Lecture 1 - Linear systems and echelon forms 13/02 Ded. System:

- consistent - has at least one solution oinconsistent - has us solutions at all [00...012] c+0 x3=4 x2=8 x3=5 x4=2 1 0 -3 8 x<sub>1</sub> = 5 2 0 -1 11 x<sub>1</sub> = 3 0 4 5 -1 x<sub>2</sub> = 1 as a) T b) f of a) T rows = columns

### Echleron form

a) All monzero rows are above any row of all zeros.

b) Each leading entry (pivot) is in a column to the ryster of the leading

ending in the previous row. 

#### Reduced echelon forms

a) in echelon form

b) the givet of each nonzero row is 1.

c) each leading I is the only nonzero entry in its column

 $\begin{bmatrix} 0 & 1 & * & 0 & 0 & * & * & * & 0 & 0 & * \\ 0 & 0 & 0 & 1 & 0 & * & * & * & 0 & 0 & * \\ 0 & 0 & 0 & 0 & 1 & * & * & * & 0 & 0 & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & | & * \end{bmatrix} \begin{bmatrix} \blacksquare & * & * & * & * & * & * \\ 0 & \blacksquare & * & * & * & * & * \\ 0 & 0 & \blacksquare & * & * & * & * \\ 0 & 0 & 0 & 0 & \blacksquare & 0 & 0 \end{bmatrix}$ 

## Solving Linear Systems

# Def. Variable:

obasic - column contains pivot position ( Fi, KLIFS, Fr) · Free - column doesn't contain pivod position (xn) consistent, = solutions

1.1.  $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 4 & 5 & 6 & 4 \\ 6 & 7 & 8 & 9 \end{bmatrix}$   $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 & -6 & -6 \\ 0 & 7 & -6 & -6 \\ 0 & 7 & -6 & -$ 

45. 
$$\begin{bmatrix} 0 & * & * & * \\ 0 & 0 & * & * \\ 0 & 0 & * & * \\ 0 & 0 & * & * \\ 0 & 0 & * & * \\ 0 & 0 & * & * \\ 0 & 0 & 0 & * \end{bmatrix}$$

Lecture  $L$  — Spans, vector equations and matrix equations

$$\begin{bmatrix} 1 & 2 & * & * \\ 0 & 0 & * & * \\ 0 & 0 & 0 & * \end{bmatrix}$$

Lecture  $L$  — Spans, vector equations and matrix equations

$$\begin{bmatrix} 1 & 2 & * \\ -2 & 5 & 4 \\ -5 & 6 & - \end{bmatrix} \rightarrow x, \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -2 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -2 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -2 \\ -4 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 3 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 3 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 3 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 3 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 3 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 3 \\ -4 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ -4 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 3 \\ -4 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 4 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 3 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 0 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 4 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 4 \end{bmatrix}$$

14/02

Del. vectors 
$$v_{1}v_{2},...,v_{p} \in \mathbb{R}^{n}$$
 scalars  $c_{1}c_{2},...,c_{p}$ 
 $y = c_{1}v_{1} + ... + c_{p}v_{p}$  — linear combination of  $v_{1}...v_{p}$  with weights  $c_{1}...c_{n}$ 
 $b = \begin{bmatrix} 4 \\ 0 \\ 34 \end{bmatrix}$ 
 $a_{1} = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$ 
 $a_{2} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ 
 $b = -2a_{1} + 4a_{2}$ 

The 
$$x_1a_1+x_2a_2+...+x_pa_p=b \leftrightarrow [a_1 \ a_2 \ ... \ a_p]b$$

Def. vectors  $v_{i_1}v_{i_2}...,v_p \in \mathbb{R}^n$ 

Span  $\int v_{i_1}v_{i_2}...,v_p \uparrow \rightarrow \text{set of all linear combinations ad } v_{i_1}v_{i_2}...,v_p$ 

1.3./ 11 
$$a_1 \cdot \begin{bmatrix} \frac{1}{2} \\ 0 \end{bmatrix}$$
  $a_2 \cdot \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$   $a_3 \cdot \begin{bmatrix} 5 \\ -6 \\ 8 \end{bmatrix}$   $b : \begin{bmatrix} 2 \\ -1 \\ 6 \end{bmatrix}$   $b : a_3 - 3a_1 - a_2$ 

