

# Single value decomposition and pseudo-inverses

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## 1 Gramian matrices

Given a set of vectors  $a_1, a_2, \dots, a_n \in \mathbb{R}^m$ , the Gramian matrix is the traditionally matrix of inner products  $\langle a_i, a_j \rangle$ . If these vectors are collected into a  $m \times n$  matrix  $A$ , this matrix can be expressed as  $A^t A$ . Here, we will use the term for any matrix in this form. By starting out with the transpose instead, this means that  $AA^t$  is also a Gramian, with dual results.

**Theorem 1.1.** *If  $A \in \mathbb{R}^{m \times n}$ , then  $A^t A$  is symmetric and positive semi-definite. Iff  $A$  has rank  $m$ ,  $A^t A$  is positive definite.*

*Proof.*  $(A^t A)^t = A^t (A^t)^t = A^t A$  shows symmetry. positive semi-definiteness, let  $x \in \mathbb{R}^n$ . Then:

$$x^t A^t A x = \langle Ax, Ax \rangle = \|Ax\|^2 \quad (1.1)$$

As a norm, this is greater than or equal to zero. Hence  $A^t A$  is positive semi-definite. If  $A$  has rank  $m$  the map  $x \mapsto Ax$  has a trivial kernel by the rank-kernel theorem. Which means only the zero vector is mapped to zero, and hence  $A^t A$  is positive definite. If the rank is less than  $m$ , the kernel is non-trivial and positive definiteness cannot be true.  $\square$

## 2 Single value decomposition

Let  $A \in \mathbb{R}^{m \times n}$ . Since  $A^t A$  is symmetric, it is diagonalizable. So there is an orthogonal  $n \times n$  matrix  $O$  such that  $A^t A = O D O^t$ , where  $D$  is a diagonal matrix of eigenvalues.

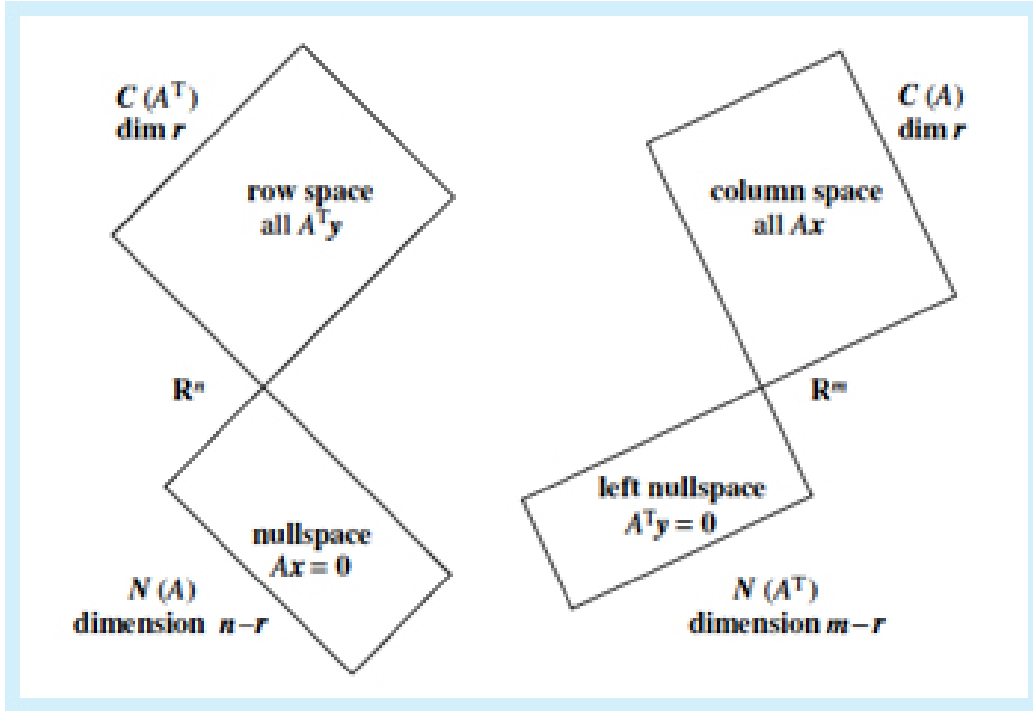


Figure 1: Visualization of dimensionality for the rank-nullity theorem

### 3 Generalized inverses

For an invertible matrix  $A$ , it's obviously true that:

$$AA^{-1}A = A \quad (3.1)$$

If  $A$  is not invertible, we may still define a *generalized inverse*  $A^g$  as a matrix that satisfies the same equation:

$$AA^gA = A \quad (3.2)$$

#### 3.1 Left and right inverses

If  $A \in \mathbb{R}^{m \times n}$  has rank  $n$ , then the null space is trivial, and hence the corresponding linear transformation is injective. This means that the equation  $Ax = b$  may or may not have a solution, but if it exists, it's unique. The matrix  $A^tA$  has rank  $n$  as well, and hence is invertible. This can be used to construct a left inverse:

$$A_L^{-1} = (A^tA)^{-1}A^t, \quad A_L^{-1}A = (A^tA)^{-1}A^tA = I_n \quad (3.3)$$

Similarly, if  $A \in \mathbb{R}^{m \times n}$  has rank  $m$ , then the image space is all of  $\mathbb{R}^m$ , and hence the corresponding linear transformation is surjective. This means that the equation  $Ax = b$  always has a solution, and it may have infinitely many. The matrix  $AA^t$  has rank  $m$  as well, and hence is invertible. Analogously, we can use this to construct a right inverse:

$$A_R^{-1} = A^t(AA^t)^{-1}, \quad AA_R^{-1} = AA^t(AA^t)^{-1} = I_m \quad (3.4)$$

Both of these inverses (when they exist) satisfies equation 3.2.