

$$\text{ODE: } \frac{\partial x}{\partial t} = f(x, t), \quad x(t_0) = x_0$$

$$\text{SDE: } \frac{\partial x}{\partial t} = f(x, t) + g(x, t) \xi(t), \quad x(t_0) = x_0$$

white noise

$$\mathbb{E}[S(t)] = 0$$

$$\mathbb{E}[S(t_1)S(t_2)] = \delta(t_1 - t_2)$$

Ex. Biochemical Oxygen Demand (BOD)

$$\frac{\partial B_t}{\partial t} = -K_1 B_t + s_t, \quad b = \text{BOD} \left[\frac{\text{mg}}{\text{L}} \right], \quad K_1 = \text{reaction rate} \left[\frac{\text{day}}{} \right], \quad s_t = \text{source/sink}$$

$$\mathbb{E}(N_t) = 0, \quad \mathbb{E}[N_t N_s] = \delta(t-s), \quad N_t = \text{Gaussian white noise}$$

$$\Rightarrow \frac{\partial B_t}{\partial t} = -K_1 B_t + s_t + \sigma N_t, \quad B_{t_0} = B_0, \quad \text{uncertainty on } s_t$$

$$\frac{\partial B_t}{\partial t} = -(K_1 + \sigma N_t) B_t + s_t = -K_1 B_t + s_t - B_t \sigma N_t, \quad B_{t_0} = B_0, \quad \text{uncertainty on } K_1$$

Markovian process - information on the probability density of the state X_t at time t is sufficient for computing model predictions for times $\geq t$

Ex. 1

$$X_k = a X_{k-1} + b X_{k-2} + W_k, \quad W_k \sim RV$$

X_k is not Markovian, $b \neq 0$, X_{k-2} is useful for predicting X_k

Define state vector: $Y_k = [X_k \ X_{k-1}]$

$$\text{Markov process: } Y_k = \begin{bmatrix} a & b \\ 1 & 0 \end{bmatrix} Y_{k-1} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} W_k$$

W_k now depends on $W_i, i < k \Rightarrow Y_k$ is not Markovian, since Y_{k-2} provides information for W_{k-1} , useful for predicting Y_k

Ex. 2

$$X_t = a + bt, \quad X_0 = a, \quad a, b \sim RV$$

X_t is Gaussian process, since linear on Gaussian variables.

X_t is not Markovian.

$$X_{t_u} = X_{t_{u-1}} + b(t_u - t_{u-1})$$

$$\Rightarrow X_{t_u} = X_{t_{u-1}} + \frac{t_u - t_{u-1}}{t_{u-1} - t_{u-2}} (X_{t_{u-1}} - X_{t_{u-2}})$$

$$\frac{\partial x}{\partial t} = f(x, t) + g(x, t) \zeta(t)$$

Wiener process/Brownian motion: $\frac{\partial w}{\partial t} = \zeta(t)$

$$dx = f(x, t) dt + g(x, t) dW$$

$$x(t) = x_0 + \int_0^t f(x, s) ds + \int_0^t g(x, s) dW(s)$$

Def. Wiener process, $W_t, t \geq 0$ - process with $W_0 = 0$, increments $W_t - W_s$ are Gaussian RV
 $\Rightarrow E[W_t - W_s] = 0, \text{Var}[W_t - W_s] = t - s$

non-overlapping increments are independent

$$W_{t+1} - W_t = \Delta W_t, E[\Delta W_t] = 0, E[\Delta W_t^2] = \Delta t, W_{t+1} = W_t + \sqrt{\Delta t} N(0, 1), W_0 = 0$$

$$X(w) = e^{bw}, X_t = e^{bW_t}$$

vector stochastic process $\{X_t, t \in T\}$ - a family of random variables/vectors indexed by parameter set T

1. $X_t \in \mathbb{Z}$ - discrete state space process \uparrow discrete parameter chain
 $t \in \mathbb{N}$ - discrete parameter set

2. $X_t \in \mathbb{R}$ - continuous state space process \uparrow random sequence
 $t \in \mathbb{N}$ - discrete parameter set

3. $X_t \in \mathbb{Z}$ - discrete state space process
 $t \in \mathbb{R}$ - continuous parameter set

4. $X_t \in \mathbb{R}$ - continuous state space process \uparrow Stochastic Random Process
 $t \in \mathbb{R}$ - continuous parameter set

Stochastic depends on time, t and $w \in \mathbb{R}$ (realization).

Ex. Random Walk (RW)

$$\Delta x > 0, S_t = \{H, T\}, p(H) = p, p(T) = q = 1-p$$

η - random variable = $\begin{cases} \Delta x & \text{id } w=H \\ -\Delta x & \text{id } w=T \end{cases}$

$$Pr[\eta(w) = \Delta x] = p, Pr[\eta(w) = -\Delta x] = q = 1-p$$

$$X_n = \sum_{i=0}^{n-1} \eta_i = \sum_{i=0}^{n-1} \eta_i + \eta_{n-1} = X_{n-1} + \eta_{n-1} \rightarrow \text{difference equation}$$

\uparrow any distribution

Stationarity of processes

$p(X_1, \dots, X_n, t_1, \dots, t_n) = p(X_1, \dots, X_n, t_1+s, \dots, t_n+s)$, $t_1, t_2 \in \mathbb{R}$ - strict sense stationary process (SSS)

$$\text{① } p(X_i, t_i) = p(X_i, t_i+s) = p(X_i)$$

$$\text{② } p(X_1, X_2, t_1, t_2) = p(X_1, X_2, t_1+s, t_2+s) \Rightarrow \text{③ } p(X_1, X_2, t_1, t_2) = p(X_1, X_2, t_2-t_1)$$

① + ② = wide sense (weak) stationary process (WSS)

$$\text{Ex. } X_t = a + bt, a, b \sim RV$$

$$\mathbb{E}[X_t] = \mathbb{E}[a + bt] = \mathbb{E}[a] + t\mathbb{E}[b] = t$$

$$\begin{aligned} R(t, \tau) &= \mathbb{E}[X_t X_{t+\tau}] = \mathbb{E}[a^2] + \mathbb{E}[ab]t + \mathbb{E}[ab]\tau + \mathbb{E}[b^2]t\tau \\ &= \text{var}(a) + \text{cov}(a, b)(t+\tau) + \text{var}(b)t\tau \quad (\mathbb{E}[a] = \mathbb{E}[b] = 0) \\ &\cdot \text{var}(a) + \text{var}(b)t\tau \quad (\text{cov}(a, b) = 0) \end{aligned}$$

weak stationary process: $R(t_1, t_2) = R(t_1 - t_2)$, $R(t, t) = \mathbb{E}[X_t X_t] = \mathbb{E}[X_t^2] = R(0)$ - constant

Wiener process: $\mathbb{E}[W(t)] = 0 < \int_{-\infty}^{\infty} p(x, t) x dx$, $R(t, t+s) = \sigma^2 t - \text{not stationary}$

Convergence:

i) $X_n \xrightarrow{P} x$ with probability

ii) $\{X_n\} \xrightarrow{P} x$ in probability $\lim_{n \rightarrow \infty} \mathbb{P}(X_n \neq x) \rightarrow 0$ almost surely

iii) $\{X_n\} \xrightarrow{P} x$ in mean square sense, iii) \Rightarrow ii) $\lim_{n \rightarrow \infty} \mathbb{E}[|X_n - x|^2] = 0$

$$\lim_{n \rightarrow \infty} \mathbb{E}[|X_n - x|^2] = 0, \mathbb{E}[|X_n|^2] < \infty, \mathbb{E}[|x|^2] < \infty$$

$$\begin{aligned} \mathbb{E}[|y|^2] &= \int_{-\infty}^{+\infty} |y|^2 p(y) dy = \int_{-\infty}^{\varepsilon} |y|^2 p(y) dy + \int_{\varepsilon}^{+\infty} |y|^2 p(y) dy \geq \varepsilon^2 \left[\int_{-\infty}^{\varepsilon} p(y) dy + \int_{\varepsilon}^{+\infty} p(y) dy \right] = e^{-\varepsilon} \Pr(|y| > \varepsilon) \\ y = X_n - x \Rightarrow \mathbb{E}[|X_n - x|^2] &= \Pr(|X_n - x| > \varepsilon) \end{aligned}$$

$$X = \lim_{n \rightarrow \infty} X_n, Y = \lim_{n \rightarrow \infty} Y_n$$

$$\text{Th 1) } \lim_{n \rightarrow \infty} (aX_n + bY_n) = aX + bY$$

$$\text{d) } \mathbb{E}[X] = \lim_{n \rightarrow \infty} \mathbb{E}[X_n] = \mathbb{E}\left[\lim_{n \rightarrow \infty} X_n\right]$$

$$\text{e) } \mathbb{E}[XY] = \lim_{n \rightarrow \infty} \mathbb{E}[X_n Y_n] = \mathbb{E}\left[\lim_{n \rightarrow \infty} X_n \lim_{n \rightarrow \infty} Y_n\right]$$

$$\mathbb{E}[(|x| - |y|)^2] = a^2 \mathbb{E}[|x|^2] + \mathbb{E}[|y|^2] - 2a \mathbb{E}[|x||y|] \geq 0 \Rightarrow D = 4a^2 \mathbb{E}[|x||y|] - 4a^2 \mathbb{E}[|x|^2] \mathbb{E}[|y|^2] \leq 0$$

