

# Probability Theory

$p(x)$  { prob. mass func. (pmd),  $x$ -discrete,  $P(\xi=x)=p(x)$   
 (prob. density func. (pdf),  $x$ -continuous,  $P(a < \xi < b) = \int_a^b p(x) dx$

Th  $F(x)$  - cumulative density function (cdf) =  $P(\xi < x)$

discrete:  $\forall x \in \mathcal{A} (P(\xi=x) \geq 0) \wedge \sum_{x \in \mathcal{A}} P(\xi=x) = 1$

$$E[\xi] = \sum_{x \in \mathcal{A}} x \cdot P(\xi=x) \quad E[f(\xi)] = \sum_{x \in \mathcal{A}} f(x) \cdot P(\xi=x)$$

continuous:  $\forall x \in \mathcal{A} (p(x) \geq 0) \wedge \int_{\mathcal{A}} p(x) dx = 1$

$$E[\xi] = \int_{\mathcal{A}} x \cdot p(x) dx \quad E[f(\xi)] = \int_{\mathcal{A}} f(x) p(x) dx$$

$$\text{Var}(\xi) = E[\xi^2] - (E[\xi])^2 = \sigma^2$$

$$E[n\xi] = n E[\xi] \quad E[n+\xi] = n + E[\xi] \quad \text{Var}(n\xi) = n^2 \text{Var}(\xi) \quad \text{Var}(n+\xi) = \text{Var}(\xi)$$

Th  $P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)} = \frac{P(A \cap B)}{P(B)}$

Bayes

$$P(B)$$

$$P(B)$$

Th  $\xi_1, \xi_2, \dots, \xi_n$  - independent random variables,  $E[\xi_i] = \mu$ ,  $\text{Var}[\xi_i] = \sigma^2 < \infty$ ,  $\bar{S}_n = \frac{\xi_1 + \xi_2 + \dots + \xi_n}{n}$

Central Limit  $\rightarrow \frac{\bar{S}_n - \mu}{\sigma/\sqrt{n}} \sim N(0, 1)$ ,  $\bar{S}_n \sim N(\mu, \frac{\sigma^2}{n})$  for large enough  $n$

$$\text{Relative Error} = \frac{\sqrt{\text{Var}(\bar{S}_n)}}{|\theta|} = \frac{\sigma}{\sqrt{n} |\theta|}$$

Hoeffding's Inequality

Def.  $\bar{S}_n$  approximates  $\mu$ .  $\delta = P(|\bar{S}_n - \mu| > \varepsilon) \rightarrow \delta \leq 2e^{-2n\varepsilon^2}$

$$P(|\bar{S}_n - \mu| > \varepsilon) \leq \delta \rightarrow P(-\varepsilon + \bar{S}_n < \mu < \varepsilon + \bar{S}_n) = 1 - \delta$$

$$2e^{-2n\varepsilon^2} \leq \delta \rightarrow n \geq \frac{1}{2\varepsilon^2} \ln\left(\frac{2}{\delta}\right)$$

$$1) X_i \sim \text{Ber}(p), \quad \bar{X}_n = \frac{\sum_{i=1}^n X_i}{n} \quad / \quad X \sim \text{Ber}(p), \quad E[X] = p, \quad \text{Var}[X] = p(1-p) /$$

$$\text{Var}(\bar{X}_n) = \text{Var}\left(\frac{\sum_{i=1}^n X_i}{n}\right) = \frac{N \text{Var}(X_i)}{N^2} = \frac{p(1-p)}{N} \quad \text{RE} = \frac{\sqrt{\text{Var}(\bar{X}_n)}}{p} = \frac{\sqrt{p(1-p)}}{\sqrt{n} p}$$

