5 Appendices

5a. Overlap with other qualifications

This qualification overlaps with AS Further Mathematics A and with other specifications in A Level Further Mathematics and AS Further Mathematics.

5b. Accessibility

Reasonable adjustments and access arrangements allow learners with special educational needs, disabilities or temporary injuries to access the assessment and show what they know and can do, without changing the demands of the assessment. Applications for these should be made before the examination series. Detailed information about eligibility for access arrangements can be found in the JCQ *Access Arrangements and Reasonable Adjustments.*

The A Level qualification and subject criteria have been reviewed in order to identify any feature which could disadvantage learners who share a protected Characteristic as defined by the Equality Act 2010. All reasonable steps have been taken to minimise any such disadvantage.

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5c. Mathematical notation

The tables below set out the notation that must be used by AS and A Level Mathematics and Further Mathematics specifications. Learners will be expected to understand this notation without need for further explanation. Any additional notation required is listed in the relevant content statement in section 2 of the specification.

1	**Set Notation**	
1.1	$\in$	is an element of
1.2	$\notin$	is not an element of
1.3	$\subseteq$	is a subset of
1.4	$\subset$	is a proper subset of
1.5	$\{x_1, x_2, \ldots\}$	the set with elements $x_1, x_2, \ldots$
1.6	$\{x : \ldots\}$	the set of all x such that $\ldots$
1.7	$\mathrm{n}(A)$	the number of elements in set A
1.8	$\varnothing$	the empty set
1.9	ε	the universal set
1.10	A'	the complement of the set A
1.11	$\mathbb{N}$	the set of natural numbers, $\{1, 2, 3, \ldots\}$
1.12	$\mathbb{Z}$	the set of integers, $\{0, \pm1, \pm2, \pm3, \ldots\}$

1.13	$\mathbb{Z}^+$	the set of positive integers, $\{1, 2, 3, \ldots\}$
1.14	$\mathbb{Z}_0^+$	the set of non-negative integers, $\{0, 1, 2, 3, \ldots\}$
1.15	$\mathbb{R}$	the set of real numbers
1.16	$\mathbb{Q}$	the set of rational numbers, $\left\{\frac{p}{q} : p \in \mathbb{Z},\ q \in \mathbb{Z}^+\right\}$
1.17	$\cup$	union
1.18	$\cap$	intersection
1.19	$(x,\ y)$	the ordered pair x, y
1.20	$[a,\ b]$	the closed interval $\{x \in \mathbb{R} : a \le x \le b\}$
1.21	$[a,\ b)$	the interval $\{x \in \mathbb{R} : a \le x < b\}$
1.22	$(a,\ b]$	the interval $\{x \in \mathbb{R} : a < x \le b\}$
1.23	$(a,\ b)$	the open interval $\{x \in \mathbb{R} : a < x < b\}$
1.24	$\mathbb{C}$	the set of complex numbers
2	**Miscellaneous Symbols**	
2.1	$=$	is equal to
2.2	$\neq$	is not equal to
2.3	$\equiv$	is identical to or is congruent to
2.4	$\approx$	is approximately equal to
2.5	∞	infinity
2.6	$\propto$	is proportional to
2.7	$\therefore$	therefore
2.8	$\because$	because
2.9	$<$	is less than
2.10	$\leqslant$, $\le$	is less than or equal to, is not greater than
2.11	$>$	is greater than
2.12	$\geqslant$, $\ge$	is greater than or equal to, is not less than
2.13	$p \Rightarrow q$	p implies q (if p then q)
2.14	$p \Leftarrow q$	p is implied by q (if q then p)
2.15	$p \Leftrightarrow q$	p implies and is implied by q (p is equivalent to q)
2.16	a	first term for an arithmetic or geometric sequence
2.17	l	last term for an arithmetic sequence
2.18	d	common difference for an arithmetic sequence
2.19	r	common ratio for a geometric sequence

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2.20	S_n	sum to n terms of a sequence
2.21	S_∞	sum to infinity of a sequence
3	**Operations**	
3.1	$a+b$	a plus b
3.2	$a-b$	a minus b
3.3	$a\times b,\ ab,\ a.b$	a multiplied by b
3.4	$a\div b,\ \dfrac{a}{b}$	a divided by b
3.5	$\sum\limits_{i=1}^{n} a_i$	$a_1+a_2+\ldots+a_n$
3.6	$\prod\limits_{i=1}^{n} a_i$	$a_1\times a_2\times\ldots\times a_n$
3.7	$\sqrt{a}$	the non-negative square root of a
3.8	$\lvert a \rvert$	the modulus of a
3.9	$n!$	n factorial: $n! = n\times(n-1)\times\ldots\times 2\times 1,\ n\in\mathbb{N};\ 0! = 1$
3.10	$\binom{n}{r}, {}^nC_r, {}_nC_r$	the binomial coefficient $\dfrac{n!}{r!\,(n-r)!}$ for $n,\ r\in\mathbb{Z}_0^+,\ r\leqslant n$ or $\dfrac{n(n-1)\ldots(n-r+1)}{r!}$ for $n\in\mathbb{Q},\ r\in\mathbb{Z}_0^+$
4	**Functions**	
4.1	$\mathrm{f}(x)$	the value of the function f at x
4.2	$\mathrm{f}: x\mapsto y$	the function f maps the element x to the element y
4.3	f^{-1}	the inverse function of the function f
4.4	gf	the composite function of f and g which is defined by $\mathrm{gf}(x)=\mathrm{g}(\mathrm{f}(x))$
4.5	$\lim\limits_{x\to a}\mathrm{f}(x)$	the limit of $\mathrm{f}(x)$ as x tends to a
4.6	$\Delta x,\ \delta x$	an increment of x
4.7	$\dfrac{\mathrm{d}y}{\mathrm{d}x}$	the derivative of y with respect to x
4.8	$\dfrac{\mathrm{d}^n y}{\mathrm{d}x^n}$	the nth derivative of y with respect to x
4.9	$\mathrm{f}'(x),\ \mathrm{f}''(x),\ \ldots,\ \mathrm{f}^{(n)}(x)$	the first, second, ..., n^{th} derivatives of $\mathrm{f}(x)$ with respect to x
4.10	$\dot{x},\ \ddot{x},\ \ldots$	the first, second, ... derivatives of x with respect to t

