Analysis of Visual Mandela Effect

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Problem Definition

Previous Goal: Predicting Student Depression

Problems

- Topic overlapped with other team
- The dataset we chose did not accurately reflect the real world.

Problem Definition

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New Goal: Analysis of Visual Mandela Effect

Mandela Effect

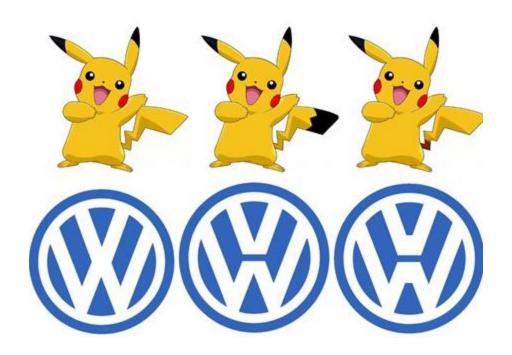
Shared False Memory across People



- Many people remember Mandela died at prison
- but in fact, he became president after he was imprisoned and lived till 2013.

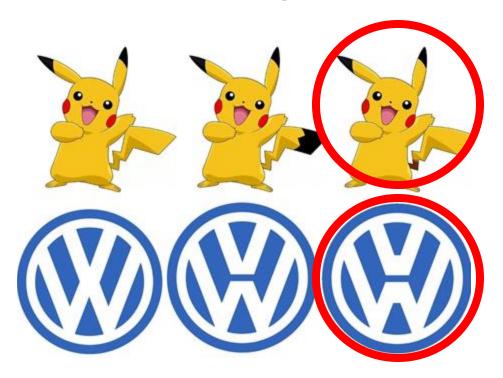
Our Topic - Visual Mandela Effect

What's The Original One?



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What's The Original One?

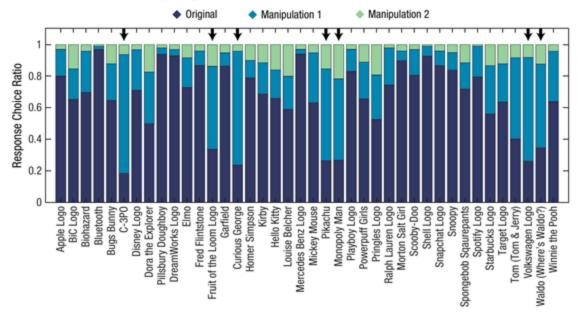


Our Goal - Analysing VME Using DS/ML

Significance Comparison of VME / non-VME

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- Are there shared features across VME images?
- If so, Can we analyze using DS/ML?

Technical Definition & Result

0. Load Dataset & Preprocessing



Dataset is public in https://osf.io/7cmwf/

Preprocess dataframe

```
root dir = Path('drive/MyOrive/Colab Notebooks/datas/Stimulus Images'
batch size = 16
num epochs = 5
learning rate = 10-4
device = "cuda" if torch.cuda.is_available() else "cpu"
or label dir in root dir.iterdir():
   if label dir.is dir():
        label = 1 if label dir.name.lower() == "vmc" else 0
        for img path in label_dir.glob("".jpg"):
           category = img_path.stem.split('_')[0]
           records.append((
                path's str(img path).
                'category's category,
                'label': label
       DataFrame (records)
```

```
train tf = transforms.Compose(
    transforms.RandomResizedCrop(224),
    transforms .RandomHorizontalFlip().
    transforms.ColorJitter(0.2,0.2,0.2,0.1),
    transforms .ToTensor().
    transforms.Normalize((0.4815,0.4578,0.4082),(0.2686,0.2613,0.2758))
val tf = transforms.Compose(
    transforms.Resize(256),
    transforms.CenterCrop(224).
    transforms.ToTensor().
    transforms.Normalize((0.4815,0.4578,0.4082),(0.2686,0.2613,0.2758))
```

463.4MB Public P 0 ---

Load data

```
_imit_(self, df, transform):
       self.df = df.reset_index(drop<)rus)
            (self): return les(self.sf)
        getites (self, ids)
       ing - self-transform(ing)
       label - torch.temor(row.label, dtype-torch.floati2)
      cat + row.category
      return ing, label, cut
kf = StrutifinkCold(m splits=0, shuffle=1rmr, random state=0)
  fold, (train ide, val ide) in enumerated
      skf-split(of, of late! )), start-1):
  train of - of.iloc[train_idx], reset_index(drop-true)
  val df - df.iloc[val bds].reset index(drop-frum)
  train ds - institutes (train df, train tf)
  val ds - vectoranet(val df, val tf)
  train leader + Outstooder (train ds, butch size-16,
                            shuffle-true, num workers-t)
  val leader - Outstander (wall do, butch size-in,
                            shaffle-taling man serkers-sty
```