Cauchy-Schwarz: $\mathbb{E}[|x||y|] \leq \sqrt{\mathbb{E}[|x|^2] \mathbb{E}[|y|^2]}$

Proof of Property 5: $\lim_{n \rightarrow \infty} (aX_n + bY_n) = aX + bY$

$$\begin{aligned}
 \text{To prove: } & \mathbb{E}[|aX_n + bY_n - (aX + bY)|^2] = 0 \quad (n \rightarrow \infty) \\
 &= \mathbb{E}[|a(X_n - X) + b(Y_n - Y)|^2] \leq 2a^2 \mathbb{E}[|X_n - X|^2] + 2b^2 \mathbb{E}[|Y_n - Y|^2] = 0 \\
 & \mathbb{E}[|X|^2] + \mathbb{E}[|Y|^2] + 2\mathbb{E}[|XY|] \leq 2\mathbb{E}[|X|^2] + 2\mathbb{E}[|Y|^2] \\
 & \mathbb{E}[|X|^2] + \mathbb{E}[|Y|^2] - 2\mathbb{E}[|XY|] \geq \mathbb{E}[|X|^2] + \mathbb{E}[|Y|^2] \\
 & \mathbb{E}[|X|^2] + \mathbb{E}[|Y|^2] - 2\mathbb{E}[|X|^2]\mathbb{E}[|Y|^2] \geq \mathbb{E}[|X|^2] + \mathbb{E}[|Y|^2] \\
 & 0 \leq \left(\mathbb{E}[|X|^2] - \mathbb{E}[|X|^2] \right)^2 = \mathbb{E}[|X|^2] + \mathbb{E}[|Y|^2] = 0
 \end{aligned}$$

Proof of Property 6: $\mathbb{E}[X] = \lim_{n \rightarrow \infty} \mathbb{E}[X_n] = \mathbb{E}\left[\lim_{n \rightarrow \infty} X_n\right]$

$$\begin{aligned}
 \text{To prove: } & \mathbb{E}[X] = \lim_{n \rightarrow \infty} \mathbb{E}[X_n] \\
 & |\mathbb{E}[X_n - X]|^2 \leq \mathbb{E}[|X_n - X|^2] \rightarrow 0 \quad (n \rightarrow \infty)
 \end{aligned}$$

Ex. 5

1) To prove: $\lim_{n \rightarrow \infty} aX_n = aX$

$$\lim_{n \rightarrow \infty} X_n = X \Rightarrow \lim_{n \rightarrow \infty} \mathbb{E}[|X_n - X|^2] = 0$$

$$\Rightarrow a \lim_{n \rightarrow \infty} \mathbb{E}[|X_n - X|^2] = \lim_{n \rightarrow \infty} \mathbb{E}[a^2 |X_n - X|^2] = \lim_{n \rightarrow \infty} \mathbb{E}[|aX_n - aX|^2] = 0 \Rightarrow \lim_{n \rightarrow \infty} aX_n = aX$$

2) To prove: $\lim_{n \rightarrow \infty} X_n + Y_n = X + Y$

$$\lim_{n \rightarrow \infty} \mathbb{E}[|X_n + Y_n - X - Y|^2] = \lim_{n \rightarrow \infty} \mathbb{E}[|X_n - X + Y_n - Y|^2]$$

$$\leq \lim_{n \rightarrow \infty} \mathbb{E}[2|X_n - X|^2 + 2|Y_n - Y|^2]$$

$$= \lim_{n \rightarrow \infty} 2\mathbb{E}[|X_n - X|^2] + \lim_{n \rightarrow \infty} 2\mathbb{E}[|Y_n - Y|^2] = 0$$

3) To prove: $\mathbb{E}\left(\lim_{n \rightarrow \infty} X_n\right) = \lim_{n \rightarrow \infty} \mathbb{E}[X_n] = \mathbb{E}[X]$

$$\lim_{n \rightarrow \infty} |\mathbb{E}[X_n] - \mathbb{E}[X]| = \lim_{n \rightarrow \infty} |\mathbb{E}[X_n - X]|$$

$$\leq \lim_{n \rightarrow \infty} \mathbb{E}[|X_n - X|]$$

$$\leq \lim_{n \rightarrow \infty} \sqrt{\mathbb{E}[|X_n - X|^2]} = 0$$

4) To prove: $\mathbb{E}\left(\lim_{n \rightarrow \infty} X_n Y_n\right) = \mathbb{E}\left(\lim_{n \rightarrow \infty} X_n \lim_{n \rightarrow \infty} Y_n\right) = \lim_{n \rightarrow \infty} \mathbb{E}[X_n Y_n] = \mathbb{E}[XY]$

$$\lim_{n \rightarrow \infty} |\mathbb{E}[X_n Y_n] - \mathbb{E}[XY]| = \lim_{n \rightarrow \infty} |\mathbb{E}[(X - X_n)Y] + \mathbb{E}[(Y - Y_n)X] - \mathbb{E}[(X - X_n)(Y - Y_n)]|$$

$$\leq \lim_{n \rightarrow \infty} |\mathbb{E}[(X - X_n)Y]| + |\mathbb{E}[(Y - Y_n)X]| + |\mathbb{E}[(X - X_n)(Y - Y_n)]|$$

$$\leq \lim_{n \rightarrow \infty} \mathbb{E}[|X - X_n|] \mathbb{E}[|Y|] + \mathbb{E}[|Y - Y_n|] \mathbb{E}[|X|] + \mathbb{E}[|X - X_n|] \mathbb{E}[|Y - Y_n|]$$

$$\leq \lim_{n \rightarrow \infty} \sqrt{\mathbb{E}[|X - X_n|^2]} \mathbb{E}[|Y|] + \sqrt{\mathbb{E}[|Y - Y_n|^2]} \mathbb{E}[|X|] + \sqrt{\mathbb{E}[|X - X_n|^2]} \mathbb{E}[|Y - Y_n|]$$

$$= 0$$

$$\dot{X}_t = \frac{\partial X_t}{\partial t} = \lim_{h \rightarrow 0} \frac{X_{t+h} - X_t}{h}$$

X_t is continuous at $t \in T \Leftrightarrow \lim_{h \rightarrow 0} X_{t+h} = X_t \Rightarrow \mathbb{E}[|X_{t+h} - X_t|^2] \rightarrow 0 \ (h \rightarrow 0)$

$$\begin{aligned}\mathbb{E}[|X_{t+h} - X_t|^2] &= \mathbb{E}[(X_{t+h} - X_t)(X_{t+h} - X_t)] \\ &= \mathbb{E}[|X_{t+h}|^2] - 2\mathbb{E}[(X_{t+h})(X_t)] + \mathbb{E}[|X_t|^2] \\ &= R_{xx}(t+h, t+h) - 2R_{xx}(t+h, t) + R_{xx}(t, t) \rightarrow 0 \ (h \rightarrow 0) \quad \text{as } (t, t), \forall t \in T\end{aligned}$$

Th X_t - mean square continuous in $t \Leftrightarrow R_{xx}(t, \tau)$ - continuous in (t, t)

$$\lim_{h, h' \rightarrow 0} \mathbb{E}[X_{t+h} X_{t+h'}] = \mathbb{E}[X_t X_t]$$

Corollary $R_{xx}(t, \tau)$ - continuous on (t, t)

$$\Leftrightarrow m_x(t) = \mathbb{E}[X_t] \text{ - continuous at } t, C_{xx}(t, \tau) \text{ - continuous on } (t, t)$$

$$\lim_{h, h' \rightarrow 0} R_{xx}(t+h, \tau+h') = R_{xx}(t, \tau) \text{ - continuous}$$

Th X_t is mean square differentiable iff $\exists \frac{\partial^2 R_{xx}(t, \tau)}{\partial t \partial \tau} \Big|_{t, t}$

Proof

$$\text{To prove: } \lim_{h \rightarrow 0} \mathbb{E}\left[\left|\frac{X_{t+h} - X_t}{h} - \dot{X}_t\right|^2\right] = 0$$

