

# Chapter 1 - Introduction

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## 1 Exercise 1.1

Suppose we are given a training set, of  $N$  observation points:

$$\mathbf{x} = (x_1, \dots, x_n)^t, \quad \mathbf{t} = (t_1, \dots, t_n)^t \quad (1.1)$$

We think of the  $t$ 's as being dependent on the  $x$ 'es:  $t = t(x)$ . We wish to devise a model through polynomial curve fitting of order  $M$ . I.e. our model is of the form:

$$y(x, \mathbf{w}) = w_0 + w_1x + w_2x^2 + \dots + w_Mx^M = \sum_{j=0}^M w_jx^j \quad (1.2)$$

Here the parameters  $\mathbf{w} = (w_0, \dots, w_M)^t$  are known as the weights. We wish to find the model which minimizes the following error function:

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N [y(x_n, \mathbf{w}) - t_n]^2 \quad (1.3)$$

### 1.1 Solution

To minimize the error function, we differentiate with respect to the  $i$ 'th weight, using the chain rule:

$$\frac{\partial E}{\partial w_i} = \frac{1}{2} \sum_{n=1}^N \frac{\partial}{\partial w_i} [y(x_n, \mathbf{w}) - t_n]^2 = \sum_{n=1}^N [y(x_n, \mathbf{w}) - t_n] \frac{\partial y(x_n, \mathbf{w})}{\partial w_i} \quad (1.4)$$

The last derivative is:

$$\frac{\partial y(x_n, \mathbf{w})}{\partial w_i} = \frac{\partial}{\partial w_i} \sum_{j=0}^M w_jx_n^j = \sum_{j=0}^M \delta_{ij}x_n^j = x_n^i \quad (1.5)$$

Now equation 1.4 becomes:

$$\frac{\partial E}{\partial w_i} = \sum_{n=1}^N \left[ \sum_{j=0}^M w_j x_n^j - t_n \right] x_n^i = \sum_{n=1}^N \left[ \sum_{j=0}^M w_j x_n^{i+j} - t_n x_n^i \right] \quad (1.6)$$

Now define:

$$A_{ij} = \sum_{n=1}^N x_n^{i+j} \quad T_i = \sum_{n=1}^N t_n x_n^i \quad (1.7)$$

Then we can rewrite:

$$\frac{\partial E}{\partial w_i} = \sum_{j=0}^M A_{ij} w_j - T_i \quad (1.8)$$

Setting this derivative equal to zero, we get:

$$\sum_{j=0}^M A_{ij} w_j = T_i \quad (1.9)$$

## 2 Exercise 1.2

Consider the same problem as last exercise, but with an additional regularization term added to the error function:

$$\tilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N [y(x_n, \mathbf{w}) - t_n]^2 + \frac{\lambda}{2} \|\mathbf{w}\|^2 \quad (2.1)$$

We wish to find the equations the weights must satisfy in this case.

### 2.1 Solution

The derivative of the error function is modified:

$$\frac{\partial \tilde{E}}{\partial w_i} = \frac{\partial E}{\partial w_i} + \frac{\partial}{\partial w_i} \left[ \frac{\lambda}{2} \|\mathbf{w}\|^2 \right] \quad (2.2)$$

The last correction term is:

$$\frac{\lambda}{2} \frac{\partial}{\partial w_i} (w_0^2 + w_1^2 + \dots + w_M^2) = \lambda w_i \quad (2.3)$$

According to equation 1.8 we have:

$$\frac{\partial \tilde{E}}{\partial w_i} = \sum_{j=0}^M A_{ij} w_j - T_i + w_i \quad (2.4)$$

Table 1: Content of the boxes (Exercise 1.3)

	r	b	g
Apples	3	1	3
Oranges	4	1	3
Limes	3	0	4

Setting this equal to zero we get:

$$\sum_{j=0}^M A_{ij}w_j + \lambda w_i = T_i \quad (2.5)$$

We may absorb the  $\lambda$  term into the  $A$  matrix by the following modification:

$$\tilde{A}_{ij} = A_{ij} + \lambda \delta_{ij} \quad (2.6)$$

Then we get:

$$\sum_{j=0}^M \tilde{A}_{ij}w_j = T_i \quad (2.7)$$

### 3 Exercise 1.3

We have three colored boxes,  $r$  (red),  $b$  (blue), and  $g$  (green). The contents of the three boxes are shown in table 1. A box is chosen at random according to the following probability distribution:

$$p(r) = \frac{1}{5}, \quad p(b) = \frac{1}{5}, \quad p(g) = \frac{3}{5} \quad (3.1)$$

Next, a random piece of fruit (equal chance for each piece) is chosen from the box.

1. What is the probability of the fruit being an apple?
2. Given that the selected fruit is an orange, what is that probability that the green box was picked?

#### 3.1 Solution 1

The probability of getting an apple (A) is:

$$p(A) = p(A|r)p(r) + p(A|b)p(b) + p(A|g)p(g) \quad (3.2)$$

Inserting:

$$p(A) = \frac{3}{10} \cdot \frac{1}{5} + \frac{1}{2} \cdot \frac{1}{5} + \frac{3}{10} \cdot \frac{3}{5} = \frac{3}{50} + \frac{1}{10} + \frac{9}{50} = \frac{3+5+9}{50} = \frac{17}{50} = 34\% \quad (3.3)$$

### 3.2 Solution 2

We wish to find  $p(g|O)$ , where 'O' is short for orange. For this we need Bayes' rule:

$$p(g|O) = \frac{p(O|g)p(g)}{p(O)} \quad (3.4)$$

The denominator can be found similarly to problem 1:

$$p(O) = p(O|r)p(r) + p(O|b)p(b) + p(O|g)p(g) \quad (3.5)$$

Inserting:

$$p(O) = \frac{4}{10} \cdot \frac{1}{5} + \frac{1}{2} \cdot \frac{1}{5} + \frac{3}{10} \cdot \frac{3}{5} = \frac{4 + 5 + 9}{50} = \frac{18}{50} = 36\% \quad (3.6)$$

