

Kwanyoung Park

✉ kwanyoung_park@berkeley.edu 🏠 <https://kwanyoungpark.github.io>
⌚ <https://github.com/kwanyoungpark>

EDUCATION

University of California, Berkeley Ph.D. in Electrical Engineering and Computer Science Berkeley Artificial Intelligence Research (BAIR) lab Advisor: Sergey Levine and Pieter Abbeel	Aug '25 - Present
Seoul National University B.S. in Computer Science & Engineering B.S. in Mathematical Sciences (Minor)	Mar '19 - Aug '25 <i>Summa Cum Laude</i>
* Leave of absence for military service: July 2021 - Jan 2023	
Stanford University Visiting student	Jun '23 - Aug '23
Gyeonggi Science High School High school for gifted students in science and mathematics	Mar '16 - Feb '19

RESEARCH INTERESTS

- Offline reinforcement learning
- Model-based reinforcement learning
- Unsupervised reinforcement learning
- Robot learning

PUBLICATIONS (* denotes equal contribution.)

1. **Kwanyoung Park**, Seohong Park, Youngwoon Lee, Sergey Levine
Scalable Offline Model-Based RL with Action Chunks
Preprint, 2025
2. **Kwanyoung Park**, Youngwoon Lee
Model-based Offline Reinforcement Learning with Lower Expectile Q-Learning
International Conference on Learning Representations (**ICLR**), **2025**
3. Junik Bae, **Kwanyoung Park**, Youngwoon Lee
TLDR: Unsupervised Goal-Conditioned RL via Temporal Distance-Aware Representations
Conference on Robot Learning (**CoRL**), **2024**
4. **Kwanyoung Park***, Hyunseok Oh*, Youngki Lee
VECA: A New Benchmark and Toolkit for General Cognitive Development
AAAI Conference on Artificial Intelligence (**AAAI**), **2022**
(Oral presentation, Acceptance Rate: 384/9,251 = 4.15%)
5. Junseok Park, **Kwanyoung Park**, Hyunseok Oh, Ganghun Lee, Minsu Lee, Youngki Lee, Byoung-Tak Zhang
Toddler-Guidance Learning: Impacts of Critical Period on Multimodal AI Agents
ACM International Conference on Multimodal Interaction (**ICMI**), **2021**
(Oral presentation)

6. **Kwanyoung Park**, Junseok Park, Hyunseok Oh, Byoung-Tak Zhang, Youngki Lee
Learning Task-agnostic Representation via Toddler-inspired Learning
NeurIPS 2020 Workshop on BabyMind, 2020

EXPERIENCE

Berkeley Artificial Intelligence Research (BAIR)	Aug '25 - Present
- <i>PhD Student</i> (Advisor: Sergey Levine , Pieter Abbeel)	
<ul style="list-style-type: none">• Researched on scaling model-based offline RL method to long-horizon tasks, by enabling extremely long (100 steps) model-generated rollouts with action chunking [1].• Researching on meta-RL approach for model-based RL, where the agent can find their own planning strategy through interaction.	
Yonsei RL Lab	Jan '24 - Aug '25
- <i>Undergraduate Research Intern</i> (Advisor: Youngwoon Lee)	
<ul style="list-style-type: none">• Researched on a model-based offline RL method that enables reliable long simulated rollouts (15 steps) by applying lower-expectile regression to λ-returns, improving long-term decision-making [2].• Participated in research on a goal-conditioned unsupervised RL algorithm that utilizes temporal distances [3].	
SNU Human-Centered Computer Systems Lab	Feb '23 - Dec '23
- <i>Undergraduate Research Intern</i> (Advisor: Youngki Lee)	
<ul style="list-style-type: none">• Researched on a NeRF model architecture (with Gaussian Splatting) that can reduce network consumption for on-device applications.	
Ministry of National Defense	Jul '21 - Jan '23
- <i>Research Engineer (Military Service)</i>	
<ul style="list-style-type: none">• Worked as main developer of an NLP project• Trained a BERT-based model for Korean language and fine-tuned it for sentence generation.	
SNU Human-Centered Computer Systems Lab	Jun '19 - Jun '21
- <i>Undergraduate Research Intern</i> (Advisor: Youngki Lee)	
<ul style="list-style-type: none">• Developed VECA, which is the first benchmark to assess the overall cognitive development of an AI agent, including a toolkit to generate diverse and distinct cognitive tasks [4].• Researched the impact of guidance (e.g. offline trajectory, dense rewards) during reinforcement learning and its performance on transfer learning [5].• Developed a representation learning algorithm based on the agents interaction using VECA [6].	

SCHOLARSHIPS

KFAS Overseas PhD Scholarship	Sep '25 - Present
<ul style="list-style-type: none">• Korea Foundation for Advanced Studies (KFAS)• Stipend support during the doctoral studies.	
Berkeley Fellowship	Sep '25 - Present
<ul style="list-style-type: none">• UC Berkeley• Stipend support for the first semester of doctoral studies.	
Presidential Science Scholarship	Mar '19 - Aug' 25
<ul style="list-style-type: none">• Korea Student Aid Foundation (KOSAF)• Full tuition, living expenses support for undergraduate studies.	

- Gyeonggi-do
- Full-ride scholarship

AWARDS

- 2025 | **Summa Cum Laude**, Seoul National University
- 2023 | **Special Award**, MAICON 2023 (Military AI Competition)
- 2022 | **Special Award**, MAICON 2022 (Military AI Competition)
- 2018 | **Honorable Mention**, IMMC (International Mathematical Modeling Challenge)
- 2018 | **Bronze Prize**, Samsung Humantech Paper Award (Advisor: Hyunju Ju)
Modeling a Remora-Inspired Sucker Structure for Ship Flood Prevention Pads
- 2015 | **1st place**, KOI (Korea Olympiad in Informatics)

SKILLS

Programming Language

- C, C++, Python (Pytorch, Tensorflow, Jax), C# (Unity), Java

Machine Learning

- Reinforcement learning, Vision, 3D geometry (NeRF), NLP

Languages

- Korean: Native
- English: Proficient
 - GRE: 163/170 (Verbal), 169/170 (Quant), 4.5/6.0 (Writing)
- Japanese: Proficient
 - JLPT N1: 168/180

SERVICES

Reviewer

- Conferences: ICLR 2025, NeurIPS 2026, ICLR 2026
- Workshops: WCBM @ CoRL 2024, World Models @ ICLR 2025

TEACHING

Teaching Assistant

- AAI4160 Reinforcement Learning, Spring 2024