Cauchy: $\{X_u\} \rightarrow X \Rightarrow |X_u - X_\infty| \rightarrow 0 \ (u, u \rightarrow \infty)$

$$\begin{aligned}\lim_{h, h' \rightarrow 0} \frac{1}{hh'} \mathbb{E}[(X_{t+h} - X_t)(X_{t+h'} - X_t)] &= \lim_{h, h' \rightarrow 0} \frac{1}{hh'} (\mathbb{E}[X_{t+h} X_{t+h'}] + \mathbb{E}[X_t X_t] - \mathbb{E}[X_t X_{t+h}] - \mathbb{E}[X_{t+h} X_t]) \\ &= \lim_{h, h' \rightarrow 0} \frac{1}{hh'} (\mathbb{E}[X_{t+h} X_{t+h'}] - \mathbb{E}[X_{t+h} X_t] - (\mathbb{E}[X_t X_{t+h'}] - \mathbb{E}[X_t X_t])) \\ &= R_{xx}(t+h, t+h') - R_{xx}(t+h, t) - R_{xx}(t, t+h') + R_{xx}(t, t) \\ &= \frac{1}{h} \frac{\partial R_{xx}(t+h, t)}{\partial h} - \frac{1}{h} \frac{\partial R_{xx}(t, t)}{\partial h} = \frac{\partial^2 R_{xx}(t, t)}{\partial t \partial \tau} \Big|_{t, t}\end{aligned}$$

Properties: X_t - mean square differentiable

$$1) m_{\dot{X}}(t) = \frac{\partial}{\partial t} \mathbb{E}[X_t] = \frac{\partial}{\partial t} m_x(t)$$

$$2) R_{\dot{X}\dot{X}}(t, \tau) = \frac{\partial^2}{\partial t \partial \tau} \mathbb{E}[X_t X_\tau] = \mathbb{E}[\dot{X}_t \dot{X}_\tau] = \frac{\partial}{\partial t} R_{xx}(t, \tau)$$

$$3) R_{\dot{X}\dot{X}}(t, \tau) = \frac{\partial^2}{\partial t \partial \tau} \mathbb{E}[X_t X_\tau] = \mathbb{E}[\dot{X}_t \dot{X}_\tau] = \frac{\partial^2}{\partial t \partial \tau} R_{xx}(t, \tau)$$

$$4) \mathcal{L}_{\dot{X}\dot{X}}(t, \tau) = \frac{\partial^2}{\partial t \partial \tau} \mathcal{L}_{xx}(t, \tau)$$

Ex. $X_t = at + b$, $a, b \in \mathbb{R}$ $\Rightarrow \dot{X}_t = a$

$$\lim_{h \rightarrow 0} \mathbb{E}\left[\left|\frac{|X_{t+h} - X_t|}{h}\right|^2\right] = \mathbb{E}\left[\left|\frac{a(t+h) - at}{h} - a\right|^2\right] = 0, \quad \forall h$$

Ex. $Y_t = X_t^2 = a^2 t^2 + 2atb + b^2 \Rightarrow \dot{Y}_t = 2a^2 t + 2ab = da(at+b) = 2a X_t$

$$\frac{\partial Y_t}{\partial t} = 2X_t \quad \frac{\partial X_t}{\partial t} = a \quad a = 2a^2 t + 2ab$$

$$\lim_{h \rightarrow 0} \mathbb{E}\left[\left|\frac{Y_{t+h} - Y_t}{h}\right|^2\right] = \lim_{h \rightarrow 0} \mathbb{E}\left[\left(\frac{(a(t+h)+b)^2 - (at+b)^2}{h} - (2a^2 t + 2ab)\right)^2\right] = \mathbb{E}[a^4] h^2 \rightarrow 0$$

Ex. $W_t = \frac{\partial w_t}{\partial t} = \lim_{h \rightarrow 0} \frac{w_{t+h} - w_t}{h}$

$$\mathbb{E}[W_t] = \mathbb{E}\left[\lim_{h \rightarrow 0} \frac{w_{t+h} - w_t}{h}\right] = \lim_{h \rightarrow 0} \mathbb{E}\left[\frac{w_{t+h} - w_t}{h}\right] = 0$$

$$\mathbb{E}[W_t' W_s] = \mathbb{E}\left[\lim_{h \rightarrow 0} \frac{w_{t+h} - w_t}{h} \lim_{k \rightarrow 0} \frac{w_{s+k} - w_s}{k}\right] = \lim_{h \rightarrow 0} \mathbb{E}\left[\frac{w_{t+h} - w_t}{h} \frac{w_{s+h} - w_s}{h}\right] = \delta(t-s)$$

Integration

$[a, b] \ni t_0 < t_1 < \dots < t_N = b$, $t_i \leq t'_i \leq t_{i+1}$, $\rho_i = \max(t_{i+1} - t_i)$

$$\lim_{n \rightarrow \infty} \sum_{i=0}^{N-1} X_{t'_i} (\rho_i) = \int_a^b X_t dt$$

Th X_t - mean square Riemann integral on $[a, b] \Leftrightarrow R_{xx}(t, T)$ - integrable on $[a, b] \times [a, b]$

Properties:

- 1) $\mathbb{E}\left[\int_a^b X_t dt\right] = \int_a^b \mathbb{E}[X_t] dt = \int_a^b \mathbb{E}[X_t] dt$
- 2) $\mathbb{E}\left[\int_a^b X_t dt, \int_a^d X_t dt\right] = \int_a^b \int_a^d \mathbb{E}[X_t X_t] dt dt$
- 3) $\text{cov}\left(\int_a^b X_t dt, \int_c^d X_t dt\right) = \int_a^b \int_c^d \text{cov}(X_t, X_t) dt dt$

Th Fundamental Theorem of Calculus

X_t - mean square integrable $\Leftrightarrow X_t = X_0 + \int_0^t \dot{X}_s ds$ with probability 1

Wiener-dévy (Brownian motion) process $\{W_t, t \geq 0\}$

- 1) $\Pr(W(0) = 0) = 1$ $\Rightarrow W_t - W_0, W_{t+h} - W_t$ has same distribution $N(0, 1)$
- 2) $\{W_t, t \geq 0\}$ has stationary independent increments, (Gaussian) $W_{t+h} - W_t$ is independent
- 3) $\mathbb{E}[W_t] = 0$
- 4) $\forall t > 0$, W_t is normally distributed.

$$W_t = \frac{\partial w_t}{\partial t} = N_t \quad \text{or} \quad dW_t = N_t dt$$

$$R_{WW}(t, \bar{t}) = \mathbb{E}[W_t W_{\bar{t}}] = \mathbb{E}[(W_t - W_{\bar{t}}) + W_{\bar{t}}] W_{\bar{t}}$$

$$\mathbb{E}[W_t - W_{\bar{t}}] = \mathbb{E}[W_t] - \mathbb{E}[W_{\bar{t}}] = 0$$

$$\text{var}(W_t - W_{\bar{t}}) = \mathbb{E}[(W_t - W_{\bar{t}})^2] = \sigma^2(t - \bar{t})$$

$$R_{WW}(t, \tau) = \mathbb{E}[(W_t - W_{\tau}) W_{\tau}] + \mathbb{E}[W_{\tau}^2] = \sigma^2 \tau$$

$\Rightarrow R_{WW}(t, \tau) = \sigma^2 \min(t, \tau)$ - continuous $\Rightarrow W_t$ - mean square continuous

$\frac{\partial}{\partial t} R_{WW}(t, \tau)$ - does not exist at $t = \tau \Rightarrow W_t$ - not differentiable

Markov process $\{X_t, t \in T\}$

$\frac{\partial X_t}{\partial t} = f(X(t)) \Leftrightarrow \frac{\partial X}{\partial t}$ depends only on $X(t)$, not on $X(\tau)$, $\tau < t$

