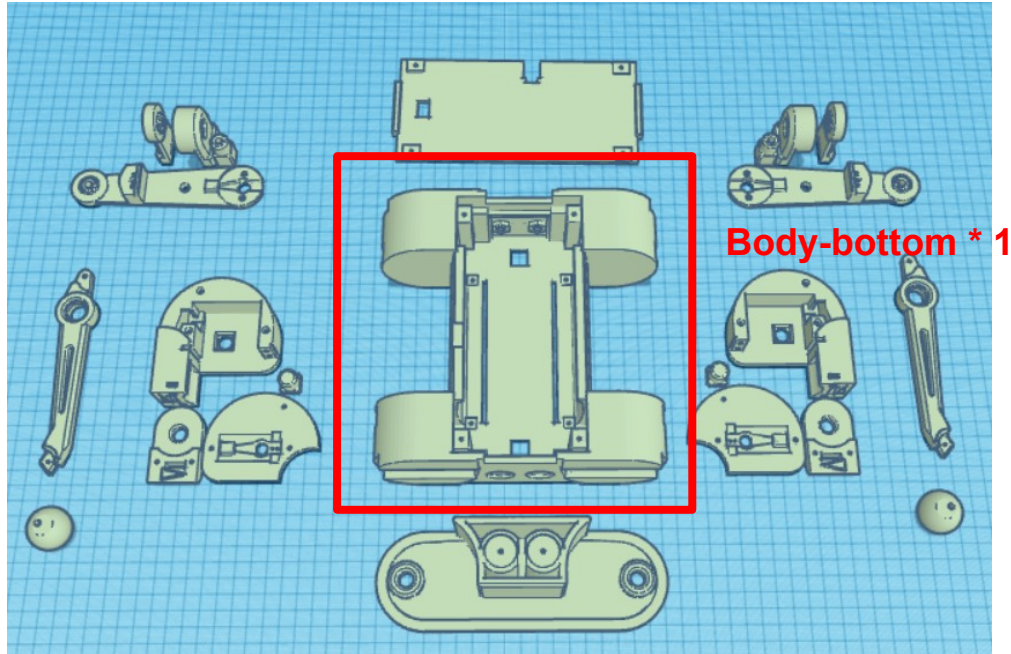
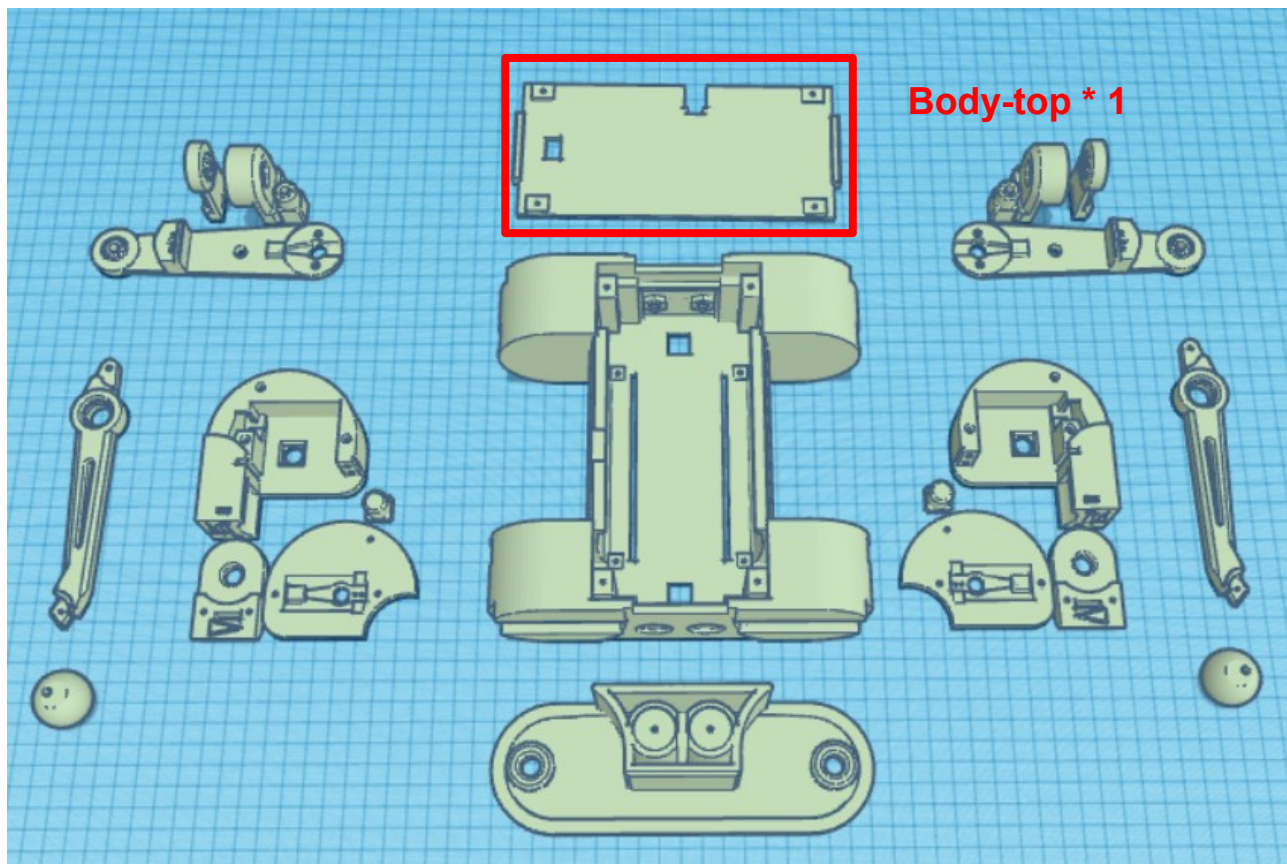
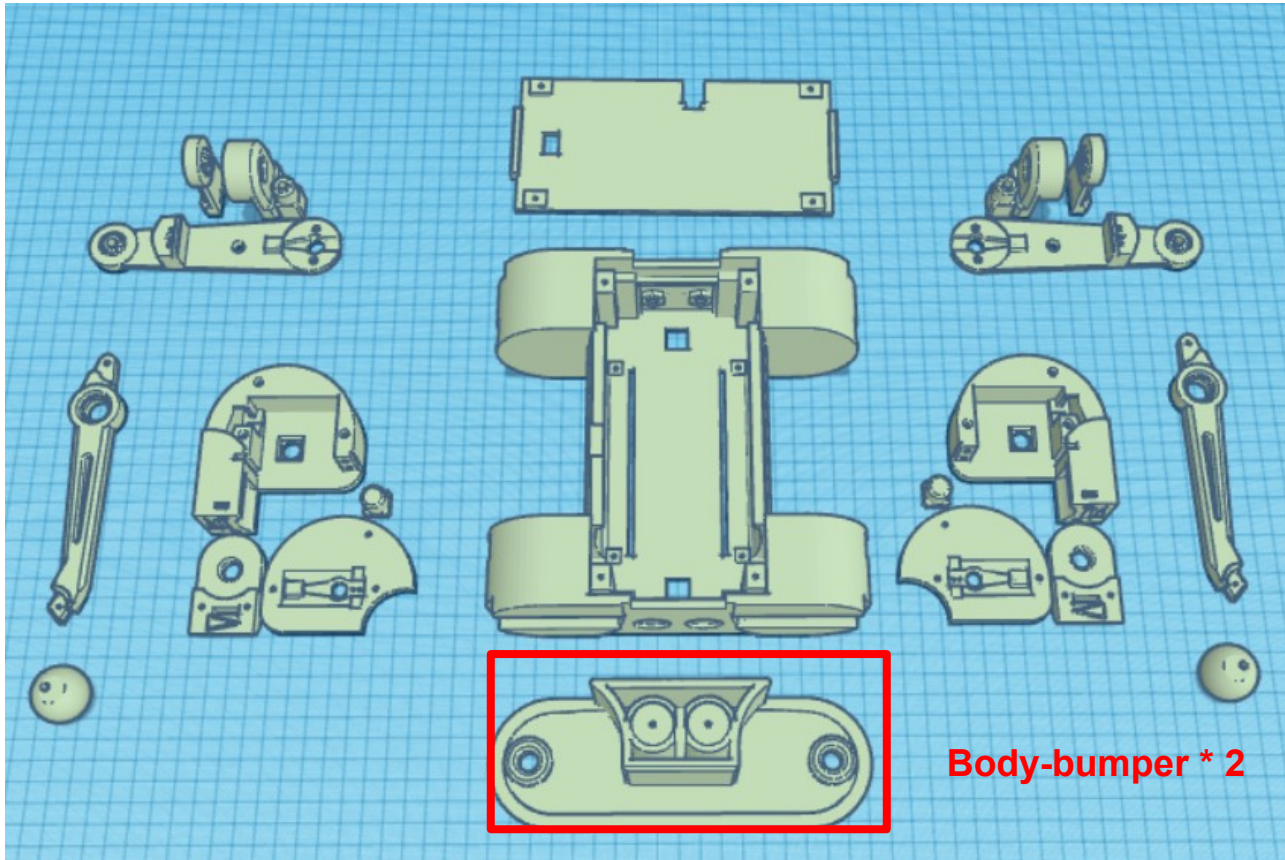


Assembling Step

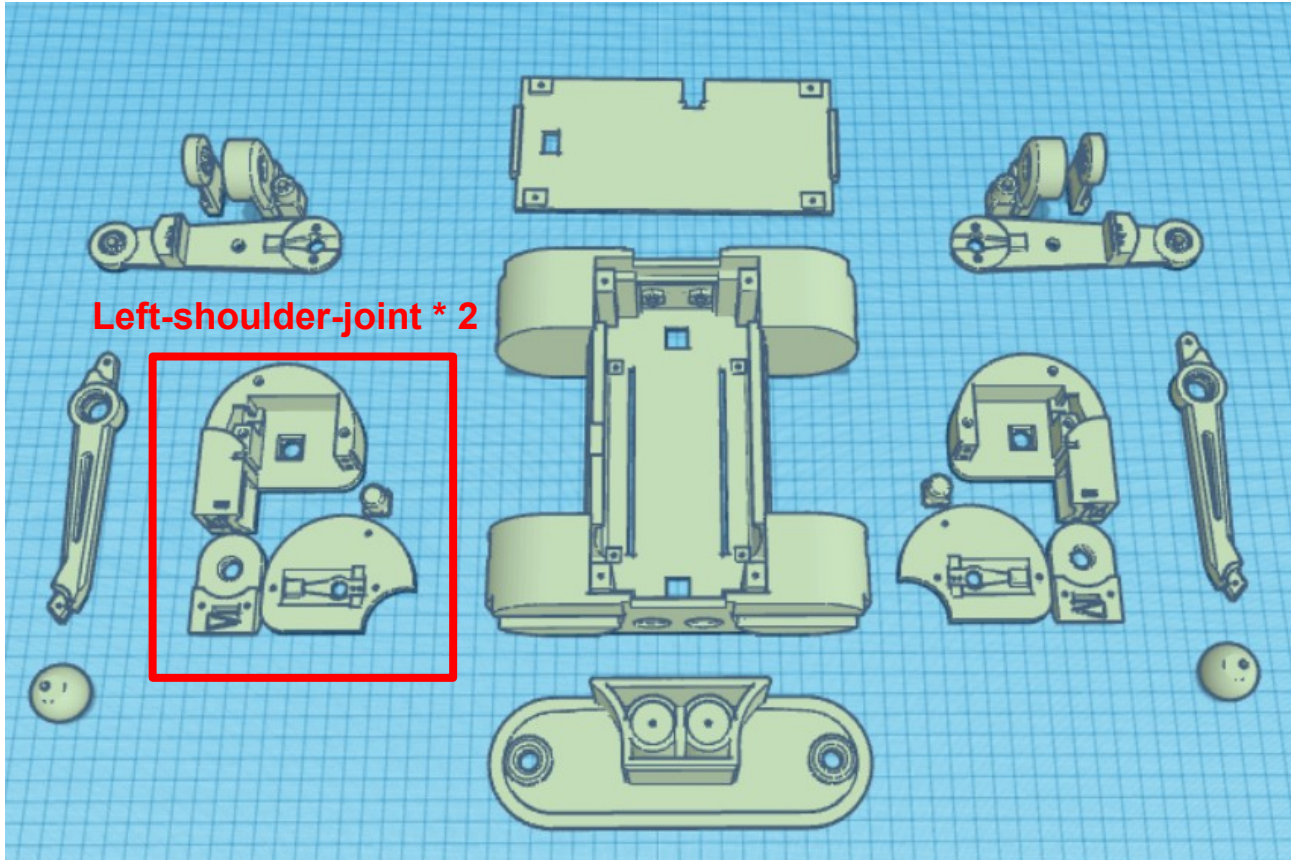
- For the 3d model components, we should have :



