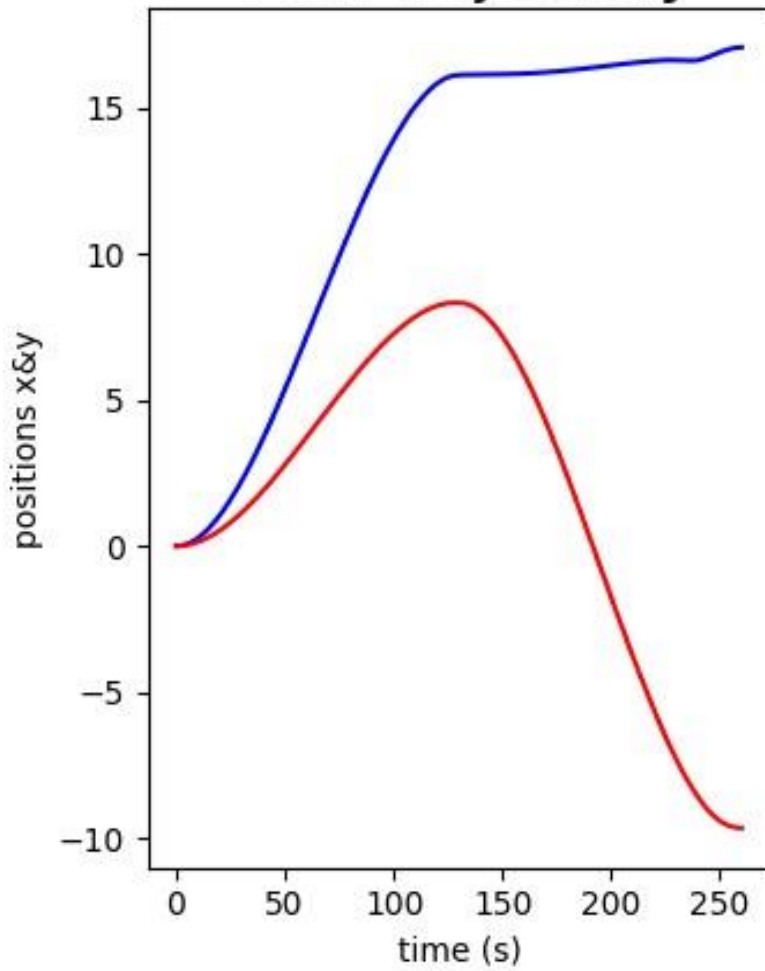
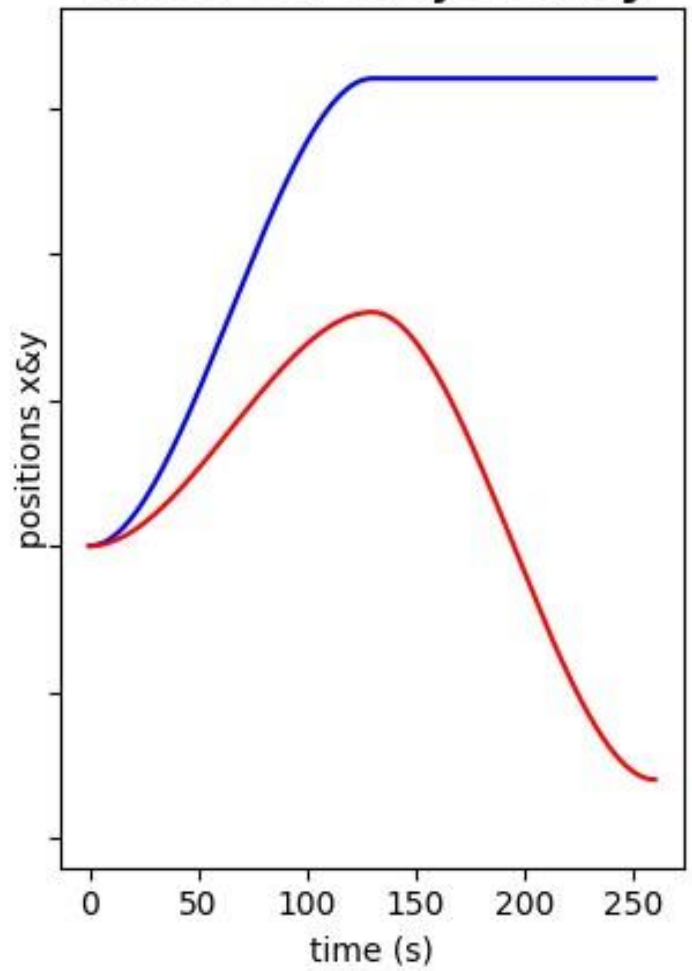


