20/02

Lecture 4 - Linear transformations

Matrix transformations

$$T(x) = \begin{bmatrix} 3 & 5 \\ 0 & 4 \\ 0 & 0 \end{bmatrix} \times \begin{array}{c} \text{domain: } \mathbb{R}^{2} \text{ (columns)} \\ \text{x codomain: } \mathbb{R}^{3} \text{ (rows)} \\ \text{x range: span of columns} \end{bmatrix} \times \mathbb{E}T(y) T(y) = \begin{bmatrix} 3y_{1} + 5y_{2} \\ 4y_{2} \\ 3 \end{bmatrix}$$

$$A = \begin{bmatrix} -2 & 5 & 1 \\ 3 & -1 & 4 \end{bmatrix} \quad Ax = \begin{bmatrix} -2 \times_{1} + 5 \times_{2} + \times_{3} \\ 3 \times_{1} - \times_{2} + 4 \times_{3} \end{bmatrix}$$

Des. matrix $A(m \times n)$ defines transformation $T: \mathbb{R}^n \to \mathbb{R}^m$ $T(x) = A \times b$ Change $(T) \longleftrightarrow A \times b$ - consistent

Linear transformations

Def.
$$T: \mathbb{R}^n \to \mathbb{R}^m$$
 is linear if:
oT(u+v)=T(u)+T(v) for $\forall u_1v \in \mathbb{R}^m$
oT(u)=cT(u) for $\forall c \in \mathbb{R}$, $\forall u \in \mathbb{R}^m$

The transformation $R^{w} \rightarrow R^{w}$ $T(0) \neq 0 \rightarrow T$ is nonlinear $T(0) \neq 0 \rightarrow T$ is nonlinear

 $T(0) = 0 \rightarrow \text{property of linear transformations, not a condition, } \sin(0) = 0$ $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3 \Rightarrow A : 3 \times 2 \qquad T: \mathbb{R}^3 \rightarrow \mathbb{R}^2 \text{ linear}$ $T(\begin{bmatrix} 1 \\ 1 \end{bmatrix}) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \qquad T(\begin{bmatrix} -1 \\ -1 \end{bmatrix}) = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix} \qquad = 3 \cdot (\kappa) = T(\kappa) + 3(\kappa)$ $T(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}) = \begin{bmatrix} 3x_1 + x_2 \\ x_1 + x_2 \\ 4x_1 - x_2 \end{bmatrix} \Rightarrow A = \begin{bmatrix} 3 & 1 \\ 1 & 4 \\ 4 & 4 \end{bmatrix} T(\begin{bmatrix} 0 \\ 4 \end{bmatrix}) = \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix} \qquad -\text{linear } \mathbb{R}^3 \rightarrow \mathbb{R}^2$

The T-rotation about the origin, Yangle

T(x)=Ax => A= [co> 4 - sin 9]

linear sin 4 co> 4] 1.9. / I. R => R => A= [-(0)(27) - in(27)] = [1/18 12]

rotate 25, reflect on x, - sin(27) os(27) = [1/18 12] a. T: $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ shear ex into ex- 2a $\rightarrow A = \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix}$ respect on $x_2 = -x_1 \rightarrow A = \begin{bmatrix} 0 & -1 \\ -1 & x \end{bmatrix}$ $\begin{bmatrix} \mathbf{3} & \mathbf{0} & \mathbf{4} \\ \mathbf{4} & \mathbf{0} & \mathbf{0} \\ \mathbf{1} & \mathbf{-1} & \mathbf{1} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3x_1 - 2x_3 \\ 4x_1 \\ x_1 - x_2 + x_3 \end{bmatrix}$ Lecture 5 - Matrix operations 21/02 Matrix addition and scalar multiplication A= 1 1 B= 2 -2 A= 1 1 B= 2 -2 2A-B= 0 4 3 5 4 -1 AtB=undefined -2 3 Def. A - mxu matrix: o zero - all entries are O osquare - wew main diagonal of a matrix - a; entries Square mostrix: o diagonal matrix - all obt-diagonal entries are 0

o identity matrix - diagonal matrix with 1's on the main diagonal olower/upper triangular matrix - all entries above/below main diagonal are 0

The T:
$$\mathbb{R}^{p} \rightarrow \mathbb{R}^{n}$$
 S: $\mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$
(SoT) (x) = 5(T(x)) all linear

