

05/03

Academic Reasoning 1

- ① $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$
 $n \geq 3, m \geq 3$ $\{v_1, v_2, v_3\}$ - linearly independent $\rightarrow \{T(v_1), T(v_2), T(v_3)\}$ - linearly independent

$$T(x) = Ax \Rightarrow T(v_1) = Av_1, T(v_2) = Av_2, T(v_3) = Av_3$$

\Rightarrow Dependency of $\{T(v_1), T(v_2), T(v_3)\}$ = dependency of columns of A

\Rightarrow false, $A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ $\begin{cases} v_1 = e_1 \\ v_2 = e_2 \\ v_3 = e_3 \end{cases} \Rightarrow \begin{cases} T(v_1) = e_1 \\ T(v_2) = 2e_1 \\ T(v_3) = 3e_1 \end{cases}$ $\begin{cases} \{v_1, v_2, v_3\} \text{ - linearly independent} \\ \text{columns of } A \text{ - linearly dependent} \\ \{T(v_1), T(v_2), T(v_3)\} \text{ - lin. dependent} \end{cases}$

- ② $\{v_1, v_2, v_3\}$ - linearly independent $\rightarrow \{v_1, v_2, v_3, v_4\}$ - linearly independent
 $\{v_3, v_4\}$ - linearly independent

false, counter example - v_1 or v_2 - linearly dependent with v_4

$$v_1 = e_1 \quad v_2 = e_2 \quad v_3 = e_3 \quad v_4 = c(v_1 \text{ or } v_2)$$

$$\Rightarrow \begin{cases} \{v_1, v_2, v_3\} \text{ - linearly independent} \\ \{v_3, v_4\} \text{ - linearly independent} \end{cases} \quad \begin{cases} \{v_1, v_2, v_3, v_4\} \text{ - linearly dependent} \\ v_4 \text{ - linearly dependent with } v_1 \text{ or } v_2 \end{cases}$$

concrete example: $v_1 = e_1, v_2 = e_2, v_3 = e_3, v_4 = e_1$

- ③ A - $n \times n$ matrix

$\exists b \in \mathbb{R}^n \Rightarrow Ax = b$ - infinitely many solutions

$\rightarrow \exists c \in \mathbb{R}^n \Rightarrow Ax = c$ - no solutions

$\exists b \in \mathbb{R}^n \Rightarrow Ax = b$ - ∞ solutions

$\Rightarrow A$ - at least one column without pivot (Invertible Matrix Theorem)

$\Rightarrow \exists c \in \mathbb{R}^n \Rightarrow Ax = c$ - 0 solutions

- ④ A - reduced echelon form = I
 $\rightarrow A^2$ - reduced echelon form = I

A - reduced echelon form = I

$\Rightarrow A$ - invertible

$\Rightarrow A^2$ - invertible

$\Rightarrow A^2$ - reduced echelon form = I

(Invertible Matrix Theorem)

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