Feasibility Assessment and Roadmap for XJTLU Campus Information and Visitor Service System

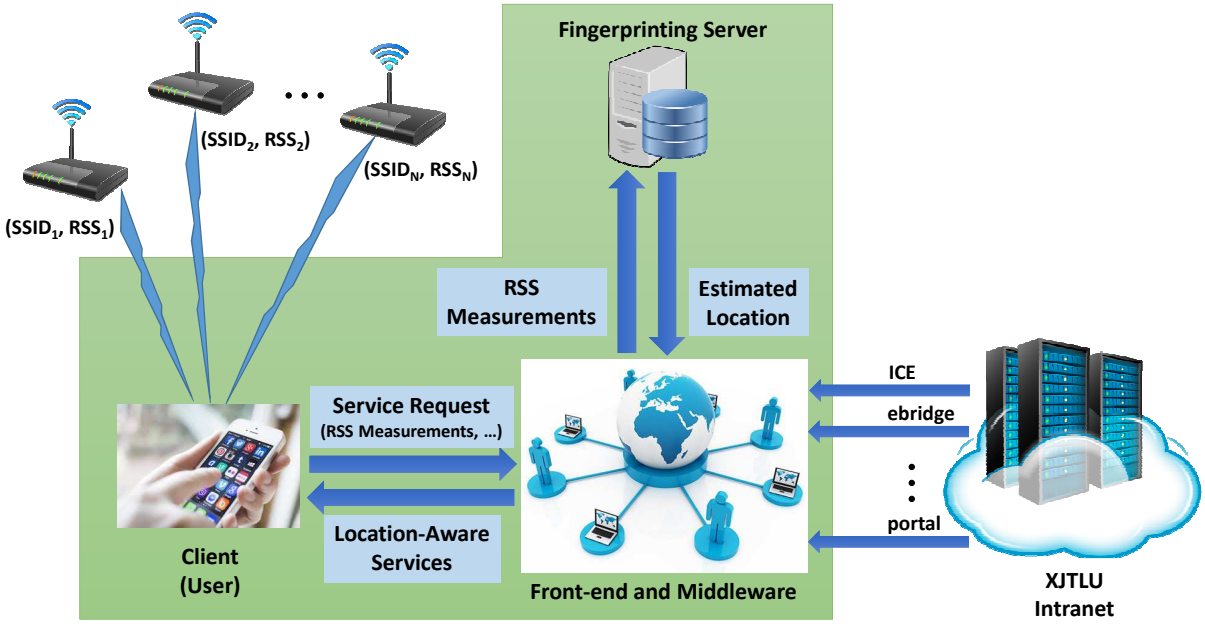
(*A Test Bed for Large-Scale Location-Aware Services in SIP*)

Kyeong Soo (Joseph) Kim
Research Institute for Smart and Green Cities
Xi'an Jiaotong-Liverpool University (XJTLU)