4.11	$\int y \, \mathrm{d}x$	the indefinite integral of y with respect to x
4.12	$\int_a^b y \, \mathrm{d}x$	the definite integral of y with respect to x between the limits $x = a$ and $x = b$
5	**Exponential and Logarithmic Functions**	
5.1	e	base of natural logarithms
5.2	e^x, $\exp x$	exponential function of x
5.3	$\log_a x$	logarithm to the base a of x
5.4	$\ln x$, $\log_\mathrm{e} x$	natural logarithm of x
6	**Trigonometric and Hyperbolic Functions**	
6.1	$\left.\begin{matrix}\sin, \cos, \tan \\ \operatorname{cosec}, \sec, \cot\end{matrix}\right\}$	the trigonometric functions
6.2	$\left.\begin{matrix}\sin^{-1}, \cos^{-1}, \tan^{-1} \\ \arcsin, \arccos, \arctan\end{matrix}\right\}$	the inverse trigonometric functions
6.3	$\circ$	degrees
6.4	rad	radians
6.5	$\left.\begin{matrix}\operatorname{cosec}^{-1}, \sec^{-1}, \cot^{-1} \\ \operatorname{arccosec}, \operatorname{arcsec}, \operatorname{arccot}\end{matrix}\right\}$	the inverse trigonometric functions
6.6	$\left.\begin{matrix}\sinh, \cosh, \tanh, \\ \operatorname{cosech}, \operatorname{sech}, \coth\end{matrix}\right\}$	the hyperbolic functions
6.7	$\left.\begin{matrix}\sinh^{-1}, \cosh^{-1}, \tanh^{-1} \\ \operatorname{cosech}^{-1}, \operatorname{sech}^{-1}, \coth^{-1}\end{matrix}\right\}$ $\left.\begin{matrix}\operatorname{arsinh}, \operatorname{arcosh}, \operatorname{artanh}, \\ \operatorname{arcosech}, \operatorname{arsech}, \operatorname{arcoth}\end{matrix}\right\}$	the inverse hyperbolic functions
7	**Complex Numbers**	
7.1	i, j	square root of -1
7.2	$x + \mathrm{i}y$	complex number with real part x and imaginary part y
7.3	$r(\cos\theta + \mathrm{i}\sin\theta)$	modulus argument form of a complex number with modulus r and argument θ
7.4	z	a complex number, $z = x + \mathrm{i}y = r(\cos\theta + \mathrm{i}\sin\theta)$
7.5	$\mathrm{Re}(z)$	the real part of z, $\mathrm{Re}(z) = x$
7.6	$\mathrm{Im}(z)$	the imaginary part of z, $\mathrm{Im}(z) = y$
7.7	$\lvert z \rvert$	the modulus of z, $\lvert z \rvert = \sqrt{x^2 + y^2}$

7.8	$\arg(z)$	the argument of z, $\arg(z) = \theta, -\pi < \theta \le \pi$
7.9	z^*	the complex conjugate of z, $x - iy$
8	**Matrices**	
8.1	$\mathbf{M}$	a matrix $\mathbf{M}$
8.2	$\mathbf{0}$	zero matrix
8.3	$\mathbf{I}$	identity matrix
8.4	$\mathbf{M}^{-1}$	the inverse of the matrix $\mathbf{M}$
8.5	$\mathbf{M}^{\mathrm{T}}$	the transpose of the matrix $\mathbf{M}$
8.6	Δ, det $\mathbf{M}$ or $\lvert\mathbf{M}\rvert$	the determinant of the square matrix $\mathbf{M}$
8.7	$\mathbf{Mr}$	image of column vector $\mathbf{r}$ under the transformation associated with the matrix $\mathbf{M}$
9	**Vectors**	
9.1	$\mathbf{a}$, $\underline{a}$, $\underset{\sim}{a}$	the vector $\mathbf{a}$, $\underline{a}$, $\underset{\sim}{a}$; these alternatives apply throughout section 9
9.2	$\overrightarrow{\mathrm{AB}}$	the vector represented in magnitude and direction by the directed line segment AB
9.3	$\hat{\mathbf{a}}$	a unit vector in the direction of $\mathbf{a}$
9.4	$\mathbf{i}, \mathbf{j}, \mathbf{k}$	unit vectors in the directions of the cartesian coordinate axes
9.5	$\lvert \mathbf{a} \rvert, a$	the magnitude of $\mathbf{a}$
9.6	$\lvert \overrightarrow{\mathrm{AB}} \rvert$, AB	the magnitude of $\overrightarrow{\mathrm{AB}}$
9.7	$\begin{pmatrix} a \\ b \end{pmatrix}$, $a\mathbf{i} + b\mathbf{j}$	column vector and corresponding unit vector notation
9.8	$\mathbf{r}$	position vector
9.9	$\mathbf{s}$	displacement vector
9.10	$\mathbf{v}$	velocity vector
9.11	$\mathbf{a}$	acceleration vector
9.12	$\mathbf{a}.\mathbf{b}$	the scalar product of $\mathbf{a}$ and $\mathbf{b}$
10	**Differential Equations**	
10.1	ω	angular speed
11	**Probability and Statistics**	
11.1	A, B, C, etc.	events
11.2	$A \cup B$	union of the events A and B

11.3	$A \cap B$	intersection of the events A and B
11.4	$\mathrm{P}(A)$	probability of the event A
11.5	A'	complement of the event A
11.6	$\mathrm{P}(A \mid B)$	probability of the event A conditional on the event B
11.7	X, Y, R, etc.	random variables
11.8	x, y, r, etc.	values of the random variables X, Y, R etc.
11.9	$x_1, x_2, \ldots$	observations
11.10	$f_1, f_2, \ldots$	frequencies with which the observations $x_1, x_2, \ldots$ occur
11.11	$\mathrm{p}(x)$, $\mathrm{P}(X = x)$	probability function of the discrete random variable X
11.12	$p_1, p_2, \ldots$	probabilities of the values $x_1, x_2, \ldots$ of the discrete random variable X
11.13	$\mathrm{E}(X)$	expectation of the random variable X
11.14	$\mathrm{Var}(X)$	variance of the random variable X
11.15	$\sim$	has the distribution
11.16	$\mathrm{B}(n,\ p)$	binomial distribution with parameters n and p, where n is the number of trials and p is the probability of success in a trial
11.17	q	$q = 1 - p$ for binomial distribution
11.18	$\mathrm{N}(\mu, \sigma^2)$	Normal distribution with mean μ and variance σ^2
11.19	$Z \sim \mathrm{N}(0, 1)$	standard Normal distribution
11.20	ϕ	probability density function of the standardised Normal variable with distribution $\mathrm{N}(0,\ 1)$
11.21	Φ	corresponding cumulative distribution function
11.22	μ	population mean
11.23	σ^2	population variance
11.24	σ	population standard deviation
11.25	$\bar{x}$	sample mean
11.26	s^2	sample variance
11.27	s	sample standard deviation
11.28	H_0	Null hypothesis
11.29	H_1	Alternative hypothesis
11.30	r	product-moment correlation coefficient for a sample
11.31	ρ	product-moment correlation coefficient for a population
12	**Mechanics**	
12.1	kg	kilograms
12.2	m	metres
12.3	km	kilometres

12.4	m/s, m s^{-1}	metres per second (velocity)
12.5	m/s^2, m s^{-2}	metres per second per second (acceleration)
12.6	F	force or resultant force
12.7	N	Newton
12.8	N m	Newton metre (moment of a force)
12.9	t	time
12.10	s	displacement
12.11	u	initial velocity
12.12	v	velocity or final velocity
12.13	a	acceleration
12.14	g	acceleration due to gravity
12.15	μ	coefficient of friction

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5d. Mathematical formulae and identities

Learners must be able to use the following formulae and identities for A Level Further Mathematics, without these formulae and identities being provided, either in these forms or in equivalent forms.