Technical Definition & Result

1. Contrastive Language-Image Pretrained

```
6) Model definition
class CLIPFusionClassifier(nn.Module):
    def init (self, clip model, hidden dim-256):
        super(), init ()
        self.clip = clip model
        embed dim = clip model.visual.output dim
        self.img proj = nn.linear(embed dim, embed dim)
        self.txt proj = nn.linear(embed dim, embed dim)
        self.fuse
                   nn.Sequential(
           nn.Linear(embed dim*2, hidden dim),
           nn.ReLU().
           nn.Dropout(0.2),
            nn.Linear(hidden dim, 1)
    def forward(self, images, text tokens):
        img emb = self.img proj(self.clip.encode image(images).float())
        txt emb = self.txt proj(self.clip.encode text(text tokens).float())
        fused = torch.cat([img emb, txt emb], dim=-1)
        logits = self.fuse(fused).squeeze(-1)
        return fused, logits
# 7) Load CLIP and instantiate model
clip model, preprocess = clip.load("RN50", device=device)
model = CLIPFusionClassifier(clip model).to(device)
for p in model.clip.parameters(): p.requires grad = False
optimizer = optim.Adam(filter(lambda p: p.requires grad, model.parameters()), lr=learning rate)
criterion = nn.BCEWithLogitsLoss()
```

Image + Language prompt
 ('a clear icon of {}')

(1) Contrastive pre-training

Text Encoder $I_1 \quad I_2 \quad I_3 \quad = \quad I_1 \cdot I_N$ $I_2 \quad I_3 \cdot I_1 \cdot I_2 \cdot I_2 \cdot I_3 \cdot I_3$

Technical Definition & Result

2. 8-fold cross validation

Training step

```
skf = StratifiedKFold(n splits=n splits, shuffle=True, random state=42)
fold metrics = []
for fold, (train idx, val idx) in enumerate(skf.split(df, df['label']), start=1):
    print(f"--- fold (fold)/(n splits) ---")
    train df = df.iloc[train idx].reset index(drop-True)
    val df = df.iloc[val idx].reset index(drop=True)
    train ds - VMEDataset(train df, train tf)
    val ds = VMEDataset(val df, val tf)
    train loader = DataLoader(train ds, batch size-batch size, shuffle=True)
    val loader = DataLoader(val ds, batch size-batch size, shuffle-False)
    for epoch in range(num epochs):
        model.train()
        running loss = 0.0
        for imgs, labels, cats in train loader:
            imgs = imgs.to(device)
            labels = labels.to(device)
            tokens = clip.tokenize([make prompt(c) for c in cats]).to(device)
            ___, logits = model(imgs, tokens)
            loss = criterion(logits, labels)
            running loss += loss.item() * imgs.size(0)
            optimizer.zero grad()
            loss.backward()
            optimizer.step()
        epoch loss = running loss / len(train ds)
        print(f" Epoch (epoch+1)/(num epochs) | Train Loss: (epoch loss: .4f)")
```

Validation step

```
# Validation
model.eval()
ys, ps, preds = [], [], []
with torch.no grad():
    for imgs, labels, cats in val loader:
        imgs=imgs.to(device)
        labels=labels.to(device)
        tokens=clip.tokenize([make prompt(c) for c in cats]).to(device)
        , logits=model(imgs, tokens)
        probs = torch.sigmoid(logits)
        ys.extend(labels.cpu().numpy())
        ps.extend(probs.cpu().numpy())
        preds.extend((probs.cpu().numpy() >= 0.5).astype(int))
auc = roc auc score(ys, ps)
preds = (np.array(ps)>=0.5).astype(int)
f1 = f1 score(ys, preds)
acc = accuracy score(ys, preds)
print(f"Fold (fold+1) ALC: {auc:.3f}, F1: {f1:.3f}, Accuracy: {acc:.3f}")
fold metrics.append((auc, f1))
```

