Dustom Object Detection Tensorflow Lite Raspberry Pi Bookworm

\$ git clone https://github.com/freedomwebtech/tflite-custom-object-bookworm
마글(F) 전입(다) 답(F) 포함글(F)

pi@raspberrypi:~ \$ git clone https://github.com/freedomwebtech/tflite-custom-object-bookworm
'tflite-custom-object-bookworm'에 복제합니다...
remote: Enumerating objects: 23, done.
remote: Counting objects: 100% (23/23), done.
remote: Compressing objects: 100% (22/22), done.
remote: Total 23 (delta 5), reused 0 (delta 0), pack-reused 0
오브젝트를 받는 중: 100% (23/23), 3.22 MiB | 5.02 MiB/s, 완료.
델타를 알아내는 중: 100% (5/5), 완료.
pi@raspberrypi:~ \$

\$ sudo rm /usr/lib/python3.11/EXTERNALLY-MANAGED

```
파일(F) 편집(E) 탭(T) 도움말(H)
GNU nano 7.2 rpi4.txt
sudo rm /usr/lib/python3.11/EXTERNALLY-MANAGED
```

\$ sudo pip3 install opency-python

\$ sudo pip3 install mediapipe

```
pi@raspberrypi:~ $ sudo pip3 install mediapipe
Looking in indexes: https://pypi.org/simple, https://www.piwheels.org/simple
Collecting mediapipe
Downloading mediapipe-0.10.13-cp311-cp311-manylinux_2_17_aarch64.manylinux201
4_aarch64.whl (33.0 MB)

Collecting absl-py
Downloading https://www.piwheels.org/simple/absl-py/absl_py-2.1.0-py3-none-an
y.whl (133 kB)

133.7/133.7 kB 110.3 kB/s eta 0:00:0

Collecting attrs>=19.1.0
Downloading https://www.piwheels.org/simple/attrs/attrs-23.2.0-py3-none-any.w
hl (60 kB)

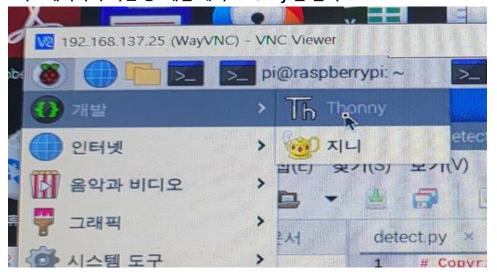
60.8/60.8 kB 170.7 kB/s eta 0:00:0

Collecting flatbuffers>=2.0
Downloading https://www.piwheels.org/simple/flatbuffers/flatbuffers-201810032
```

(중략)

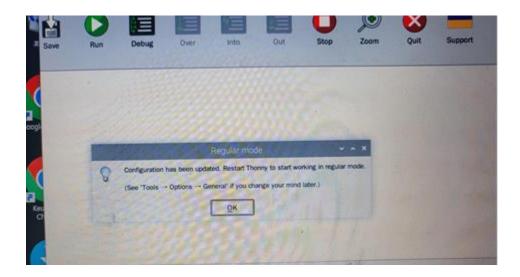
```
Downloading https://www.piwheels.org/simple/pycparser/pycparser-2.22-py3-none
any.whl (117 kB)
                                             117.6/117.6 kB 3.7 MB/s eta 0:00:00
Requirement already satisfied: six>=1.5 in /usr/lib/python3/dist-packages (from
 python-dateutil>=2.7->matplotlib->mediapipe) (1.16.0)
Installing collected packages: flatbuffers, scipy, python-dateutil, pyparsing,
pycparser, protobuf, packaging, opt-einsum, opencv-contrib-python, ml-dtypes, k
iwisolver, fonttools, cycler, contourpy, attrs, absl-py, matplotlib, jaxlib, ja
x, CFFI, sounddevice, mediapipe
Successfully installed CFFI-1.16.0 absl-py-2.1.0 attrs-23.2.0 contourpy-1.2.1 c
ycler-0.12.1 flatbuffers-20181003210633 fonttools-4.51.0 jax-0.4.26 jaxlib-0.4.
26 kiwisolver-1.4.5 matplotlib-3.8.4 mediapipe-0.10.13 ml-dtypes-0.4.0 opencv-c
ontrib-python-4.9.0.80 opt-einsum-3.3.0 packaging-24.0 protobuf-4.25.3 pycparse
 -2.22 pyparsing-3.1.2 python-dateutil-2.9.0.post0 scipy-1.13.0 sounddevice-0.4
. 6
 oflicting behaviour with the system package manager. It is recommended to use a virtual environment instead: https://pip.pypa.io/warnings/venv
pi@raspberrypi:~ $
```

. 라즈베리파이 버턴 중 '개발'에서 'Thonny'를 클릭

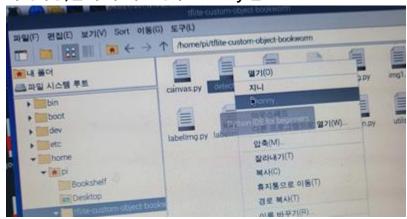


* 우측 상단에서 'Switch to regular mode'를 클릭하고, 뜨는 창에서 'ok' 눌러 종료





* Thonny 창을 닫음. 파일메니져에서 'detect.py' (USB 카메라용. detect1.py 는 파이카메라용)를 우측 버턴에서 'Thonny'를 오픈



. detect.py 에서 #47 의 'VideoCapture(0)'에서 '0'는 USB 카메라용

```
# Start capturing video input from the camera
cap = cv2.VideoCapture(0)
cap.set(cv2.CAP_PROP_FRAME_WIDTH, width)
cap.set(cv2.CAP_PROP_FRAME_HEIGHT, height)

# Visualization parameters
```

. # 133 를 comment 하고 (custom model 결과라서), #132 의 커멘트를 해제

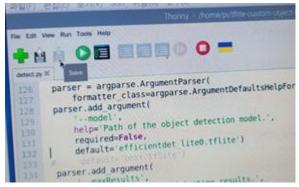
```
required=False,
default='efficientdet_lite0.tflite')

# default='best.tflite')

parser.add_argument(

'--maxResults'.
```

