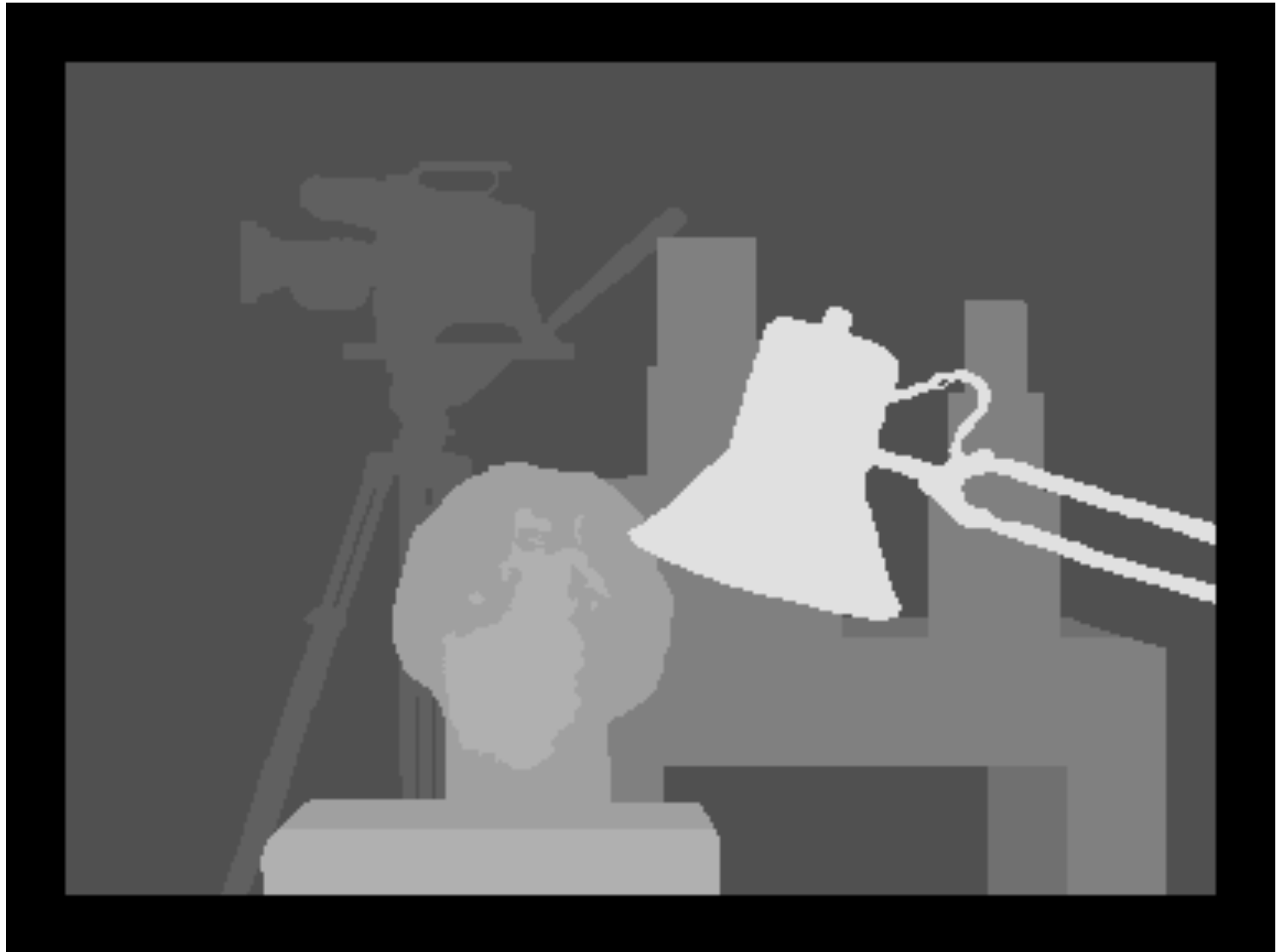


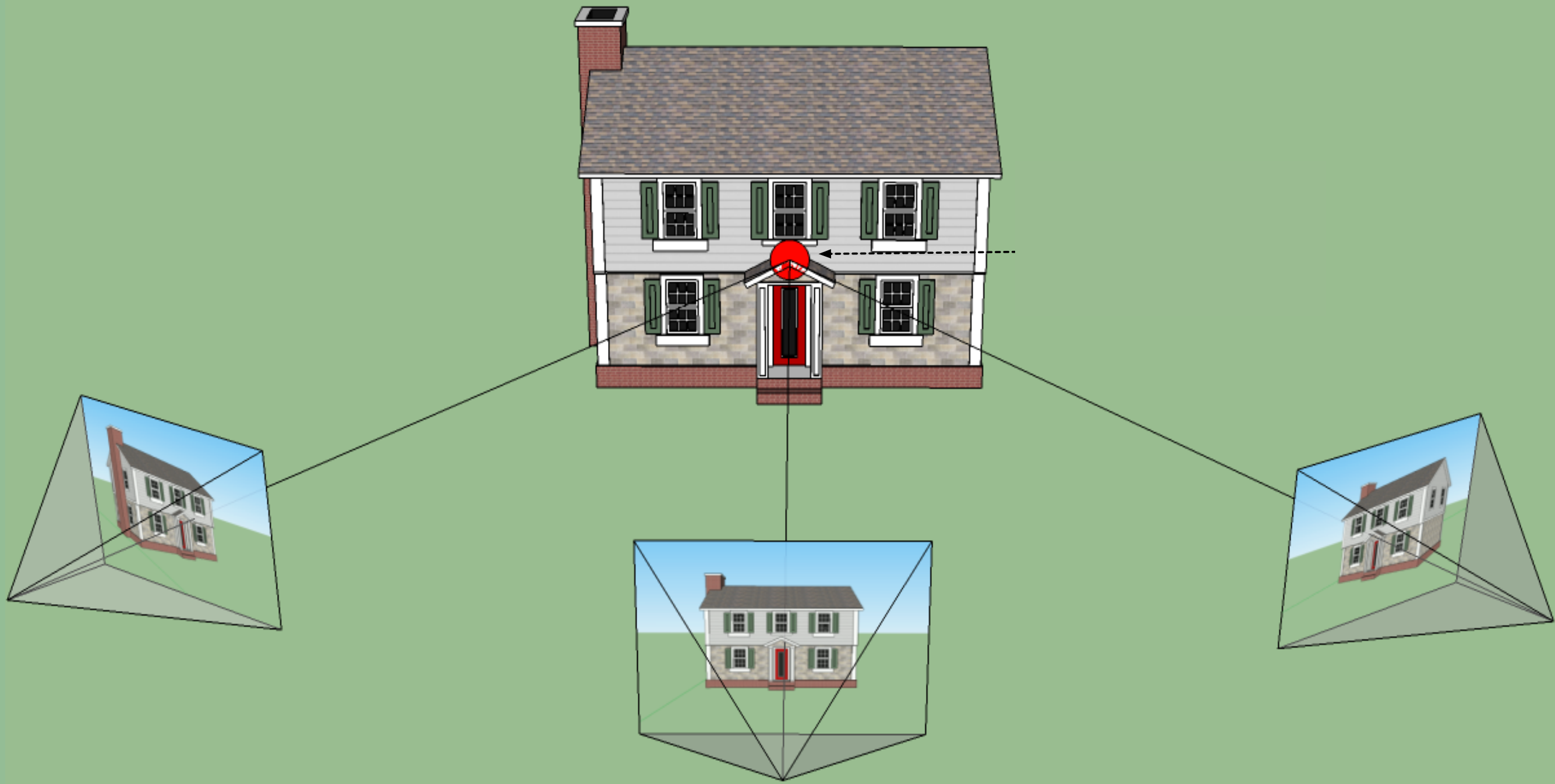
# 3D Reconstruction with Computer Vision

## Meeting 7: Stereo and Epipolar Geometry



Slides by Richard Szeliski and others  
CS 378 Fall 2014, UT Austin, Bryan Klingner, 18 September

# Idea: 3D from multiple images of a scene



# Stereo Matching

Given two or more images of the same scene or object, compute a representation of its shape

What are some possible representations?