Outline

- Technical overview
- Work packages
- Roadmapping

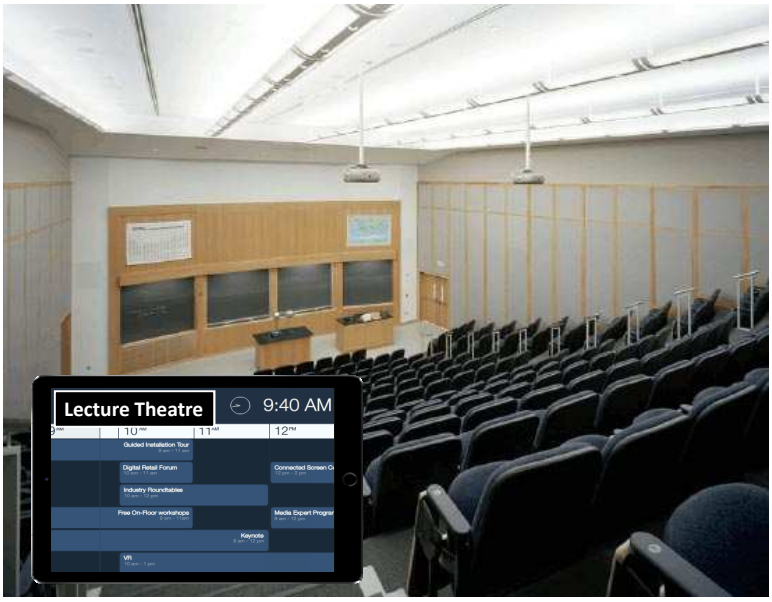
Technical Overview



XJTLU Camus Information and Visitor Service System

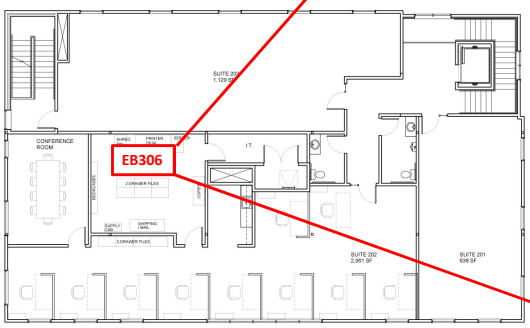
Service Example: Indoor Localisation/Navigation

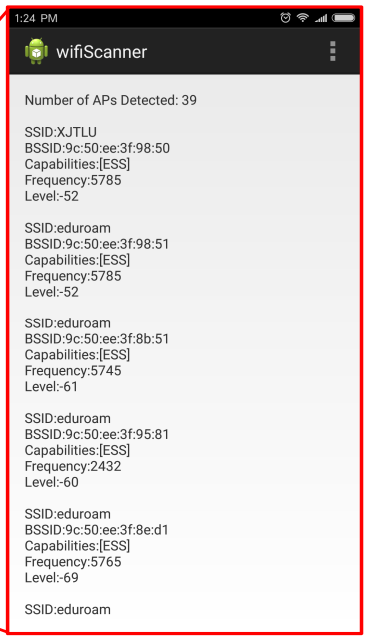
Service Example: Location-Aware Service



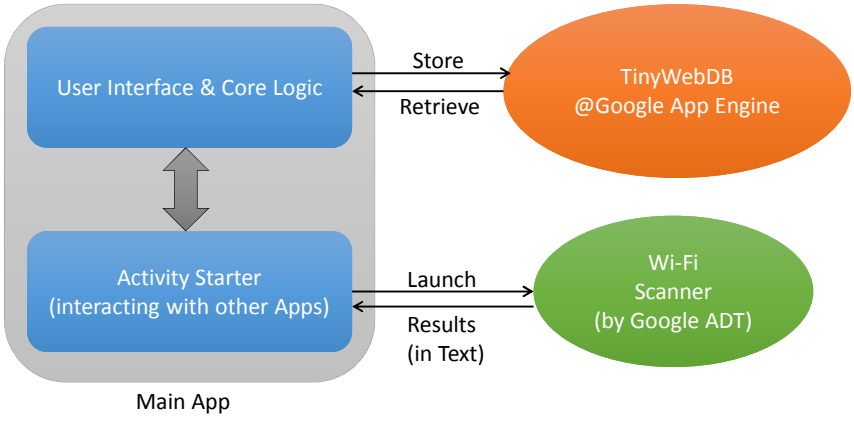
Location Fingerprint

- A tuple of $(\mathcal{L}, \mathcal{F})$
  - $\mathcal{L}$: Location information
    - Geographic coordinates or a label (e.g., "EB306")
  - $\mathcal{F}$: Vector/function of RSSs
    - e.g., $(\rho_1, \cdots, \rho_N)^T$ where ρ_i is the RSS from i_{th} access point (AP_i).

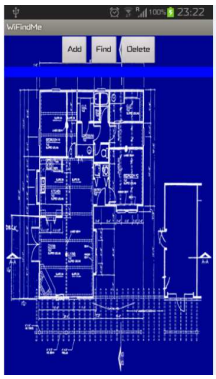




Implementation Example - 1



Implementation Example - 2



Start the app and press the 'Find' button.