These formulae and identities may only be provided where they are the starting point for a proof or as a result to be proved.

Pure Mathematics

Quadratic Equations

$ax^2 + bx + c = 0$ has roots $\dfrac{-b \pm \sqrt{b^2 - 4ac}}{2a}$

Laws of Indices

$$a^x a^y \equiv a^{x+y}$$
$$a^x \div a^y \equiv a^{x-y}$$
$$(a^x)^y \equiv a^{xy}$$

Laws of Logarithms

$x = a^n \Leftrightarrow n = \log_a x$ for $a > 0$ and $x > 0$

$$\log_a x + \log_a y \equiv \log_a (xy)$$

$$\log_a x - \log_a y \equiv \log_a \left(\frac{x}{y}\right)$$

$$k \log_a x \equiv \log_a (x^k)$$

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Coordinate Geometry

A straight line graph, gradient m passing through (x_1, y_1) has equation

$y - y_1 = m(x - x_1)$

Straight lines with gradients m_1 and m_2 are perpendicular when $m_1 m_2 = -1$

Sequences

General term of an arithmetic progression

$u_n = a + (n-1)d$

General term of a geometric progression

$u_n = ar^{n-1}$

Trigonometry

In the triangle ABC

Sine rule: $\dfrac{a}{\sin A} = \dfrac{b}{\sin B} = \dfrac{c}{\sin C}$

Cosine rule: $a^2 = b^2 + c^2 - 2bc \cos A$

Area $= \dfrac{1}{2} ab \sin C$

$\cos^2 A + \sin^2 A \equiv 1$

$\sec^2 A \equiv 1 + \tan^2 A$

$\operatorname{cosec}^2 A \equiv 1 + \cot^2 A$

$\sin 2A \equiv 2 \sin A \cos A$

$\cos 2A \equiv \cos^2 A - \sin^2 A$

$\tan 2A \equiv \dfrac{2\tan A}{1 - \tan^2 A}$

Mensuration

Circumference and area of circle, radius r and diameter d

$C = 2\pi r = \pi d \qquad A = \pi r^2$

Pythagoras' theorem: In any right-angled triangle where a, b and c are the lengths of the sides and c is the hypotenuse

$c^2 = a^2 + b^2$

Area of a trapezium $= \dfrac{1}{2}(a+b)h$, where a and b are the lengths of the parallel sides and h is their perpendicular separation

Volume of a prism = area of cross section × length

For a circle of radius r, where an angle at the centre of θ radians subtends an arc of length l and encloses an associated sector of area a

$l = r\theta \qquad a = \dfrac{1}{2} r^2 \theta$

Complex Numbers

For two complex numbers $z_1 = r_1 e^{i\theta_1}$ and $z_2 = r_2 e^{i\theta_2}$

$$z_1 z_2 = r_1 r_2 e^{i(\theta_1 + \theta_2)}$$
$$\frac{z_1}{z_2} = \frac{r_1}{r_2} e^{i(\theta_1 - \theta_2)}$$

Loci in the Argand diagram

$|z - a| = r$ is a circle radius r centred at a

$\arg(z - a) = \theta$ is a half line drawn from a at angle θ to a line parallel to the positive real axis

Exponential Form

$e^{i\theta} = \cos\theta + i\sin\theta$

Matrices

For a 2 by 2 matrix $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ the determinant $\Delta = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$

the inverse is $\frac{1}{\Delta}\begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$

The transformation represented by matrix **AB** is the transformation represented by matrix **B** followed by the transformation represented by matrix **A**.

For matrices **A**, **B**

$(\mathbf{AB})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$

Algebra

$$\sum_{r=1}^{n} r = \frac{1}{2}n(n+1)$$

For $ax^2 + bx + c = 0$ with roots α and β:

$$\alpha + \beta = \frac{-b}{a} \qquad \alpha\beta = \frac{c}{a}$$

For $ax^3 + bx^2 + cx + d = 0$ with roots α, β and γ :

$$\sum \alpha = \frac{-b}{a} \qquad \sum \alpha\beta = \frac{c}{a} \quad \alpha\beta\gamma = \frac{-d}{a}$$

Hyperbolic Functions

$$\cosh x \equiv \frac{1}{2}(e^x + e^{-x})$$

$$\sinh x \equiv \frac{1}{2}(e^x - e^{-x})$$

$$\tanh x \equiv \frac{\sinh x}{\cosh x}$$

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Calculus and Differential Equations

Differentiation

Function	Derivative
x^n	nx^{n-1}
$\sin kx$	$k\cos kx$
$\cos kx$	$-k\sin kx$
$\sinh kx$	$k\cosh kx$
$\cosh kx$	$k\sinh kx$
e^{kx}	ke^{kx}
$\ln x$	$\frac{1}{x}$
$f(x)+g(x)$	$f'(x)+g'(x)$
$f(x)g(x)$	$f'(x)g(x)+f(x)g'(x)$
$f(g(x))$	$f'(g(x))g'(x)$

Integration

Function	Integral
x^n	$\frac{1}{n+1}x^{n+1}+c,\ n\neq -1$
$\cos kx$	$\frac{1}{k}\sin kx+c$
$\sin kx$	$-\frac{1}{k}\cos kx+c$
$\cosh kx$	$\frac{1}{k}\sinh kx+c$
$\sinh kx$	$\frac{1}{k}\cosh kx+c$
e^{kx}	$\frac{1}{k}e^{kx}+c$
$\frac{1}{x}$	$\ln\lvert x\rvert+c,\ x\neq 0$
$f'(x)+g'(x)$	$f(x)+g(x)+c$
$f'(g(x))g'(x)$	$f(g(x))+c$