. 수정한 후, 상단의 저장 버턴을 클릭하여 저장



. picamera 경우는 'detect1.py'를 불러서 같은 방법으로 수정

```
parser = argparse.ArgumentParser(
110
             formatter_class=argparse.ArgumentDefaultsHelpFormatter)
111
         parser.add_argument(
112
113
              - - model',
            help='Path of the object detection model.',
114
            required=False,
115
             default='efficientdet_lite0.tflite')
116
             default='best.tflite')
117
       parser.add_argument(
118
```

```
parser = argparse.ArgumentParser(
110
            formatter_class=argparse.ArgumentDefaultsHelpFor
111
112
        parser.add_argument(
113
        help='Path of the object detection model.',
114
      default='efficientdet lite@.tflite')

# default='best tflite'
115
116
117
118 parser.add_argument(
119
        help= Max humber of detection results.
120
            required=False,
121
       default=5)
122
123 parser.add_argument(
```

. 파이썬은 3.11 버전을 사용 중

```
파일(F) 편집(E) 탭(T) 도움말(H)

pi@raspberrypi:~ $ python

Python 3.11.2 (main, Mar 13 2023, 12:18:29) [GCC 12.2.0] on linux

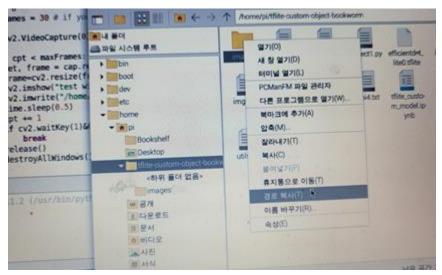
Type "help", "copyright", "credits" or "license" for more information.

>>> ■
```

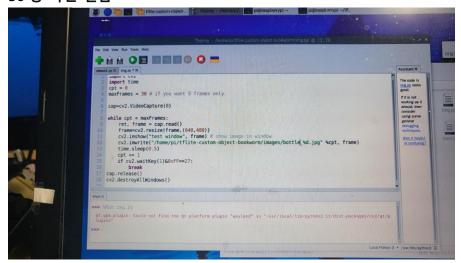
custom 이미지 만들기(img.py 이용)

\$ mkdir images

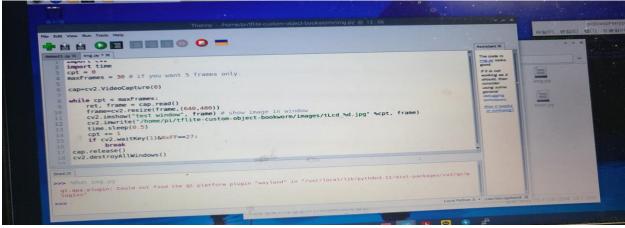
. images 폴더의 path 를 마우스 우측 버턴 이용 복사한 후 img.py 수정



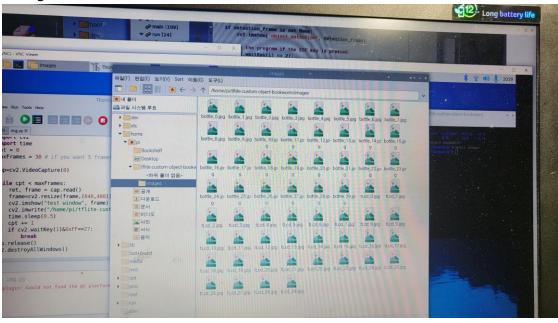
. img.py 에서 USB 카메라를 이용해서 '통'(bottle,각자가 원하는 object)을 천천히 움직여서 30 장 사진 얻음



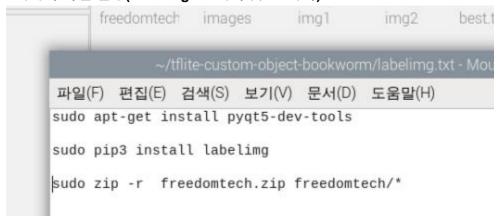
. img.py 에서 USB 카메라를 이용해서 'Text LCD'(각자가 원하는 object)를 천천히 움직여서 30 장 사진 얻음 (다른 img2 를 만들어서 별도로 하는 걸 추천. 삭제 때문에.)



. images 폴더에는 총 60 장 사진이 저장됨



. 이미지 라벨 설정(labelimg.txt 에서 첫 줄 복사)



\$ sudo apt-get install pyqt5-dev-tools

```
kworm $ sudo apt-get install pyqt5-dev-tools
파키지 목록을 읽는 중입니다... 완료
의존성 트리를 만드는 중입니다... 완료
상태 정보를 읽는 중입니다... 완료
 다음 패키지가 자동으로 설치되었지만 더 이상 필요하지 않습니다:
  libraspberrypi0
 나음 새 패키지를 설치할 것입니다:
 pyqt5-dev-tools
9개 업그레이드, 1개 새로 설치, 9개 제거 및 9개 업그레이드 안 함.
177 k바이트 아카이브를 받아야 합니다.
이 작업 후 479 k바이트의 디스크 공간을 더 사용하게 됩니다.
받기:1 http://deb.debian.org/debian bookworm/main arm64 pyqt5-dev-tools arm64 5.15.9+dfsg-1 [177 kB]
Selecting previously unselected package pyqt5-dev-tools.
(데이터베이스 읽는중 ...현재 149209개의 파일과 디렉터리가 설치되어 있습니다.)
Preparing to unpack .../pyqt5-dev-tools_5.15.9+dfsg-1_arm64.deb ...
Unpacking pyqt5-dev-tools (5.15.9+dfsg-1) ...
pyqt5-dev-tools (5.15.9+dfsg-1) 설정하는 중입니다 ...
Processing triggers for man-db (2.11.2-2) ...
pi@raspberrypi:~/tflite-custom-object-bookworm $
```

. 두번째 줄 실행 (\$ sudo pip3 install labelimg)

. canvas.py 삭제(\$ sudo rm -rf /usr/local/lib/python3.11/dist-packages/libs/canvas.py)하고 이곳에 새로운 canvas.py(repository 에 있는)를 복사.