Results of Wi-Fi scanning.

Find the location and display the picture.

Major Challenges in Large-Scale Implementation

- Scalability
- Localisation accuracy
- Non-stationarity of location fingerprints
  - Incremental/online learning algorithms with pruning/forgetting mechanisms*
- Passive vs. active location estimation
- Integration with other services
- Security/privacy issues

** R. Elwell and R. Polikar, "Incremental learning in nonstationary environments with controlled forgetting," Proc. IJCNN'09.*

Work Packages

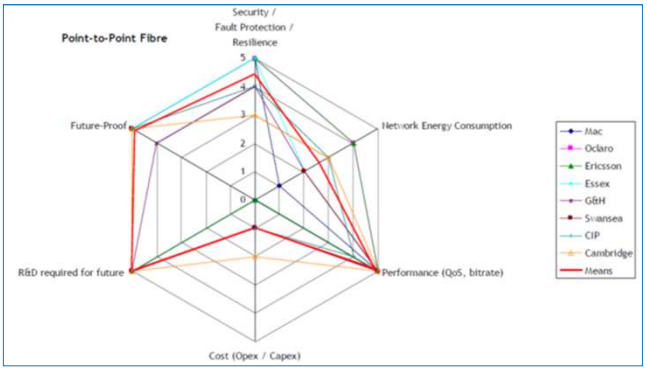
WP1: Indoor localisation based on location fingerprinting
- Dr K Kim
- Dr Lee
- Dr Huang
- Prof Lim

WP2: Scalable and secure location-aware service system
- Prof Chen
- Dr K Kim

WP3: Data analysis and visualisation of users' behaviours to improve the educational environments
- Dr J Kim
- Dr Wang
- Dr Craig

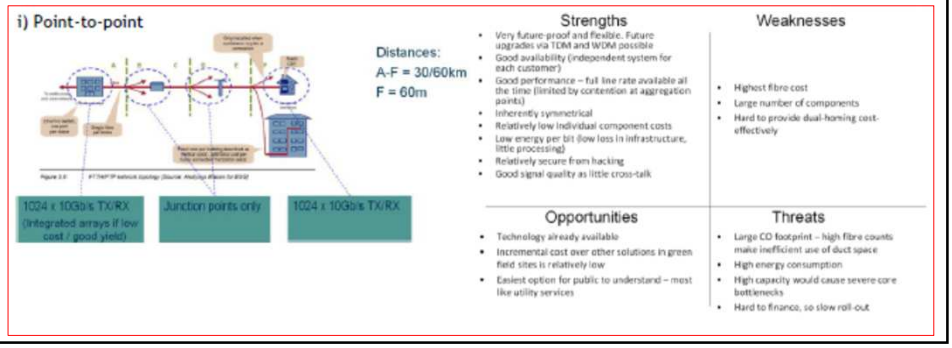
WP4: Extending and sharing with external units
- Dr Lee
- Dr K Kim

Roadmapping



Scoring Exercise

Comparative Analysis



Backup Slides

Wi-Fi Fingerprinting

Location Estimation

- Deterministic
  - **Nearest Neighbour Methods**
  - Neural Network Methods
- Probabilistic
  - Bayesian Inference
  - Support Vector Machine (SVM)
  - Gaussian Process Latent Variable Model (GP-LVM)

Nearest Neighbour Methods*

- A simple approach based on the notion of distance in the signal space:
  - Given a fingerprint of $(\mathcal{L}, (\rho_1, \cdots, \rho_N)^T)$ and an RSS measurement of $(s_1, \cdots, s_N)^T$, the *Euclidean distance* measure between them is defined as

$$\sqrt{\sum_{i=1}^{N} (s_i - \rho_i)^2}$$

  - Then, we find a fingerprint providing a minimum distance, $\mathcal{L}$ of which is the estimated location.

** P. Bahl and V. N. Padmanabhan, "RADAR: An in-building RF-based user location and tracking system," Proc. of INFOCOM 2000, vol. 2, pp. 775-784, Mar. 2000.*