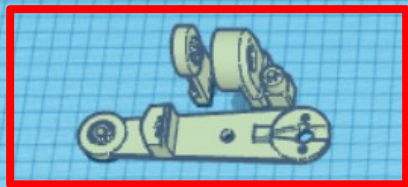




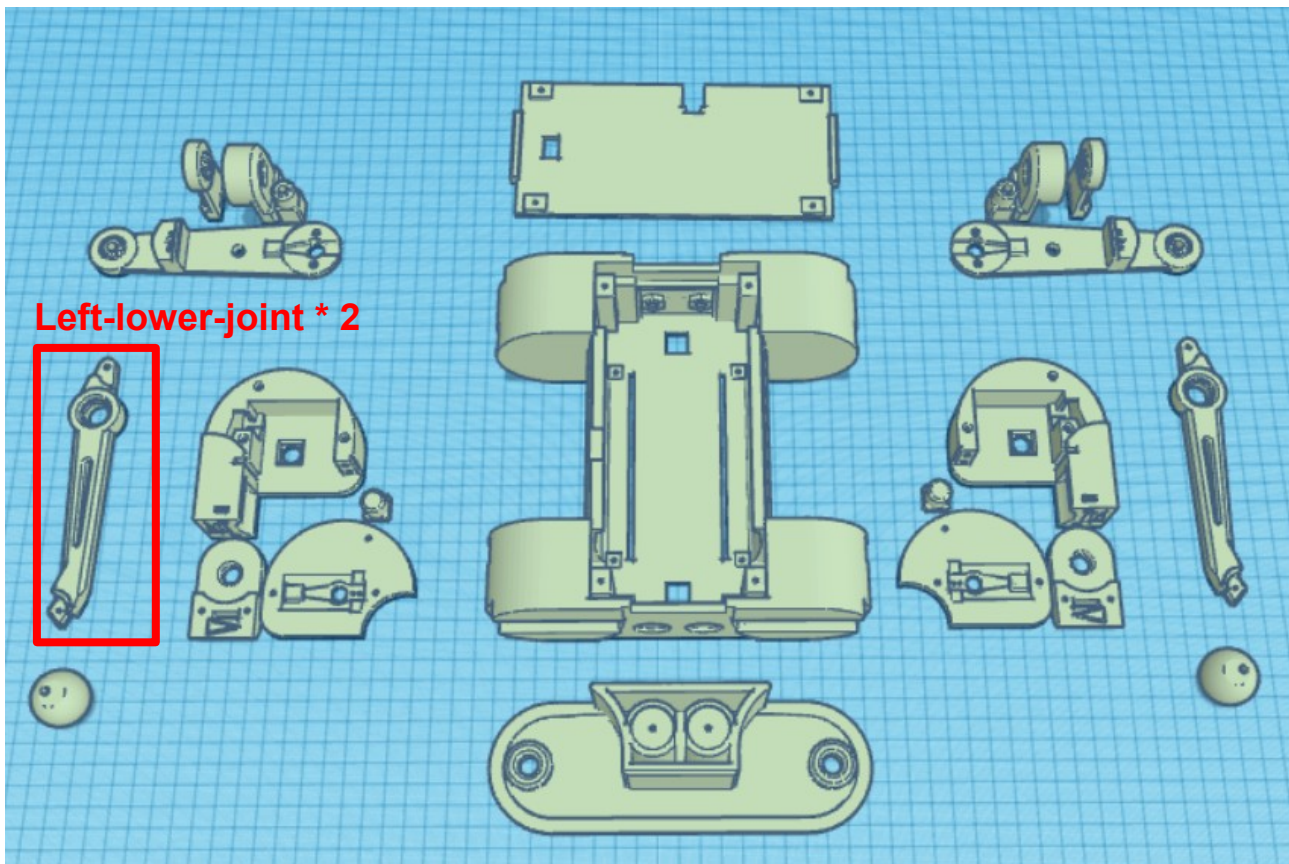
Left-shoulder-joint * 2

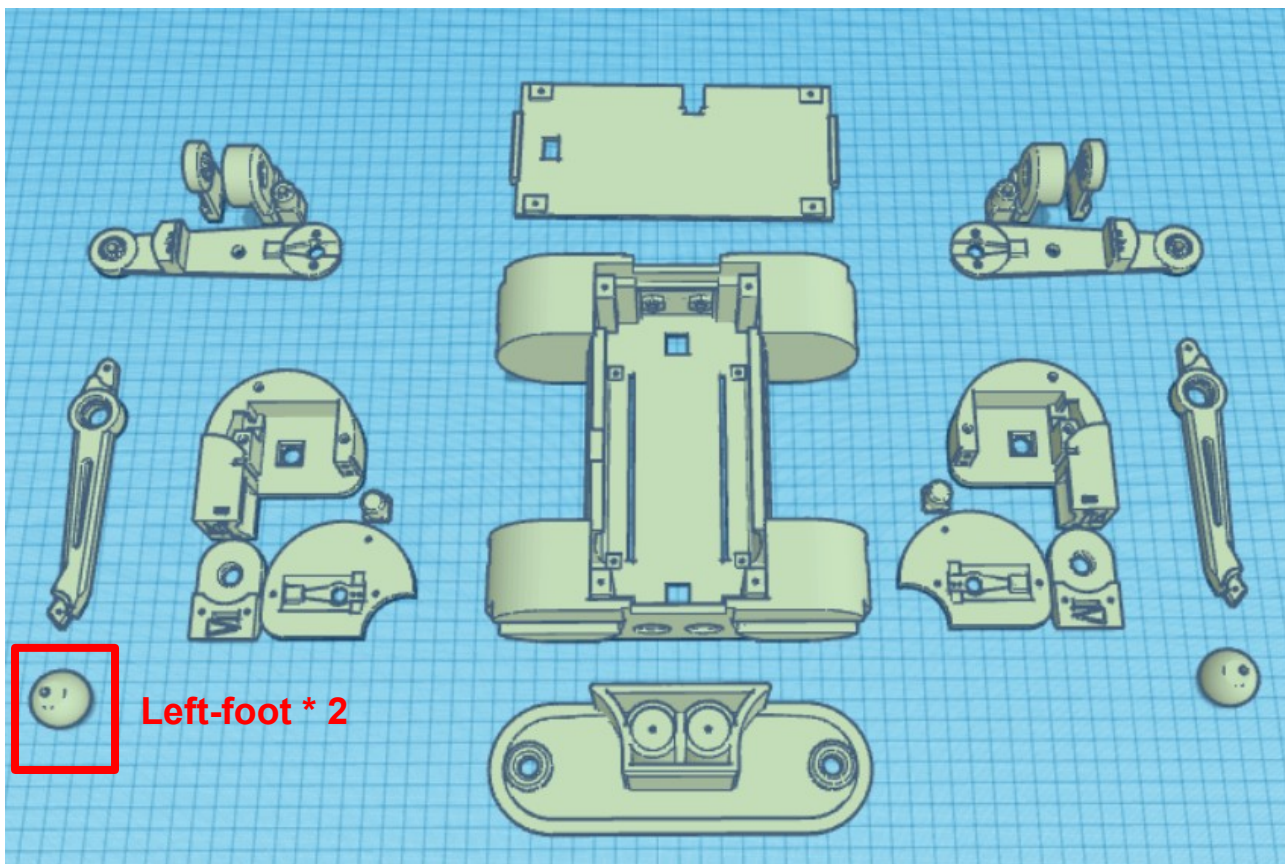


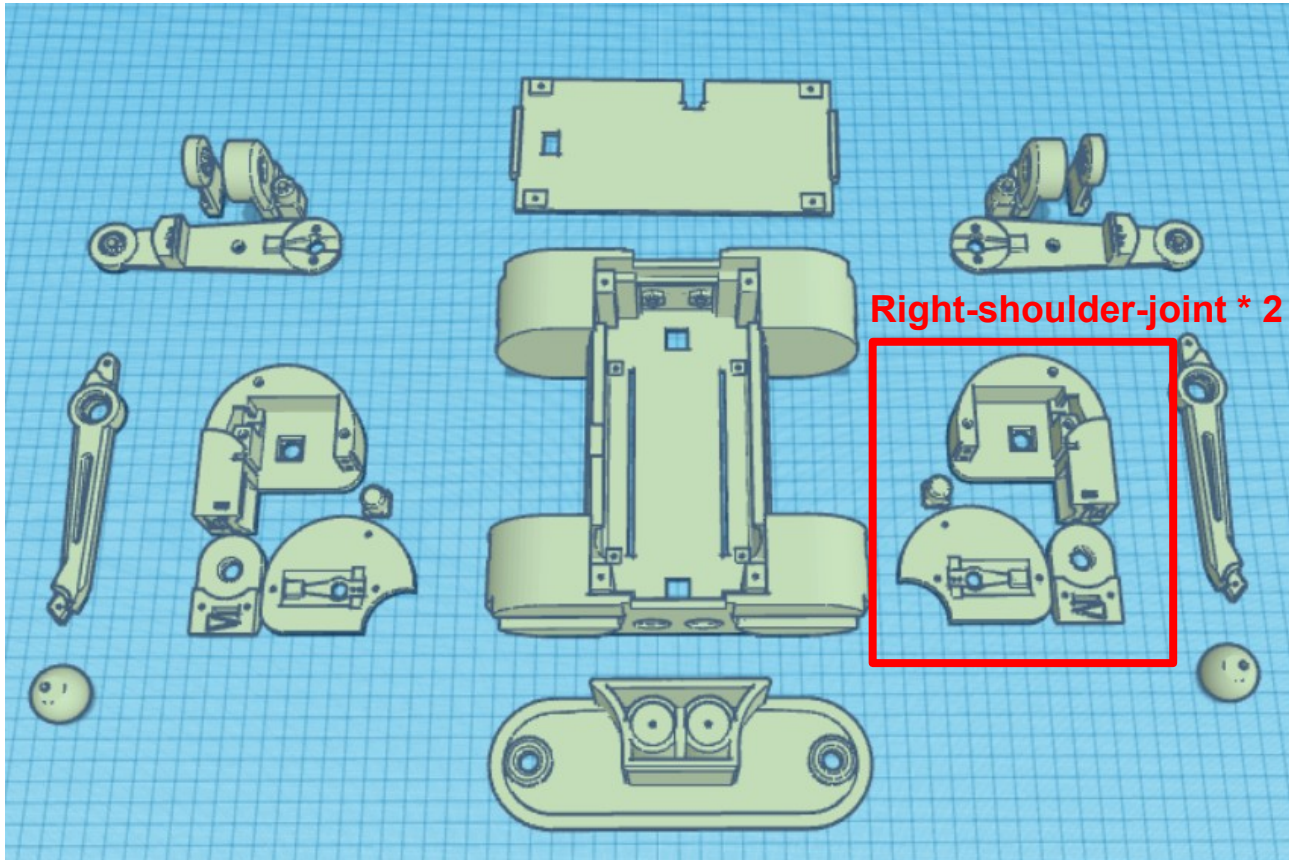
Left-upper-joint * 2

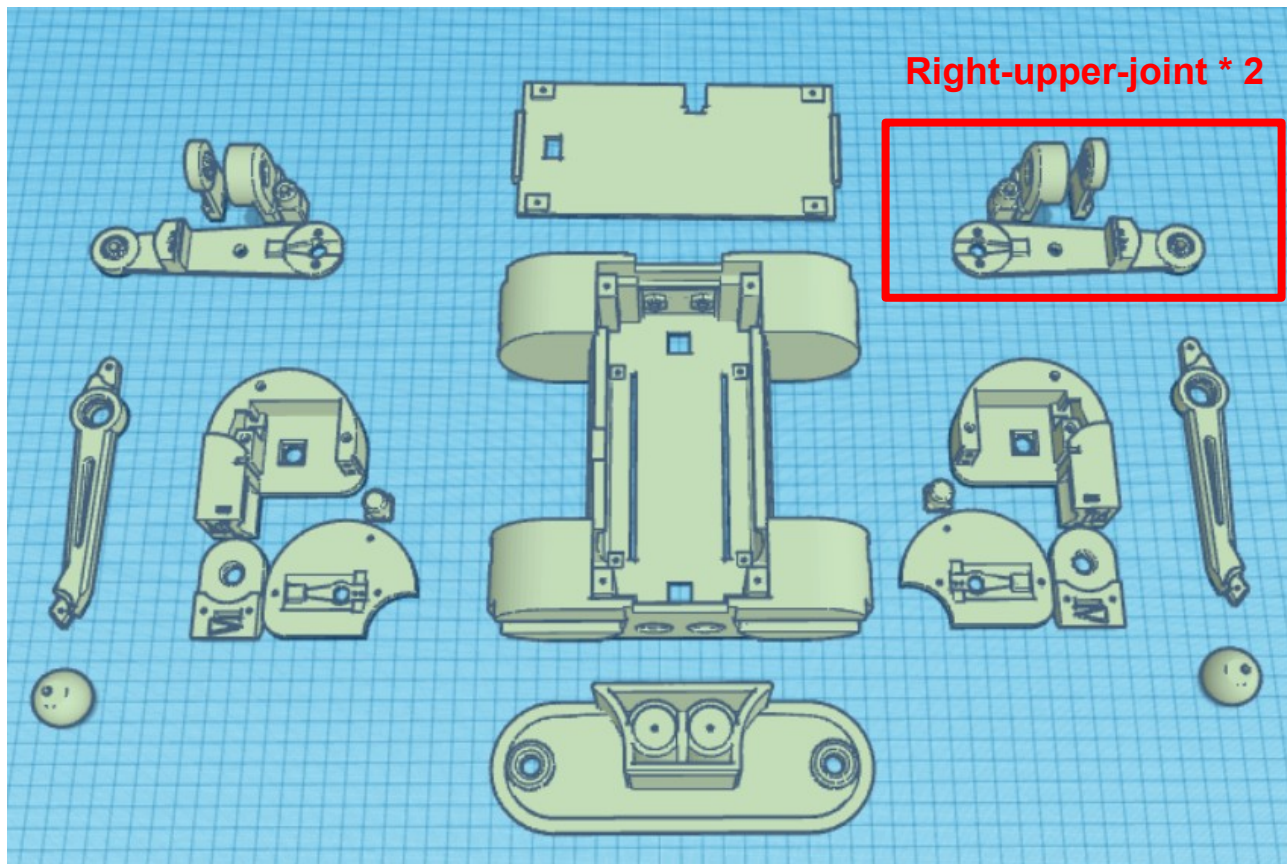