Def. A-nxu matrix S(x)=AxB-nxp matrix T(x)=Bx

The A - mx w matrix

$$A = \begin{bmatrix} -5 & 3 \\ -4 & -1 \end{bmatrix}$$
 $B = \begin{bmatrix} 1 & -1 & 2 \\ 2 & 6 & 0 \end{bmatrix}$ $AB = \begin{bmatrix} 1 & 23 & -10 \\ -6 & -2 & -8 \end{bmatrix}$

$$(AB)_{ij} = a_{i1}b_{ij} + a_{12}b_{2j} + ... + a_{im}b_{nj}$$

$$A = \begin{bmatrix} A & 2 & 3 & 4 \\ 4 & 3 & 2 & 4 \\ -4 & -2 & -3 & -4 \end{bmatrix}$$

$$B = \begin{bmatrix} A & A & A \\ 4 & -4 & -2 \end{bmatrix}$$

$$A = \begin{bmatrix} A & A & A \\ -4 & 2 \end{bmatrix}$$

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$$A =$$

 $A = \begin{bmatrix} 0 & 1 & B = 0 & 1 & AB = \begin{bmatrix} 1 & 0 & BA = -1 & 0 \\ -1 & 0 & 1 & 0 & 0 \end{bmatrix} = AB = -BA$

Def. A - we want in x
$$k \in \mathbb{N}$$
 $k \geq 0$
 $A^{k} = AA ... A \quad k = 0, \quad A^{k} = 0$
 $A = \begin{bmatrix} \cos \gamma - \sin \gamma \\ k & \cos \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ k & \cos \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ k & \cos \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ k & \cos \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ k & \cos \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ k & \cos \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ k & \cos \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ \sin \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ \sin \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ \sin \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ \sin \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma - \sin \gamma \\ \sin \gamma \end{bmatrix} = \begin{bmatrix} \cos \gamma \\ \cos \gamma \end{bmatrix} = \begin{bmatrix}$

An ape imitating an ape is aping.

Transpose of a matrix

$$A^{T}$$
 - $n_{x}w$ form of the same matrix
$$A = \begin{bmatrix} 1 & 2 \end{bmatrix} \quad A^{2} \begin{bmatrix} 7 & 10 \end{bmatrix} \quad AB = \begin{bmatrix} -1 & 4 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$A^{2} = \begin{bmatrix} 7 & 10 \\ 15 & 22 \end{bmatrix}$$

$$A^{3} = \begin{bmatrix} 1 & -1 \\ 2 & 4 \end{bmatrix}$$

$$A^{3} = \begin{bmatrix} 1 & -1 \\ 2 & 4 \end{bmatrix}$$

$$A^{4} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}$$

$$A^{5} = \begin{bmatrix} 7 & 2 \\ 10 & 22 \end{bmatrix}$$

$$A^{7} = \begin{bmatrix} 7 & 15 \\ 10 & 22 \end{bmatrix}$$

$$A^{7} = \begin{bmatrix} 7 & 2 \\ 10 & 22 \end{bmatrix}$$

(AB) T + AT BT

The A,B - appropriate size matrices (AT)T=A

 $(A+B)^T = A^T + B^T$

24/02

Th A-non matrix

A-invertible A-row equivalent to Su

A-n pivots A = 0 -only trivial solution

A-independent columns columns of A-span \mathbb{R}^n equivalent

A-invertible A = 0 A =

A-nxu matrix, n linearly independent columns => A2 - invertible

Def.
$$T: \mathbb{R}^n \to \mathbb{R}^n$$
 (linear) -invertibe if $\exists S, S: \mathbb{R}^n \to \mathbb{R}^n$
s.t. $\forall x \in \mathbb{R}^n$, $S(T(x)) = x$ and $T(S(x)) = x$, $S = T^{-1} = inverse$ of T

The T: R" - R" - invertible if A-invertible T(x)=Ax ->T-1(x) = A-1 x

$$A = \begin{bmatrix} 5 & 0 & 0 \\ -3 & -4 & 0 \\ 8 & 5 & -4 \end{bmatrix} \xrightarrow{5} \begin{bmatrix} 5 & 0 & 0 \\ 0 & -7 & 0 \\ 0 & 0 & -4 \end{bmatrix}$$
 invertible

AB-invertible
$$V = V = (AB)^{-1} = B^{-1}A^{-1}$$

=> $ABU = L$ => $AB = invertible$