2)  $Y$  - RV, CDF =  $F_Y$ , RV  $T = F_Y^{-1}(X)$ ,  $X \sim U(0, 1)$

$$F_T(a) = P(T \leq a) = P(F_Y^{-1}(X) \leq a) = P(X \leq F_Y(a)) = \int_0^{F_Y(a)} 1 dx = F_Y(a)$$

$$3) f(x) = \frac{\sqrt{x(1-x)}}{C^x}, \quad 0 \leq x \leq 1, \quad C \geq 1$$

$$\lim_{x \rightarrow 1} f(x) = 0 \quad \lim_{x \rightarrow 0} f(x) = \infty$$

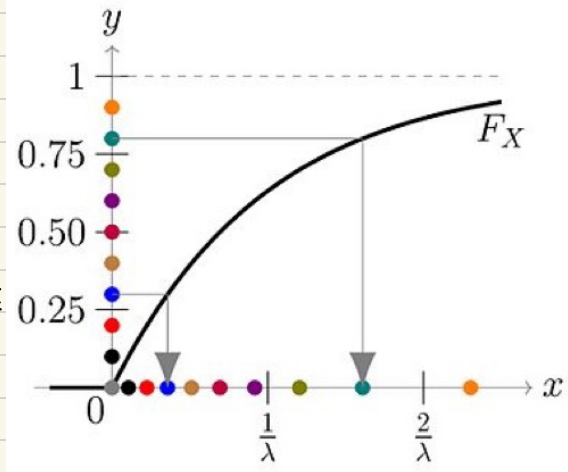
## Monte Carlo

Approximating an expectation by the sample mean of a function of simulated random variables.

### Inverse Transform

Sample any probability distribution with an invertible cumulative distribution  $F$ .

sample  $F^{-1}(X)$ ,  $X \sim U(0,1)$



2) Fibonacci sequence:

$$F(n) = \begin{cases} 1 & \text{if } n=1, 2 \\ F(n-1) + F(n-2) & \text{else} \end{cases}$$

$$F^*, F^*(1) = X_1 \sim U(0,1), F^*(2) = X_2 \sim U(1,2)$$

$$P(F^*(10) > 300) \sim 0.28, F^*(10) = 21F^*(1) + 34F^*(2) = 21X_1 + 34X_2$$

3)  $X \sim N(0,1)$  - continuous  $\Rightarrow P(X=0.3) = \int_{0.3}^{0.3} f(x) dx = F(x)|_{0.3}^{0.3} = F(0.3) - F(0.3) = 0$

4) a) Sample from circle, center  $\vec{x}$ , radius  $r$ ,  $f(x) = 2\pi$

$$\vec{x}' = \vec{x} + r \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}, \theta \sim U(0, 2\pi), Y \text{ has density } f(x)$$

Inverse Transform for sampling  $Y$ :

$$F(x) = \int_0^x f(t) dt = \int_0^x 2\pi dt = t^2 \Big|_0^x = x^2 \Rightarrow F^{-1}(x) = \sqrt{x}$$

$$\Rightarrow \vec{x}' = \vec{x} + r \sqrt{X} \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}, \theta \sim U(0, 2\pi), X \sim U(0,1)$$

b) 2 samplers, sampling  $A$  or  $B$  respectively, estimate  $p(A|B)$

1) sample  $X_i$  using sampler for  $B$

a)  $Y_i = RV$ , 1 if  $X_i \in A$ , otherwise 0

3) Repeat 1 & 2  $N$  times,  $\hat{p} = \bar{Y}_n = \frac{\sum_{i=1}^N Y_i}{N}$ ,  $\hat{p} \xrightarrow{p} p$  for large  $N$

c)  $Y_i \sim \text{Ber}(p) \Rightarrow \text{Relative Error} = \frac{\sqrt{\text{Var}(\bar{Y}_n)}}{\bar{p}} = \frac{\sqrt{p(1-p)}}{\bar{p}} = \frac{\sqrt{p(1-p)}}{\bar{p}}$

d) move  $A$  to the left s.t.  $P(A \cap B) > 0$  decreases

$P(A \cap B) \downarrow \Rightarrow p \downarrow \Rightarrow \text{Relative Error} \uparrow$

# Advanced Sampling Methods

## Acceptance Rejection

$$\varphi(x) = \frac{f(x)}{C} = \frac{f(x)}{\int_{-\infty}^{\infty} f(x) dx} \quad C - \text{normalizing constant, } \int \varphi(x) dx = 1$$