Technical Definition&Result

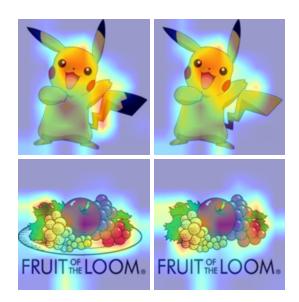
2. 8-fold cross validation - Result

```
=== Fold 1/8 ===
Epoch 1/5 - Train Loss: 0.6152
Epoch 2/5 - Train Loss: 0.5100
Epoch 3/5 - Train Loss: 0.4711
Epoch 4/5 - Train Loss: 0.4420
Epoch 5/5 - Train Loss: 0.4030
Fold 2 AUC: 1.000, F1: 0.000, Accuracy: 0.800
=== Fold 2/8 ===
Epoch 1/5 - Train Loss: 0.3744
Epoch 2/5 - Train Loss: 0.3362
Epoch 3/5 - Train Loss: 0.2860
Epoch 4/5 - Train Loss: 0.2307
Epoch 5/5 - Train Loss: 0.1831
Fold 3 AUC: 1.000, F1: 0.500, Accuracy: 0.867
=== Fold 3/8 ===
Epoch 1/5 - Train Loss: 0.1537
Epoch 2/5 - Train Loss: 0.1166
Epoch 3/5 - Train Loss: 0.0885
Epoch 4/5 - Train Loss: 0.0633
Epoch 5/5 - Train Loss: 0.0482
Fold 4 AUC: 1.000, F1: 1.000, Accuracy: 1.000
=== Fold 4/8 ===
Epoch 1/5 - Train Loss: 0.0361
Epoch 2/5 - Train Loss: 0.0285
Epoch 3/5 - Train Loss: 0.0224
Epoch 4/5 - Train Loss: 0.0178
Epoch 5/5 - Train Loss: 0.0153
```

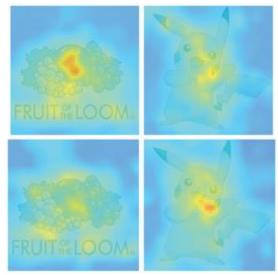
```
=== Fold 5/8 ===
Epoch 1/5 - Train Loss: 0.0116
Epoch 2/5 - Train Loss: 0.0102
Epoch 3/5 - Train Loss: 0.0097
Epoch 4/5 - Train Loss: 0.0073
Epoch 5/5 - Train Loss: 0.0065
Fold 6 AUC: 1.000, F1: 1.000, Accuracy: 1.000
=== Fold 6/8 ===
Epoch 1/5 - Train Loss: 0.0059
Epoch 2/5 - Train Loss: 0.0058
Epoch 3/5 - Train Loss: 0.0052
Epoch 4/5 - Train Loss: 0.0043
Epoch 5/5 - Train Loss: 0.0041
Fold 7 AUC: 1.000, F1: 1.000, Accuracy: 1.000
=== Fold 7/8 ===
Epoch 1/5 - Train Loss: 0.0041
Epoch 2/5 - Train Loss: 0.0032
Epoch 3/5 - Train Loss: 0.0030
Epoch 4/5 - Train Loss: 0.0029
Epoch 5/5 - Train Loss: 0.0027
Fold 8 AUC: 1.000, F1: 1.000, Accuracy: 1.000
=== Fold 8/8 ===
Epoch 1/5 - Train Loss: 0.0026
Epoch 2/5 - Train Loss: 0.0024
Epoch 3/5 - Train Loss: 0.0023
Epoch 4/5 - Train Loss: 0.0021
Epoch 5/5 - Train Loss: 0.0020
Fold 9 AUC: 1.000, F1: 1.000, Accuracy: 1.000
```

Technical Definition&Result

3. GradCam Heat map visualization& Comparison with behavioural heat map



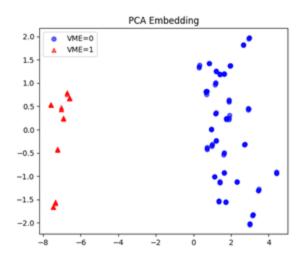
Our heatmap using GradCam

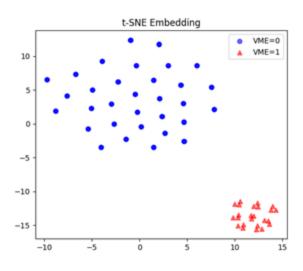


Behavioural heatmap from Prasad, D., & Bainbridge, W. A. (2022).

Technical Definition&Result

4. Feature projection using PCA&t-SNE





PCA

t-SNE

Conclusion

Significance of This Experiment

- 1. Showed that a ML model can distinguish between VME-eliciting and non-VME eliciting images.
- 2. Showed another approach to studying VME.
- 3. Showed the possibility of automated discovery.

Conclusion

Limitations

- 1. VME is about microscopic, detail-level mismatches, but our model and processing pipeline do not explicitly preserve these features.
- 2. The dataset was too small, due to lack of study on VME.