Area under a curve $= \int_a^b y\,dx\,(y \geq 0)$

Volumes of revolution about the x and y axes

$V_x = \pi\int_a^b y^2\,dx \qquad V_y = \pi\int_c^d x^2\,dy$

Simple Harmonic Motion

$\ddot{x} = -\omega^2 x$

Vectors

$|x\mathbf{i}+y\mathbf{j}|=\sqrt{x^2+y^2}$

$|x\mathbf{i}+y\mathbf{j}+z\mathbf{k}|=\sqrt{x^2+y^2+z^2}$

Scalar product of two vectors $\mathbf{a}=\begin{pmatrix}a_1\\a_2\\a_3\end{pmatrix}$ and $\mathbf{b}=\begin{pmatrix}b_1\\b_2\\b_3\end{pmatrix}$ is

$$\begin{pmatrix}a_1\\a_2\\a_3\end{pmatrix}\cdot\begin{pmatrix}b_1\\b_2\\b_3\end{pmatrix}=a_1b_1+a_2b_2+a_3b_3=|\mathbf{a}||\mathbf{b}|\cos\theta$$

where θ is the angle between the vectors **a** and **b**

The equation of the line through the point with position vector **a** parallel to vector **b** is

$\mathbf{r}=\mathbf{a}+t\mathbf{b}$

The equation of the plane containing the point with position vector **a** and perpendicular to vector **n** is

$(\mathbf{r}-\mathbf{a}).\mathbf{n}=0$

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Mechanics

Forces and Equilibrium

Weight = mass $\times g$

Friction: $F\le\mu R$

Newton's second law in the form: $F=ma$

Kinematics

For motion in a straight line with variable acceleration

$v=\dfrac{\mathrm{d}r}{\mathrm{d}t}$ $\qquad a=\dfrac{\mathrm{d}v}{\mathrm{d}t}=\dfrac{\mathrm{d}^2r}{\mathrm{d}t^2}$

$r=\int v\,\mathrm{d}t$ $\qquad v=\int a\,\mathrm{d}t$

$v=\dfrac{\mathrm{d}s}{\mathrm{d}t}$ $\qquad a=\dfrac{\mathrm{d}v}{\mathrm{d}t}=\dfrac{\mathrm{d}^2s}{\mathrm{d}t^2}$

$s=\int v\,\mathrm{d}t$ $\qquad v=\int a\,\mathrm{d}t$

Statistics

The mean of a set of data: $\bar{x}=\dfrac{\sum x}{n}=\dfrac{\sum fx}{\sum f}$

The standard Normal variable: $Z=\dfrac{X-\mu}{\sigma}$ where $X\sim N(\mu,\sigma^2)$

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Learners will be given the following formulae in the Formulae Booklet in each assessment.

Pure Mathematics

Arithmetic series

$$S_n = \frac{1}{2}n(a+l) = \frac{1}{2}n\{2a+(n-1)d\}$$

Geometric series

$$S_n = \frac{a(1-r^n)}{1-r}$$

$$S_\infty = \frac{a}{1-r} \text{ for } |r| < 1$$

Binomial series

$$(a+b)^n = a^n + {}^nC_1 a^{n-1} b + {}^nC_2 a^{n-2} b^2 + \ldots + {}^nC_r a^{n-r} b^r + \ldots + b^n \quad (n \in \mathbb{N}),$$

where $^nC_r = {}_nC_r = \begin{pmatrix} n \\ r \end{pmatrix} = \frac{n!}{r!(n-r)!}$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2!}x^2 + \ldots + \frac{n(n-1)\ldots(n-r+1)}{r!}x^r + \ldots \quad (|x| < 1, n \in \mathbb{R})$$

Series

$$\sum_{r=1}^{n} r^2 = \frac{1}{6}n(n+1)(2n+1), \quad \sum_{r=1}^{n} r^3 = \frac{1}{4}n^2(n+1)^2$$

Maclaurin series

$$f(x) = f(0) + f'(0)x + \frac{f''(0)}{2!}x^2 + \ldots + \frac{f^{(r)}(0)}{r!}x^r + \ldots$$

$$e^x = \exp(x) = 1 + x + \frac{x^2}{2!} + \ldots + \frac{x^r}{r!} + \ldots \text{ for all } x$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \ldots + (-1)^{r+1}\frac{x^r}{r} + \ldots (-1 < x \leq 1)$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \ldots + (-1)^r \frac{x^{2r+1}}{(2r+1)!} + \ldots \text{ for all } x$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \ldots + (-1)^r \frac{x^{2r}}{(2r)!} + \ldots \text{ for all } x$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2!}x^2 + \ldots + \frac{n(n-1)\ldots(n-r+1)}{r!}x^r + \ldots \quad (|x| < 1, n \in \mathbb{R})$$

Matrix transformations

Reflection in the line $y = \pm x$: $\begin{pmatrix} 0 & \pm 1 \\ \pm 1 & 0 \end{pmatrix}$

Anticlockwise rotation through θ about O: $\begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$

Rotations through θ about the coordinate axes. The direction of positive rotation is taken to be anticlockwise when looking towards the origin from the positive side of the axis of rotation.

$$\mathbf{R}_x = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos\theta & -\sin\theta \\ 0 & \sin\theta & \cos\theta \end{pmatrix}$$

$$\mathbf{R}_y = \begin{pmatrix} \cos\theta & 0 & \sin\theta \\ 0 & 1 & 0 \\ -\sin\theta & 0 & \cos\theta \end{pmatrix}$$

$$\mathbf{R}_z = \begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Differentiation

$\mathrm{f}(x)$	$\mathrm{f}'(x)$
$\tan kx$	$k \sec^2 kx$
$\sec x$	$\sec x \tan x$
$\cot x$	$-\operatorname{cosec}^2 x$
$\operatorname{cosec} x$	$-\operatorname{cosec} x \cot x$
$\arcsin x$ or $\sin^{-1} x$	$\dfrac{1}{\sqrt{1-x^2}}$
$\arccos x$ or $\cos^{-1} x$	$-\dfrac{1}{\sqrt{1-x^2}}$
$\arctan x$ or $\tan^{-1} x$	$\dfrac{1}{1+x^2}$

Quotient rule $y=\dfrac{u}{v}$, $\dfrac{\mathrm{d}y}{\mathrm{d}x}=\dfrac{v\dfrac{\mathrm{d}u}{\mathrm{d}x}-u\dfrac{\mathrm{d}v}{\mathrm{d}x}}{v^2}$

Differentiation from first principles

$$\mathrm{f}'(x)=\lim_{h\to 0}\frac{\mathrm{f}(x+h)-\mathrm{f}(x)}{h}$$

Integration

$$\int \frac{\mathrm{f}'(x)}{\mathrm{f}(x)}\,\mathrm{d}x=\ln|\mathrm{f}(x)|+c$$

$$\int \mathrm{f}'(x)(\mathrm{f}(x))^n\,\mathrm{d}x=\frac{1}{n+1}(\mathrm{f}(x))^{n+1}+c$$

Integration by parts $\int u\frac{\mathrm{d}v}{\mathrm{d}x}\mathrm{d}x = uv - \int v\frac{\mathrm{d}u}{\mathrm{d}x}\mathrm{d}x$