→ cannot always compute

1) pick  $g(x)$  - spans same range as  $f(x)$

2) pick  $M$  s.t.  $Mg(x) \geq f(x)$

3) sampling:  $s$  from  $g(x)$ ,  $u \sim U(0,1)$ , accept if  $u \leq \frac{f(s)}{Mg(s)}$

Efficiency:  $C/M$

## Simplex

$n$ -dimensional simplex  $\mathcal{A} = \left\{ \vec{x} = (x_1, \dots, x_{n+1})^T \mid \sum_{i=1}^{n+1} x_i = 1 \wedge x_i \geq 0, 0 \leq x_i \leq 1 \right\}$

1)  $n$  samples of  $\log(x_i)$ ,  $x_i \sim U(0,1)$

2) normalize by dividing by sum

3) return normalized

## Importance Sampling

$$\mathbb{E}_P[f(X)] = \int_{\mathcal{R}} f(x) p(x) dx = \int_{\mathcal{R}} q(x) \left( f(x) \frac{p(x)}{q(x)} \right) dx = \int_{\mathcal{R}} H(x) q(x) dx = \mathbb{E}_q[H(X)] \approx \frac{1}{n} \sum_{i=1}^n H(X_i^q)$$

1) pick  $q(x)$

2) generate  $X_1^q, \dots, X_n^q$ , calculate  $Y = \frac{1}{n} \sum_{i=1}^n H(X_i^q)$

3) construct confidence interval on  $Y \in \left[ -z_{\alpha/2} \frac{\hat{\sigma}}{\sqrt{n}} + Y, z_{\alpha/2} \frac{\hat{\sigma}}{\sqrt{n}} + Y \right]$

## Importance Splitting

$$P(B|A) = P(B|L_1)P(L_2|L_1)P(L_3|L_2)P(L_4|L_3)$$

1) pre-determined # samples from  $A$

2) sample reaches  $L_i$ , split it into  $k$  to start from  $L_i$ , if  $\varphi(X) < \tau$ , discard

3)  $P(L_{i+1}|L_i) = \frac{\text{\# samples reach } L_{i+1} \text{ from } L_i}{\text{\# samples simulated from } L_i}$

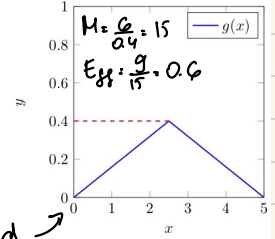
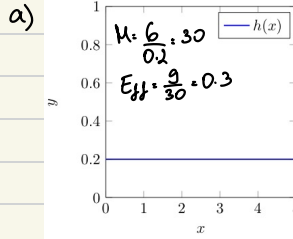
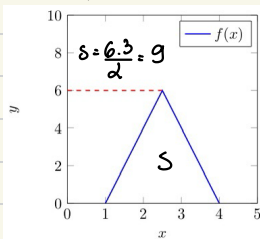
$$P(B|A) = P(B|L_n) \cdot \prod_{i=1}^{n-1} P(L_{i+1}|L_i) \cdot P(L_1|A)$$

Strong Markov Property must hold

1)  $X \sim N(\mu, \sigma^2)$ , Importance Sampling for  $\int x f(x) dx$   
 $q(x) = \frac{x f(x)}{\mu} \Rightarrow \int x f(x) dx = \int x q(x) \frac{\mu}{x f(x)} dx = \int \mu q(x) dx = \mu \int q(x) dx = \mu$   
 $f'(x) = \mu$   $\text{Var}(f'(X; q)) = \mathbb{E}[f'(X; q)^2] - (\mathbb{E}[f'(X; q)])^2 = \mu^2 - \mu^2 = 0$

## 2) Importance Splitting

3)  $\varphi(x) = \frac{f(x)}{N C}$  on  $[0, 5]$



preferred  $\rightarrow$

b)  $x_1 = 3, x_2 = 2, x_3 = 2, x_4 = 2.5, x_5 = 1$

random draws from  $U(0, 1)$ : 0.8, 0.2, 0.95, 1, 0.25, 0.4, 0.7, 0.3

1)  $x_1 = 3, u = 0.8$

$\frac{f(x_1)}{Mg(x_1)} = \frac{4}{4.5} \approx 0.88 > 0.8 \Rightarrow \text{accept}$