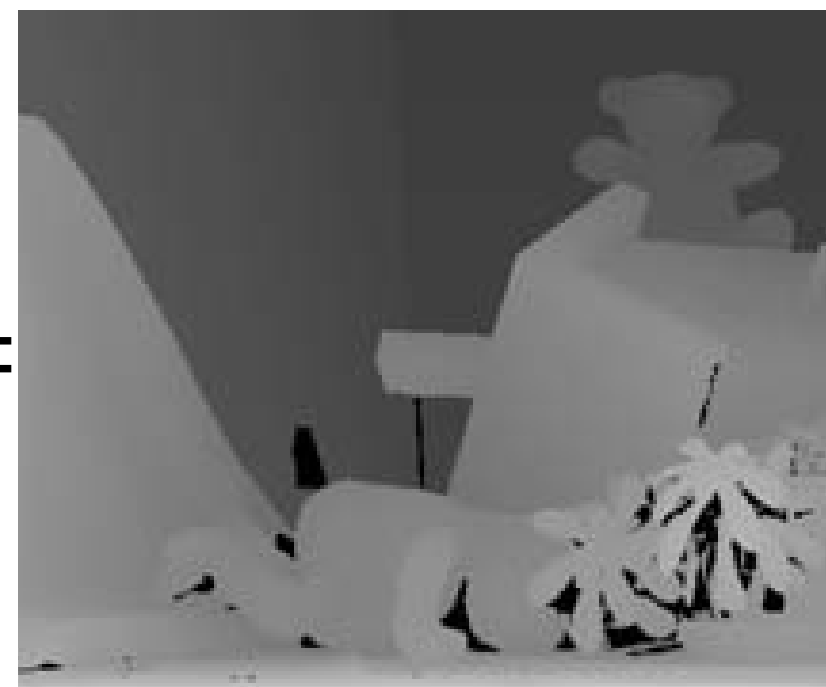
- depth maps
- volumetric models
- 3D surface models
- planar (or offset) layers