The mean value of f(x) on the interval [a, b] is $\frac{1}{b-a}\int_a^b \mathrm{f}(x)\,\mathrm{d}x$

Area of sector enclosed by polar curve is $\frac{1}{2}\int r^2\,\mathrm{d}\theta$

f(x)	$\int \mathrm{f}(x)\,\mathrm{d}x$
$\frac{1}{\sqrt{a^2-x^2}}$	$\sin^{-1}\left(\frac{x}{a}\right)$ $\quad \left(\lvert x\rvert < a\right)$
$\frac{1}{a^2+x^2}$	$\frac{1}{a}\tan^{-1}\left(\frac{x}{a}\right)$
$\frac{1}{\sqrt{a^2+x^2}}$	$\sinh^{-1}\left(\frac{x}{a}\right)$ or $\ln\left(x+\sqrt{x^2+a^2}\right)$
$\frac{1}{\sqrt{x^2-a^2}}$	$\cosh^{-1}\left(\frac{x}{a}\right)$ or $\ln\left(x+\sqrt{x^2-a^2}\right)$ $\quad (x > a)$

5

Numerical methods

Trapezium rule: $\int_a^b y\,\mathrm{d}x \approx \frac{1}{2}h\{(y_0+y_n)+2(y_1+y_2+\ldots+y_{n-1})\}$, where $h=\frac{b-a}{n}$

The Newton-Raphson iteration for solving $\mathrm{f}(x)=0$: $x_{n+1}=x_n-\frac{\mathrm{f}(x_n)}{\mathrm{f}'(x_n)}$

Complex numbers

Circles: $\lvert z-a\rvert=k$

Half lines: $\arg(z-a)=\alpha$

Lines: $\lvert z-a\rvert=\lvert z-b\rvert$

De Moivre's theorem: $\{r(\cos\theta+\mathrm{i}\sin\theta)\}^n=r^n(\cos n\theta+\mathrm{i}\sin n\theta)$

Roots of unity: The roots of $z^n=1$ are given by $z=\exp\left(\frac{2\pi k}{n}\mathrm{i}\right)$ for $k = 0, 1, 2, \ldots, n-1$

Vectors and 3-D coordinate geometry

Cartesian equation of the line through the point A with position vector $\mathbf{a} = a_1\mathbf{i}+a_2\mathbf{j}+a_3\mathbf{k}$ in direction $\mathbf{u} = u_1\mathbf{i}+u_2\mathbf{j}+u_3\mathbf{k}$ is $\frac{x-a_1}{u_1}=\frac{y-a_2}{u_2}=\frac{z-a_3}{u_3}(=\lambda)$

Cartesian equation of a plane is $n_1x+n_2y+n_3z+d=0$

Vector product: $\mathbf{a}\times\mathbf{b}=\begin{pmatrix}a_1\\a_2\\a_3\end{pmatrix}\times\begin{pmatrix}b_1\\b_2\\b_3\end{pmatrix}=\begin{vmatrix}\mathbf{i} & a_1 & b_1\\ \mathbf{j} & a_2 & b_2\\ \mathbf{k} & a_3 & b_3\end{vmatrix}=\begin{pmatrix}a_2b_3-a_3b_2\\a_3b_1-a_1b_3\\a_1b_2-a_2b_1\end{pmatrix}$

The distance between skew lines is $D=\dfrac{|(\mathbf{b}-\mathbf{a}).\mathbf{n}|}{|\mathbf{n}|}$, where **a** and **b** are position vectors of points on each line and **n** is a mutual perpendicular to both lines

The distance between a point and a line is $D=\dfrac{|ax_1+by_1-c|}{\sqrt{a^2+b^2}}$, where the coordinates of the point are (x_1, y_1) and the equation of the line is given by $ax+by=c$

The distance between a point and a plane is $D=\dfrac{|\mathbf{b.n}-p|}{|\mathbf{n}|}$, where **b** is the position vector of the point and the equation of the plane is given by $\mathbf{r.n}=p$

Small angle approximations

$\sin\theta\approx\theta, \cos\theta\approx 1-\frac{1}{2}\theta^2, \tan\theta\approx\theta$ where θ is small and measured in radians

Trigonometric identities

$\sin(A\pm B)=\sin A\cos B\pm\cos A\sin B$

$\cos(A\pm B)=\cos A\cos B\mp\sin A\sin B$

$\tan(A\pm B)=\dfrac{\tan A\pm\tan B}{1\mp\tan A\tan B}\quad\left(A\pm B\neq(k+\frac{1}{2})\pi\right)$

Hyperbolic functions

$\cosh^2 x-\sinh^2 x=1$

$\sinh^{-1} x=\ln[x+\sqrt{(x^2+1)}]$

$\cosh^{-1} x=\ln[x+\sqrt{(x^2-1)}], x\geq 1$

$\tanh^{-1} x=\frac{1}{2}\ln\left(\dfrac{1+x}{1-x}\right), -1<x<1$

Simple harmonic motion

$x=A\cos(\omega t)+B\sin(\omega t)$

$x=R\sin(\omega t+\varphi)$

Statistics

Probability

$\mathrm{P}(A\cup B)=\mathrm{P}(A)+\mathrm{P}(B)-\mathrm{P}(A\cap B)$

$\mathrm{P}(A\cap B)=\mathrm{P}(A)\mathrm{P}(B\mid A)=\mathrm{P}(B)\mathrm{P}(A\mid B)$ **or** $\mathrm{P}(A\mid B)=\dfrac{\mathrm{P}(A\cap B)}{\mathrm{P}(B)}$

Standard deviation

$\sqrt{\dfrac{\sum(x-\bar{x})^2}{n}}=\sqrt{\dfrac{\sum x^2}{n}-\bar{x}^2}$ **or** $\sqrt{\dfrac{\sum f(x-\bar{x})^2}{\sum f}}=\sqrt{\dfrac{\sum fx^2}{\sum f}-\bar{x}^2}$

5

Sampling distributions

For any variable X, $\mathrm{E}(\overline{X}) = \mu$, $\mathrm{Var}(\overline{X}) = \frac{\sigma^2}{n}$ and $\overline{X}$ is approximately normally distributed when n is large enough (approximately $n > 25$)

If $X \sim \mathrm{N}(\mu, \sigma^2)$ then $\overline{X} \sim \mathrm{N}\left(\mu, \frac{\sigma^2}{n}\right)$ and $\frac{\overline{X} - \mu}{\sigma/\sqrt{n}} \sim \mathrm{N}(0, 1)$

Unbiased estimates of the population mean and variance are given by $\frac{\sum x}{n}$ and $\frac{n}{n-1}\left(\frac{\sum x^2}{n} - \left(\frac{\sum x}{n}\right)^2\right)$

Expectation algebra

Use the following results, including the cases where $a = b = \pm 1$ and/or $c = 0$:

1. $\mathrm{E}(aX + bY + c) = a\mathrm{E}(X) + b\mathrm{E}(Y) + c$,
2. if X and Y are independent then $\mathrm{Var}(aX + bY + c) = a^2\mathrm{Var}(X) + b^2\mathrm{Var}(Y)$.