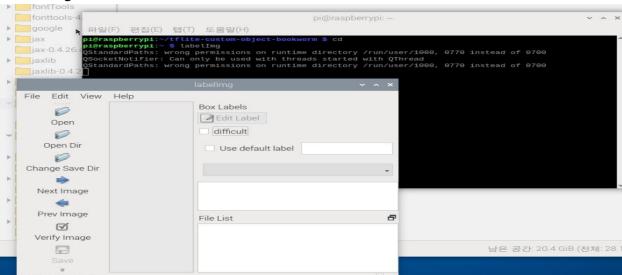
```
파일(F) 편집(E) 탭(T) 도움말(H)

pi@raspberrypi:~ $ sudo rm -rf /usr/local/lib/python3.11/dist-packages/libs/canv
as.py
pi@raspberrypi:~ $ cd tflite-custom-object-bookworm/
pi@raspberrypi:~/tflite-custom-object-bookworm $ sudo mv canvas.py /usr/local/lib/python3.11/dist-packages/libs
pi@raspberrypi:~/tflite-custom-object-bookworm $
```

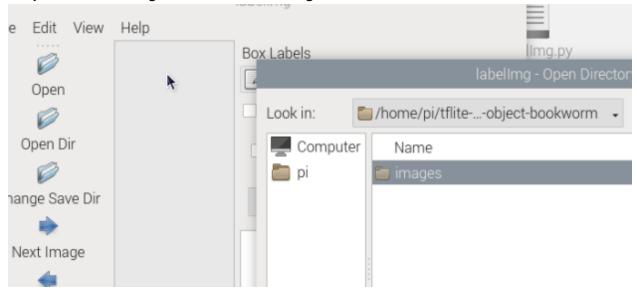
. labelimg.py (/usr/local/lib/python3.11/dist-packages/labelImg/labelImg.py)

```
pi@raspberrypi:~/tflite-custom-object-bookworm $ sudo rm -rf /usr/local/lib/python3.11/dist-packages/lab
elImg/labelImg.py
pi@raspberrypi:~/tflite-custom-object-bookworm $ sudo mv labelImg.py /usr/local/lib/python3.11/dist-pack
ages/labelImg
pi@raspberrypi:~/tflite-custom-object-bookworm $
```

\$ labelImg



. 'Open Dir'과 'Change Save Dir'을 모두 img1 (또는 이미지가 있는 폴더)폴더로 지정



. format 은 'PascalVoc' (TensorFlow 용)선택

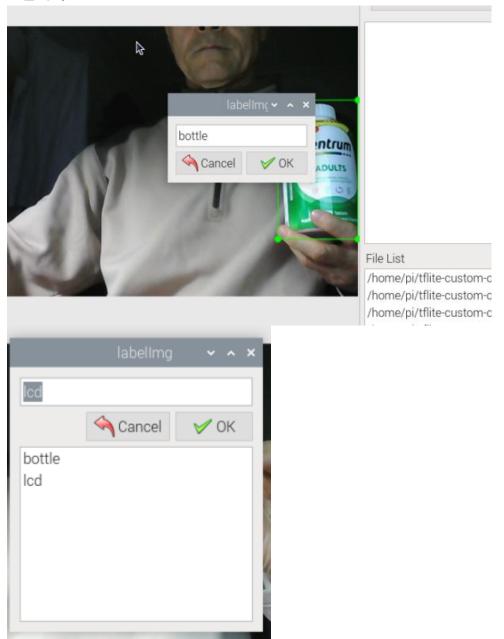


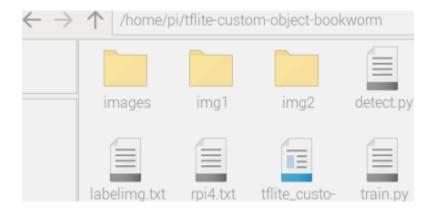
- . 'Create RectBox'를 선택하고 라벨링 시작
- . 그림 사이즈가 작으면 좌측 하단 메뉴 중에서 'Zoom In'을 선택하고 뜨는 창에서

'Fit Window'를 선택

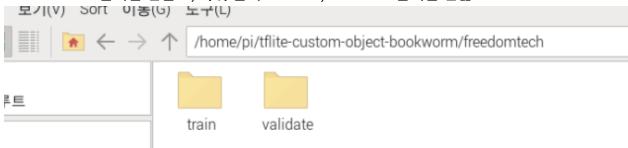


. 다시 'Create RectangleBox'를 누르고 직사각형으로 라벨링. 이름은 'bottle'로 (선택한 object 에 맞는 이름으로) 쓰고 'Ok' 클릭. 좌측에서 'Save' 버턴을 누르고 'Next Image'를 클릭 . 2 번째는 폴더를 img2(본인이 정한 이미지 폴더)를 만들고 'Icd'(선택한 object 에 맞는 이름으로)이름으로 라벨링 (마음에 안 들 경우 폴더 삭제가 쉬움). 나중에 images 폴더를 만들어서 합칩.



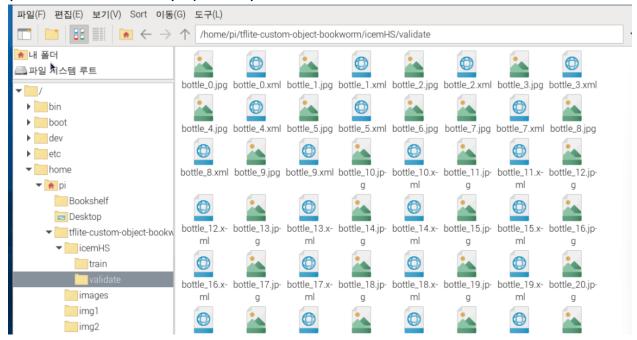


. feedomtech 폴더를 만들고, 하위 폴더로 'train', 'validate' 폴더를 만듦



. 폴더 'train', 'validate'에 images 폴더 모두를 복사해 넣음

('편집'에 있는 '모두 선택(^A)'을 이용)