x:blue line    y:red line

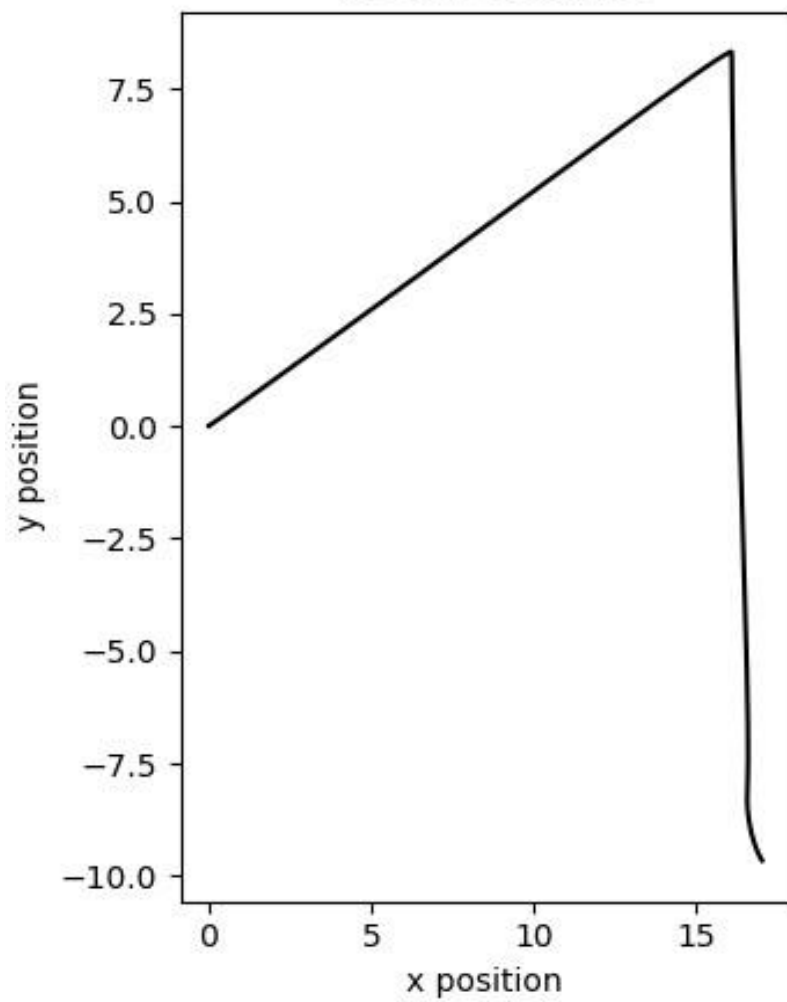
real trajectory



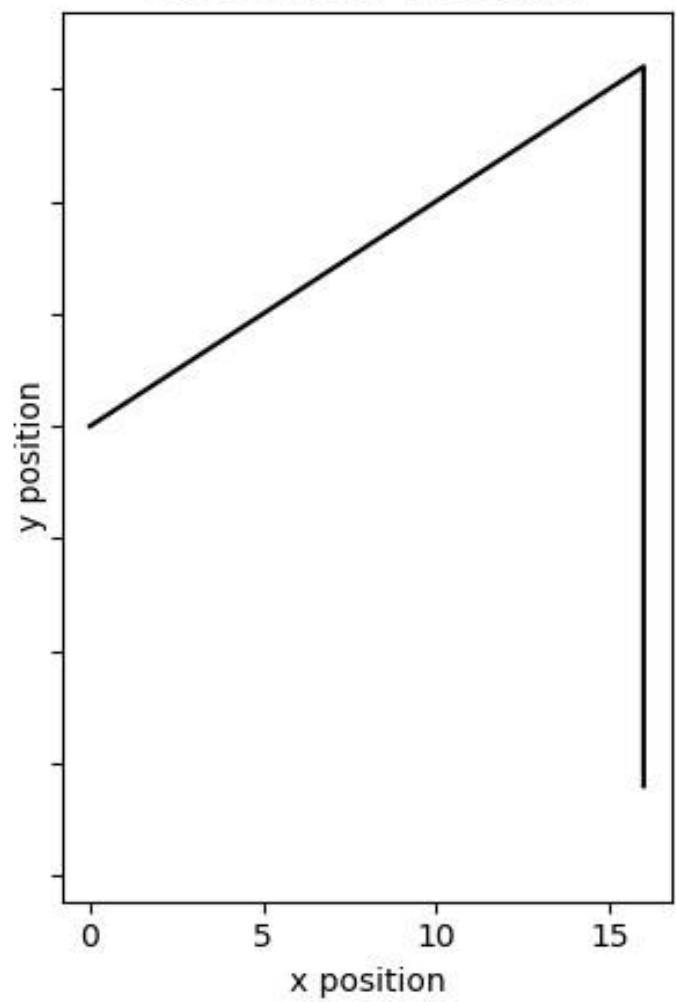