$\frac{f(x_1)}{Mh(x_1)} = \frac{4}{6} \approx 0.66 < 0.8 \Rightarrow \text{reject}$

2)  $x_2 = 2, u = 0.2$

$\frac{f(x_2)}{Mg(x_2)} = \frac{4}{4.5} \approx 0.88 > 0.2 \Rightarrow \text{accept}$

$\frac{f(x_2)}{Mh(x_2)} = \frac{4}{6} \approx 0.66 > 0.2 \Rightarrow \text{accept}$

3)  $x_3 = 2, u = 0.95$

$\frac{f(x_3)}{Mg(x_3)} = \frac{4}{4.5} \approx 0.88 < 0.95 \Rightarrow \text{reject}$

$\frac{f(x_3)}{Mh(x_3)} = \frac{4}{6} \approx 0.66 < 0.95 \Rightarrow \text{reject}$

4)  $x_4 = 2.5, u = 1$

$\frac{f(x_4)}{Mg(x_4)} = \frac{6}{6} = 1 = 1 \Rightarrow \text{accept}$

$\frac{f(x_4)}{Mh(x_4)} = \frac{6}{6} = 1 = 1 \Rightarrow \text{accept}$

5)  $x_5 = 1, u = 0.25$

$\frac{f(x_5)}{Mg(x_5)} = \frac{0}{4} = 0 < 0.25 \Rightarrow \text{reject}$

$\frac{f(x_5)}{Mh(x_5)} = \frac{0}{6} = 0 < 0.25 \Rightarrow \text{reject}$

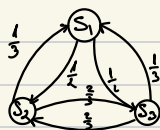
# Markov Chain Monte Carlo

## Markov Chains

$$p_{ij} = P(X_{t+1} = j | X_t = i)$$

$$S = \{s_1, \dots, s_n\} \quad n \in \mathbb{N} \text{ states}$$

$$X = (X_1, \dots, X_N) \quad X_i \in S$$



Def. Markov Property:  $P(X_{t+1} = x_{t+1} | X_t = x_t, X_{t-1} = x_{t-1}, \dots, X_0 = x_0) = P(X_{t+1} = x_{t+1} | X_t = x_t)$

$$M = \begin{bmatrix} 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{3} & 0 & \frac{2}{3} \\ \frac{1}{3} & \frac{2}{3} & 0 \end{bmatrix}$$

$$\bar{\pi}_t = [P(X_t = s_1) \quad P(X_t = s_2) \quad P(X_t = s_3)] \quad \bar{\pi}_1 = [1 \quad 0 \quad 0]$$

$$P(X_{t+1} = s_1) = P(X_{t+1} = s_1 | X_t = s_1) P(X_t = s_1) + \dots + P(X_{t+1} = s_1 | X_t = s_3) P(X_t = s_3)$$

$$\bar{\pi}_2 = \bar{\pi}_1 M = [0 \quad \frac{1}{2} \quad \frac{1}{2}] \quad \bar{\pi}_3 = \bar{\pi}_2 M = \bar{\pi}_1 M^2 = [\frac{1}{3} \quad \frac{1}{3} \quad \frac{1}{3}]$$

$$\bar{\pi}_k = \bar{\pi}_1 M^{k-1}, \quad k \rightarrow \infty \Rightarrow \bar{\pi} M = \bar{\pi}, \quad M v = \lambda v \text{ for } \lambda = 1, \sum_{i=1}^n \bar{\pi}[i] = 1 \wedge \forall i (\bar{\pi}[i] \geq 0)$$

M-irreducible (strongly connected)  $\rightarrow \exists! v | \bar{\pi}$

M-aperiodic (no pattern in states)

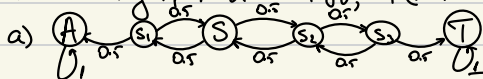
## Metropolis-Hastings

sample from probability distribution  $P(x)$ , proposal distribution  $Q(q'|q)$   
arbitrarily pick  $q_0, q = q_0$

repeat  $\left\{ \begin{array}{l} \text{generate } q' \text{ from } Q(q'|q) \\ A(q'|q) = \min(1, P(q') Q(q|q') / P(q) Q(q'|q)) \\ u \sim U(0, 1), \quad u < A(q'|q), \quad q = q' \end{array} \right.$