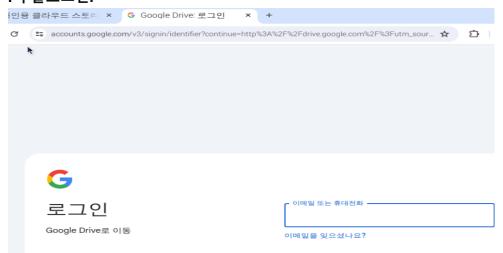
.labelimg.txt 의 세번째 명령 실행 (\$ sudo zip -r freedomtech.zip freedomtech/*)

```
pi@faspberrypi:~/tflite-custom-object-bookworm $ sudo zip -r freedomtech.zip f
reedomtech/*
  adding: freedomtech/train/ (stored 0%)
  adding: freedomtech/train/bottle_9.xml (deflated 48%)
  adding: freedomtech/train/bottle_8.xml (deflated 49%)
  adding: freedomtech/train/bottle_5.xml (deflated 49%)
  adding: freedomtech/train/tlcd_15.xml (deflated 48%)
  adding: freedomtech/train/tlcd_14.xml (deflated 48%)
  adding: freedomtech/train/bottle_17.xml (deflated 48%)
  adding: freedomtech/train/bottle_4.jpg (deflated 0%)
  adding: freedomtech/train/bottle_12.xml (deflated 48%)
  adding: freedomtech/train/tlcd_12.xml (deflated 48%)
  adding: freedomtech/train/tlcd_12.xml (deflated 48%)
  adding: freedomtech/train/tlcd_12.xml (deflated 48%)
  adding: freedomtech/train/tlcd_12.xml (deflated 48%)
```

(중략)

```
adding: freedomtech/validate/bottle_27.jpg (deflated 0%)
 adding: freedomtech/validate/tLcd_10.jpg (deflated 0%)
 adding: freedomtech/validate/bottle_2.jpg (deflated 0%)
 adding: freedomtech/validate/bottle_0.xml (deflated 49%)
 adding: freedomtech/validate/tLcd_7.xml (deflated 48%)
 adding: freedomtech/validate/tLcd_25.xml (deflated 47%)
 adding: freedomtech/validate/tLcd_5.jpg (deflated 0%)
 adding: freedomtech/validate/tLcd_8.jpg (deflated 0%)
 adding: freedomtech/validate/tLcd_11.xml (deflated 48%)
 adding: freedomtech/validate/tLcd_16.jpg (deflated 0%)
 adding: freedomtech/validate/bottle_14.jpg (deflated 0%)
 adding: freedomtech/validate/bottle_11.jpg (deflated 0%)
 adding: freedomtech/validate/tLcd_13.xml (deflated 48%)
 adding: freedomtech/validate/tLcd_19.xml (deflated 47%)
 adding: freedomtech/validate/bottle_22.xml (deflated 48%)
pi@raspberrypi:~/tflite-custom-object-bookworm $
```

. 구글로그인.



. 본인 인증절차를 거침



드라이버에 upload (구글 계정이 필요). 자기 이름의 좌측에 있는 점 9 개를 눌러서 뜨는 창에서 'Drive'를 클릭





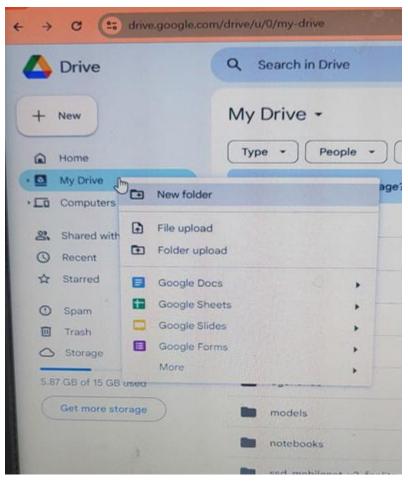
로그인

Google Drive로 이동

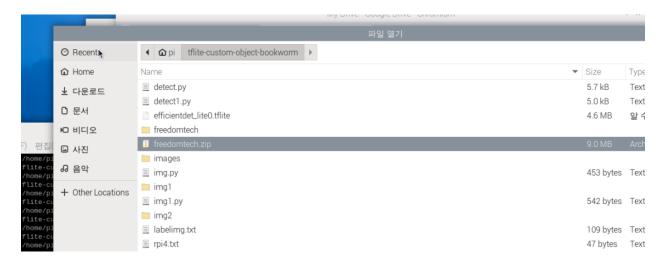
이메일 또는 휴대전화 -	
1	
2.	

이메일을 잊으셨나요?

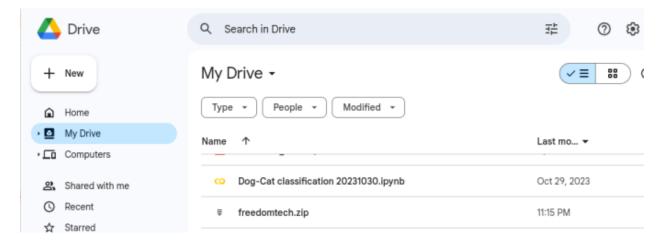
내 컴퓨터가 아닌가요? 게스트 모드를 사용하여 비공개로 로그인하세요. 게스트 모드 사용 방법 자세히 알아보기 . 좌측 'My Drive'를 선택하고 뜨는 창에서 'File upload'를 클릭



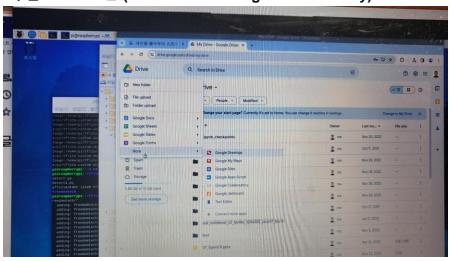
- . 압축 파일 (freedomtech.zip)
- 을 선택하고 하단의 'open' 클릭