desired trajectory



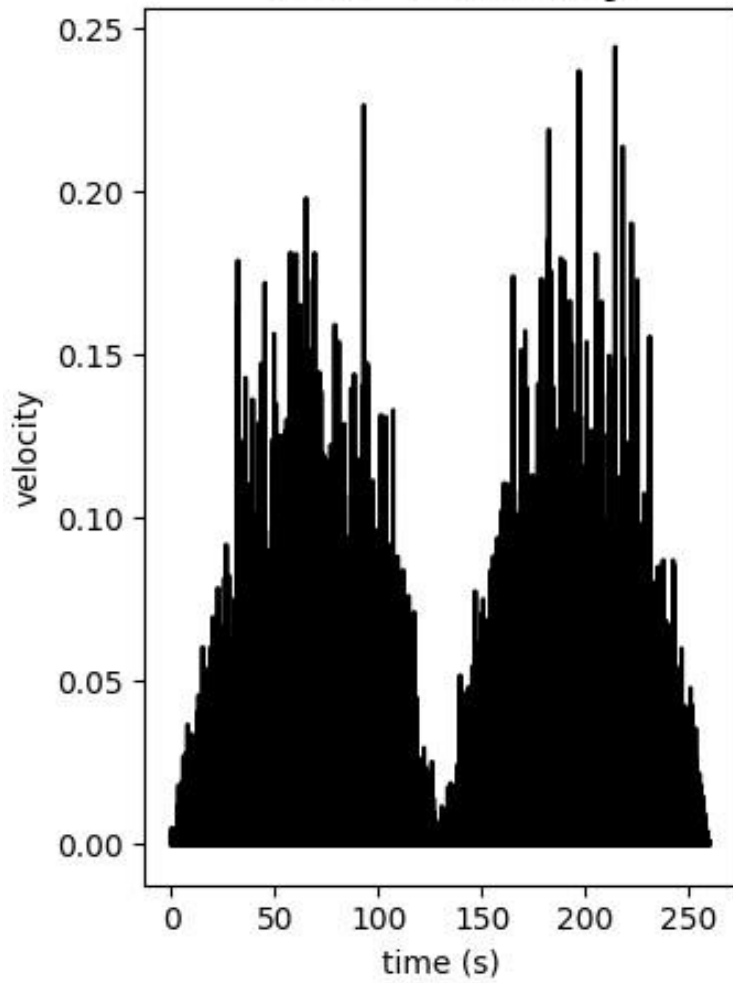
real route



desired route



real velocity



desired velocity