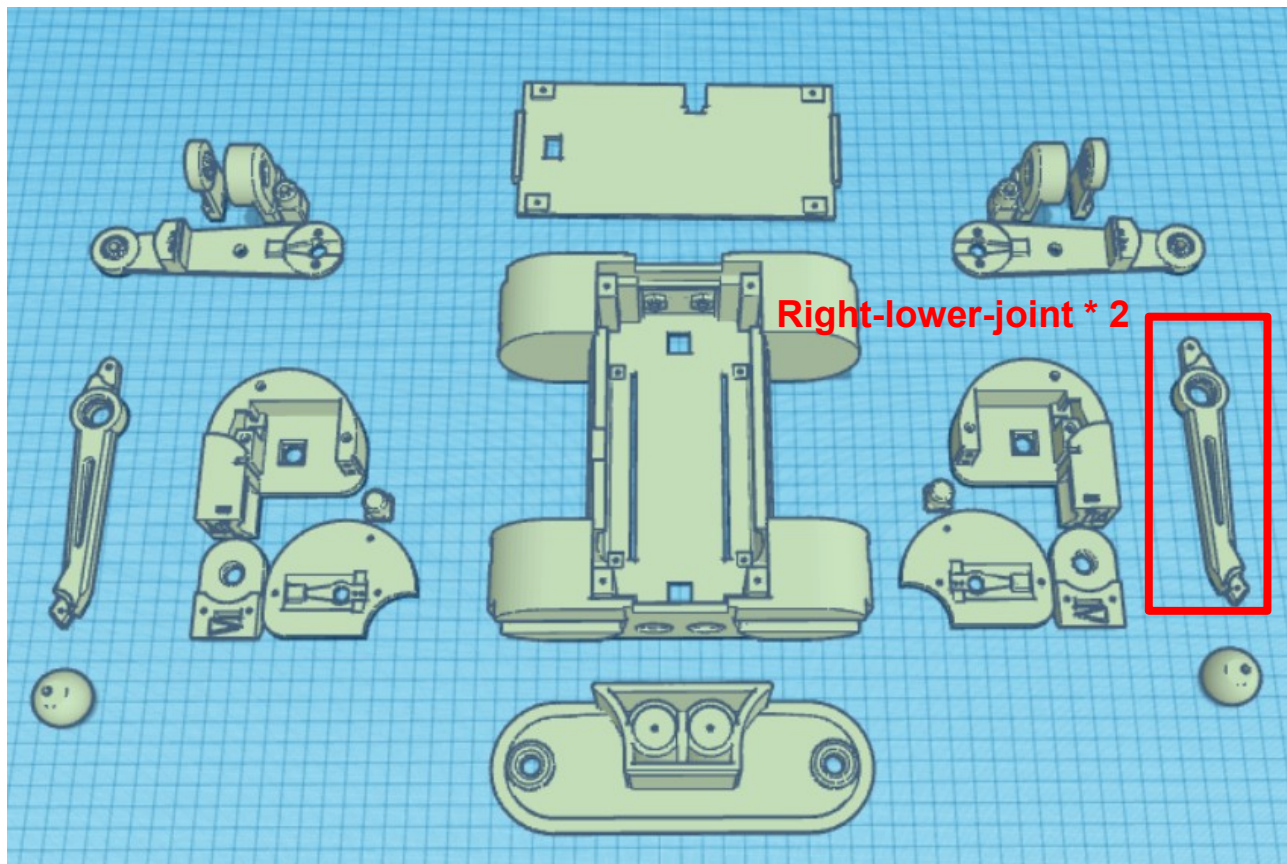
Left-lower-joint * 2

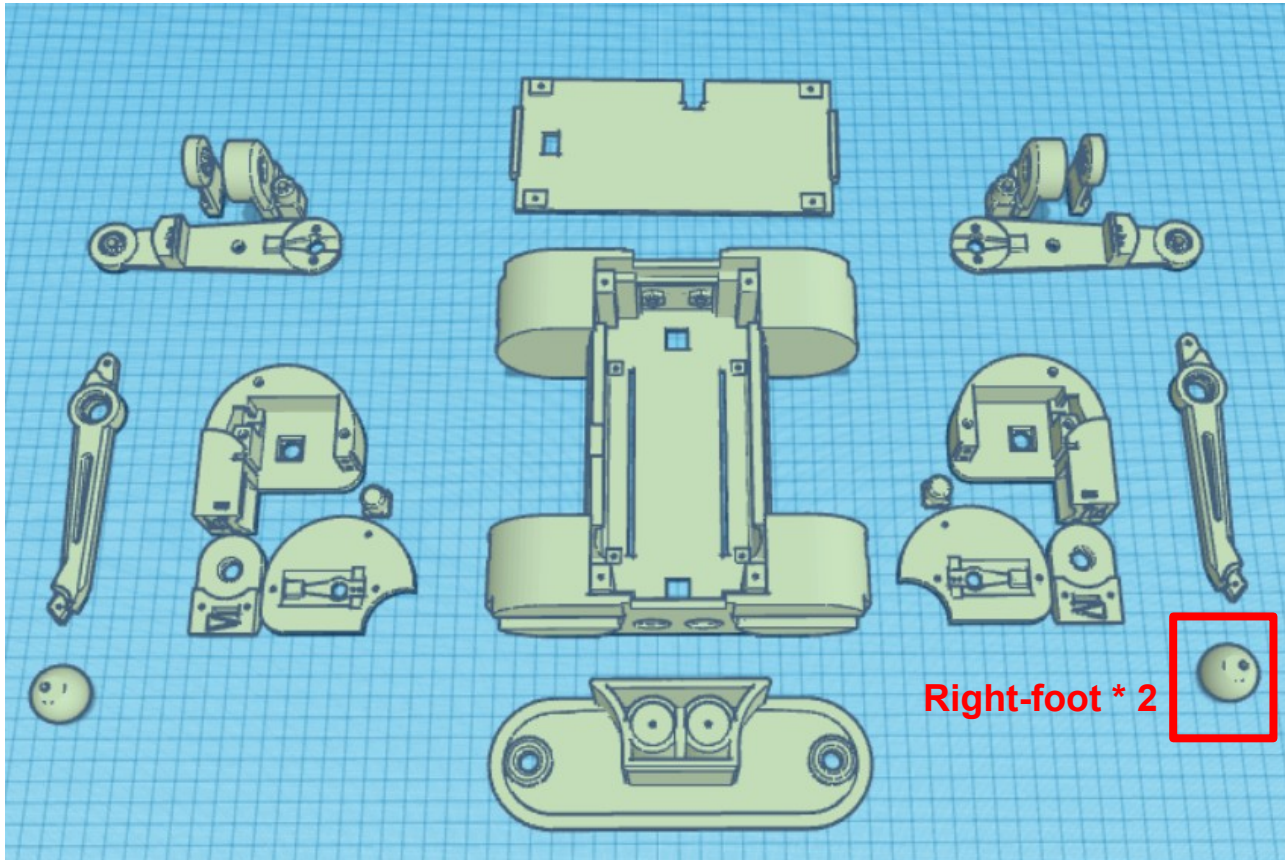








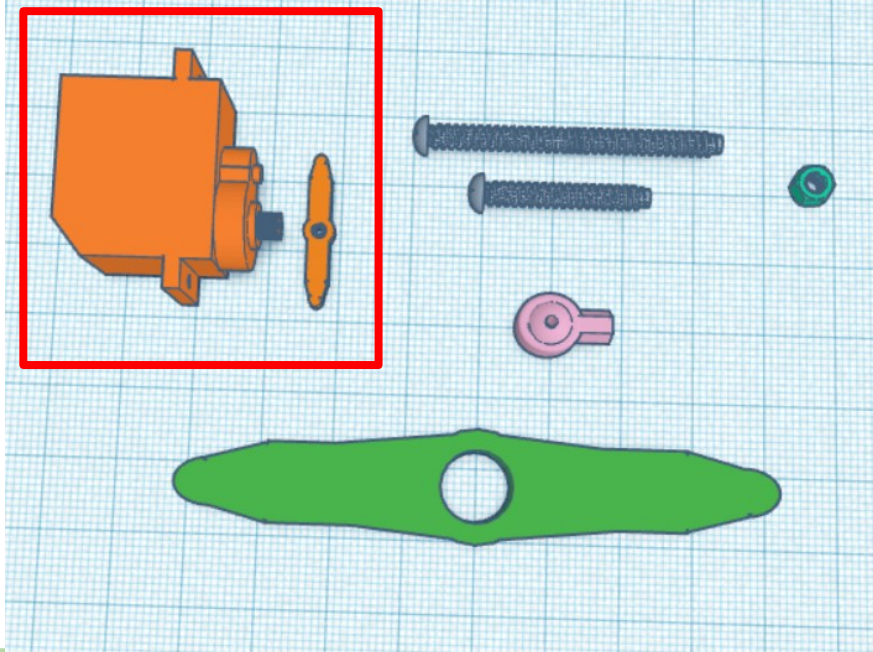




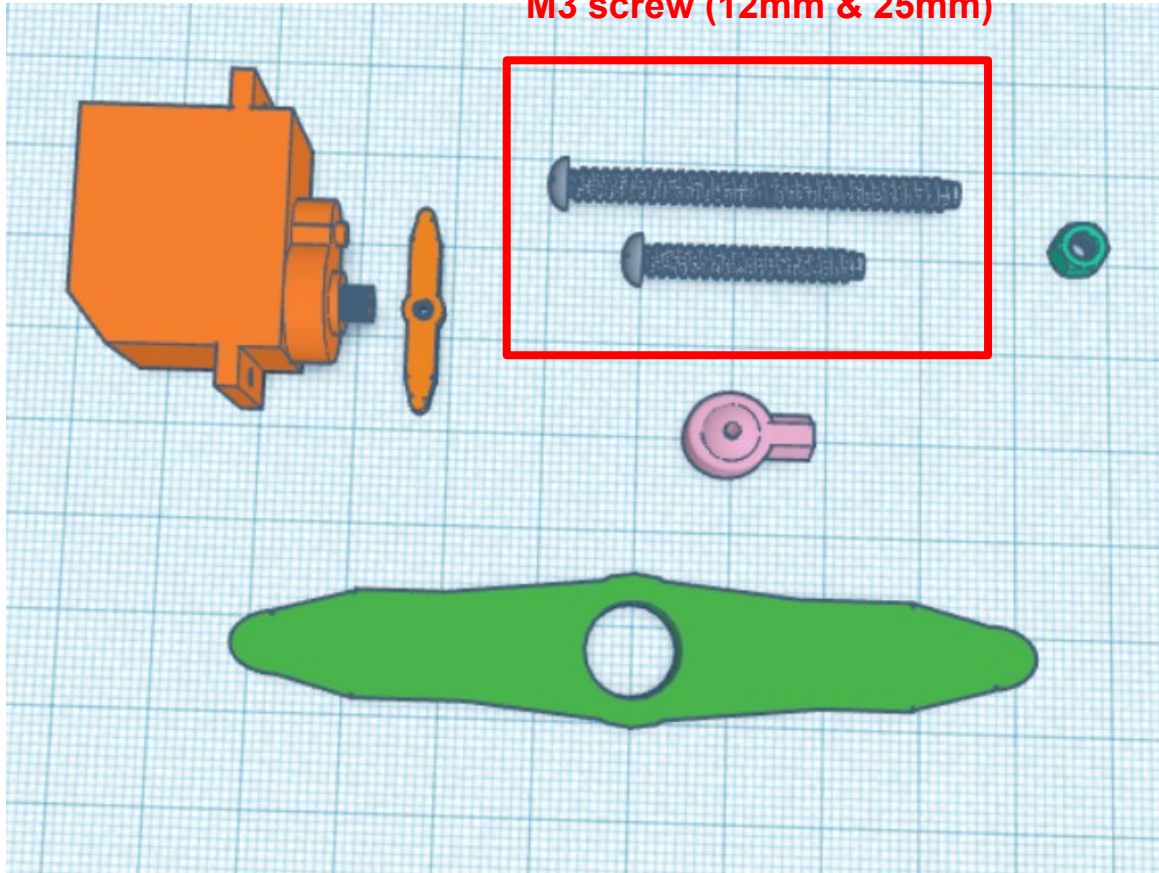
Assemble Step

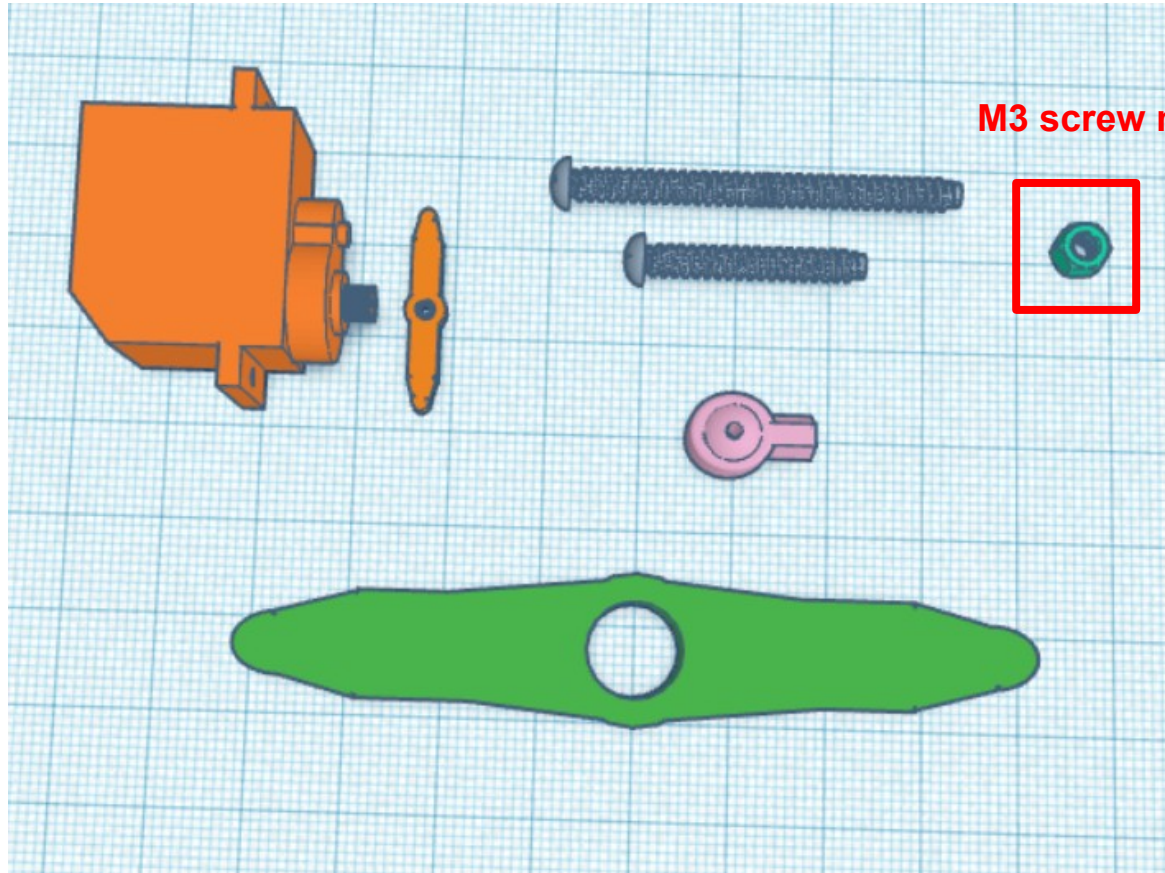
- For the other components, we have :