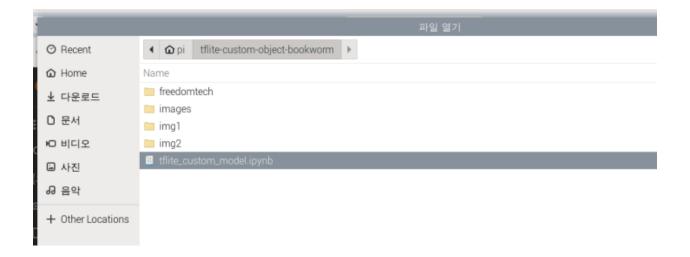
. 랩탑에서 구굴 드라이버 염

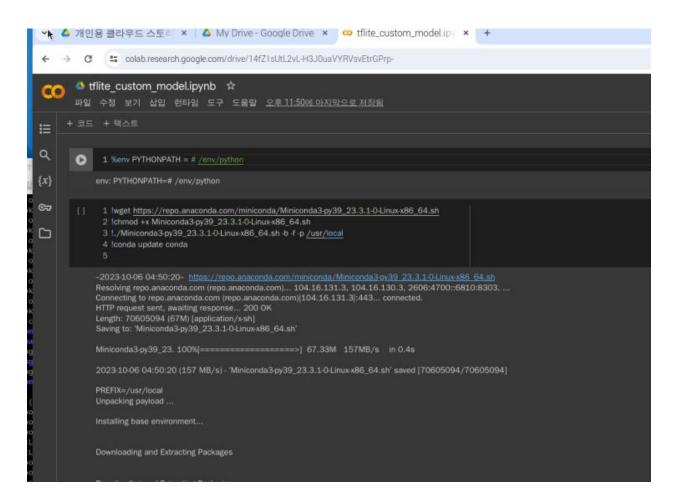


. 구글 Colab 오픈 (+New/ More / Google Colaboratory)

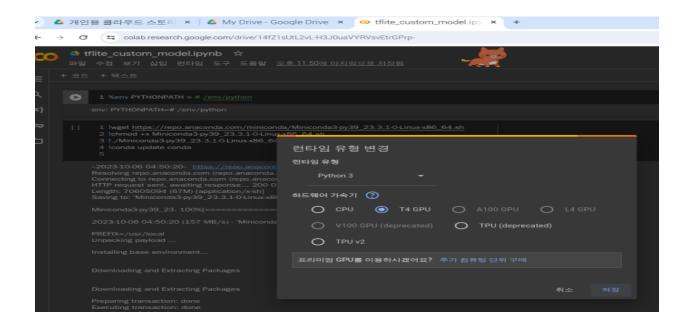


. Colab 에서 '노트열기'를 선택하고 '업로드'/'둘러보기'/Home 에서노프북 파일을 열기





. Colab 상단 메뉴에서 '런타임'을 눌러서 '런타임 유형 변경'을 눌러 뜨는 창에서 'T4 GPU' 선택



(뜨는 창에서 'GPU 없이 연결' 선택)

. cell 별로 실행

%env PYTHONPATH = # /env/python

```
[1] 1 %env PYTHONPATH = # /env/python

env: PYTHONPATH=# /env/python
```

!wget https://repo.anaconda.com/miniconda/Miniconda3-py39_23.3.1-0-Linux-x86_64.sh !chmod +x Miniconda3-py39_23.3.1-0-Linux-x86_64.sh !/Miniconda3-py39_23.3.1-0-Linux-x86_64.sh -b -f -p /usr/local !conda update conda

```
1 !wget https://repo.anaconda.com/miniconda/Miniconda3-py39_23.3.1-0-Linux-x86_64.sh
2 !chmod +x Miniconda3-py39_23.3.1-0-Linux-x86_64.sh
3 !./Miniconda3-py39_23.3.1-0-Linux-x86_64.sh -b -f -p /usr/local
4 !conda update conda
5

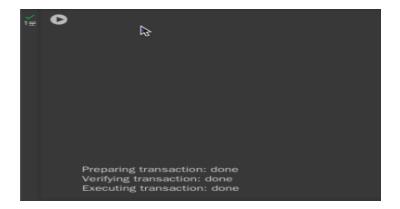
--2024-05-04 15:06:50-- https://repo.anaconda.com/miniconda/Miniconda3-py39_23.3.1-0-Linux-x86_64.sh
Resolving repo.anaconda.com (repo.anaconda.com)... 104.16.32.241, 104.16.191.158, 2606:4700::6810:20f1, ...
Connecting to repo.anaconda.com (repo.anaconda.com)|104.16.32.241|:443... connected.
HTTP request sent, awaiting response... 200 0K
Length: 70605094 (67M) [application/x-sh]
Saving to: 'Miniconda3-py39_23.3.1-0-Linux-x86_64.sh'
Miniconda3-py39_23. 100%[===========] 67.33M 65.9MB/s in 1.05
2024-05-04 15:06:52 (65.9 MB/s) - 'Miniconda3-py39_23.3.1-0-Linux-x86_64.sh' saved [70605094/70605094]
PREFIX=/usr/local
Unpacking payload ...
Installing base environment...

Downloading and Extracting Packages
```

(중략. 'y/n'를 물어 보면 'y')

```
3.41.1-h5eee18b_U -> 3.45.3-h5eee18b_U
 tqdm
                           4.65.0-py39hb070fc8_0 -> 4.66.2-py39h2f386ee_0
                              2023c-h04d1e81_0 -> 2024a-h04d1e81_0
 tzdata
                         1.26.15-py39h06a4308_0 -> 2.1.0-py39h06a4308_1
 urllib3
                            5.2.10-h5eee18b 1 -> 5.4.6-h5eee18b 1
                            1.2.13-h5eee18b 0 -> 1.2.13-h5eee18b 1
 zstandard
                            0.19.0-py39h5eee18b_0 -> 0.22.0-py39h2c38b39_0
Proceed ([y]/n)? y
  Proceed ([y]/n)? y
  Downloading and Extracting Packages
  Preparing transaction: done
  Verifying transaction: done
  Executing transaction: done
```

(중략)

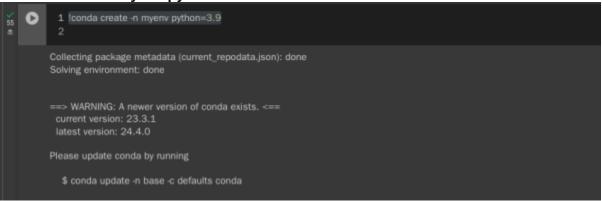


import sys

sys.path.append('/usr/local/lib/python3.9/site-packages')

```
[5] 1 import sys
2 sys.path.append('/usr/local/lib/python3.9/site-packages')
3
```