Def. $\Pr\{X_{t_u}(w) \leq \lambda | X_{t_1}, \dots, X_{t_{u-1}}\} = \Pr\{X_{t_u}(w) \leq \lambda | X_{t_{u-1}}\}, \forall \lambda, t_1, \dots, t_u$

probability density function: $p(X_{t_u} | X_{t_1}, \dots, X_{t_{u-1}}) = p(X_{t_u} | X_{t_{u-1}})$

$$p(X_{t_u}, X_{t_{u-1}}, \dots, X_{t_1}) = p(X_{t_u} | X_{t_{u-1}}, \dots, X_{t_1}) = p(X_{t_u} | X_{t_{u-1}}) p(X_{t_{u-1}}, \dots, X_{t_1}) = \dots = p(X_{t_u} | X_{t_{u-1}}) \dots p(X_{t_2} | X_{t_1}) p(X_{t_1})$$

$$\frac{\partial X_t}{\partial t} = f(X_t, t) + g(X_t, t) \mathcal{Z}(t), \mathcal{Z}(t) = \frac{\partial W_t}{\partial t} = N_t$$

$$\Rightarrow dX_t = f(X_t, t) dt + g(X_t, t) dW_t$$

$X_t = X_{t_0} + \int_{t_0}^t f(X_s, s) ds + \int_{t_0}^t g(X_s, s) dW_s, \{X_t, t \geq 0\}$ - Markov process

$$X_{t+st} = X_t + \int_t^{t+st} f(X_s, s) ds + \int_t^{t+st} g(X_s, s) dW_s \approx X_t + f(X_t, t) st + g(X_t, t) dW_t \xrightarrow{W_t \sim N(0, t)}$$

$$X_t = e^{W_t} \Rightarrow \frac{\partial X_t}{\partial t} = e^{W_t} \frac{\partial W_t}{\partial t} = f(t) = e^{at} \rightarrow \text{deterministic} \Rightarrow \frac{\partial f}{\partial t} = ae^{at} = af(t)$$

$$\mathbb{E}[X_t - X_{t+st}] = e^{W_t+st} - e^{W_t} = e^{W_t+sW_t} - e^{W_t} = e^{W_t}(e^{sW_t} - 1) = X_t(sW_t + \frac{sW_t^2}{2} - s)$$

$$\mathbb{E}[\delta X_t - X_t \delta W_t] = \mathbb{E}[X_t \frac{\delta W_t}{2}] = \mathbb{E}[X_t] \mathbb{E}\left[\frac{\delta W_t}{2}\right] - \mathbb{E}[X_t] \frac{\delta t}{2}, \delta W_t = W_{t+st} - W_t$$

$$\Rightarrow \mathbb{E}[\delta X_t - X_t \delta W_t] = \mathbb{E}\left[\frac{\delta W_t}{2}\right] = \mathbb{E}[\delta W_t] = \mathbb{E}[(W_{t+st} - W_t)^2] = st$$

$$dX_t = X_t dW_t + \frac{1}{2} X_t (dW_t)^2, X_t = 1 + \int_0^t X_s dW_s + \int_0^t \frac{X_s}{2} dW_s^2, X_t = e^{W_t}$$

Stochastic Integral, $\int_0^t G_s dW_s$

$$\text{Ex. } \int_0^t s ds = \lim_{n \rightarrow \infty} \sum_{i=0}^n t_i (t_{i+1} - t_i) = \frac{t^2 - t_0^2}{2}$$

$$\Rightarrow \int_0^t W_s dW_s = \lim_{n \rightarrow \infty} \sum_{i=0}^n W_{t_i} (W_{t_{i+1}} - W_{t_i}) =$$

$$\cdot \frac{W_{t_1}^2 - W_{t_0}^2}{2} - \frac{1}{2} \lim_{n \rightarrow \infty} \sum_{i=0}^n (W_{t_{i+1}} - W_{t_i})^2 + \lim_{n \rightarrow \infty} \sum_{i=0}^n (W_{t_{i+1}} - W_{t_i})(W_{t_{i+1}} - W_{t_i})$$

$$\begin{aligned} & \lim_{\Delta t \rightarrow 0} \sum_{i=0}^n (w_{t_{i+1}} - w_{t_i})^2 = t - t_0 \\ & \lim_{\Delta t \rightarrow 0} \sum_{i=0}^n (w_{t_{i+1}} - w_{t_i})^2 = \sum (t_i' - t_i) \\ & \lim_{\Delta t \rightarrow 0} \sum_{i=0}^n (w_{t_{i+1}} - w_{t_i})(w_{t_{i+1}} - w_{t_i}) = 0 \\ & \Rightarrow \int_{t_0}^t w_s \, dw_s = \frac{w_t^2 - w_{t_0}^2}{2} - \frac{t - t_0}{2} + \sum (t_i' - t_i) \end{aligned}$$

Ex. 7

$$\begin{aligned} & 1) \text{ To prove: } \lim_{\Delta t \rightarrow 0} \sum_{i=0}^n (w_{t_{i+1}} - w_{t_i})^2 = t - t_0 \\ & \mathbb{E} \left[\sum (w_{t_{i+1}} - w_{t_i})^2 - (t - t_0)^2 \right] = \mathbb{E} \left[\sum (w_{t_{i+1}} - w_{t_i})^2 \right] - 2(t - t_0) \sum (w_{t_{i+1}} - w_{t_i})^2 + (t - t_0)^2 \\ & = \mathbb{E} \left[\sum (w_{t_{i+1}} - w_{t_i})^2 \right] - 2(t - t_0) \mathbb{E} \left[\sum (w_{t_{i+1}} - w_{t_i})^2 \right] + (t - t_0)^2 \\ & = \mathbb{E} \left[\sum (w_{t_{i+1}} - w_{t_i})^2 \right] \mathbb{E} \left[\sum (w_{t_{i+1}} - w_{t_i})^2 \right] - \underbrace{\mathbb{E} \left[\left(\mathbb{E} \left[\sum (w_{t_{i+1}} - w_{t_i})^2 \right] \right)^2 \right]}_{\text{non overlapping increments } (w_{t_{i+1}} - w_{t_i})^2} + \mathbb{E} \left[\sum (w_{t_{i+1}} - w_{t_i})^2 \right] - (t - t_0)^2 \\ & = (t - t_0)^2 \\ & \Rightarrow - \sum \left(\mathbb{E} \left[(w_{t_{i+1}} - w_{t_i})^2 \right] \right)^2 + \sum \mathbb{E} \left[(w_{t_{i+1}} - w_{t_i})^4 \right] = O(\Delta t) = O(w) \\ & \text{Wiener: } \lim_{\Delta t \rightarrow 0} \mathbb{E} \left[\sum (w_{t_{i+1}} - w_{t_i})^4 \right] = 0 \Rightarrow \lim_{\Delta t \rightarrow 0} \sum (w_{t_{i+1}} - w_{t_i})^2 = t - t_0 \end{aligned}$$

$$\begin{aligned} & 2) \text{ To prove: } \lim_{\Delta t \rightarrow 0} \sum_{i=0}^n (w_{t_{i+1}} - w_{t_i})(w_{t_{i+1}}' - w_{t_i}) = 0 \\ & \mathbb{E} \left[\sum (w_{t_{i+1}} - w_{t_i})(w_{t_{i+1}}' - w_{t_i})^2 \right] = \sum \mathbb{E} \left[(w_{t_{i+1}} - w_{t_i})^2 | w_{t_{i+1}}' - w_{t_i} \right] = \mathbb{E} \left[(w_{t_{i+1}} - w_{t_i})^2 \right] \mathbb{E} \left[(w_{t_{i+1}}' - w_{t_i})^2 \right] \\ & = \sum (t_i' - t_i)(t_i' - t_i) = \sum O(\Delta t) O(\Delta t) = O(\Delta t) = O(w) \end{aligned}$$

Def. Itô Integral: $\int_{t_0}^t G_s \, dw_s = \lim_{\Delta t \rightarrow 0} \sum G_{t_i} (w_{t_{i+1}} - w_{t_i})$

Properties:

$$\begin{aligned} 1) \quad & \mathbb{E} \left[\int_{t_0}^t G_s \, dw_s \right] = 0 \\ 2) \quad & \mathbb{E} \left[\int_{t_0}^{t_0} G_s \, dw_s \int_{t_0}^t H_s \, dw_s \right] = \int_{t_0}^t \mathbb{E} [G_s H_s] \, ds \end{aligned}$$

Ex. 8

$$\begin{aligned} 1) \quad & \text{To prove: } \mathbb{E} \left[\int_{t_0}^t G_s \, dw_s \right] = 0 \\ & \mathbb{E} \left[\int_{t_0}^t G_s \, dw_s \right] = \mathbb{E} \left[\lim_{\Delta t \rightarrow 0} \sum G_{t_i} (w_{t_{i+1}} - w_{t_i}) \right] \\ & = \lim_{\Delta t \rightarrow 0} \sum \mathbb{E} [G_{t_i} (w_{t_{i+1}} - w_{t_i})] \\ & = \lim_{\Delta t \rightarrow 0} \sum \mathbb{E} [G_{t_i}] \mathbb{E} [(w_{t_{i+1}} - w_{t_i})] = 0 \end{aligned}$$

$$2) \quad \text{To prove: } \mathbb{E} \left[\int_{t_0}^t G_s \, dw_s \int_{t_0}^t H_s \, dw_s \right] = \int_{t_0}^t \mathbb{E} [G_s H_s] \, ds$$

$$\begin{aligned}
 E\left[\int_{t_0}^t G_s dW_s \int_{t_0}^t H_s dW_s\right] &= E\left[\sum_{i=0}^{n-1} G_{t_i} (W_{t_{i+1}} - W_{t_i}) \sum_{j=0}^{m-1} H_{t_j} (W_{t_{j+1}} - W_{t_j})\right] \\
 &= \sum_{i=0}^{n-1} E\left[\sum_{j=0}^{m-1} G_{t_i} H_{t_j} (W_{t_{i+1}} - W_{t_i})(W_{t_{j+1}} - W_{t_j})\right] \\
 &= \sum_{i=0}^{n-1} E\left[G_{t_i} H_{t_i} (W_{t_{i+1}} - W_{t_i})^2\right] \\
 &= \sum_{i=0}^{n-1} E\left[G_{t_i} H_{t_i}\right] E\left[(W_{t_{i+1}} - W_{t_i})^2\right] \\
 &= \sum_{i=0}^{n-1} E\left[G_{t_i} H_{t_i}\right] \Delta t = \sum_{i=0}^{n-1} E\left[G_{t_i} H_{t_i}\right] \Delta t = \int_{t_0}^t E[G_s dW_s] ds
 \end{aligned}$$

$$Ex. \int_{t_0}^t W_s dW_s = \frac{W_t^2 - W_{t_0}^2}{2} - \frac{t-t_0}{2} (Stratonovitch)$$