+



=



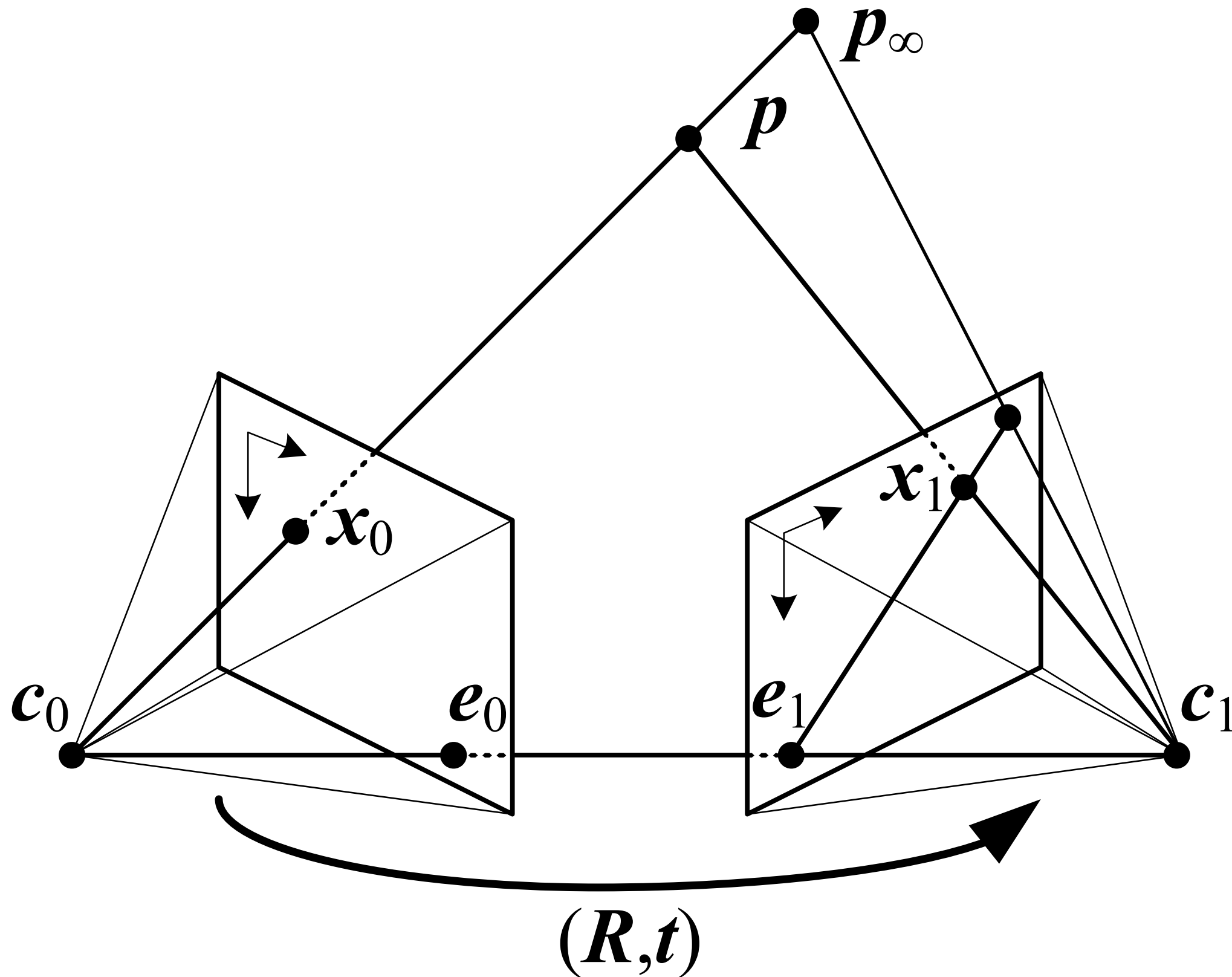
+



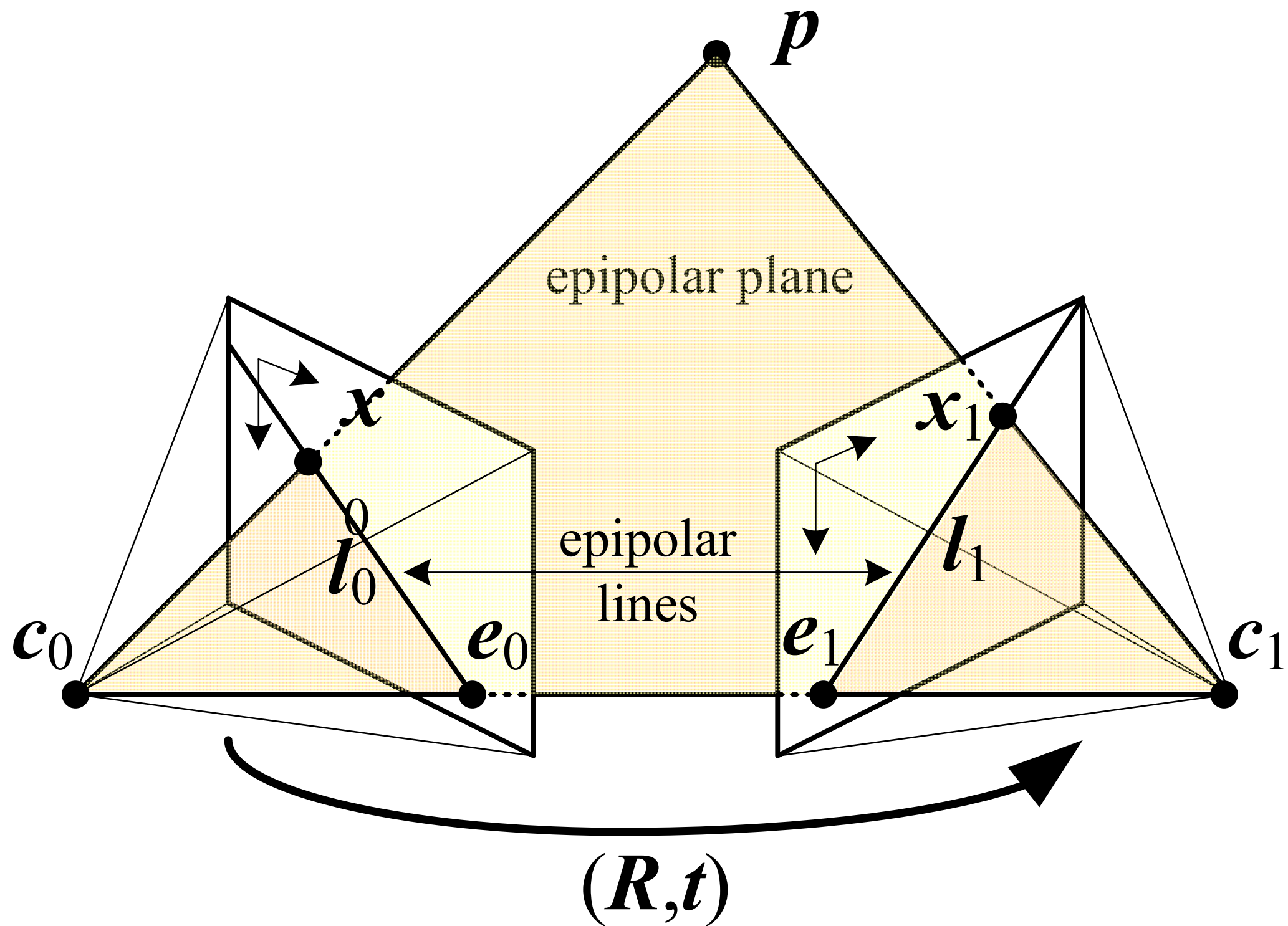
=



# Epipolar Geometry



# Epipolar Geometry



# Stereo: epipolar geometry

for *two* images (or images with collinear camera centers), can find epipolar lines

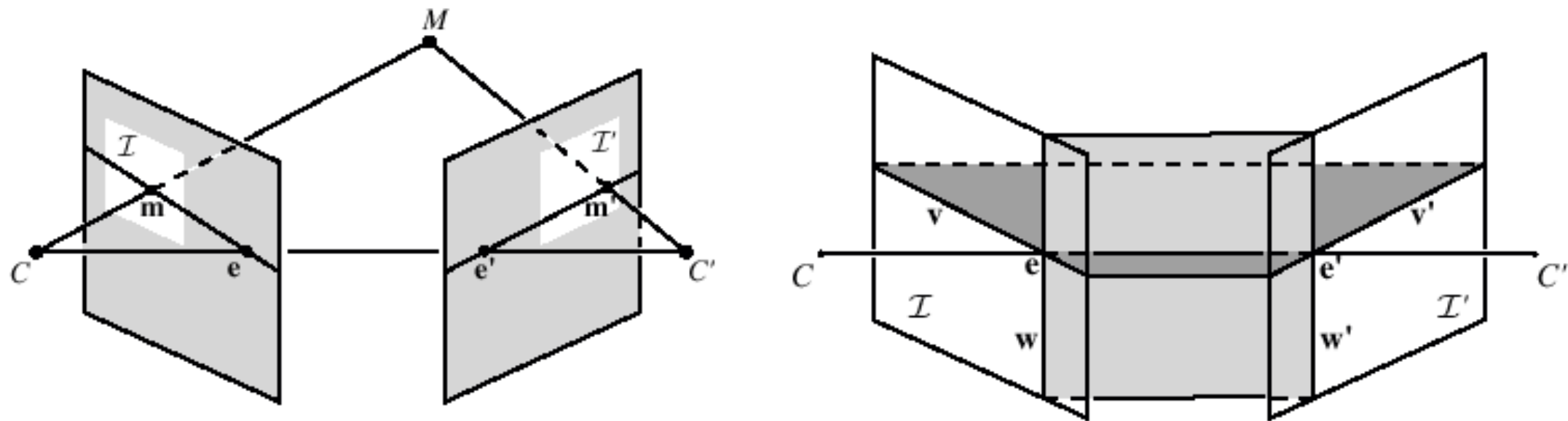
epipolar lines are the projection of the *pencil* of planes passing through the centers