13 
$$\begin{bmatrix} 4 & -4 & 1 \\ 0 & 3 & 5 \\ -1 & 8 & -4 \end{bmatrix}$$
  $\begin{bmatrix} 3 \\ -1 \\ -2 \\ -2 \\ -3 \end{bmatrix}$   $\begin{bmatrix} A_1 - 4A_2 + 2A_3 = 3 \\ 3A_2 + 5A_3 = -7 \\ -2A_1 + 6A_1 - 4A_3 = -3 \end{bmatrix}$  wo solution

12 
$$\begin{bmatrix} 4 \\ 4 \\ -2 \end{bmatrix}$$
  $\begin{bmatrix} -2 \\ 4 \end{bmatrix}$   $\begin{bmatrix} 4 \\ 4 \\ -3 \end{bmatrix}$   $\begin{bmatrix} 4 \\ 4 \\ -4 \end{bmatrix}$   $\begin{bmatrix} 4 \\ 4 \\ -4 \end{bmatrix}$   $\begin{bmatrix} 4 \\ 4 \\ -4 \end{bmatrix}$   $\begin{bmatrix} 4 \\ 4 \\ 4 \end{bmatrix}$   $\begin{bmatrix} 4 \\ 4$ 

# Matrix-vector product

### Matrix equations

The A-man madrix with columns a, ... an be Re

vector equation: X1 a1 + x2 a2 + ... + x1 a1 = b

matrix equation: Ax=b

linear system: [a, a, ... an | b]

The A-man madrix th A-min matrix

th, bet? Ax=b has a solution.

b-linear combination of the columns of A lequivalent

?

A - pivot position in every row.

**1.h.**  $\int_{0}^{7} \begin{bmatrix} 7 & -3 \\ 2 & 1 \\ 9 & -6 \\ -3 & 2 \end{bmatrix} \begin{bmatrix} -2 \\ -5 \end{bmatrix} = \begin{bmatrix} 1 \\ -9 \\ 12 \\ -4 \end{bmatrix}$  **-> -2**  $\begin{bmatrix} 4 \\ 2 \\ 9 \\ -3 \end{bmatrix}$  **-S**  $\begin{bmatrix} -3 \\ 4 \\ 5 \end{bmatrix}$  **-9 -1** 

b1 +-3 -> no solution

Lecture 3 - Solution sets and linear independence 17/02 x1 = - x3 x2 = 2 x3 x3 - free Homojeneous systems Ded. System Axabi homogeneous if b=0 → always consistent
 nonhomogeneous if b≠0 free variable → ∞ solutions Solutions of (non) homogeneous systems The wonhows, eneous Ax=b, x=xp+xu xp-particular solution xi-general solution of homogeneous Ax=0  $A = \begin{bmatrix} 3 & 5 & 2 & 6 \\ 2 & 4 & 2 & 2 \\ 1 & 1 & 0 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1 & 7 \\ 0 & 1 & 1 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ Ax = 0

=> solution set: span of two vector in R' 1 3 1 0 [13 1 0 5] -4 -9 2 0 ~ 0 1 2 0 x = x 3 -2 0 -3 -6 0 0 0 0 0 4.5. / S. X1+3x2+x3=0 -4x1-9x2+2x3=0 -3x1 - 6x3=0

 $\begin{cases} \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ 4 \end{bmatrix}, \begin{bmatrix} 6 \\ 5 \end{bmatrix} \end{bmatrix} \rightarrow \text{linearly dependent} \\ \begin{cases} \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -3 \\ 6 \end{bmatrix}, \begin{bmatrix} -9 \\ 2 \end{bmatrix} \end{bmatrix} \rightarrow \text{linearly independent} \\ \begin{bmatrix} -3 \\ 3 \end{bmatrix}, \begin{bmatrix} 6 \\ 6 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix} \end{bmatrix} \begin{pmatrix} -3 \\ 2 \end{bmatrix} \begin{pmatrix} -3 \\ 2 \end{pmatrix} \begin{pmatrix} -3 \\ 2 \end{pmatrix}$ 

The Set full veil..., up ?.

olinearly dependent is 21 vector is linear combination of other olinearly independent otherwise

The fu, v2, ..., up? in R" is p> w, linearly dependent
fu, v2, ..., up? in R" is containing o rector linearly dependent

Vx, V2, V5, V4 ER"