Discrete distributions

X is a random variable taking values x_i in a discrete distribution with $\mathrm{P}(X = x_i) = p_i$

Expectation: $\mu = \mathrm{E}(X) = \sum x_i p_i$

Variance: $\sigma^2 = \mathrm{Var}(X) = \sum (x_i - \mu)^2 p_i = \sum x_i^2 p_i - \mu^2$

	$P(X = x)$	$\mathrm{E}(X)$	$\mathrm{Var}(X)$
Binomial $\mathrm{B}(n, p)$	$\binom{n}{x} p^x (1-p)^{n-x}$	np	$np(1-p)$
Uniform distribution over $1, 2, \ldots, n$, $\mathrm{U}(n)$	$\frac{1}{n}$	$\frac{n+1}{2}$	$\frac{1}{12}(n^2 - 1)$
Geometric distribution $\mathrm{Geo}(p)$	$(1-p)^{x-1} p$	$\frac{1}{p}$	$\frac{1-p}{p^2}$
Poisson $\mathrm{Po}(\lambda)$	$e^{-\lambda} \frac{\lambda^x}{x!}$	λ	λ

Continuous distributions

X is a continuous random variable with probability density function (p.d.f.) $\mathrm{f}(x)$

Expectation: $\mu = \mathrm{E}(X) = \int x\,\mathrm{f}(x)\,\mathrm{d}x$

Variance: $\sigma^2 = \mathrm{Var}(X) = \int (x - \mu)^2 \mathrm{f}(x)\,\mathrm{d}x = \int x^2 \mathrm{f}(x)\,\mathrm{d}x - \mu^2$

Cumulative distribution function $\mathrm{F}(x) = \mathrm{P}(X \leq x) = \int_{-\infty}^{x} \mathrm{f}(t)\,\mathrm{d}t$

	p.d.f.	E(X)	Var(X)
Continuous uniform distribution over $[a, b]$	$\frac{1}{b-a}$	$\frac{1}{2}(a+b)$	$\frac{1}{12}(b-a)^2$
Exponential	$\lambda e^{-\lambda x}$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$
Normal $\mathrm{N}(\mu, \sigma^2)$	$\frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$	μ	σ^2

Percentage points of the normal distribution

If Z has a normal distribution with mean 0 and variance 1 then, for each value of p, the table gives the value of z such that $P(Z \le z) = p$.

p	0.75	0.90	0.95	0.975	0.99	0.995	0.9975	0.999	0.9995
z	0.674	1.282	1.645	1.960	2.326	2.576	2.807	3.090	3.291

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Non-parametric tests

Goodness-of-fit test and contingency tables: $\sum \frac{(O_i - E_i)^2}{E_i} \sim \chi^2_\nu$

Approximate distributions for large samples

Wilcoxon Signed Rank test: $T \sim \mathrm{N}\left(\frac{1}{4}n(n+1), \frac{1}{24}n(n+1)(2n+1)\right)$

Wilcoxon Rank Sum test (samples of sizes m and n, with $m \le n$) :

$$W \sim \mathrm{N}\left(\frac{1}{2}m(m+n+1), \frac{1}{12}mn(m+n+1)\right)$$

Correlation and regression

For a sample of n pairs of observations (x_i, y_i)

$$S_{xx} = \sum (x_i - \bar{x})^2 = \sum x_i^2 - \frac{\left(\sum x_i\right)^2}{n}, S_{yy} = \sum (y_i - \bar{y})^2 = \sum y_i^2 - \frac{\left(\sum y_i\right)^2}{n},$$

$$S_{xy} = \sum (x_i - \bar{x})(y_i - \bar{y}) = \sum x_i y_i - \frac{\sum x_i \sum y_i}{n}$$

Product-moment correlation coefficient:

$$r = \frac{S_{xy}}{\sqrt{S_{xx}S_{yy}}} = \frac{\sum x_i y_i - \frac{\sum x_i \sum y_i}{n}}{\sqrt{\left[\left(\sum x_i^2 - \frac{\left(\sum x_i\right)^2}{n}\right)\left(\sum y_i^2 - \frac{\left(\sum y_i\right)^2}{n}\right)\right]}}$$

The regression coefficient of y on x is $b = \frac{S_{xy}}{S_{xx}} = \frac{\sum (x_i - \bar{x})(y_i - \bar{y})}{\sum (x_i - \bar{x})^2}$

Least squares regression line of y on x is $y = a + bx$ where $a = \bar{y} - b\bar{x}$

Spearman's rank correlation coefficient: $r_s = 1 - \frac{6\sum d_i^2}{n(n^2 - 1)}$

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Critical values for the product moment correlation coefficient, r

1-Tail Test	5%	2½%	1%	½%
2-Tail Test	10%	5%	2%	1%
n				
1	–	–	–	–
2	–	–	–	–
3	0.9877	0.9969	0.9995	0.9999
4	0.9000	0.9500	0.9800	0.9900
5	0.8054	0.8783	0.9343	0.9587
6	0.7293	0.8114	0.8822	0.9172
7	0.6694	0.7545	0.8329	0.8745
8	0.6215	0.7067	0.7887	0.8343
9	0.5822	0.6664	0.7498	0.7977
10	0.5494	0.6319	0.7155	0.7646
11	0.5214	0.6021	0.6851	0.7348
12	0.4973	0.5760	0.6581	0.7079
13	0.4762	0.5529	0.6339	0.6835
14	0.4575	0.5324	0.6120	0.6614
15	0.4409	0.5140	0.5923	0.6411
16	0.4259	0.4973	0.5742	0.6226
17	0.4124	0.4821	0.5577	0.6055
18	0.4000	0.4683	0.5425	0.5897
19	0.3887	0.4555	0.5285	0.5751
20	0.3783	0.4438	0.5155	0.5614
21	0.3687	0.4329	0.5034	0.5487
22	0.3598	0.4227	0.4921	0.5368
23	0.3515	0.4132	0.4815	0.5256
24	0.3438	0.4044	0.4716	0.5151
25	0.3365	0.3961	0.4622	0.5052
26	0.3297	0.3882	0.4534	0.4958
27	0.3233	0.3809	0.4451	0.4869
28	0.3172	0.3739	0.4372	0.4785
29	0.3115	0.3673	0.4297	0.4705
30	0.3061	0.3610	0.4226	0.4629
31	0.3009	0.3550	0.4158	0.4556
32	0.2960	0.3494	0.4093	0.4487
33	0.2913	0.3440	0.4032	0.4421
34	0.2869	0.3388	0.3972	0.4357
35	0.2826	0.3338	0.3916	0.4296
36	0.2785	0.3291	0.3862	0.4238
37	0.2746	0.3246	0.3810	0.4182
38	0.2709	0.3202	0.3760	0.4128
39	0.2673	0.3160	0.3712	0.4076
40	0.2638	0.3120	0.3665	0.4026
41	0.2605	0.3081	0.3621	0.3978
42	0.2573	0.3044	0.3578	0.3932
43	0.2542	0.3008	0.3536	0.3887
44	0.2512	0.2973	0.3496	0.3843
45	0.2483	0.2940	0.3457	0.3801
46	0.2455	0.2907	0.3420	0.3761
47	0.2429	0.2876	0.3384	0.3721
48	0.2403	0.2845	0.3348	0.3683
49	0.2377	0.2816	0.3314	0.3646
50	0.2353	0.2787	0.3281	0.3610
51	0.2329	0.2759	0.3249	0.3575
52	0.2306	0.2732	0.3218	0.3542
53	0.2284	0.2706	0.3188	0.3509
54	0.2262	0.2681	0.3158	0.3477
55	0.2241	0.2656	0.3129	0.3445
56	0.2221	0.2632	0.3102	0.3415
57	0.2201	0.2609	0.3074	0.3385
58	0.2181	0.2586	0.3048	0.3357
59	0.2162	0.2564	0.3022	0.3328
60	0.2144	0.2542	0.2997	0.3301