Servo motor * 12

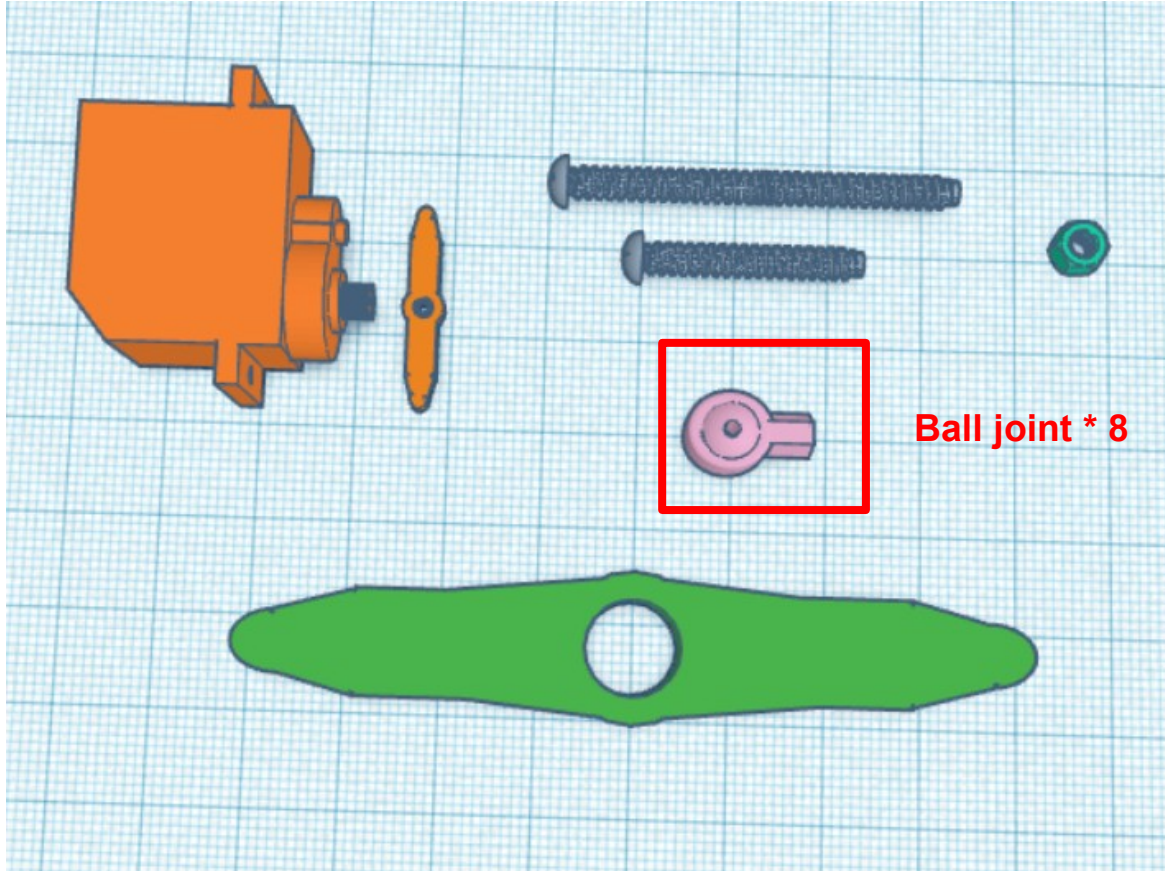


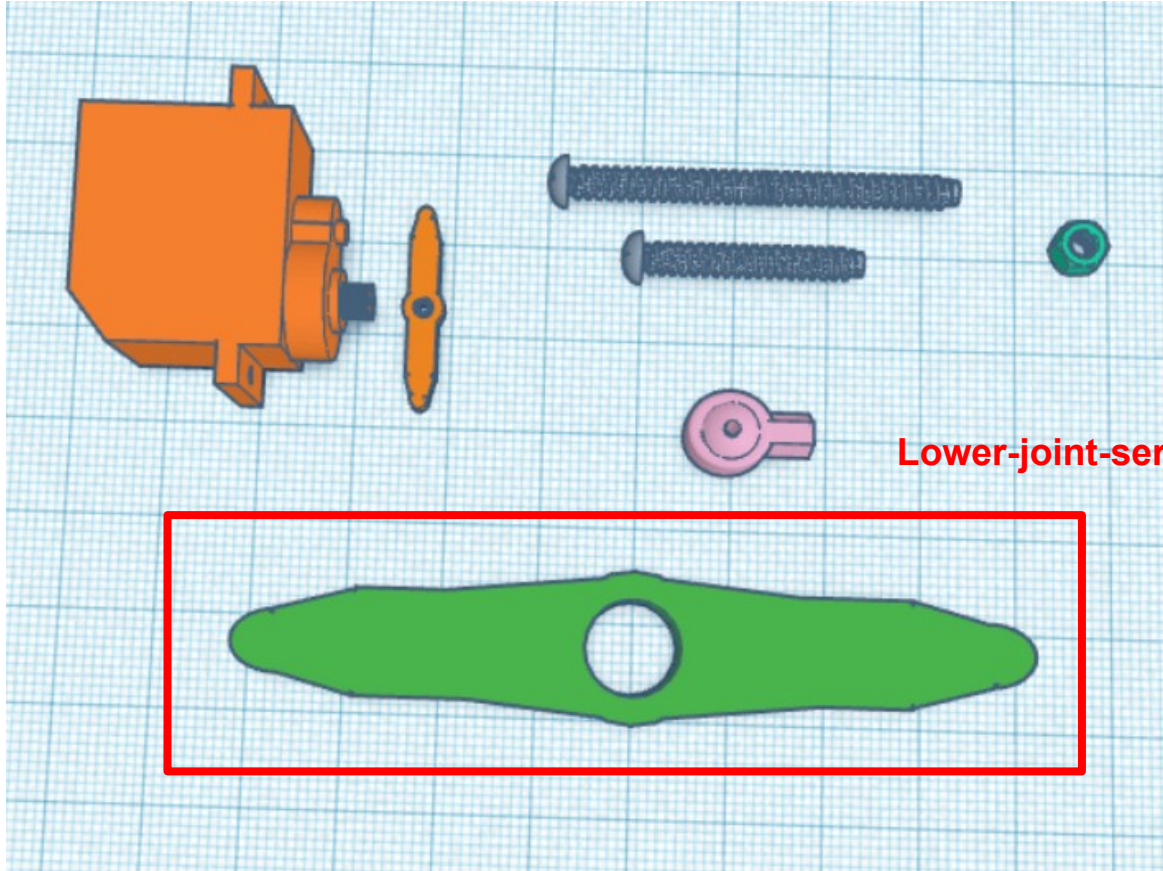
M3 screw (12mm & 25mm)





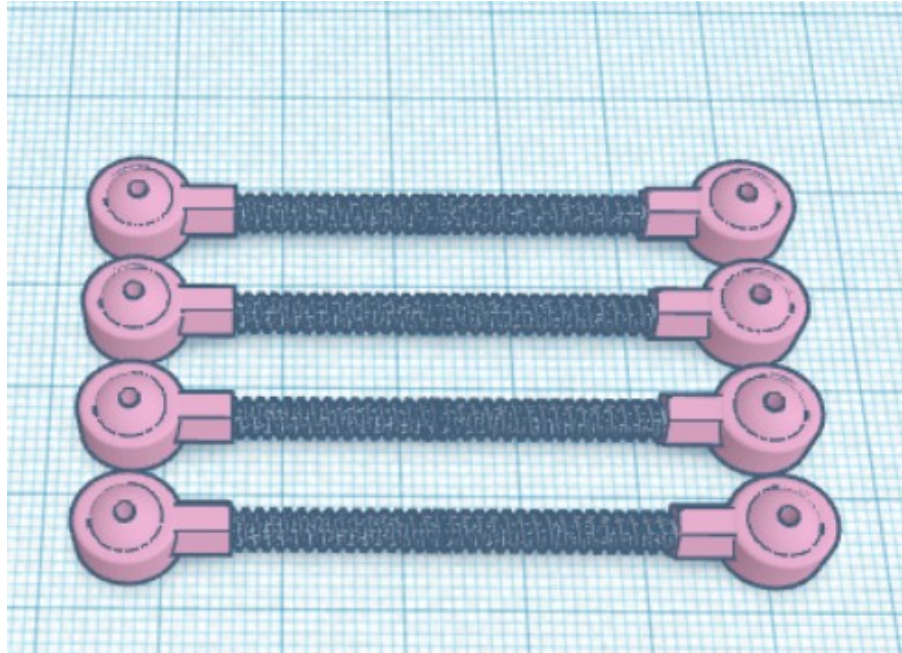
M3 screw nut



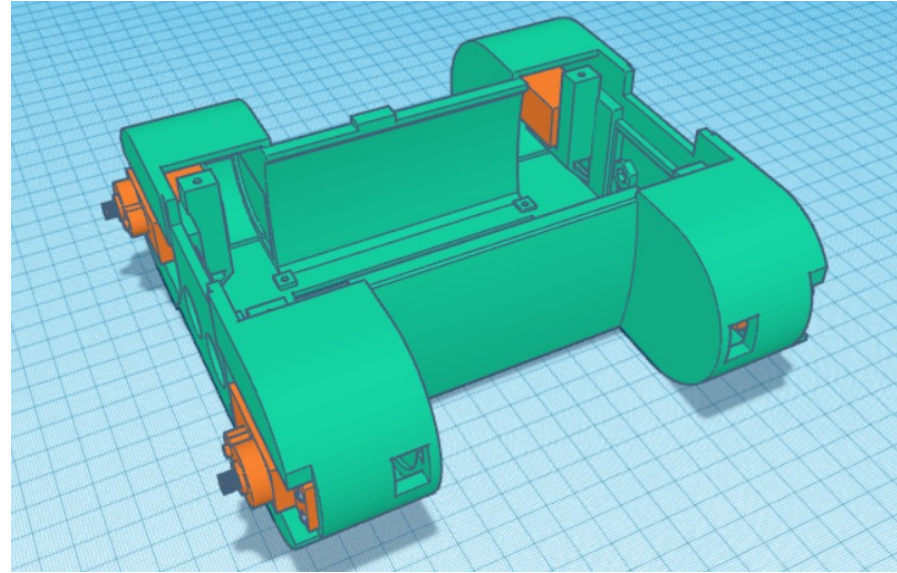
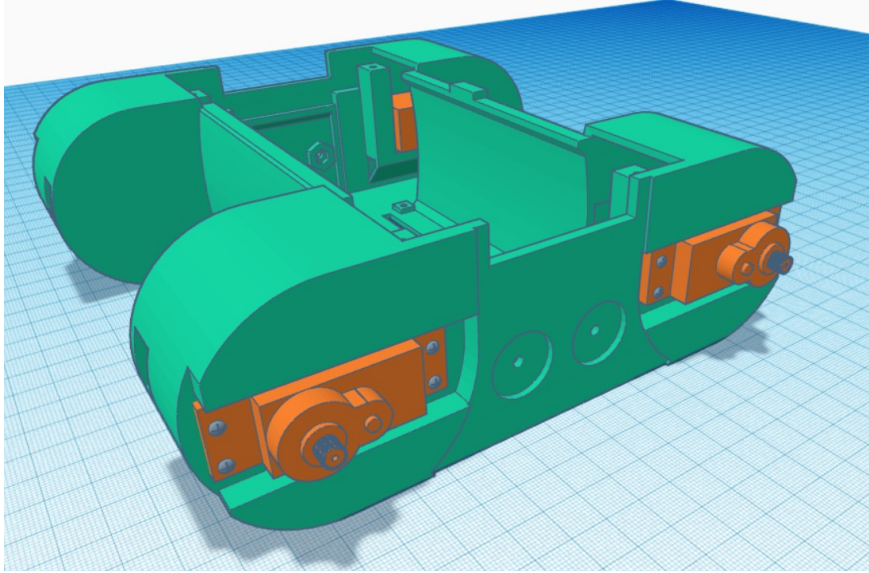


