeton University Gordon Y.S. Wu Fellowship in Engineering (2023)****Princeton University Teaching Assistantship, Full Graduate Funding (2021-2023)**