!conda create -n myenv python=3.9



(중략. 'y/n' 물어보면 'y')

```
sqlite pkgs/main/linux-64::sqlite-3.45.3-h5eee18b_0
tk pkgs/main/linux-64::tk-8.6.12-h1ccaba5_0
tzdata pkgs/main/noarch::tzdata-2024a-h04d1e81_0
wheel pkgs/main/linux-64::wheel-0.43.0-py39h06a4308_0
xz pkgs/main/linux-64::xz-5.4.6-h5eee18b_1
zlib pkgs/main/linux-64::zlib-1.2.13-h5eee18b_1

Proceed ([y]/n)? y
```

(중략)

```
pip-23.3.1 | 2.6 MB |: 100% 1.0/1 [00:00<00:00, 1.32it/s]

Preparing transaction: done
Verifying transaction: done
Executing transaction: done
#
# To activate this environment, use
#
# $ conda activate myenv
#
# To deactivate an active environment, use
#
# $ conda deactivate
```

%%shell eval "\$(conda shell.bash hook)" conda activate myenv pip install tflite-model-maker



(중략)

```
Building wheels for collected packages: fire, kaggle, promise
Building wheel for fire (setup.py) ... done
Qreated wheel for fire: filename—fire 0.6.0-py2.py3-none-any.whl size=117029 sha256=3371e5ea60826a2e390411e04f787710477e7cc0ca4ad3f1a65cd469a8c6949a
Stored in directory: /root/.cache/pip/wheels/ec/ce/ba/9d5764d2266c500c18776c7d8f1e3c023075994cbc6dea47db
Building wheel for kaggle: (setup.py) ... done
Created wheel for kaggle: (setup.py) ... done
Created wheel for kaggle: (setup.py) ... done
Building wheel for promise (setup.py) ... done
Created wheel for promise: (laname=promise-2.3-py3-none-any.whl size=21483 sha256=fd6a9f0686c725eed722a20cee6fc9b86baf9644876ca7ccde6508511b272b2d
Stored in directory: /root/.cache/pip/wheels/e1/e8/83/ddea66100678d139b14bc87692ece57c6a2a937956d2532608
Successfully built fire kaggle promise
Installing collected packages: webencodings, text-unidecode, tensorflow-estimator, tensorboard-plugin-wit, sentencepiece, pytz, py-cpuinfo, libclang, keras, gin-config, flatbuffers, dm-tree, dataclast Successfully installed CFFi-1.16.0 Cython-3.0.10 MarkupSafe-2.1.5 PyYAML-6.0.1 absi-py-1.4.0 array-record-0.5.1 astunparse-1.6.3 attrs-23.2.0 audioread-3.0.1 bleach-6.1.0 cachetools-5.3.3 or
WARNING: Running pip as the 'root' user can result in broken permissions and conflicting behaviour with the system package manager. It is recommended to use a virtual environment instead: by
```

%%shell

eval "\$(conda shell.bash hook)" conda activate myenv pip install ipykernel

```
1 %%shell
2 eval "$(conda shell.bash hook)"
3 conda activate myerv
4 pip install ipykernel
5

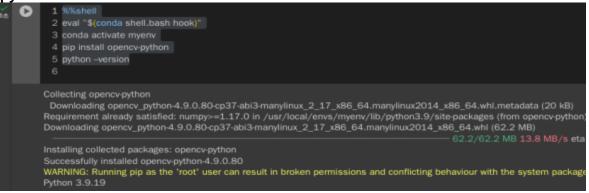
Collecting pexpect>4.3 (from ipython>=7.23.1.>ipykernel)
Downloading pexpect4.9.0-py2.py3-none-any.whl.metadata (2.5 kB)
Requirement already satisfied: importlib-metadata>=4.8.3 in /usr/local/envs/myenv/lib/python3.9/site-packages (from jupyter-client>=6.1.12->ipykernel) (7.1.0)
Requirement already satisfied: python-dateutil>=2.8.2 in /usr/local/envs/myenv/lib/python3.9/site-packages (from jupyter-client>=6.1.12->ipykernel) (2.9.0.post0)
Requirement already satisfied: python-dateutil>=2.8.2 in /usr/local/envs/myenv/lib/python3.9/site-packages (from jupyter-client>=6.1.12->ipykernel) (2.9.0.post0)
Requirement already satisfied: python-20.2 in /usr/local/envs/myenv/lib/python3.9/site-packages (from jupyter-client>=6.1.12->ipykernel) (4.2.1)
Requirement already satisfied: python-20.2 in /usr/local/envs/myenv/lib/python3.9/site-packages (from importlib-metadata>=4.8.3->jupyter-client>=6.1.12->ipykernel) (3
Collecting parso-0.9.0,0.>=0.8.3 (from jedi>=0.16->ipython>=7.23.1->ipykernel)
Downloading parso-0.8.4-py2.py3-none-any.whl.metadata (7.7 kB)
Collecting ptyprocess>=0.5 (from pexpect>4.3->ipython>=7.23.1->ipykernel)
Downloading pytyprocess-0.7.0-py2.py3-none-any.whl.metadata (1.3 kB)
Collecting wewidth (from prompt-toolkit<3.1.0.>=3.0.41->ipython>=7.23.1->ipykernel)
Downloading wewidth (from prompt-toolkit<3.1.0.>=3.0.41->ipython>=7.23.1->ipykernel)
Downloading executing>=1.2.0 (from stack-data->ipython>=7.23.1->ipykernel)
Downloading executing>=1.2.0 (from stack-data->ipython>=7.23.1->ipykernel)
Downloading secuting>=0.1-py2.py3-none-any.whl.metadata (1.0 kB)
Collecting asttokens>=2.1.0 (from stack-data->ipython>=7.23.1->ipykernel)
```