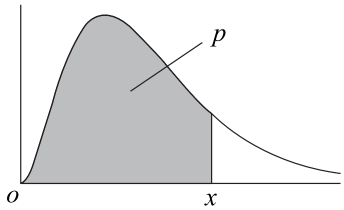
Critical values for Spearman's rank correlation coefficient, r_s

1-Tail Test	5%	2½%	1%	½%
2-Tail Test	10%	5%	2%	1%
n				
1	–	–	–	–
2	–	–	–	–
3	–	–	–	–
4	1.0000	–	–	–
5	0.9000	1.0000	1.0000	–
6	0.8286	0.8857	0.9429	1.0000
7	0.7143	0.7857	0.8929	0.9286
8	0.6429	0.7381	0.8333	0.8810
9	0.6000	0.7000	0.7833	0.8333
10	0.5636	0.6485	0.7455	0.7939
11	0.5364	0.6182	0.7091	0.7545
12	0.5035	0.5874	0.6783	0.7273
13	0.4835	0.5604	0.6484	0.7033
14	0.4637	0.5385	0.6264	0.6791
15	0.4464	0.5214	0.6036	0.6536
16	0.4294	0.5029	0.5824	0.6353
17	0.4142	0.4877	0.5662	0.6176
18	0.4014	0.4716	0.5501	0.5996
19	0.3912	0.4596	0.5351	0.5842
20	0.3805	0.4466	0.5218	0.5699
21	0.3701	0.4364	0.5091	0.5558
22	0.3608	0.4252	0.4975	0.5438
23	0.3528	0.4160	0.4862	0.5316
24	0.3443	0.4070	0.4757	0.5209
25	0.3369	0.3977	0.4662	0.5108
26	0.3306	0.3901	0.4571	0.5009
27	0.3242	0.3828	0.4487	0.4915
28	0.3180	0.3755	0.4401	0.4828
29	0.3118	0.3685	0.4325	0.4749
30	0.3063	0.3624	0.4251	0.4670
31	0.3012	0.3560	0.4185	0.4593
32	0.2962	0.3504	0.4117	0.4523
33	0.2914	0.3449	0.4054	0.4455
34	0.2871	0.3396	0.3995	0.4390
35	0.2829	0.3347	0.3936	0.4328
36	0.2788	0.3300	0.3882	0.4268
37	0.2748	0.3253	0.3829	0.4211
38	0.2710	0.3209	0.3778	0.4155
39	0.2674	0.3168	0.3729	0.4103
40	0.2640	0.3128	0.3681	0.4051
41	0.2606	0.3087	0.3636	0.4002
42	0.2574	0.3051	0.3594	0.3955
43	0.2543	0.3014	0.3550	0.3908
44	0.2513	0.2978	0.3511	0.3865
45	0.2484	0.2945	0.3470	0.3822
46	0.2456	0.2913	0.3433	0.3781
47	0.2429	0.2880	0.3396	0.3741
48	0.2403	0.2850	0.3361	0.3702
49	0.2378	0.2820	0.3326	0.3664
50	0.2353	0.2791	0.3293	0.3628
51	0.2329	0.2764	0.3260	0.3592
52	0.2307	0.2736	0.3228	0.3558
53	0.2284	0.2710	0.3198	0.3524
54	0.2262	0.2685	0.3168	0.3492
55	0.2242	0.2659	0.3139	0.3460
56	0.2221	0.2636	0.3111	0.3429
57	0.2201	0.2612	0.3083	0.3400
58	0.2181	0.2589	0.3057	0.3370
59	0.2162	0.2567	0.3030	0.3342
60	0.2144	0.2545	0.3005	0.3314

5

Critical values for the χ^2 distribution

If X has a χ^2 distribution with v degrees of freedom then, for each pair of values of p and v, the table gives the value of x such that
$P(X \le x) = p$.