**Rectification:** warping the input images (perspective transformation) so that epipolar lines are horizontal

# Rectification

Project each image onto same plane, which is parallel to the epipole

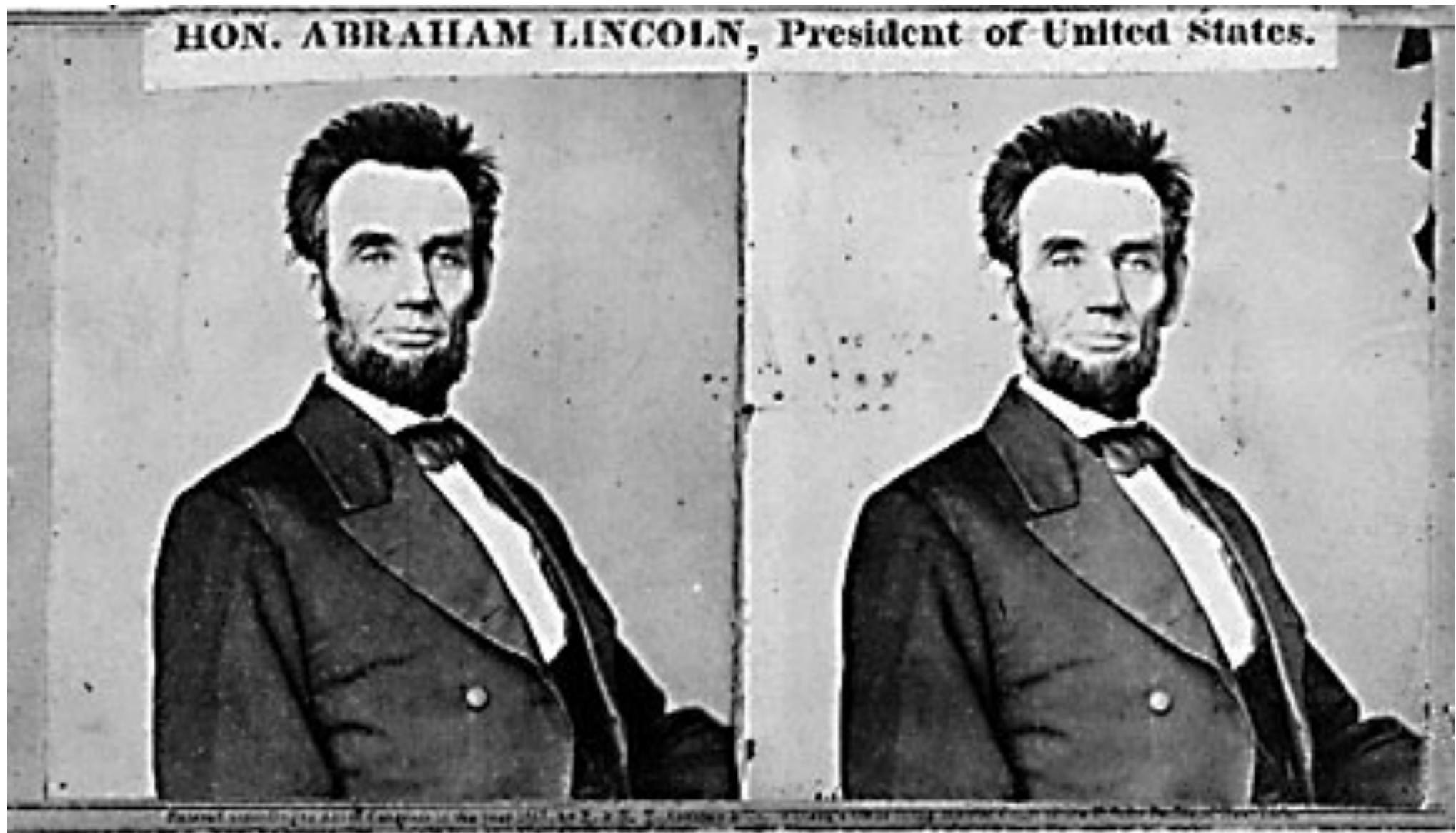
Resample lines (and shear/stretch) to place lines in correspondence, and minimize distortion