(중략)

```
Downloading astack_data-0.6.3-py3-none-any.whl (24 kB)
Downloading astack_data-0.2.1-py2.py3-none-any.whl (27 kB)
Downloading executing-2.0.1-py2.py3-none-any.whl (24 kB)
Downloading parso-0.8.4-py2.py3-none-any.whl (10 kB)
Downloading ptyprocess-0.7.0-py2.py3-none-any.whl (13 kB)
Downloading ptyprocess-0.7.0-py2.py3-none-any.whl (14 kB)
Downloading pure_eval-0.2.2-py3-none-any.whl (14 kB)
Downloading pure_eval-0.2.2-py3-none-any.whl (14 kB)
Downloading wexiefth-0.2.1-3py2.py3-none-any.whl (14 kB)
Installing collected packages: wexiefth, pure-eval, ptyprocess, traitlets, tornado, pyzmq, pygments, prompt-toolkit, pexpect, parso, nest-asyncio, executing, exceptiongroup, debugpy, asttokens, stack Successfully installed asttokens-2.4.1 comm-0.2.2 debugpy-1.8.1 exceptiongroup-1.2.1 executing-2.0.1 ipykernel-6.29.4 ipython-8.18.1 jedi-0.19.1 jupyter-client-8.6.1 jupyter-core-5.7.2 matplotilibrit WARNING: Running pip as the 'root' user can result in broken permissions and conflicting behaviour with the system package manager. It is recommended to use a virtual environment instead: https://doi.org/10.1001/pygmanager.
```

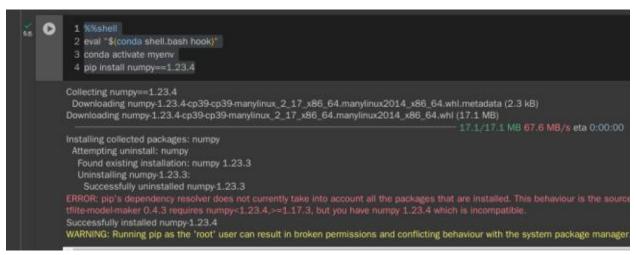
%%shell

eval "\$(conda shell.bash hook)" conda activate myenv pip install opency-python python -version



%%shell

eval "\$(conda shell.bash hook)" conda activate myenv pip install numpy==1.23.4



('ERROR'는 무시)

%%shell
eval "\$(conda shell.bash hook)"
conda activate myenv
pip install pycocotools



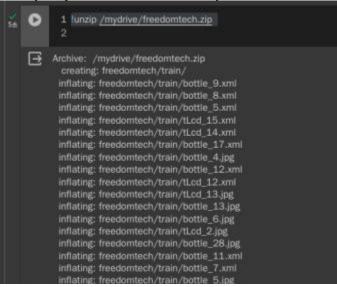
from google.colab import drive drive.mount('/content/gdrive')
!In -s /content/gdrive/My\ Drive/ /mydrive
!ls /mydrive

. 승인 필요 (뜨는 창에서 '구글드라이브 연결' 선택 후, 내 구글 계정을 선택하고 계속 'continue')



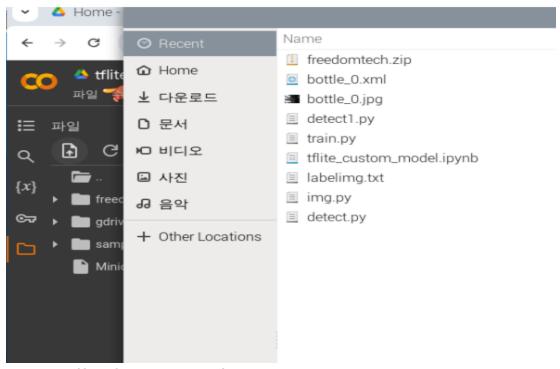
```
0
      1 from google.colab import drive
      2 drive.mount('/content/gdrive')
      3 IIn-s /content/gdrive/My\ Drive/ /mydrive
     Mounted at /content/gdrive
     07_OpenCV.pptx
                                        SafeDriving1213.zip
     20231122_DogCat1.ipynb
     'Ch05 GUI_64bit2.docx'
'Ch05 GUI_64bit2.pdf'
                                        Sample_Yolov5.ipynb
                                        'SciTech2025 Fighter.pdf'
                                  ssd_mobilenet_v2_fpnlite_320x320_coco17_tpu-8
     'Colab Notebooks'
     detect hands1
                                    TensorFlowImgClass.ipynb
     'Dog-Cat classification 20231030.ipynb' test
     egohands
                                    TF2_1130.ipynb
     ICSEng_2023_Proceedings.pdf
                                        TF2_custom_221213.ipynb
     images.zip
                                  TF2_safeDrive_221202.ipynb
     'JGCD LSFMRIVreviwers.txt'
                                         TF2_TFRecord_20221203.ipynb
     layoutwindow1.py
                                   tflite_custom_model.ipynb
     Lee1.ipynb
                                   train.record
     MNIST_TF.ipynb
                                     Untitled0.ipynb
     models
                                  Untitled2.ipynb
                                        Untitled3.ipynb
     SafeDrive211030.ipynb
     SafeDrive230114.v2i.yolov5pytorch.zip
                                            Untitled4.ipynb
     SafeDrive_class_1121.ipynb
                                        Untitled5.ipynb
     safeDrive_label_map.pbtxt
                                         Yolov5_230131_SafeDrive.ipynb
```

!unzip /mydrive/freedomtech.zip

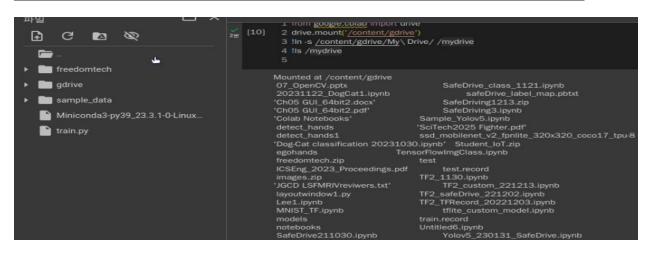


(중략. 좌측 폴더에 'freedomtech' 만들어짐)

. 좌측 노란 폴더를 클릭('/content'가 최상위 폴더임)하고 상단의 위쪽 화살표(파일열기)를 클릭하여 train.py 를 선택하고 하단의 'open'를 클릭하여 train.py 를 읽어 들임