Metropolis Algorithm -  $Q(q|q') \cdot Q(q'|q), \quad A(q'|q) = \min(1, P(q') / P(q))$

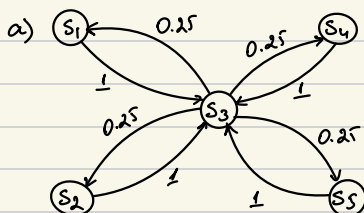
1) T - 3 km right, A - 2 km left,  $P(1 \text{ km left}) = P(1 \text{ km right}) = 0.5$



b) absorbing states  $\Rightarrow$  not irreducible

2)

$$P = \begin{bmatrix} 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0.25 & 0.25 & 0 & 0.25 & 0.25 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix}$$



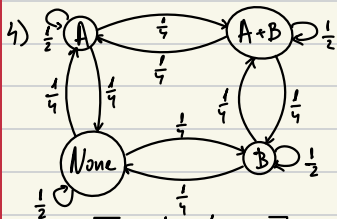
b)  $X_0 = s_3 \Rightarrow \bar{u}_0 = [0 \ 0 \ 1 \ 0 \ 0]$

i)  $\bar{u}_1 = \bar{u}_0 P = [0.25 \ 0.25 \ 0 \ 0.25 \ 0.25]$

ii)  $\bar{u}_2 = \bar{u}_1 P = \bar{u}_0 P^2 = [0 \ 0 \ 1 \ 0 \ 0]$

c)  $P(X_{2,0} = s_3) = 1$  because periodic

d) no stationary distribution because periodic



a)

$$M = \begin{bmatrix} \frac{1}{2} & \frac{1}{4} & \frac{1}{4} & 0 \\ \frac{1}{4} & \frac{1}{2} & 0 & \frac{1}{4} \\ \frac{1}{4} & 0 & \frac{1}{2} & \frac{1}{4} \\ 0 & \frac{1}{4} & \frac{1}{4} & \frac{1}{2} \end{bmatrix}$$

b) M-irreducible and aperiodic  $\Rightarrow \exists! v$  s.t.  $vM = v$

uniform distribution  $\Rightarrow v = [\frac{1}{4} \ \frac{1}{4} \ \frac{1}{4} \ \frac{1}{4}]$

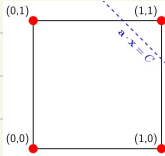
$vM = [\frac{1}{4} \ \frac{1}{4} \ \frac{1}{4} \ \frac{1}{4}] = v$

c)  $f$ -fitness function, stationary distribution  $\sim f$   
Metropolis Hastings with  $P = f$ .

# Optimization & Planning

## Knapsack Problem Model

$W = \{w_1, \dots, w_n\}$  weights,  $C$  capacity,  $s_i = 1$  if item  $i$  in knapsack, otherwise  $s_i = 0$   
 $\vec{x} = (s_1, s_2, \dots, s_n)^T$  solution,  $\vec{a} = (w_1, w_2, \dots, w_n)^T \Rightarrow \vec{a} \cdot \vec{x} = \sum_{i=1}^n w_i \cdot s_i$ ,  $\vec{a} \cdot \vec{x} \leq C \Rightarrow \vec{x}$ -feasible



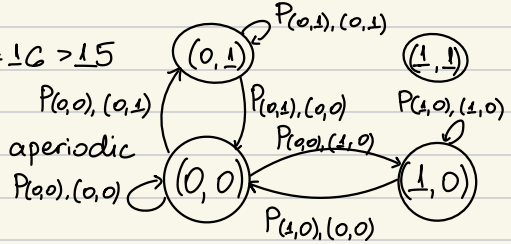
$$\vec{a} = (5, 11)^T$$

$$C = 15$$

$$\vec{a} \cdot \vec{x} = \begin{pmatrix} 5 \\ 11 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 5 + 11 = 16 > 15$$

solution space  $\mathcal{S} = \{ \vec{x} \in \{0, 1\}^n \mid \vec{a} \cdot \vec{x} \leq C \}$

ergodic, aperiodic



## Nearest Neighbor Random Walk

$X_t = (x_0, \dots, x_{n-1})$  at step  $t$ ,  $u \sim U(0, 1)$

$X_{t+1} = \begin{cases} X_t & \text{if } u < \frac{1}{2} \\ X_t' & \text{otherwise} \end{cases}$