Lower-joint-servo-gear * 4

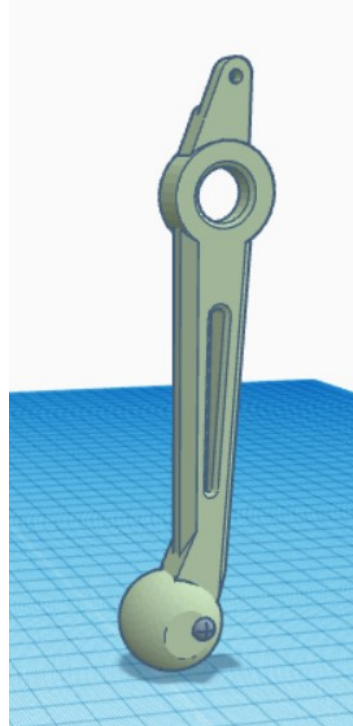
- First we need to cut the M3 screw and put ball joint at its two end
- Repeat four times, make sure they have the same length



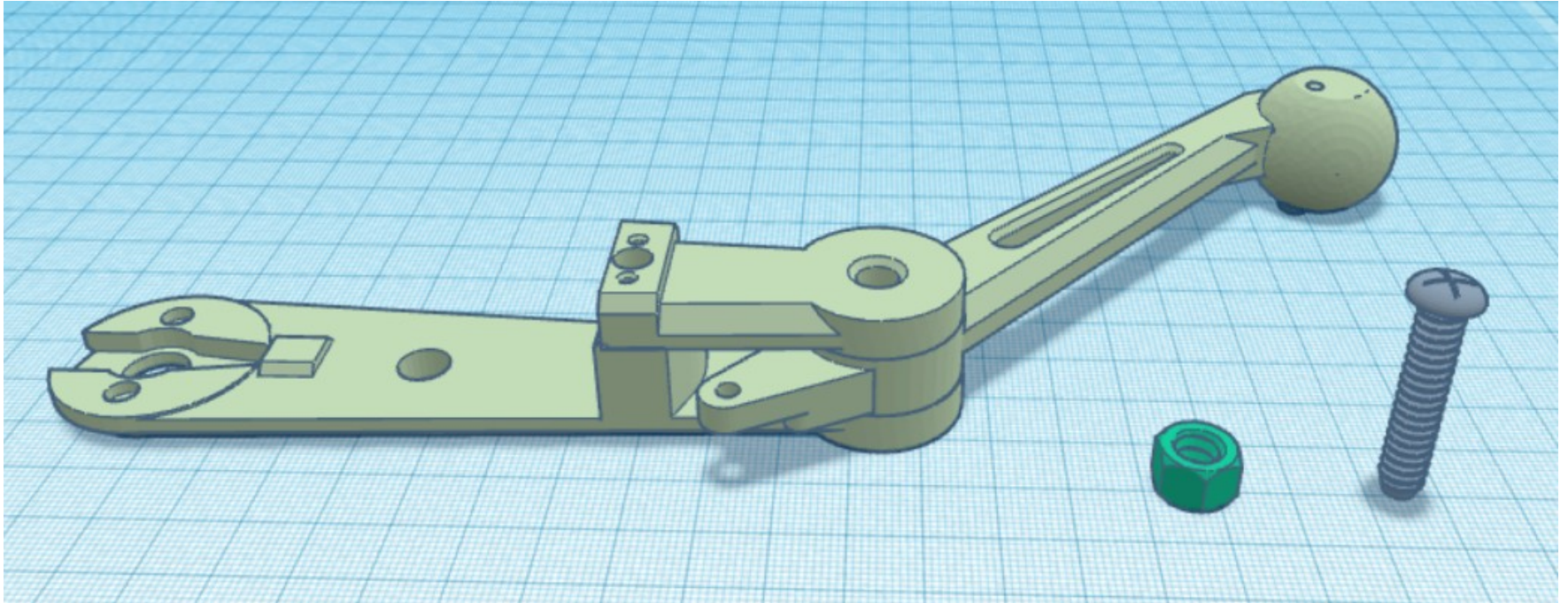
- Next, we work on the body part
- Screw the the body with the servos on each shoulder

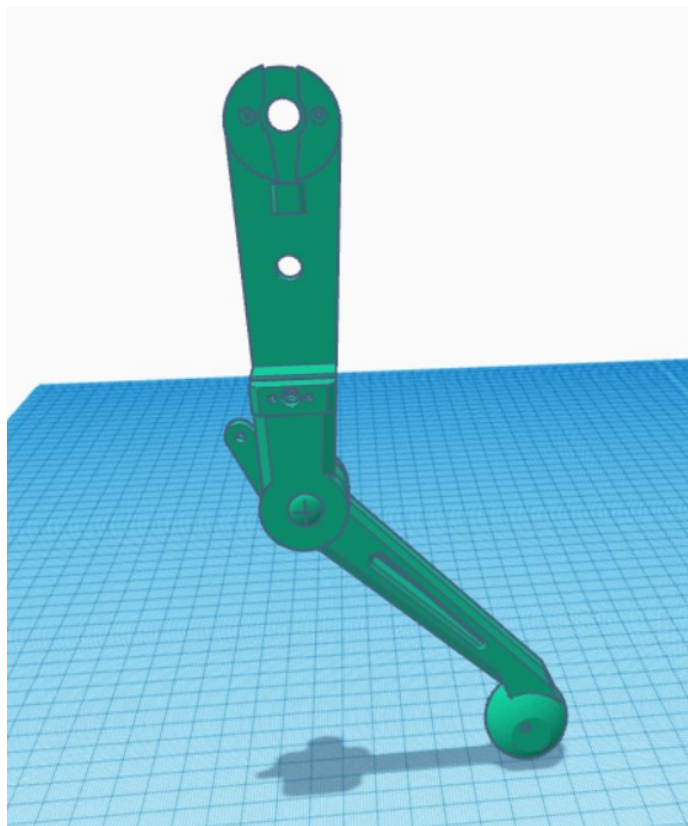


- Then we connect the foot (right) and the lower joint (right)
- Screw them together

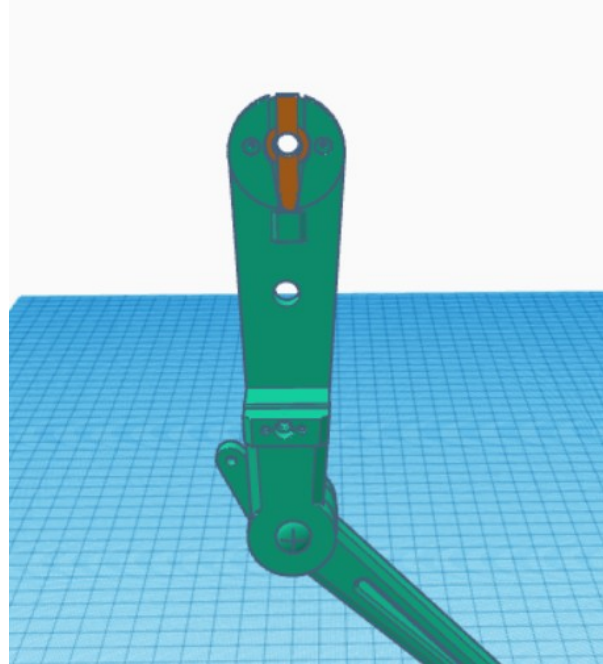
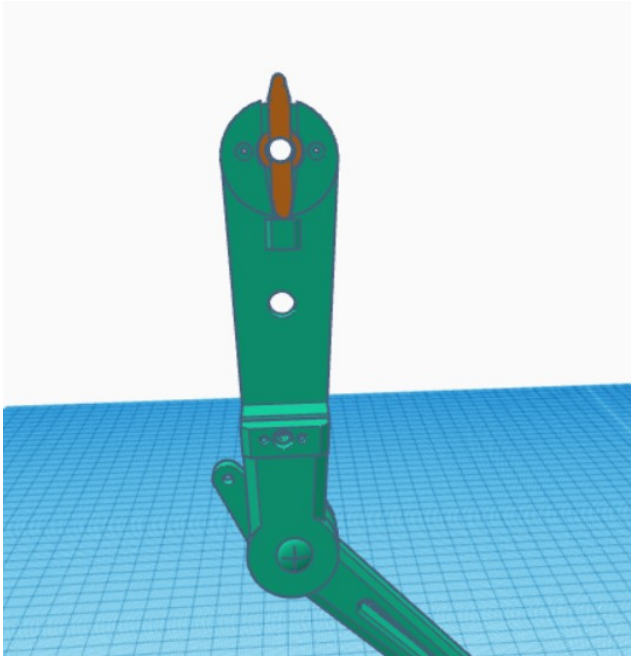


- Connect the lower joint (right) and the upper joint (right) together with servo motor
- Screw them together

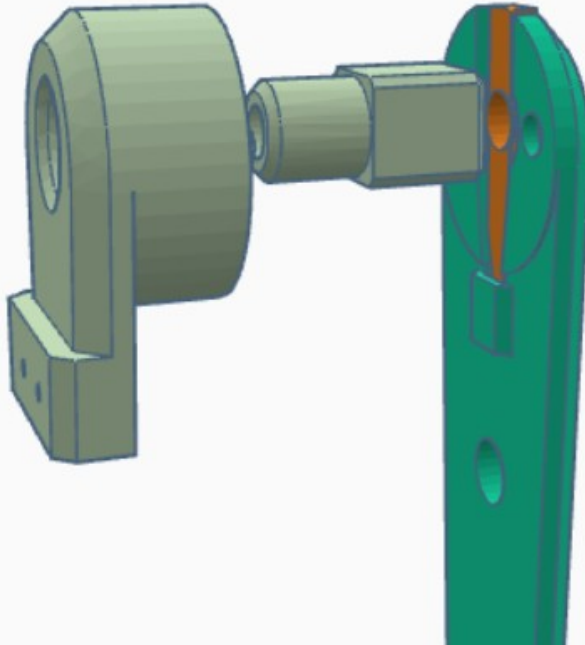




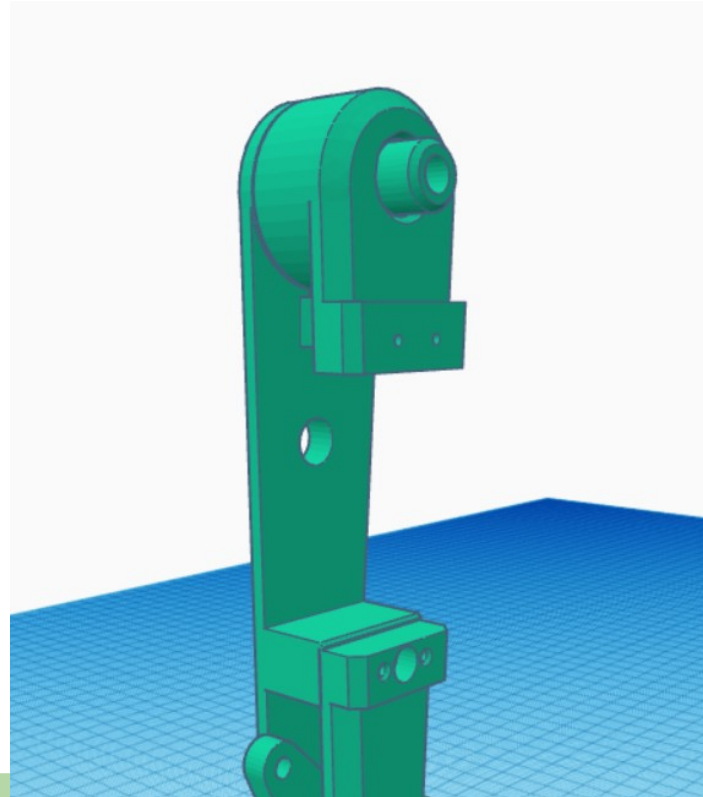
- Put the servo gear into the groove, cut the extra part if needed