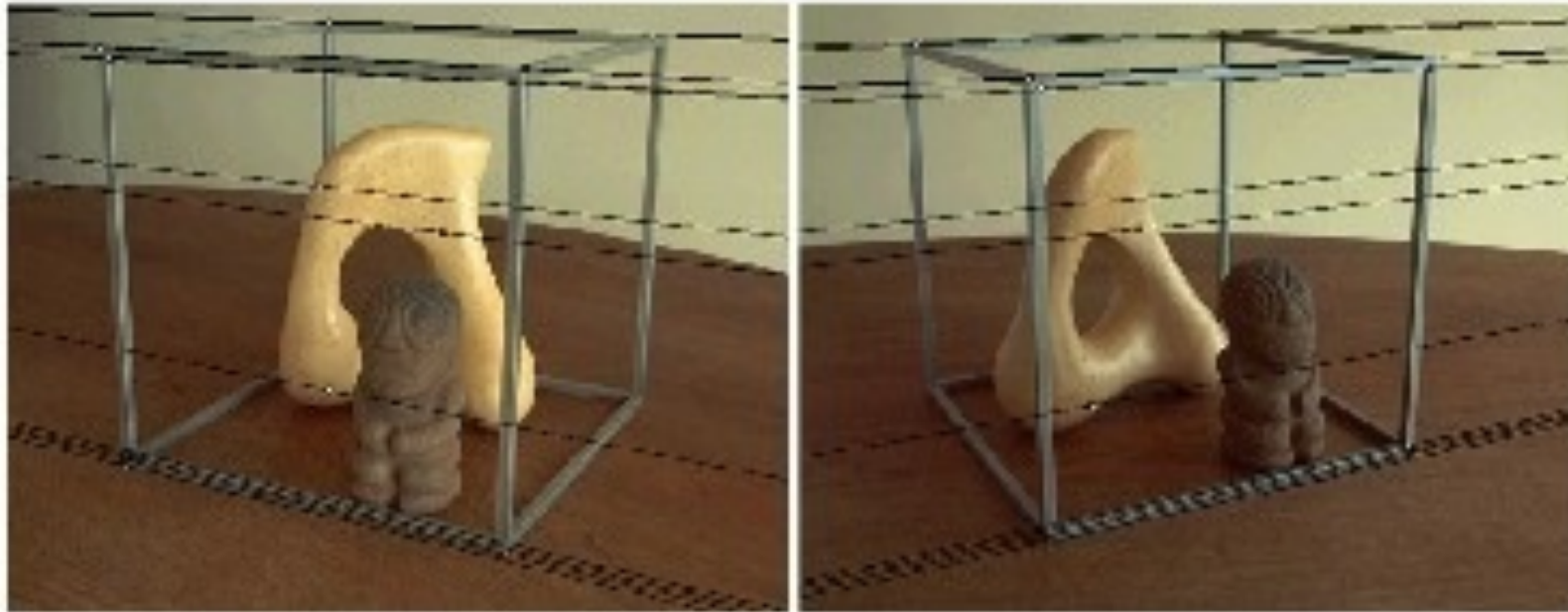
[Loop and Zhang, CVPR'99]



# Stereo image pair



# Rectification



(a) Original image pair overlaid with several epipolar lines.



(b) Image pair transformed by the specialized projective mapping  $H_p$  and  $H'_p$ . Note that the epipolar lines are now parallel to each other in each image.