$X_t'$ : pick an item at random; if item in  $X_t$ , remove it; if not, add it

## Metropolis-Hastings

$P(\vec{x}) = \begin{cases} \frac{1}{Z} \exp(\beta \cdot \vec{a} \cdot \vec{x}) & \text{if } \vec{a} \cdot \vec{x} \leq C \\ 0 & \text{else} \end{cases}$   $\beta$ -temperature  $\left\{ \begin{array}{l} \beta \uparrow = \text{exploitation} \\ \beta \downarrow = \text{exploration} \end{array} \right.$   $Z$ -normalizing const.

$\hookrightarrow$  target distribution = fitness function (better solutions are more likely)

$$A(q' | q) = \min \left( 1, \frac{P(q')}{P(q)} \right) = \min \left( 1, \frac{\exp(\beta \cdot \vec{a} \cdot q')}{\exp(\beta \cdot \vec{a} \cdot q)} \right) = \min(1, \exp(\beta \cdot \vec{a} \cdot (q' - q)))$$

## Simulated Annealing

$\beta(t) = c \log(t)$ ,  $c > 0 \Rightarrow$  increasing temperature/exploration with time

1)  $L = \vec{a} \cdot \vec{x} \leq C$ , minimize  $\vec{a} \cdot \vec{x}$

a)  $\vec{a} = (2, 3, 1, 7)^T$ ,  $C = 11$ ,  $L = 8$ ,  $\vec{x} = (1, 1, 1, 0)^T$

$\vec{a} \cdot \vec{x} = 6 < 8 \Rightarrow$  not feasible

b)  $P(x) = \begin{cases} \frac{1}{Z} \exp\left(\frac{\beta}{\vec{a} \cdot \vec{x}}\right) & \text{if } L \leq \vec{a} \cdot \vec{x} \leq C \\ 0 & \text{else} \end{cases}$

2) Vertex-Cover  $S \subset V$ ,  $G = (V, E)$

a)  $\vec{x} = (x_1, x_2, \dots, x_n)^T = (1, 0, \dots, 1)^T$  if  $x_i = 1$   $i^{\text{th}}$  vertex in  $S$

$S = \{ \vec{x} \mid \forall (u, v) \in E, x_u + x_v \geq 1 \}$

b) transition = remove/add vertex

c)  $P(\vec{x}) = \begin{cases} \frac{1}{Z} \exp(-\vec{x}) & \text{if } \forall (u, v) \in E, x_u + x_v \geq 1 \\ 0 & \text{else} \end{cases}$

d) exploitation,  $\beta(t) = c_1 e^{c_2 t} \begin{cases} A: c_1 = 0.16, c_2 = 2 \\ T: c_1 = 0.04, c_2 = 4 \end{cases}$

$\beta_A(t) \cdot \beta_T(t) \Rightarrow 0.16e^{2t} \cdot 0.04e^{4t} \Rightarrow 4e^{2t} \Rightarrow t = \ln 2$ ,  $\beta_A(t) \cdot 0.32te^{2t} < 0.16te^{4t} = \beta_T(t)$

3) a) Metropolis-Hastings,  $\beta = 0$ : Every transition picked is chosen. } not equivalent

Nearest-Neighbor Random Walk:  $\frac{1}{2}$  probability of self loop

b) information about solution  $\Rightarrow$  Nearest-Neighbor Random Walk in region  $>$  uniform sampling

c) Bias in random walks might make them less efficient than uniform sampling.

4) Inhomogeneous Markov Chain,  $P(X_{t+1} = x_{t+1} \mid X_t = x_t)$  depends on  $t$

Simulated Annealing,  $P(X_t = b \mid X_{t-1} = a) \neq P(X_{t+1} = b \mid X_t = a)$ ,  $t \neq t_1$