Def. Stratonovitch Integral: $\int_{t_0}^t G_s dW_s = \sum_{i=0}^{n-1} \frac{G_{t_i} + G_{t_{i+1}}}{2} (G_{t_{i+1}} - G_{t_i}) (W_{t_{i+1}} - W_{t_i}), \quad t_i' = \frac{t_{i+1} + t_i}{2}$

$$Ex. \int_{t_0}^t W_s dW_s = \frac{W_t^2 - W_{t_0}^2}{2} \text{ (Stratonovitch)}$$

Stochastic Differential Equation

$$dX_t = f(X_t, t) dt + g(X_t, t) dW_t$$

$$X_t = X_{t_0} + \int_{t_0}^t f(X_s, s) ds + \int_{t_0}^t g(X_s, s) dW_s$$

$$X_{t+\Delta t} = X_t + \int_t^{t+\Delta t} f(X_s, s) ds + \int_t^{t+\Delta t} g(X_s, s) dW_s \approx X_t + \int_t^{t+\Delta t} f(X_t, t) dt + \int_t^{t+\Delta t} g(X_t, t) dW_s = X_t + f(X_t, t) \Delta t + g(X_t, t) (W_{t+\Delta t} - W_t)$$

↳ Euler scheme for SDE differential equation, Markov process

⇒ X_t - Markov process

$$ODE: \frac{dx}{dt} = f(x), \frac{\partial}{\partial t} v(x(t)) = \frac{\partial v(x(t))}{\partial x} \cdot \frac{\partial x}{\partial t} = f(x(t)) \frac{\partial v(x(t))}{\partial x}$$

$$SDE: dX_t = f(X_t) dt + g(X_t) dW_t$$

$$\Rightarrow dv = \frac{\partial v}{\partial x} \cdot dX_t = \frac{\partial v}{\partial x} \cdot (f(X_t) dt + g(X_t) dW_t) \text{ is wrong.}$$

$$dv = v'(x(t)) dX_t + \frac{1}{2} g^2(X_t) v''(X_t) dt = \boxed{v'(X_t) f(X_t) + \frac{1}{2} g^2(X_t) v''(X_t)} dt + g(X_t) v'(X_t) dW_t$$

$$\int_{t_0}^t g(X_t) dW_t = \sum_{j=0}^{n-1} \int_{t_j}^{t_{j+1}} g(t) (W_{t_{j+1}} - W_{t_j}) dt \quad \hookrightarrow \text{SDE correction}$$

Ex.

$$\frac{dB_t}{dt} = -k_1 B_t + s_t + \sigma N_t \quad \Rightarrow \quad B_{t_0} = B_0$$

$$dB_t = (-k_1 B_t + s_t) dt + \sigma dW_t$$

$$dS_t = A(t, S_t) dt + B(t, S_t) dW_t$$

$$S(t) = S(0) + \int_0^t A(z, S_z) dz + \int_0^t B(z, S_z) dW_z$$

Ito's Differential Rule

$$Y_t = Y(t) = u(t, S_t) \quad u: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$$

$$dY_t = \frac{\partial u}{\partial t} dt + \frac{\partial u}{\partial x} \cdot dS_t + \frac{1}{2} \frac{\partial^2 u}{\partial x^2} B^2 dt \quad \text{where } x = S_t, \text{ let } u_t = \frac{\partial u}{\partial t}$$

$$\Rightarrow dY_t = [u_t(t, S_t) + u_x(t, S_t) A(t, S_t) + \frac{1}{2} u_{xx}(t, S_t) B^2(t, S_t)] dt + u_x B(t, S_t) dW_t \rightarrow \text{Ito's Rule}$$

$$\text{Ex. } dS_t = dW_t, \quad S_t = W_t, \quad u(t, x) = y_0 e^{xt+\sigma x}$$

$$u_x = \sigma y_0 e^{xt+\sigma x} - \sigma u, \quad u_{xx} = \sigma^2 y_0 e^{xt+\sigma x} = \sigma^2 u, \quad u_t = y_0 e^{xt+\sigma x} = \mu u$$

$$dY_t = \left[\mu Y_t + \frac{\sigma^2}{2} Y_t \right] dt + \sigma Y_t dW_t = \left[\mu + \frac{\sigma^2}{2} \right] Y_t dt + \sigma Y_t dW_t, \quad Y_t = y_0 e^{yt+\sigma W_t}, \quad Y_0 = y_0$$

$$S_t, \delta S_t \ll 1$$

$$u(t+\delta t, S_t + \delta S_t) = u(t, S_t) + \delta t \frac{\partial u}{\partial t}(t, S_t) + \delta S_t \frac{\partial u}{\partial x}(t, S_t) + \frac{(\delta t)^2}{2} \frac{\partial^2 u}{\partial t^2} + \frac{\partial^2 u}{\partial x \partial t} \delta t \delta S_t + \frac{(\delta S_t)^2}{2} \frac{\partial^2 u}{\partial x^2}$$

$$dt dt = 0, \quad dW_t dt = 0, \quad dt dW_t = 0, \quad dW_t dW_t = dt$$

$$\text{Ex. } dS_t = dW_t, \quad S_t = W_t, \quad u(t, x) = \sinh(c+t+x)$$

$$dY_t = [\cosh(c+t+W_t) + \frac{1}{2} \sinh^2(c+t+W_t)] dt + \cosh(c+t+W_t) dW_t$$

$$\cosh^2 x - \sinh^2 x = 1 \Rightarrow \cosh(x) = \sqrt{1 + \sinh^2(x)}$$

$$\Rightarrow dY_t = \sqrt{1+Y_t^2} + \frac{1}{2} Y_t^2 + \sqrt{1+Y_t^2} dW_t, \quad Y_t = \sinh(c+t+W_t), \quad Y_0 = \sinh(c)$$

$$dX_t = f(X_t, t) dt + g(X_t, t) dW_t$$

$$d\phi = \frac{\partial \phi}{\partial t} dt + \frac{\partial \phi}{\partial x} dX_t + \frac{1}{2} g^2 \frac{\partial^2 \phi}{\partial x^2} dt = d\Phi_t \text{ for stochastic process } \Phi_t = \phi(X_t, t)$$

Taylor series expansion or $\Delta X = f(X_t, t) \Delta t + g(X_t, t) \Delta W + \dots$

$$\text{of Euler Scheme (st)} \quad X_{t+\Delta t} = X_t + f(X_t, t) \Delta t + g(X_t, t) (W_{t+\Delta t} - W_t) + \dots$$

$$\Rightarrow \Delta \phi = \phi(X_t + \Delta X, t + \Delta t) - \phi(X_t, t) = \frac{\partial \phi}{\partial t} \Delta t + \frac{1}{2} \frac{\partial^2 \phi}{\partial x^2} (\Delta x)^2 + \frac{\partial \phi}{\partial x} \Delta X + \frac{1}{2} \frac{\partial^2 \phi}{\partial x^2} (\Delta X)^2 + \dots =$$

$$= \frac{\partial \phi}{\partial t} \Delta t + \frac{\partial \phi}{\partial x} (f(X_t, t) \Delta t + g(X_t, t) \Delta W) + \frac{1}{2} \frac{\partial^2 \phi}{\partial x^2} (f(X_t, t) \Delta t + g(X_t, t) \Delta W)^2 + \dots =$$

$$= \frac{\partial \phi}{\partial t} \Delta t + \frac{\partial \phi}{\partial x} (f(X_t, t) \Delta t + g(X_t, t) \Delta W) + \frac{1}{2} \frac{\partial^2 \phi}{\partial x^2} g(X_t, t)^2 \Delta W^2 + \dots =$$

$$= \frac{\partial \phi}{\partial t} \Delta t + \frac{\partial \phi}{\partial x} \Delta X + \frac{1}{2} \frac{\partial^2 \phi}{\partial x^2} g(X_t, t)^2 \Delta t + \dots$$

$$\text{Ex. } dX_t = \mu X_t dt + \sigma X_t dW_t, \quad \phi = X^t, \quad \frac{\partial \phi}{\partial t} = 0, \quad \frac{\partial \phi}{\partial x} = dx, \quad \frac{\partial^2 \phi}{\partial x^2} = d$$