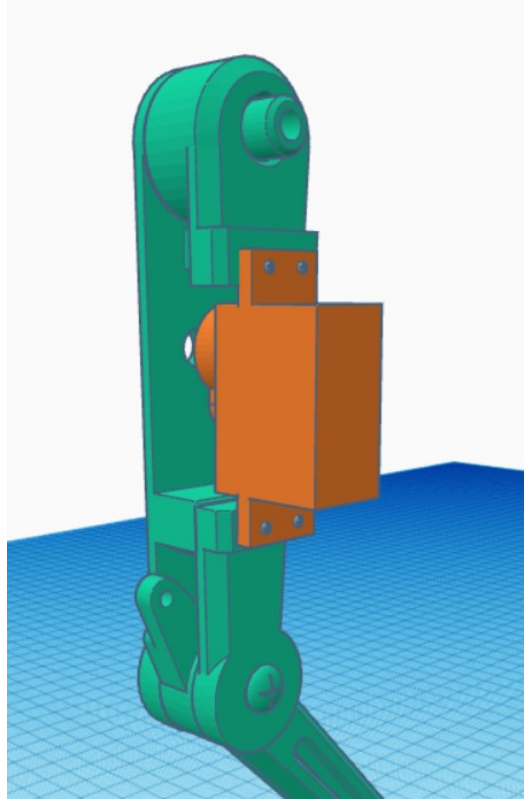
- Connect the remaining upper joint parts



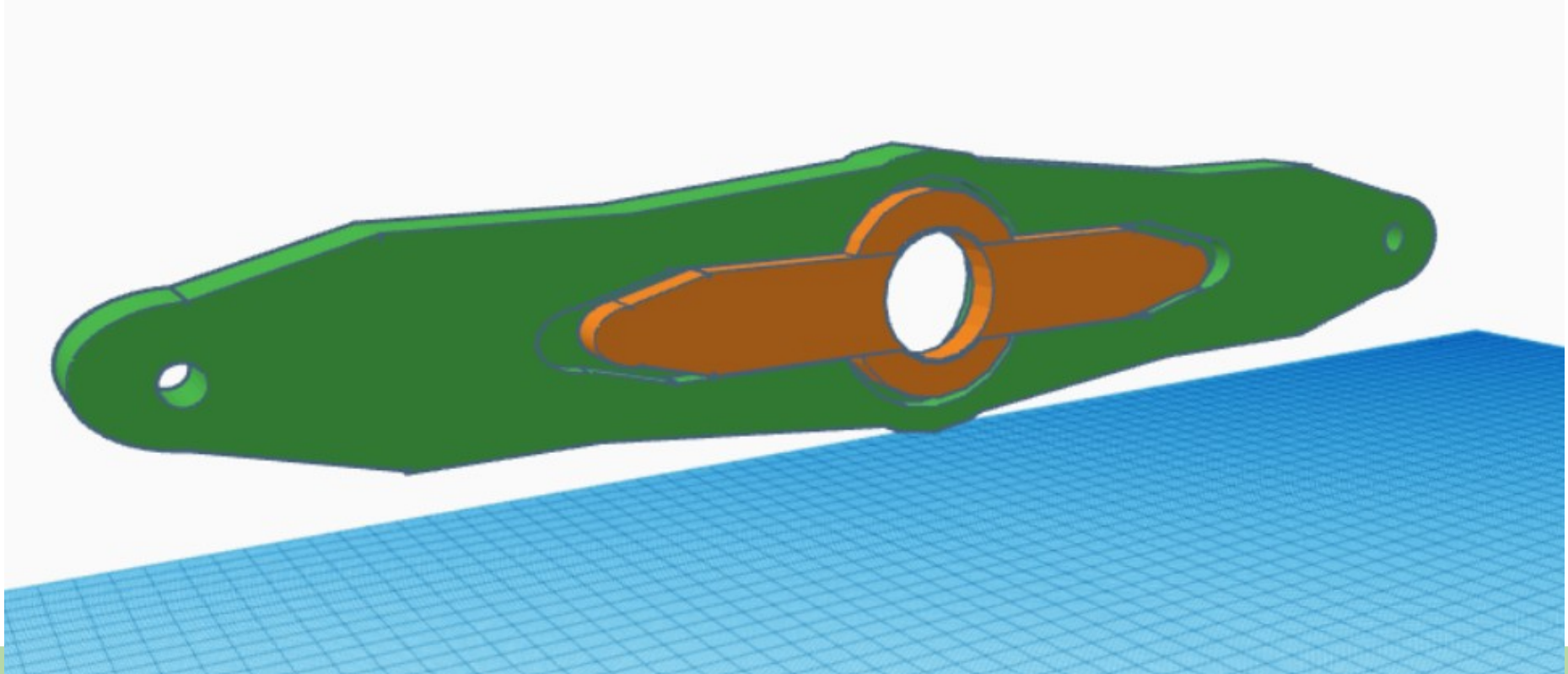
- Connect the remaining upper joint parts



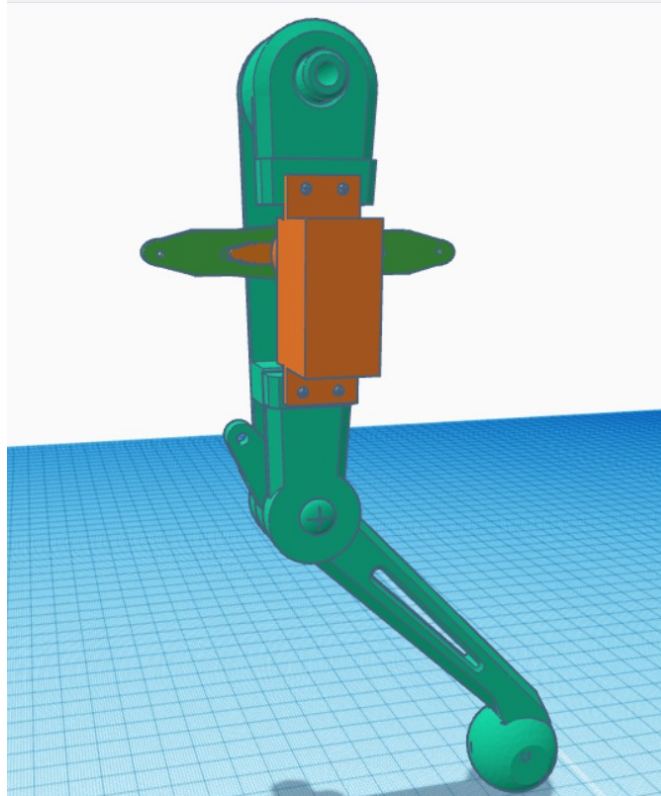
- Screw the servo and the upper joint



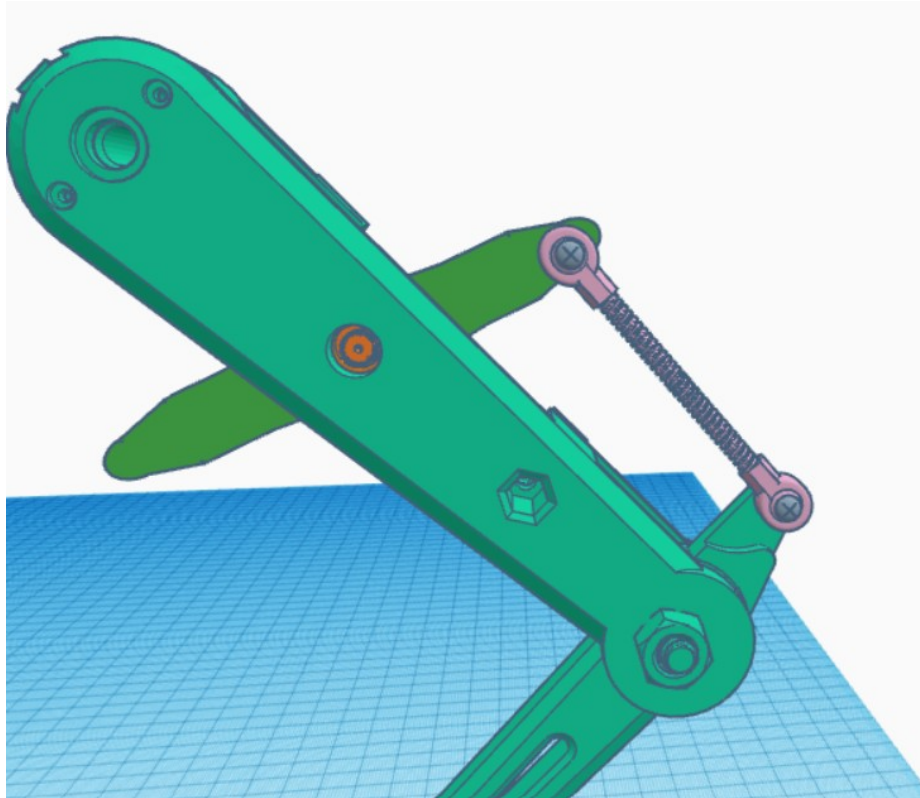
- Put servo gear into the Lower-joint-servo-gear's groove



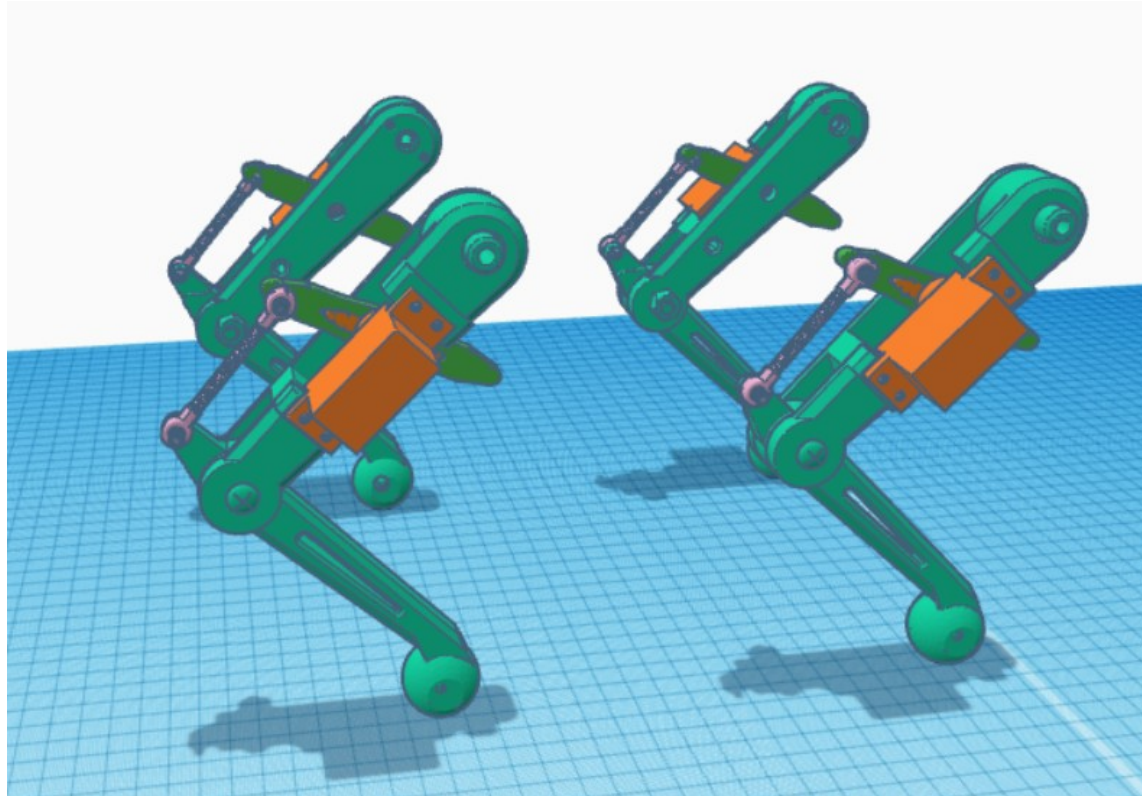
- Connect the lower-joint-servo-gear to the servo motor



