

ECEN 449: Microprocessor System Design

Lab 2: Using the Software Development Kit (SDK)

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Introduction:

The purpose of this lab is to learn how to do the general procedures of implementing the microprocessors and GPIO using block diagrams in vivado and using the SDK to run code on the FPGA board.

Procedure:

Part 1:

- 1. Put in microprocessor and GPIO both into a block diagram
- 2. Then I created an HDL wrapper
- 3. Generate bitstream
- 4. Opened up the SDK
- 5. Imported and edited the c code
- 6. Programmed the FPGA
- 7. Test the functionality

Part 2:

- 1. Did the same thing as part one from steps 1-4 but also included a 8bit GPIO into the block diagram
- 2. Created new c code and programmed the FPGA
- 3. Test functionality

Results:

The results were predictable. In part 2, the first 2 buttons increased and decreased the count. The next 2 buttons, one of them showed the current count and the other showed the switched LED positions value. I went through the header file xparameters.h to obtain the address of the block and use it in the SetDataDirection function. The logic is almost the same as lab 1, however, this time C was used.

Outputs:

```
TCF Debug Virtual Terminal - MicroBlaze Debug Module at USER2

Value of LEDs = 0x0

Value of LEDs = 0x1

Value of LEDs = 0x3

Value of LEDs = 0x4

Value of LEDs = 0x5

Value of LEDs = 0x6

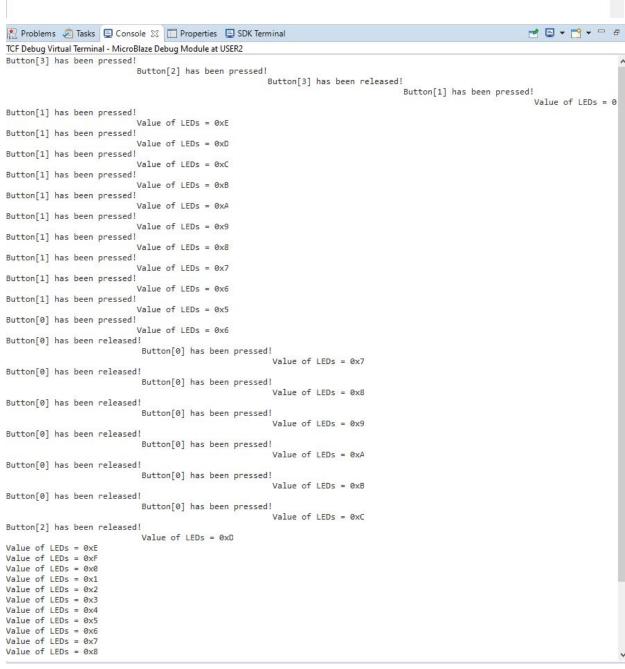
Value of LEDs = 0x7

Value of LEDs = 0x8

Value of LEDs = 0x9

Value of LEDs = 0xA

Value of LEDs = 0xA
```



Conclusion:

I learned how to use the SDK to create a MicroBlaze system and use GPIO blocks to create inputs and output for the system. I also learned how to implement the FPGA using C. The process of reading through the header files and the C code helps me understand the syntax and the use of the new functions: SetDataDirection, DiscreteWrite, DiscreteRead, etc in SDK.

Post-Lab Questions:

In the first part of the lab, we created a delay function by implementing a counter. The goal was to update the LEDs approximately every second as we did in the previous lab. Compare the count value in this lab to the count value you used as a delay in the previous lab. If they are different, explain why? Can you determine approximately how many clock cycles are required to execute one iteration of the delay for-loop? If so, how many?

The count I used for this lab compared to lab 1 both update every the second even though the counts are different. In lab 1 I used 150000000 because the clock given for the FPGA is 150 MHz. The count I used for this lab was 10000000, this is because the system updates at 1 Hz. 2.

Why is the count variable in our software delay declared as volatile?

Because the count variable can change on its own at any time.

What does the while(1) expression in our code do?

The while loop is an infinite loop that runs until an interrupt/abort happens.

Compare and contrast this lab with the previous lab. Which implementation do you feel is easier? What are the advantages and disadvantages associated with a purely software implementation such as this when compared to a purely hardware implementation such as the previous lab?

Lab 1 was easier than lab 2 because of how little steps we had to take doing the hardware implementation. This is only because we had to do simple tasks for the first 2 labs. As the labs get harder and harder the more likely software implementation will be needed.