$$dX_t^2 = 0 + 2X_t(\mu X_t dt + \sigma X_t dW_t) + \frac{1}{2} \sigma^2 X_t^2 dt = 2\mu X_t^2 dt + d\sigma X_t^2 dW_t + X_t^2 \sigma^2 dt =$$

$$= (2\mu + \sigma^2) X_t^2 dt + 2\sigma X_t^2 dW_t$$

$$dX_t = f(X_t, t) dt + g(X_t, t) dW_t - \frac{1}{2} \hat{t} \hat{\phi} \text{ Equation}$$

$$\Rightarrow dX_t = (f(X_t, t) - \frac{1}{2} g(X_t, t) \frac{\partial g(X_t, t)}{\partial x}) dt + g(X_t, t) dW_t - \text{Stratonovitz Equation}$$

$$dX_t = f(X_t, t) dt + g(X_t, t) dW_t - \text{Stratonovitz Equation}$$

$$\Rightarrow dX_t = (f(X_t, t) + \frac{1}{2} g(X_t, t) \frac{\partial g(X_t, t)}{\partial x}) dt + g(X_t, t) dW_t - \text{Sto} \hat{\phi} \text{ Equation}$$

$$\text{Ex. Sto} \hat{\phi}: d\Phi_t = \frac{b^2}{2} \Phi_t dt + b \Phi_t dW_t \Rightarrow \text{Stratonovitz: } d\Phi_t = b \Phi_t dW_t, \Phi_0 = 1$$

$$\text{Ex. } dM_t = -a M_t dt + a dW_t \Rightarrow E[M_t] = 0, E[M_t M_s] = \frac{a}{2} e^{-|t-s|}$$

$\frac{dX_t}{dt} = f(X_t, t) + g(X_t, t) M_t$ - not Markovian process

$| dX_t = f(X_t, t) dt + g(X_t, t) M_t dt \quad \{ X_t, M_t \} \text{ - Markovian process}$

$$dM_t = -a M_t dt + a dW_t$$

Ex. 13

$$Y_t = (W_t + \sqrt{Y_0})^2, t \geq 0$$

To prove: $dY_t = dt + 2\sqrt{Y_t} dW_t, t \geq 0$ - Ito $\hat{\phi}$ SDE

$$X_t = W_t, \phi(x, t) = (x + \sqrt{Y_0})^2 \Rightarrow \frac{\partial \phi}{\partial t} = 0, \frac{\partial \phi}{\partial x} = 2(x + \sqrt{Y_0}), \frac{\partial^2 \phi}{\partial x^2} = 2$$

$$d\Phi_t = 2(X_t + \sqrt{Y_0}) dX_t + \frac{1}{2} \cdot 2 \cdot dt = 2(W_t + \sqrt{Y_0}) dW_t + dt$$

$$\Rightarrow dY_t = dt + 2(W_t + \sqrt{Y_0}) dW_t = dt + 2\sqrt{Y_t} dW_t$$

Stratonovitz SDE: $dY_t = 2(W_t + \sqrt{Y_t}) dW_t = 2\sqrt{Y_t} dW_t$, correction: $-2\sqrt{Y_t} \frac{\partial}{\partial y} [\sqrt{Y_t}] = -dt$

Ex. 14

$$\text{Ito } \hat{\phi} \text{ SDE: } dX_t = \mu X_t dt + \sigma X_t dW_t, X_0 = x_0$$

$$\tilde{Z}_t = \ln X_t \text{ or } \phi(x, t) = \ln x \Rightarrow \frac{\partial \phi}{\partial t} = 0, \frac{\partial \phi}{\partial x} = \frac{1}{x}, \frac{\partial^2 \phi}{\partial x^2} = -\frac{1}{x^2}$$

$$d\Phi_t = \frac{1}{X_t} dX_t - \frac{1}{2} \cdot \frac{1}{X_t^2} \cdot \sigma^2 X_t^2 dt = \mu dt + \sigma dW_t - \frac{1}{2} \sigma^2 dt$$

$$\Rightarrow d\tilde{Z}_t = (\mu - \frac{1}{2} \sigma^2) dt + \sigma dW_t$$

$$\text{Analytical: } \tilde{Z}_t = (\mu - \frac{1}{2} \sigma^2)(t - t_0) + \sigma (W_t - W_{t_0}) + \tilde{Z}_{t_0}$$

$$\text{Solution: } X_t = e^{\tilde{Z}_t} = X_{t_0} e^{(\mu - \frac{1}{2} \sigma^2)(t - t_0) + \sigma (W_t - W_{t_0})}$$

Ex. 15

$$\int_{t_0}^t W_s dW_s, X_t = W_t, \phi(x, t) = x^2 \Rightarrow \frac{\partial \phi}{\partial t} = 0, \frac{\partial \phi}{\partial x} = dx, \frac{\partial^2 \phi}{\partial x^2} = 2$$

$$d\Phi_t = 2X_t dt + \frac{1}{2} \cdot 2 \cdot dt \Rightarrow \Phi_t = \Phi_{t_0} + 2 \int_{t_0}^t X_s dX_s + \int_{t_0}^t dt$$

$$\Rightarrow W_t^2 = W_{t_0}^2 + 2 \int_{t_0}^t W_s dW_s + (t - t_0) \Rightarrow \int_{t_0}^t W_s dW_s = \frac{1}{2} (W_t^2 - W_{t_0}^2) - \frac{1}{2} (t - t_0)$$

Ex. 16

$$\begin{aligned} \mathbb{E}[W_t^4], \quad X_t = w_t \quad (g=1), \quad \phi(x,t) = x^4 \Rightarrow \frac{\partial \phi}{\partial t} = 0, \quad \frac{\partial \phi}{\partial x} = 4x^3, \quad \frac{\partial^2 \phi}{\partial x^2} = 12x^2 \\ d\phi_t = 4X_t^3 dX_t + \frac{1}{2} \cdot 12X_t^2 dt = 4w_t^3 dw_t + 6w_t^2 dt \\ \Rightarrow w_t^4 = w_0^4 + 4 \int_0^t w_s^3 ds + 6 \int_0^t w_s^2 ds \\ \Rightarrow \mathbb{E}[W_t^4] = \mathbb{E}[w^4] + 4 \mathbb{E}\left[\int_0^t w_s^3 ds\right] + 6 \mathbb{E}\left[\int_0^t w_s^2 ds\right] = 6 \int_0^t \mathbb{E}[w_s^2] ds = 6 \int_0^t s ds = 3t^2 \end{aligned}$$

Ex. 17

$$\text{SDE } dX_t = aX_t dt - Y_t dW_t, \quad X_0 = x_0$$

$$\text{SDE } dY_t = aY_t dt + X_t dW_t, \quad Y_0 = y_0$$

$$R_t = X_t^2 + Y_t^2, \quad t \geq 0$$

$$dX_t = aX_t dt - Y_t dW_t, \quad \phi_1(x,t) = x^2 \Rightarrow \frac{\partial \phi_1}{\partial t} = 0, \quad \frac{\partial \phi_1}{\partial x} = 2x, \quad \frac{\partial^2 \phi_1}{\partial x^2} = 2, \quad g = -y$$

$$d\phi_{1,t} = 2X_t dX_t + \frac{1}{2} \cdot 2 \cdot Y_t^2 dt = 2X_t(aX_t dt - Y_t dW_t) + Y_t^2 dt = 2aX_t^2 dt + Y_t^2 dt - 2X_t Y_t dW_t$$

$$dY_t = aY_t dt + X_t dW_t, \quad \phi_2(y,t) = y^2 \Rightarrow \frac{\partial \phi_2}{\partial t} = 0, \quad \frac{\partial \phi_2}{\partial y} = 2y, \quad \frac{\partial^2 \phi_2}{\partial y^2} = 2, \quad g = x$$

$$d\phi_{2,t} = 2Y_t dY_t + \frac{1}{2} \cdot 2 \cdot X_t^2 dt = 2Y_t(aY_t dt + X_t dW_t) + X_t dt = 2aY_t^2 dt + X_t^2 dt + 2Y_t X_t dW_t$$

$$dR_t = d\phi_{1,t} + d\phi_{2,t} = daR_t dt + R_t dt = (da+1)R_t \Rightarrow \frac{\partial R_t}{\partial t} = (da+1)R_t, \quad R_0 = x_0^2 + y_0^2 \Rightarrow \text{deterministic}$$

Estimation of Probability Density

Def.: Kernel - function, st. $\int_{-\infty}^{\infty} K(x) dx = 1$

N - # realizations of X_t

$\Rightarrow \hat{p}(x,t) = \frac{1}{N} \sum_{i=1}^N K\left(\frac{x - X_t^{(i)}}{\lambda}\right)$ where λ - bandwidth of Kernel estimator