p	0.01	0.025	0.05	0.90	0.95	0.975	0.99	0.995	0.999
$v = 1$	$0.0^{3}1571$	$0.0^{3}9821$	$0.0^{2}3932$	2.706	3.841	5.024	6.635	7.879	10.83
2	0.02010	0.05064	0.1026	4.605	5.991	7.378	9.210	10.60	13.82
3	0.1148	0.2158	0.3518	6.251	7.815	9.348	11.34	12.84	16.27
4	0.2971	0.4844	0.7107	7.779	9.488	11.14	13.28	14.86	18.47
5	0.5543	0.8312	1.145	9.236	11.07	12.83	15.09	16.75	20.51
6	0.8721	1.237	1.635	10.64	12.59	14.45	16.81	18.55	22.46
7	1.239	1.690	2.167	12.02	14.07	16.01	18.48	20.28	24.32
8	1.647	2.180	2.733	13.36	15.51	17.53	20.09	21.95	26.12
9	2.088	2.700	3.325	14.68	16.92	19.02	21.67	23.59	27.88
10	2.558	3.247	3.940	15.99	18.31	20.48	23.21	25.19	29.59
11	3.053	3.816	4.575	17.28	19.68	21.92	24.73	26.76	31.26
12	3.571	4.404	5.226	18.55	21.03	23.34	26.22	28.30	32.91
13	4.107	5.009	5.892	19.81	22.36	24.74	27.69	29.82	34.53
14	4.660	5.629	6.571	21.06	23.68	26.12	29.14	31.32	36.12
15	5.229	6.262	7.261	22.31	25.00	27.49	30.58	32.80	37.70
16	5.812	6.908	7.962	23.54	26.30	28.85	32.00	34.27	39.25
17	6.408	7.564	8.672	24.77	27.59	30.19	33.41	35.72	40.79
18	7.015	8.231	9.390	25.99	28.87	31.53	34.81	37.16	42.31
19	7.633	8.907	10.12	27.20	30.14	32.85	36.19	38.58	43.82
20	8.260	9.591	10.85	28.41	31.41	34.17	37.57	40.00	45.31
21	8.897	10.28	11.59	29.62	32.67	35.48	38.93	41.40	46.80
22	9.542	10.98	12.34	30.81	33.92	36.78	40.29	42.80	48.27
23	10.20	11.69	13.09	32.01	35.17	38.08	41.64	44.18	49.73
24	10.86	12.40	13.85	33.20	36.42	39.36	42.98	45.56	51.18
25	11.52	13.12	14.61	34.38	37.65	40.65	44.31	46.93	52.62
30	14.95	16.79	18.49	40.26	43.77	46.98	50.89	53.67	59.70
40	22.16	24.43	26.51	51.81	55.76	59.34	63.69	66.77	73.40
50	29.71	32.36	34.76	63.17	67.50	71.42	76.15	79.49	86.66
60	37.48	40.48	43.19	74.40	79.08	83.30	88.38	91.95	99.61
70	45.44	48.76	51.74	85.53	90.53	95.02	100.4	104.2	112.3
80	53.54	57.15	60.39	96.58	101.9	106.6	112.3	116.3	124.8
90	61.75	65.65	69.13	107.6	113.1	118.1	124.1	128.3	137.2
100	70.06	74.22	77.93	118.5	124.3	129.6	135.8	140.2	149.4

Wilcoxon signed rank test

W_+ is the sum of the ranks corresponding to the positive differences,
W_- is the sum of the ranks corresponding to the negative differences,
T is the smaller of W_+ and W_-.

For each value of n the table gives the **largest** value of T which will lead to rejection of the null hypothesis at the level of significance indicated.

Critical values of *T*

	Level of significance			
One Tail Two Tail	0.05 0.10	0.025 0.05	0.01 0.02	0.005 0.01
$n = 6$	2	0		
7	3	2	0	
8	5	3	1	0
9	8	5	3	1
10	10	8	5	3
11	13	10	7	5
12	17	13	9	7
13	21	17	12	9
14	25	21	15	12
15	30	25	19	15
16	35	29	23	19
17	41	34	27	23
18	47	40	32	27
19	53	46	37	32
20	60	52	43	37

For larger values of n, each of W_+ and W_- can be approximated by the normal distribution with mean $\frac{1}{4}n(n+1)$ and variance $\frac{1}{24}n(n+1)(2n+1)$.

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Wilcoxon rank sum test

The two samples have sizes m and n, where $m \leq n$.
R_m is the sum of the ranks of the items in the sample of size m.
W is the smaller of R_m and $m(m+n+1) - R_m$.

For each pair of values of m and n, the table gives the **largest** value of W which will lead to rejection of the null hypothesis at the level of significance indicated.

Critical values of W

	Level of significance											
One Tail	0.05	0.025	0.01	0.05	0.025	0.01	0.05	0.025	0.01	0.05	0.025	0.01
Two Tail	0.1	0.05	0.02	0.1	0.05	0.02	0.1	0.05	0.02	0.1	0.05	0.02
n	$m = 3$			$m = 4$			$m = 5$			$m = 6$		
3	6	–	–									
4	6	–	–	11	10	–						
5	7	6	–	12	11	10	19	17	16			
6	8	7	–	13	12	11	20	18	17	28	26	24
7	8	7	6	14	13	11	21	20	18	29	27	25
8	9	8	6	15	14	12	23	21	19	31	29	27
9	10	8	7	16	14	13	24	22	20	33	31	28
10	10	9	7	17	15	13	26	23	21	35	32	29

	Level of significance											
One Tail	0.05	0.025	0.01	0.05	0.025	0.01	0.05	0.025	0.01	0.05	0.025	0.01
Two Tail	0.1	0.05	0.02	0.1	0.05	0.02	0.1	0.05	0.02	0.1	0.05	0.02
n	$m = 7$			$m = 8$			$m = 9$			$m = 10$		
7	39	36	34									
8	41	38	35	51	49	45						
9	43	40	37	54	51	47	66	62	59			
10	45	42	39	56	53	49	69	65	61	82	78	74

For larger values of m and n, the normal distribution with mean $\frac{1}{2}m(m+n+1)$ and variance $\frac{1}{12}mn(m+n+1)$ should be used as an approximation to the distribution of R_m.

Mechanics

Kinematics

Motion in a straight line

$v = u + at$

$s = ut + \frac{1}{2}at^2$

$s = \frac{1}{2}(u + v)t$

$v^2 = u^2 + 2as$

$s = vt - \frac{1}{2}at^2$

Motion in two dimensions

$\mathbf{v} = \mathbf{u} + \mathbf{a}t$

$\mathbf{s} = \mathbf{u}t + \frac{1}{2}\mathbf{a}t^2$

$\mathbf{s} = \frac{1}{2}(\mathbf{u} + \mathbf{v})t$

$\mathbf{v.v} = \mathbf{u.u} + 2\mathbf{a.s}$

$\mathbf{s} = \mathbf{v}t - \frac{1}{2}\mathbf{a}t^2$

Newton's experimental law

Between two smooth spheres $v_1 - v_2 = -e(u_1 - u_2)$

Between a smooth sphere with a fixed plane surface $v = -eu$

Motion in a circle

Tangential velocity is $v = r\dot{\theta}$

Radial acceleration is $\frac{v^2}{r}$ or $r\dot{\theta}^2$ towards the centre

Tangential acceleration is $\dot{v} = r\ddot{\theta}$

Centres of mass

Triangular lamina: $\frac{2}{3}$ along median from vertex

Solid hemisphere, radius r: $\frac{3}{8}r$ from centre

Hemispherical shell, radius r: $\frac{1}{2}r$ from centre

Circular arc, radius r, angle at centre 2α: $\frac{r\sin\alpha}{\alpha}$ from centre

Sector of circle, radius r, angle at centre 2α: $\frac{2r\sin\alpha}{3\alpha}$ from centre

Solid cone or pyramid of height h: $\frac{1}{4}h$ above the base on the line from centre of base to vertex

Conical shell of height h: $\frac{1}{3}h$ above the base on the line from centre of base to vertex

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