**BAD!**



# Rectification



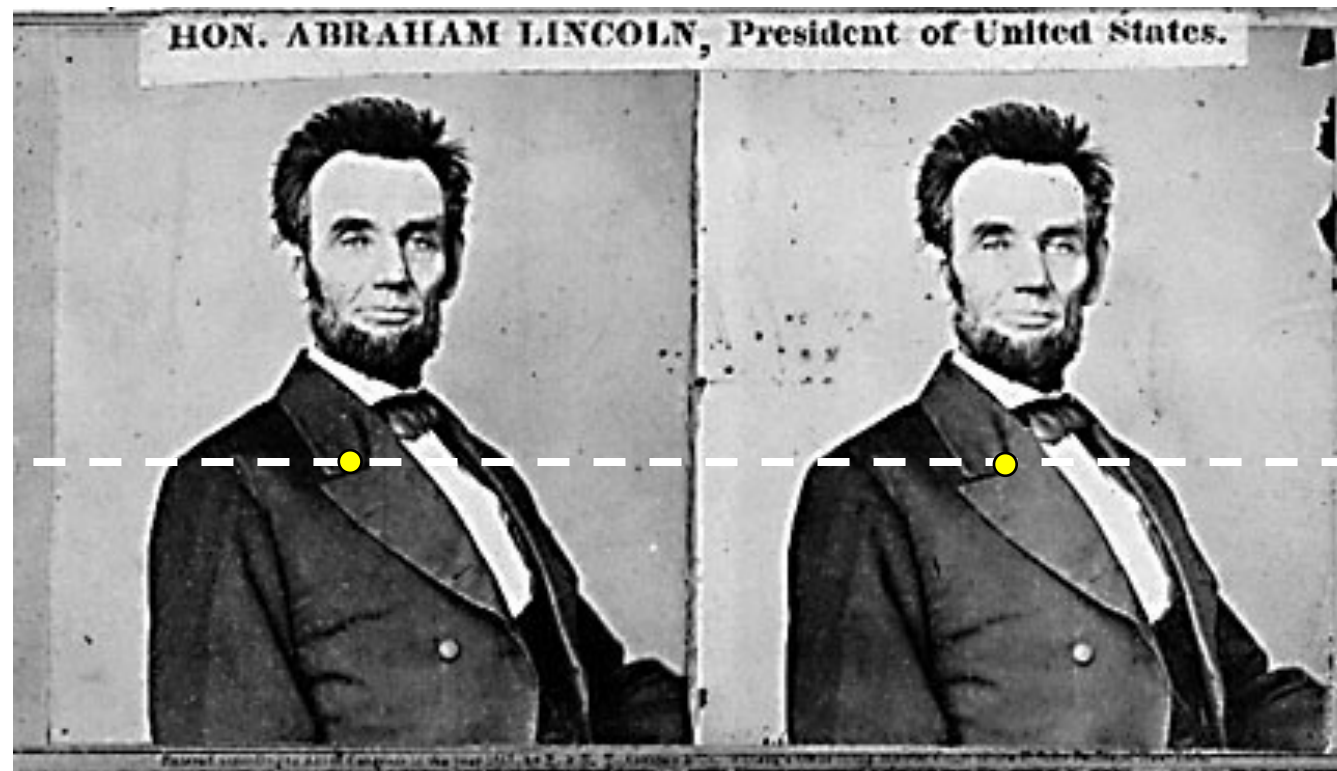
(c) Image pair transformed by the similarity  $\mathbf{H}_r$  and  $\mathbf{H}'_r$ . Note that the image pair is now rectified (the epipolar lines are horizontally aligned).



(d) Final image rectification after shearing transform  $\mathbf{H}_s$  and  $\mathbf{H}'_s$ . Note that the image pair remains rectified, but the horizontal distortion is reduced.

GOOD!

# Your basic stereo algorithm



For each epipolar line

For each pixel in the left image

- compare with every pixel on same epipolar line in right image
- pick pixel with minimum match cost

Improvement: match **windows**

- This should look familiar...



# Worktime: Project 1