$\lambda_{\text{opt}} = O\left(\frac{1}{N^{1/(d+1)}}$) where d-dimensionality of X_t $\Rightarrow \text{error} = O\left(\frac{1}{N^{2/(d+1)}}$)

Fokker Planck Equation

$$\frac{\partial p}{\partial t} = - \sum_i \frac{\partial(f_i p)}{\partial x_i} + \frac{1}{2} \sum_i \sum_j \frac{\partial^2((gg^T)ijp)}{\partial x_i \partial x_j}, \quad t \geq t_0 \quad \text{where } p(x, x_1, \dots, t | x_{t_0}, x_{t_0}, \dots, t_0) - \text{prob. dens. func.}$$

if $X_{t_0} = x_0 \Rightarrow p(x_{t_0}, x_{t_0}, \dots, t_0) = \delta(X_{t_0} - x_0)$

$$\phi(x,t) = K(x)$$

$$\begin{aligned} dK(X_t) \cdot \frac{\partial K}{\partial x} dX_t + \frac{1}{2} g(X_t, t)^T \frac{\partial^2 K}{\partial x^2} dt = \frac{\partial K}{\partial x} (f(X_t, t) dt + g(X_t, t) dW_t) + \frac{1}{2} g(X_t, t)^T \frac{\partial^2 K}{\partial x^2} dt \\ d\mathbb{E}[K(X_t)] = \mathbb{E}\left[\frac{\partial K}{\partial x} f(X_t, t) + \frac{1}{2} g(X_t, t)^T \frac{\partial^2 K}{\partial x^2}\right] dt \quad \text{or} \quad \frac{\partial}{\partial t} \mathbb{E}[K(X_t)] = \mathbb{E}\left[\frac{\partial K}{\partial x} f(X_t, t) + \frac{1}{2} g(X_t, t)^T \frac{\partial^2 K}{\partial x^2}\right] \end{aligned}$$

$$\frac{\partial}{\partial t} \int_{-\infty}^{\infty} K(x) p(x,t) dx = \int_{-\infty}^{\infty} \frac{\partial K}{\partial x} f(x,t) p(x,t) dx + \int_{-\infty}^{\infty} K(x) \frac{1}{2} \frac{\partial^2 g^2}{\partial x^2} p(x,t) dx$$

$$\int_{-\infty}^{\infty} K(x) \frac{\partial p}{\partial t} dx = \int_{-\infty}^{\infty} K(x) \frac{\partial \bar{p}}{\partial x} dx + \int_{-\infty}^{\infty} K(x) \frac{1}{2} \frac{\partial^2 g^2}{\partial x^2} p(x,t) dx \quad \text{or} \quad \int_{-\infty}^{\infty} K(x) \left(\frac{\partial p}{\partial t} + \frac{\partial \bar{p}}{\partial x} - \frac{1}{2} \frac{\partial^2 g^2}{\partial x^2} p(x,t) \right) dx = 0$$

Ex. $dX_t = \mu dt + \sigma dW_t$, $X_{t_0} = x_0$

$$\frac{\partial p}{\partial t} = -\mu \frac{\partial p}{\partial x} + \frac{1}{2} \sigma^2 \frac{\partial^2 p}{\partial x^2}, \quad t = t_0, \quad p(x, t_0) = \delta(x - x_0) \Rightarrow p(x, t | x_0, t_0) = N(x_0 + \mu t, \sigma^2)$$

Numerical Approximation

$$\frac{\partial x}{\partial t} = f(x, t), \quad x(t_0) = x_0$$

$$\text{Euler scheme: } x_{n+1} = x_n + \Delta t f(x_n, u)$$

$$dX_t = f(X_t) dt + g(X_t) dW_t \quad \forall t \in T, \quad X(0) = x_0$$

$$X_t = X_{t_0} + \int_{t_0}^t f(X_s) ds + \int_{t_0}^t g(X_s) dW_s$$

$$\Rightarrow X_{t_{n+1}} = X_{t_n} + \int_{t_n}^{t_{n+1}} f(X_s) ds + \int_{t_n}^{t_{n+1}} g(X_s) dW_s \leftarrow \text{exact solution}$$

$$\text{Euler-Maruyama: } X_{n+1} = X_n + f(\tilde{X}_n) \Delta t + g(\tilde{X}_n) [W(t_{n+1}) - W(t_n)]$$

Def. $\lvert p \rvert$ -order of convergence if $\exists K, \delta > 0$ s.t. $|x(T) - x_N| \leq K(\Delta t)^p$, $\forall t$, $0 < \Delta t < \delta$

local error of Euler scheme: $O(\Delta t^2)$

global error of Euler scheme: $E_N = O(\Delta t)$

$$E_N = E_{N-1} + O(\Delta t^2) = E_{N-2} + 2O(\Delta t^2) = \dots = N O(\Delta t^2) = \frac{1}{\Delta t} O(\Delta t^2) = T O(\Delta t) = O(\Delta t)$$

Def. $\lvert p \rvert$ -strong order of convergence if $\exists K, \delta > 0$ s.t. $\mathbb{E}[|X_T - X_N|] \leq K(\Delta t)^p$, $\forall t$, $0 < \Delta t < \delta$

Def. $\lvert p \rvert$ -weak order of convergence if $\exists K, \delta > 0$ s.t. $|\mathbb{E}[h(X_T, T)] - \mathbb{E}[h(X_N, N)]| \leq K(\Delta t)^p$, $\forall t$, $0 < \Delta t < \delta$

Euler-Maruyama $\begin{cases} \text{weak: } \frac{1}{2} \\ \text{strong: } \frac{1}{2} \end{cases}$ the polynomial

$$d\phi = \frac{\partial \phi}{\partial t} dt + \frac{\partial \phi}{\partial x} dX_t + \frac{1}{2} \frac{\partial^2 \phi}{\partial x^2} dt = \frac{\partial \phi}{\partial t} dt + \frac{\partial \phi}{\partial x} f dt + \frac{1}{2} \frac{\partial^2 \phi}{\partial x^2} dt + \frac{\partial \phi}{\partial x} g dW_t$$

$$\text{where } L^0 \phi = \frac{\partial \phi}{\partial t} + \frac{\partial \phi}{\partial x} f + \frac{1}{2} \frac{\partial^2 \phi}{\partial x^2}$$

$$L^1 \phi = \frac{\partial \phi}{\partial x} g$$

$$\begin{aligned}
 d\hat{f} &= L^0 f dt + L^1 f dW_t \Rightarrow f(X_t, s) = f(X_{t_0}, t_0) + \int_{t_0}^s L^0 f d\tau + \int_{t_0}^s L^1 f dW_\tau \\
 d\hat{g} &= L^0 g dt + L^1 g dW_t \Rightarrow g(X_t, s) = g(X_{t_0}, t_0) + \int_{t_0}^s L^0 g d\tau + \int_{t_0}^s L^1 g dW_\tau \\
 \Rightarrow X_t &= X_{t_0} + \int_{t_0}^t [f(X_{t_0}, t_0) + \int_{t_0}^s L^0 f d\tau + \int_{t_0}^s L^1 f dW_\tau] ds + \int_{t_0}^t [g(X_{t_0}, t_0) + \int_{t_0}^s L^0 g d\tau + \int_{t_0}^s L^1 g dW_\tau] dW_s \\
 &= X_{t_0} + f(X_{t_0}, t_0)(t - t_0) + g(X_{t_0}, t_0)(W_t - W_{t_0}) + \text{error terms}
 \end{aligned}$$

Euler scheme: $X_{t+\Delta t} = X_t + f(X_t, t)\Delta t + g(X_t, t)(W_{t+\Delta t} - W_t)$ or $X_{u+1} = X_u + f(X_u, u)\Delta t + g(X_u, u)\Delta W_u$

Error terms:

$$\begin{aligned}
 \rightarrow \int_{t_0}^t \int_{t_0}^s L^0 f d\tau dW_s &< K_1 \int_{t_0}^t \int_{t_0}^s dW_\tau dW_s = \frac{K_1}{2} (\Delta W_n - \Delta t) = O(\Delta t) - \text{local}, \sqrt{\text{var}(E_N)} = O(\Delta t^{0.5}) - \text{global} \quad (\text{Wiener}) \\
 \text{var}(E_N) &= \text{var}(E_{N-1}) + O(\Delta t^2) = \text{var}(E_{N-1}) + 2O(\Delta t^2) = \dots = N O(\Delta t^2) = \frac{1}{\Delta t} O(\Delta t^2) = T O(\Delta t) = O(\Delta t)
 \end{aligned}$$

$$\rightarrow \int_{t_0}^t \int_{t_0}^s L^0 f d\tau d\tau ds < K_1 \int_{t_0}^t \int_{t_0}^s d\tau ds = O(\Delta t^2) - \text{local} \Rightarrow O(\Delta t) - \text{global}$$

$$\rightarrow \int_{t_0}^t \int_{t_0}^s L^1 f dW_\tau ds < K_2 \int_{t_0}^t \int_{t_0}^s dW_\tau ds = O(\Delta t \Delta W_u) = O(\Delta t^{1.5}) - \text{local} \Rightarrow O(\Delta t) - \text{global} \quad (\text{Wiener})$$

$$\rightarrow \int_{t_0}^t \int_{t_0}^s L^1 g d\tau dW_s < K_3 \int_{t_0}^t \int_{t_0}^s d\tau dW_s = O(\Delta t \Delta W_u) = O(\Delta t^{1.5}) - \text{local} \Rightarrow O(\Delta t) - \text{global} \quad (\text{Wiener})$$