(뜨는 경고창은 '확인' 누르고 무시)



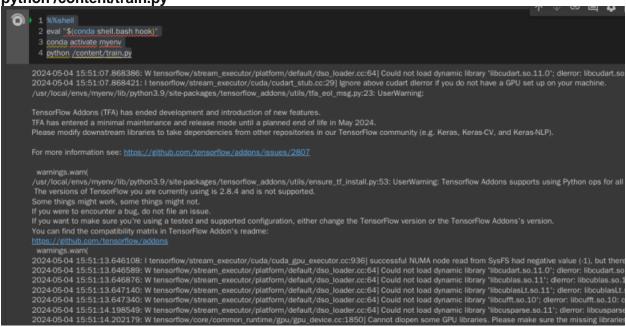
. train.py 를 클릭해서 class 이름 변경 (train_data 및 val_data 에서 'bottle', 'lcd'로 변경)

```
train.py X
17
19 train_data = object_detector.DataLoader.from_pascal_voc(
20
      'freedomtech/train',
21
      'freedomtech/train',
22
      ['bottle', 'lcd']
23)
24
25 val_data = object_detector.DataLoader.from_pascal_voc(
26
      'freedomtech/validate',
27
      'freedomtech/validate'.
28
      ['bottle', 'lcd']
```

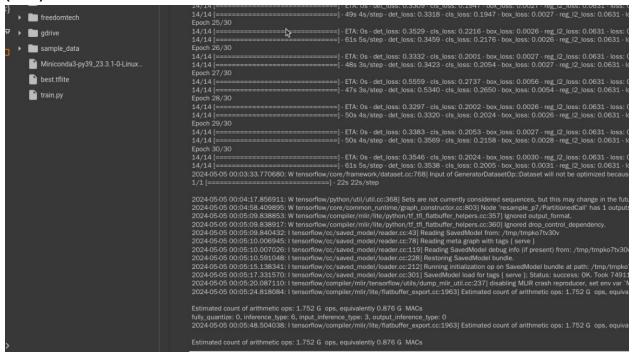
epochs=30 (개인적으로 실행 시 80 으로 변경. 현재는 30 을 유지. 100 으로 하면 90 에서 중단할수 있음)으로 변경후 저장확인(파일이름 좌측 상단의 '*'기호가 사라지면(조금 기다리면) 저장된것임) 후 'x'하여 닫음.

. 학습

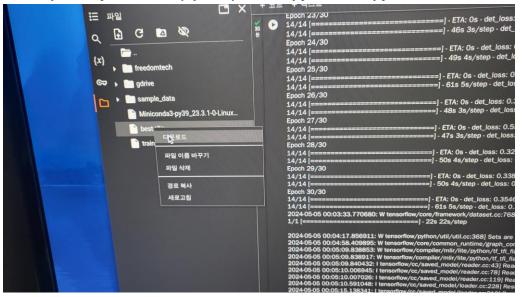
%%shell eval "\$(conda shell.bash hook)" conda activate myenv python /content/train.py

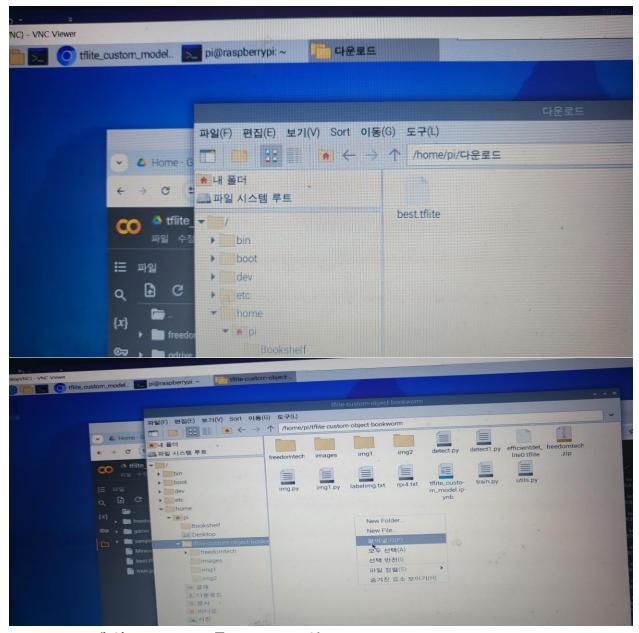


(중략)



. 좌측에 'best.tflite' 가 만들어지면 우측 버턴 '다운로드'하여 home/downloads 로 옮긴 후에 다시 repository 로 옮기고 (update), detect.py, detect1.py 에서 이들로 수정한 후 detect 실행.





. repository 에 있는 detect.py 를 Thonny 로 염



. 파일 수정 (#132 는 comment, #133 은 uncomment)

```
help='Path of the object detection model.',
required=False,
default='efficientdet_lite0.tflite')
default='best.tflite')
parser.add argument(
```

. 실행 (상단 녹색의 우측 화살표 클릭)

```
File Edit View Run Tools Help
detect.py ⋈
            formatter_class=argparse.ArgumentDefaultsHelpFormatter)
 127
 128
        parser.add argument(
 129
            '--model',
            help='Path of the object detection model.',
 131
            required=False,
 132 #
             default='efficientdet lite0.tflite')
 133
            default='best.tflite')
 134
        parser.add argument(
 135
            '--maxResults',
            help='Max number of detection results.',
 136
137
            required=False,
138
            default=5)
 139
        parser.add argument(
 140
            '--scoreThreshold',
 141
            help='The score threshold of detection results.',
 142
            required=False,
 143
            type=float,
144
            default=0.25)
Shell ⋈
 INFU: Created TensorFlow Lite XNNPACK delegate for CPU.
 qt.qpa.plugin: Could not find the Qt platform plugin "wayland" in "/usr/local/lib/python3.11/dist
  /usr/local/lib/python3.11/dist-packages/google/protobuf/symbol_database.py:55: UserWarning: Symbo
  ype() is deprecated. Please use message_factory.GetMessageClass() instead. SymbolDatabase.GetProte
```