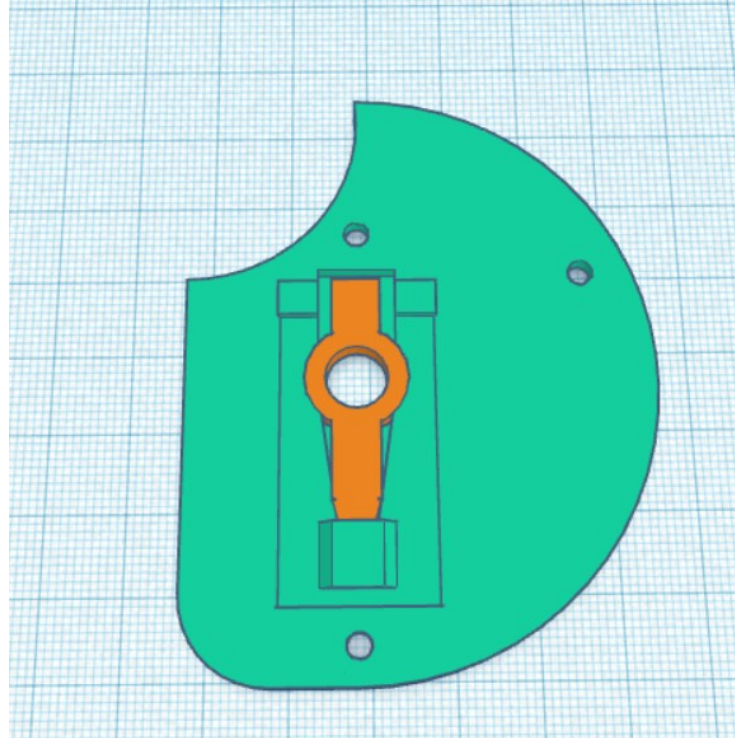
- Screw the ball joint with the lower-joint-servo-gear and lower joint



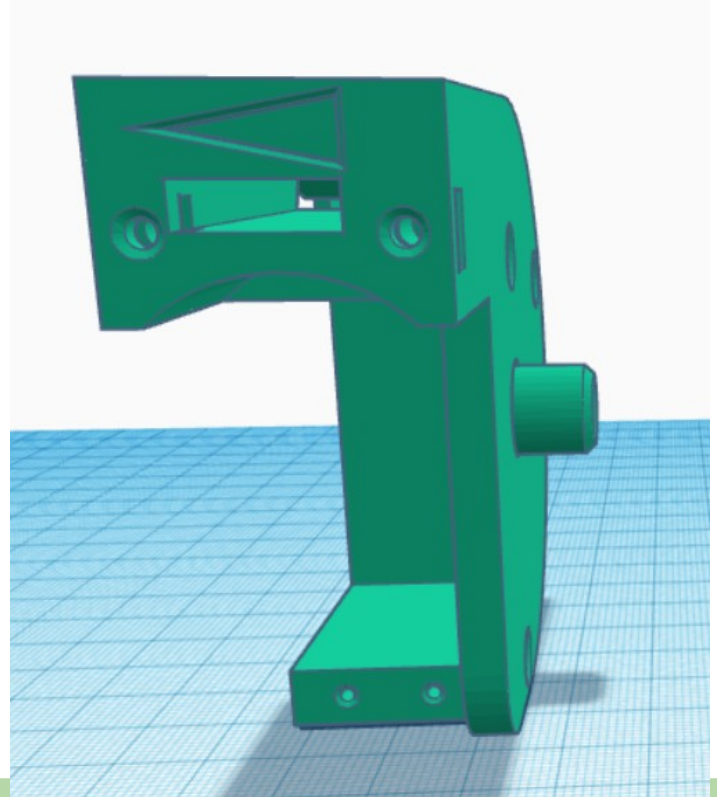
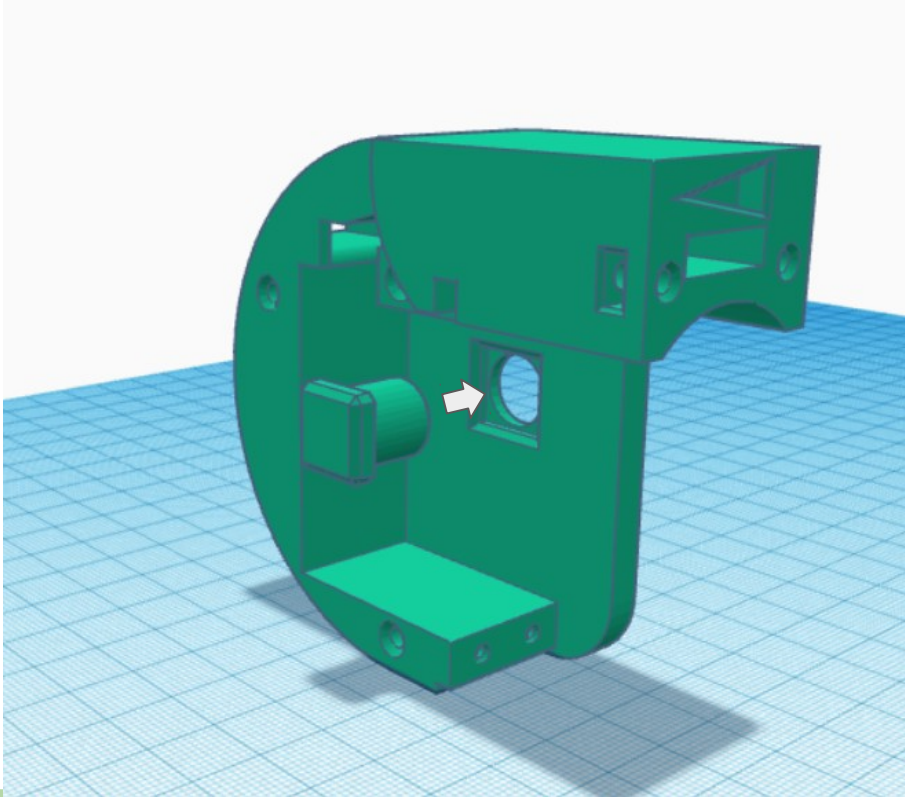
- Same step for the left leg



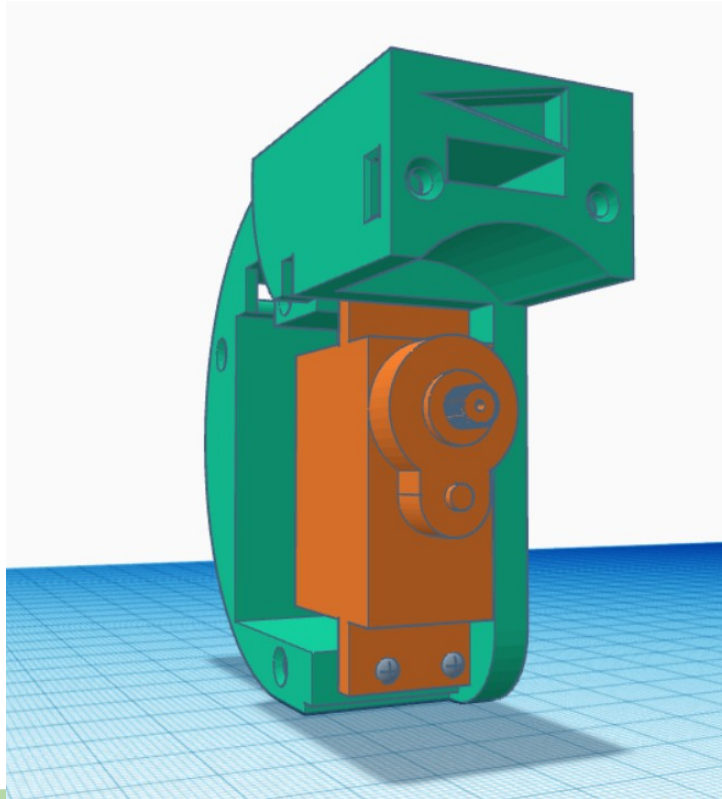
- After that, we work on the shoulder part (right)
- Put the servo gear into the groove, cut the extra part if needed



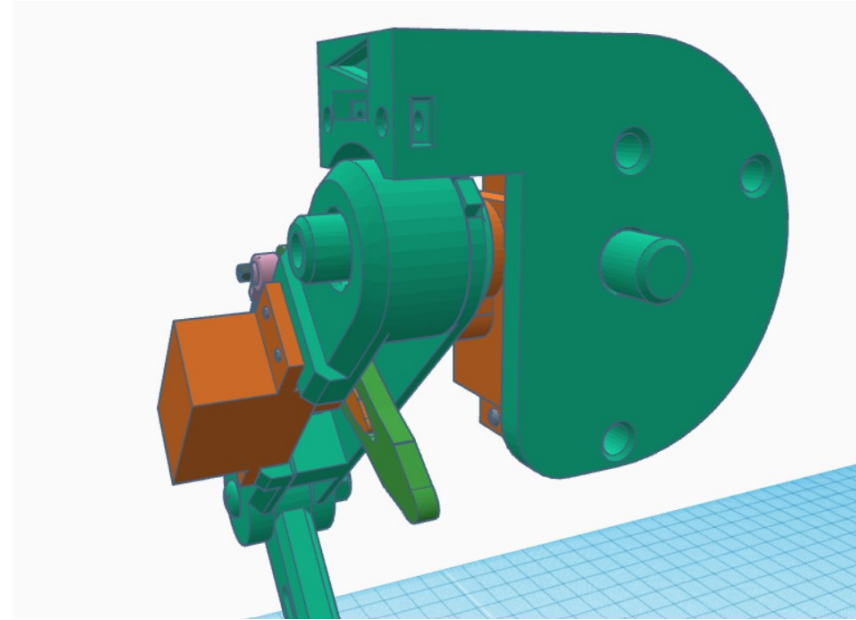
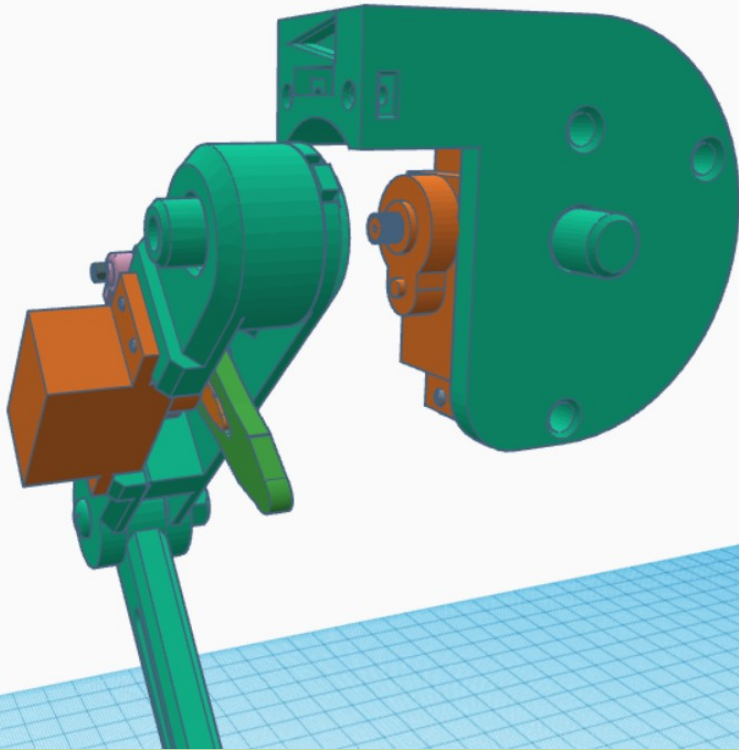
- Connect the the shoulder part (right)



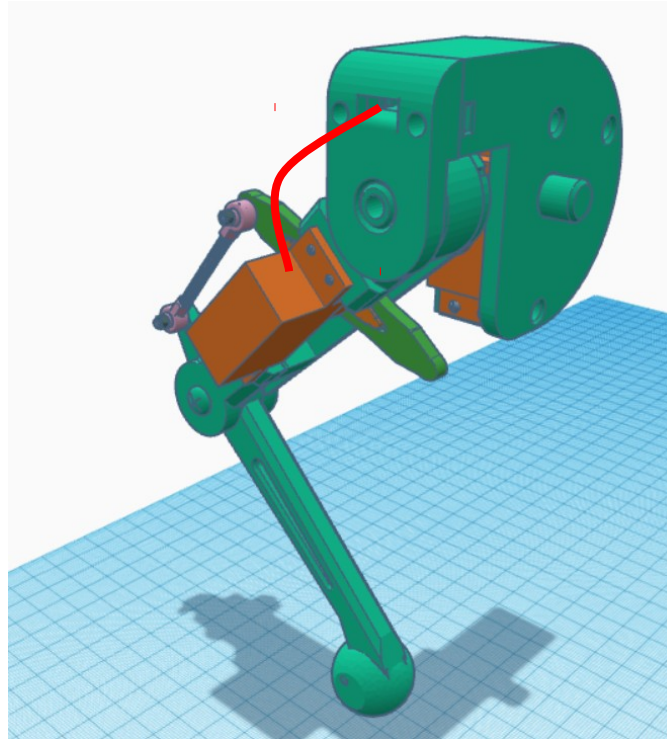
- Screw the servo with the shoulder (right)