\Rightarrow Euler-Maruyama - dominated by $\int_{t_0}^t \int_{t_0}^s L^1 g dW_\tau dW_s$

$$\begin{aligned}
 dL^1 g &= L^0 L^1 g d\tau + L^1 L^1 g dW_\tau \Rightarrow L^1 g(X_t, \tau) = L^1 g(X_{t_0}, t_0) + \int_{t_0}^\tau L^0 L^1 g d\tau + \int_{t_0}^\tau L^1 L^1 g dW_\tau \\
 \Rightarrow X_t &= X_{t_0} + \int_{t_0}^t [f(X_{t_0}, t_0) + \int_{t_0}^s L^0 f d\tau + \int_{t_0}^s L^1 f dW_\tau] ds + \int_{t_0}^t [g(X_{t_0}, t_0) + \int_{t_0}^s L^0 g d\tau + \int_{t_0}^s L^1 g dW_\tau] dW_s \\
 &= X_{t_0} + f(X_{t_0}, t_0)(t - t_0) + g(X_{t_0}, t_0)(W_t - W_{t_0}) + L^1 g(X_{t_0}, t_0) + L^1 g(X_{t_0}, t_0) \int_{t_0}^t dW_s dW_s + \text{error terms} \\
 &= X_{t_0} + f(X_{t_0}, t_0)(t - t_0) + g(X_{t_0}, t_0)(W_t - W_{t_0}) + \frac{1}{2} g(X_{t_0}, t_0) \frac{\partial^2}{\partial x^2} (W_t - W_{t_0})^2 - (t - t_0) + \text{error terms}
 \end{aligned}$$

Milstein scheme: $X_{u+1} = X_u + f(X_u, u)\Delta t + g(X_u, u)\Delta W_u + \frac{1}{2} g(X_u, u) \frac{\partial^2}{\partial x^2} (\Delta W_u^2 - \Delta t) \Rightarrow \text{weak: } \frac{1}{2}, \text{ strong: } 1$

Pr. 1

$\mathbb{E}\left[\int_{t_0}^t G_s dW_s\right] = 0$ does not hold for Stratonovitz integrals.

$$\int_{t_0}^t W_s dW_s \stackrel{\text{Stratonovitz}}{=} \frac{W_t^2}{2} - \frac{W_{t_0}^2}{2} \Rightarrow \mathbb{E}\left[\frac{W_t^2}{2} - \frac{W_{t_0}^2}{2}\right] = \frac{1}{2}(t - t_0)$$

$\mathbb{E}[\text{Stratonovitz}] = \text{Itô}$ correction $\Rightarrow \mathbb{E}[I\hat{t}_0] = 0$

Pr. 2

$$\begin{aligned}\Phi_t &= \cos(\omega_0 t + b), \quad X_t = \omega_0 t, \quad dX_t = d\omega_0 t, \quad g=1, \quad \phi(x) = \cos(ax+b) \Rightarrow \frac{\partial \phi}{\partial t} = 0, \quad \frac{\partial \phi}{\partial x} = -a \sin(ax+b), \quad \frac{\partial^2 \phi}{\partial x^2} = -a^2 \cos(ax+b) \\ d\Phi_t &\stackrel{It\ddot{o}}{=} -a \sin(\omega_0 t + b) d\omega_0 t - \frac{1}{2} a^2 \cos(\omega_0 t + b) dt \\ &= -a \sqrt{1 - \cos^2(\omega_0 t + b)} d\omega_0 t - \frac{1}{2} a^2 \cos(\omega_0 t + b) dt \\ &= -\frac{1}{2} a^2 \phi_t dt + a \sqrt{1 - \phi_t^2} d\omega_0 t \\ \phi_0 &= \cos(\omega_0 \cdot 0 + b) = \cos(b)\end{aligned}$$

Pr. 3

$$\begin{aligned}\Phi_t &= (\omega_0 t)^4, \quad X_t = \omega_0 t, \quad dX_t = d\omega_0 t, \quad g=1, \quad \phi(x) = x^4 \Rightarrow \frac{\partial \phi}{\partial t} = 0, \quad \frac{\partial \phi}{\partial x} = 4x^3, \quad \frac{\partial^2 \phi}{\partial x^2} = 12x^2 \\ d\Phi_t &\stackrel{It\ddot{o}}{=} 4X_t^3 dX_t + \frac{1}{2} \cdot g \cdot 12X_t^2 dt = 6X_t^2 dt + 4X_t^3 dX_t \\ &= 6\omega_0^2 dt + 4\omega_0^3 d\omega_0 t \quad \omega_0 \stackrel{?}{=} \sqrt{\phi_t} \\ &= 6\sqrt{\phi_t} dt + 4\sqrt[4]{\phi_t^3} d\omega_0 t \\ \phi_0 &= \omega_0 = 0\end{aligned}$$

Pr. 4

$$\begin{aligned}\Phi_t &= (\omega_0 t)^4, \quad d\Phi_t \stackrel{It\ddot{o}}{=} 6\sqrt{\phi_t} dt + 4\sqrt[4]{\phi_t^3} d\omega_0 t \Rightarrow g(\Phi_t) = 4\sqrt[4]{\phi_t^3}, \quad \frac{\partial g}{\partial \phi} = 3\sqrt[4]{\phi_t^3} \\ \text{Stratonovich correction term: } &-\frac{1}{2} g(\Phi_t) \frac{\partial g}{\partial \phi} = -\frac{1}{2} \cdot 4 \cdot \sqrt[4]{\phi_t^3} \cdot 3 \cdot \sqrt[4]{\phi_t^3} = -6\sqrt{\phi_t} \\ d\Phi_t &\stackrel{str}{=} 4\sqrt[4]{\phi_t^3} d\omega_0 t\end{aligned}$$

Pr. 5

$$\begin{aligned}\frac{\partial x}{\partial t} &= ax^2 - bx^3 + c \sin(x), \quad x(0)=1, \quad t \geq 1, \quad A_t = a + N_t \\ \frac{\partial X_t}{\partial t} &\stackrel{str}{=} (a + N_t) X_t^2 + b X_t^3 + c \sin(X_t) \\ &= a X_t^2 - b X_t^3 + c \sin(X_t) + X_t^2 N_t \\ dX_t &\stackrel{str}{=} (a X_t^2 - b X_t^3 + c \sin(X_t)) dt + X_t^2 dN_t \Rightarrow g(X_t) = X_t^2 \quad \frac{\partial g}{\partial x} = 2X_t \\ \text{Stratonovich correction term: } &-\frac{1}{2} g(X_t) \frac{\partial g}{\partial x} \cdot \frac{1}{2} \cdot X_t^2 \cdot dX_t = X_t^3 \\ dX_t &\stackrel{It\ddot{o}}{=} (a X_t^2 - b X_t^3 + c \sin(X_t) + X_t^2) dt + X_t^2 dN_t, \quad X_0 = 1\end{aligned}$$

Pr. 6

$$dX_t = U dt + g d\omega_0 t, \quad X_0 = 0, \quad t \geq 0$$

$$dM_t = -a M_t dt, \quad M_0 = 1, \quad t \geq 0$$

X-position, M-mass, u-velocity of water, decaying matter

$$d\begin{pmatrix} X_t \\ M_t \end{pmatrix} \stackrel{\text{Itô}}{=} \begin{pmatrix} u \\ -aM_t \end{pmatrix} dt + \begin{pmatrix} g \\ 0 \end{pmatrix} dW_t, \quad \begin{pmatrix} X_0 \\ M_0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\vec{f}(X_t, M_t, t) \quad \vec{g}(X_t, M_t, t)$$

$$\text{Fokker-Planck: } \frac{\partial p}{\partial t} = -\frac{\partial}{\partial x}(up) - \frac{\partial}{\partial x}(-amp) + \frac{1}{2} \frac{\partial^2}{\partial x^2}(g^2 p) = -u \frac{\partial p}{\partial x} + a \frac{\partial mp}{\partial x} + \frac{q^2}{2} \frac{\partial^2 p}{\partial x^2}$$

$$p(x, m, 0) = \delta(x) \delta(m-1)$$