Now we have:

$$p(g|O) = \frac{3/10 \cdot 3/5}{18/50} = \frac{9 \cdot 50}{50 \cdot 18} = \frac{9}{18} = \frac{1}{2} \quad (3.7)$$

## 4 Exercise 1.4

Let  $p_x(x)$  be a probability density function for a continuous variable  $x$ . Consider a variable transformation  $x = g(y)$ . The pdf for the transformed variable is then:

$$p_y(y) = p_x(x) \left| \frac{dx}{dy} \right| = p_x(g(y)) |g'(y)| \quad (4.1)$$

Show that in general, a non-linear transformation will change the location of a maximum of the pdf, while a linear one will not.

### 4.1 Solution

If  $p_x$  has a maximum at  $x = \hat{x}$  then we must have:

$$\frac{dp_x(\hat{x})}{dx} = 0 \quad (4.2)$$

Now, consider the derivative of  $p_y$ :

$$\frac{dp_y(y)}{dy} = \frac{dp_x}{dx} \frac{dg}{dy} |g'(y)| + p_x(g(y)) \text{sgn}(g'(y)) g''(y) \quad (4.3)$$

If  $y = g(\hat{x})$ , the first term is zero, but the second need not be. Therefore, the location of a maximum will generally move. However, for a linear transformation the second derivative is zero, and so the second term becomes zero as well.

## 5 Exercise 1.5

The variance of a continuous random variable  $f(x)$  is defined as:

$$\text{var}[f(x)] = \mathbb{E}[(f(x) - \mathbb{E}[f(x)])^2] \quad (5.1)$$

Show that this may be written:

$$\text{var}[f(x)] = \mathbb{E}[f(x)^2] - \mathbb{E}[f(x)]^2 \quad (5.2)$$

### 5.1 Solution

Expand the square inside the expectation value:

$$(f(x) - \mathbb{E}[f(x)])^2 = f(x)^2 + \mathbb{E}[f(x)]^2 - 2f(x)\mathbb{E}[f(x)] \quad (5.3)$$

The expectation values is:

$$\mathbb{E}[f(x)^2] + \mathbb{E}[f(x)]^2 - 2\mathbb{E}[f(x)] \cdot \mathbb{E}[f(x)] = \mathbb{E}[f(x)^2] - \mathbb{E}[f(x)]^2 \quad (5.4)$$

## 6 Exercise 1.6

Show that two independent random variable  $x$  and  $y$  have zero covariance.

### 6.1 Solution

The covariance can be written:

$$\int \int (x - \mathbb{E}[x])(y - \mathbb{E}[y])p(x, y)dx \, dy \quad (6.1)$$

Here  $p(x, y)$  is the joint distribution function of  $x$  and  $y$ . But since these are independent  $p(x, y) = p(x)p(y)$ . So this integral splits into two parts:

$$\int \int (x - \mathbb{E}[x])(y - \mathbb{E}[y])p(x)p(y)dx \, dy = \int (x - \mathbb{E}[x])dx \cdot \int (y - \mathbb{E}[y])dy \quad (6.2)$$

Each of these factors is zero, and therefore so is the covariance.

## 7 Exercise 1.7

Show that:

$$I = \int_{-\infty}^{\infty} \exp\left(-\frac{1}{2\sigma^2}x^2\right) dx = \sqrt{2\pi\sigma^2} \quad (7.1)$$

## 7.1 Solution

Consider the square of  $I$ :

$$I^2 = \int_{-\infty}^{\infty} \exp\left(-\frac{1}{2\sigma^2}x^2\right) dx \cdot \int_{-\infty}^{\infty} \exp\left(-\frac{1}{2\sigma^2}y^2\right) dy \quad (7.2)$$

Rearrange the order:

$$I^2 = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \exp\left(-\frac{1}{2\sigma^2}x^2\right) \exp\left(-\frac{1}{2\sigma^2}y^2\right) dx dy = \quad (7.3)$$

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \exp\left(-\frac{1}{2\sigma^2}(x^2 + y^2)\right) dx dy \quad (7.4)$$

This may be regarded as an integral over the plane. We may now shift to polar coordinates, noting that  $x^2 + y^2 = r^2$  and  $dx dy = r dr d\theta$ :

$$I^2 = \int_0^{2\pi} \int_0^{\infty} \exp\left(-\frac{r^2}{2\sigma^2}\right) r dr d\theta = 2\pi \int_0^{\infty} \exp\left(-\frac{r^2}{2\sigma^2}\right) r dr \quad (7.5)$$

For the  $r$ -integral, substitute  $u = r^2$ . Then  $du/dr = 2r$ , and so  $dr = \frac{1}{2r}du$ :

$$\int_0^{\infty} \exp\left(-\frac{r^2}{2\sigma^2}\right) r dr = \int_0^{\infty} \exp\left(-\frac{u}{2\sigma^2}\right) r \frac{1}{2r} du = \frac{1}{2} \int_0^{\infty} \exp\left(-\frac{u}{2\sigma^2}\right) du \quad (7.6)$$

This is elemental to integrate:

$$\frac{1}{2} \left[ -2\sigma^2 \exp\left(-\frac{u}{2\sigma^2}\right) \right]_0^{\infty} = \sigma^2 \quad (7.7)$$

Hence  $I^2 = 2\pi\sigma^2$ , and therefore  $I = \sqrt{2\pi\sigma^2}$ .