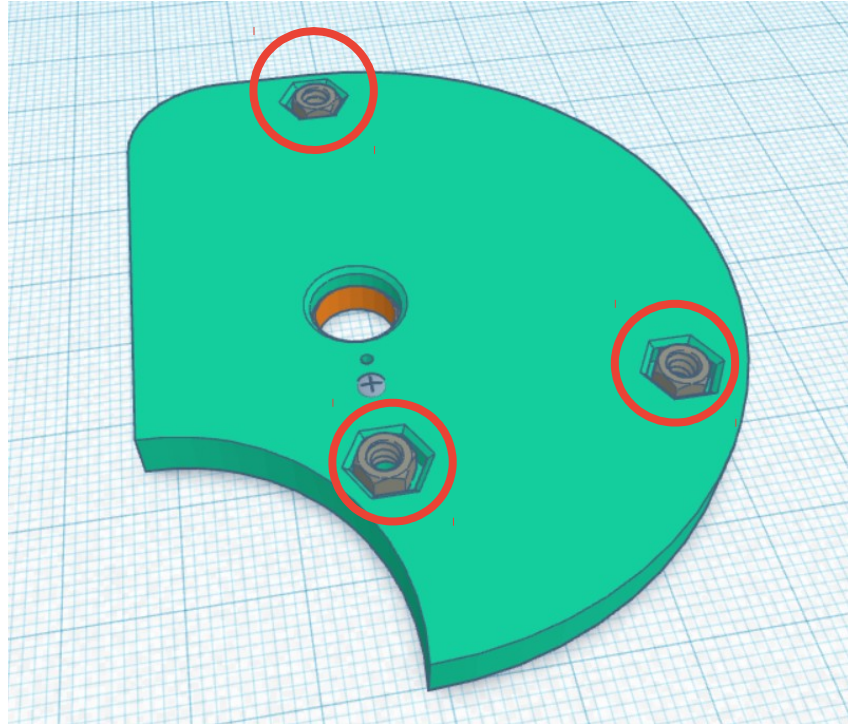
- Connect the upper joint (right) with the shoulder (right)



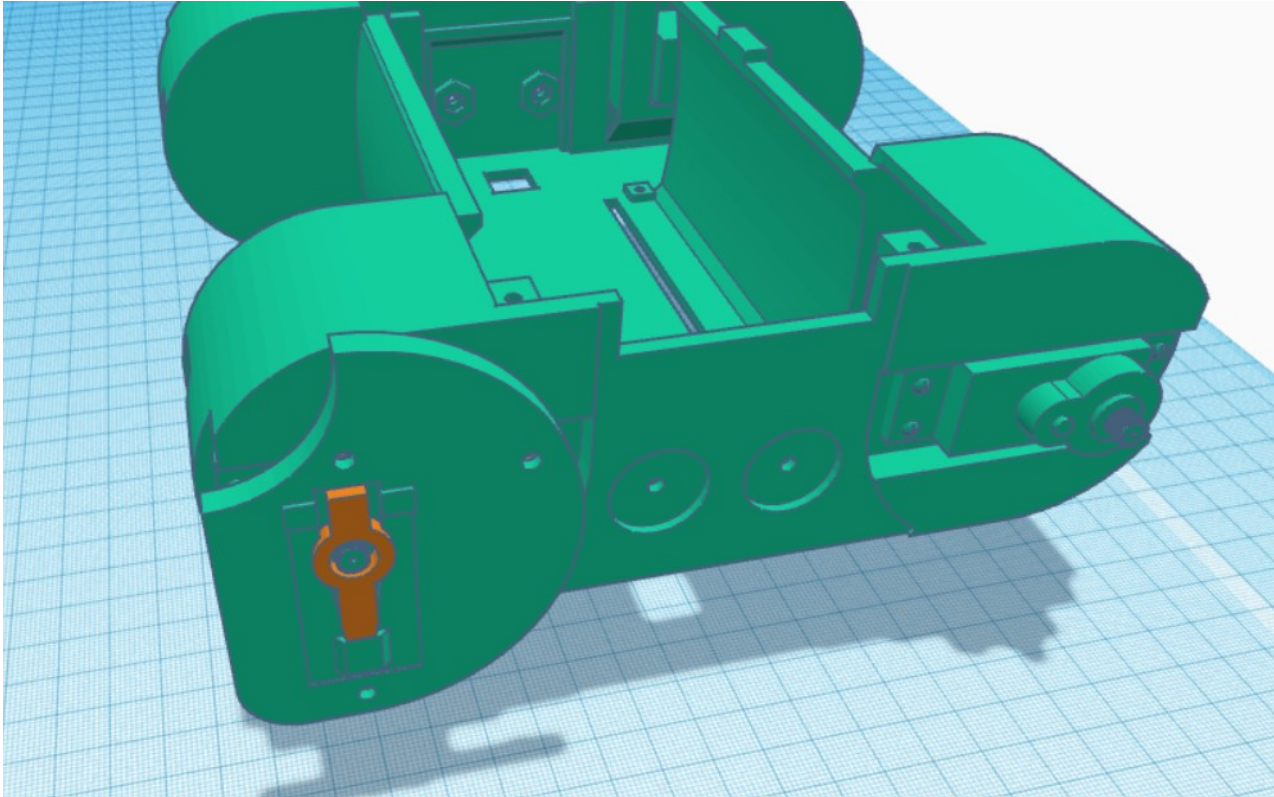
- Connect the remaining parts of the shoulder
- Make sure the wire can pass through the hole



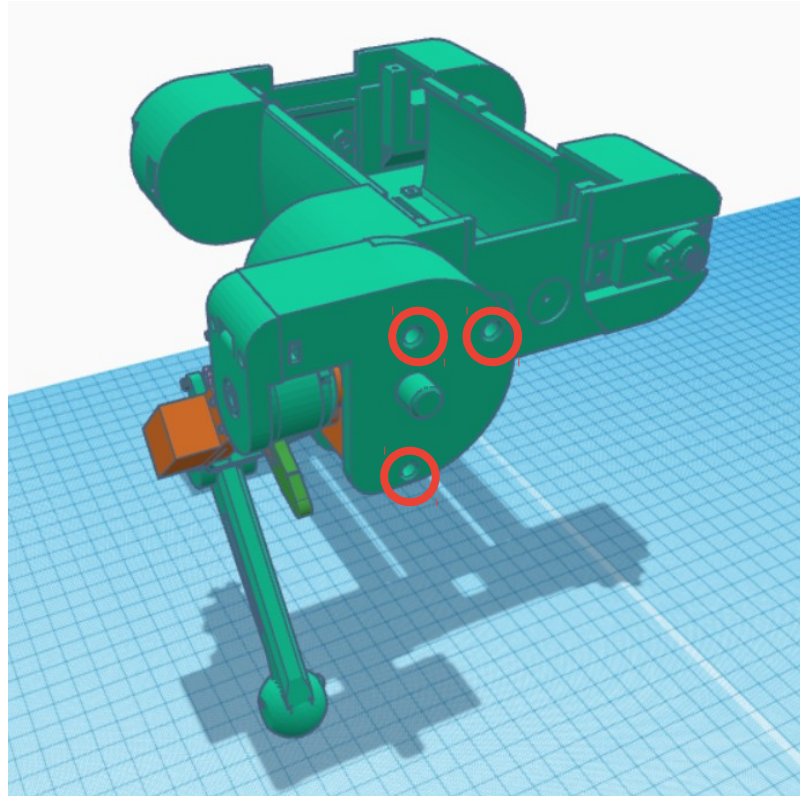
- Add the M3 screw nuts into the shoulder groove



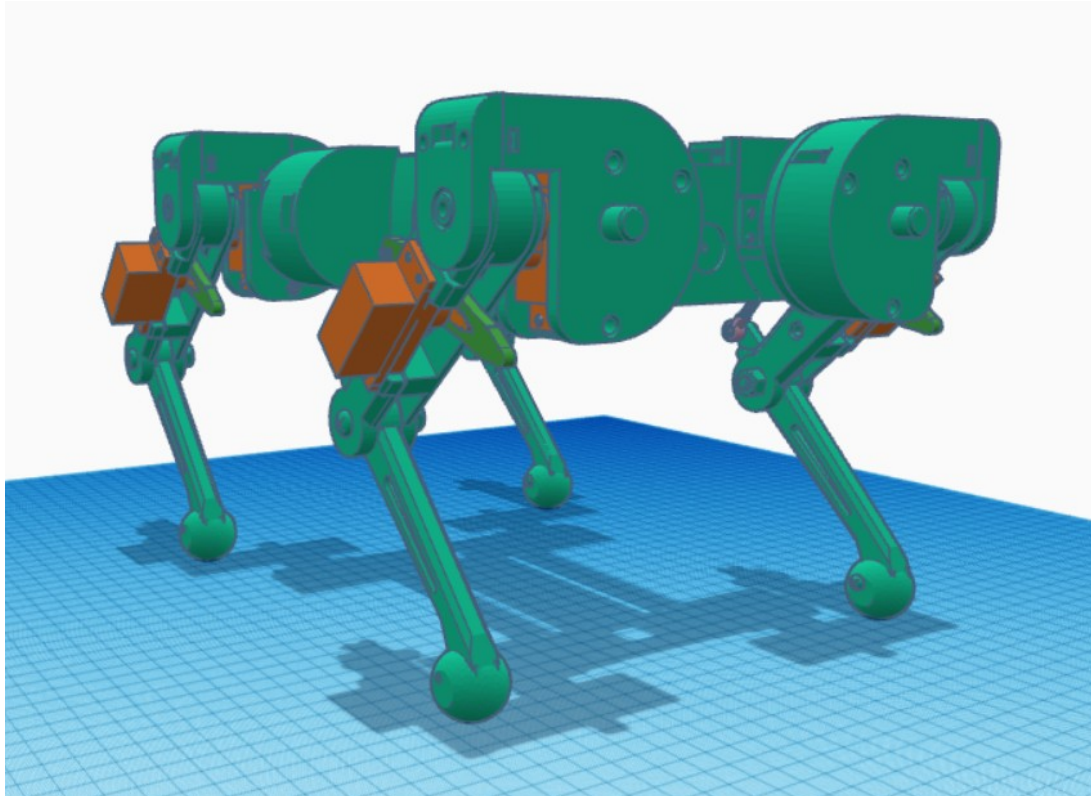
- Connect the shoulder with the body



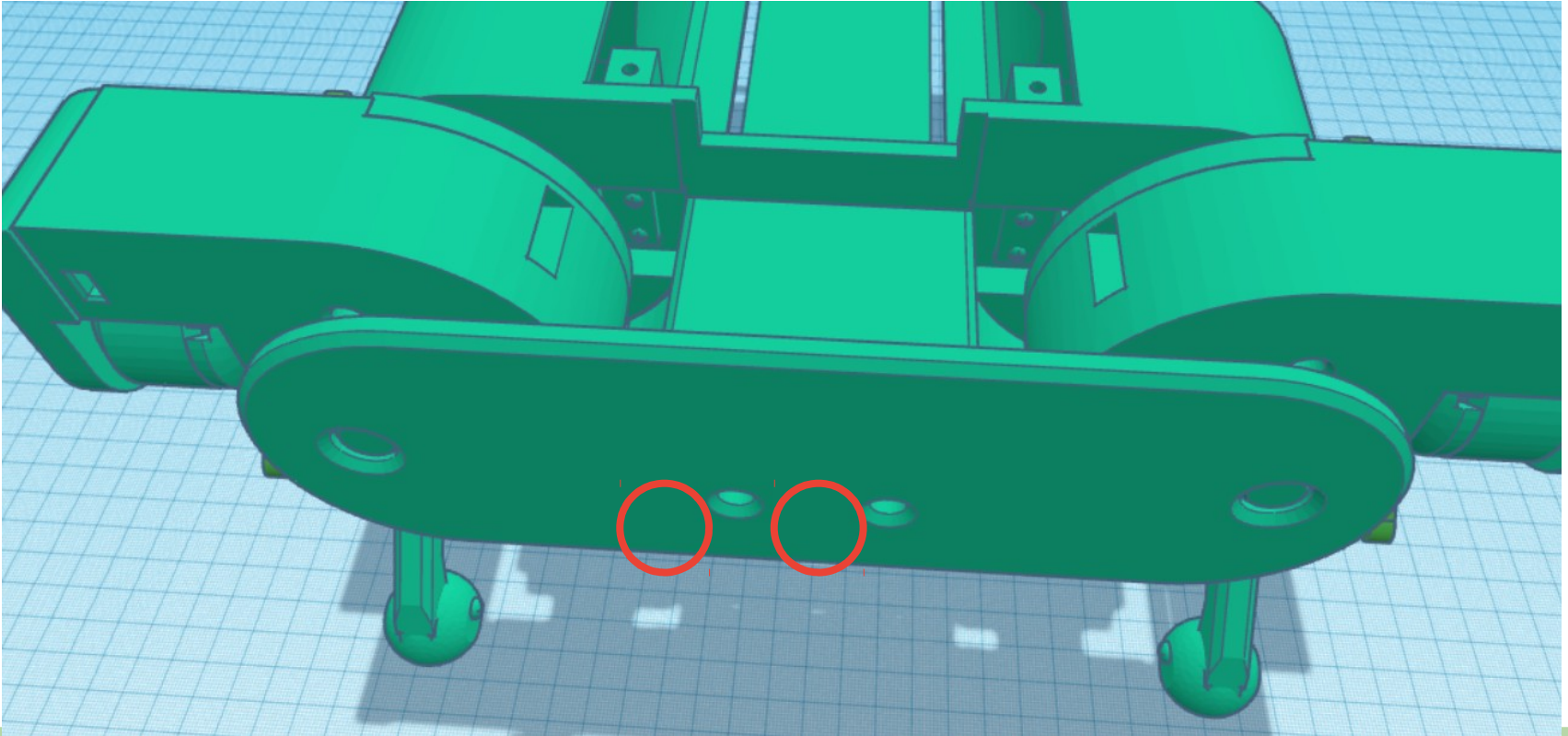
- Screw the shoulder with the leg



- Repeat the same step to finish the remaining legs



- Screw the body bumper with body



- Done!