Code:

```
#include <xparameters.h>
#include <xgpio.h>
#include <xstatus.h>
#include <xil printf.h>
#define WAIT VAL 0x1000000
#define GPIO DEVICE XPAR LED DEVICE ID
int delay(void);
int main(){
       int count;
       int count masked;
       XGpio led; //Hardware io
       int status;
       status = XGpio Initialize(&leds, GPIO DEVICE ID);
       XGpio SetDataDirection(&leds,1,0x00);
       if(status!=XST SUCCESS){
               xil printf("Initialization failed");
       count=0;
       while(1) //infinite loop to keep circuit always executing
               count masked = count & 0xf;//get lower 4 bits of count, so that count masked rolls over
every 16 counts
               XGpio DiscreteWrite(&led,1,count masked);//write count masked to leds
               xil printf("Value of LEDs = 0x\%x\n\r",count masked); //Print count to console
               delay();
               count++;
       }
       return (0);
}
int delay (void)
{
       volatile int delay count=0; // volatile prevents compiler optimization
       while(delay count<WAIT VAL)
               delay count++;// each iteration of while loop is 2 clock cycles
       return(0);
}
```

```
#include <xgpio.h>
#include <xstatus.h>
#include <xil printf.h>
//Definitions
#define GPIO DEVICE ID LEDS XPAR LED DEVICE ID //device IDs
#define GPIO DEVICE ID SWB XPAR BTN SW DEVICE ID
#define WAIT VAL 10000000 //100 MHz clock input (we need to divide it by 10 mil to get 1 Hz)
#define boolean Bool //boolean is more pleasant to type than Bool
#define false 0 //vivado requires this in order to compile
#define true 1
int delay(void) { //slows the 100 MHz clock down to 1 MHz
       volatile int delay count = 0; //tells the compiler that this value may change at any time without
any action taken
       while (delay count < WAIT VAL) {
               delay count++;
       return (0);
}
int main() {
       int count = 0; //actual count value (may be greater than 15)
       int count masked = 0; //count masked will always be between 0 and 15
       XGpio leds; //LEDs
       XGpio swb; //switches/buttons
       int statuso; //verifying satisfactory status of the output port
       statuso = XGpio Initialize(&leds, GPIO DEVICE ID LEDS);
       XGpio SetDataDirection(&leds, 1, 0); //0 is for output
       if (statuso != XST SUCCESS) {
               xil printf("Initialization failed (LEDs)");
       }
       XGpio Initialize(&swb, GPIO DEVICE ID SWB);
       XGpio SetDataDirection(&swb, 1, 1);//1 is for input
       int switchValue = 0;
       //this is how we keep track of whether variables change
       boolean b0 = false;
       boolean b1 = false;
```

#include <xparameters.h>

```
boolean b2 = false;
        boolean b3 = false;
        for (;;) { //this loop will go until the user terminates the program manually
                boolean button0 = (0x01 \& XGpio DiscreteRead(\&swb, 1) == 0x01) //button 0 is
currently pressed (overrides button 1 being pressed)
                        && !((XGpio DiscreteRead(&swb, 1) & 0x04) == 0x04) //NOT button2
                        && !((XGpio DiscreteRead(&swb, 1) & 0x08) == 0x08); //NOT button3
                boolean button1 = ((XGpio DiscreteRead(&swb, 1) & 0x02) == 0x02) //button 1 is being
pressed
                        &&!((XGpio DiscreteRead(&swb, 1) & 0x04) == 0x04) //NOT button2
                        &&!((XGpio DiscreteRead(&swb, 1) & 0x08) == 0x08); //NOT button3
                boolean button2 = ((XGpio DiscreteRead(&swb, 1) & 0x04) == 0x04); //button 2 is
being pressed
                boolean button3 = ((XGpio DiscreteRead(&swb, 1) & 0x08) == 0x08); //button 3 is
being pressed
                if (!button2 && !button3) XGpio DiscreteWrite(&leds, 1, 0); //turn off leds when no
relevant buttons are pressed
                if (button0) { //bitwise AND with 1 to find value of last bit
                        if (!b0) { xil printf("Button[0] has been pressed!\n"); b0 = true; }
                        if (b1) { b1 = false; xil printf("Button[1] has been released!\n"); }
                        if (b2) { b2 = false; xil printf("Button[2] has been released!\n"); }
                        if (b3) { b3 = false; xil printf("Button[3] has been released!\n"); }
                        count++;
                        count masked = count & 0xF;
                        xil printf("Value of LEDs = 0x\%x\n\r", count masked);
                        //XGpio DiscreteWrite(&leds, 1, count masked);
                        delay();
                else if (button1) {
                        count--;
                        //checking changes of values
                        if (!b1) { b1 = true; xil printf("Button[1] has been pressed!\n"); }
                        if (b0) { b0 = false; xil printf("Button[0] has been released!\n"); }
                        if (b2) { b2 = false; xil printf("Button[2] has been released!\n"); }
                        if (b3) { b3 = false; xil printf("Button[3] has been released!\n"); }
                        count masked = count & 0xF;
                        xil printf("Value of LEDs = 0x\%x\n\r", count masked);
                        //XGpio DiscreteWrite(&leds, 1, count masked);
                        delay();
                }
                else if (button2) { /*button 2 pressed (show switches)*/
                        if (b1) { b1 = false; xil printf("Button[1] has been released!\n"); }
                        if (b0) { b0 = false; xil printf("Button[0] has been released!\n"); }
                        if (!b2) { b2 = true; xil printf("Button[2] has been pressed!\n"); }
                        if (b3) { b3 = false; xil printf("Button[3] has been released!\n");}
```

```
if ((XGpio DiscreteRead(&swb, 1) & 0xF0) != switchValue) {
                               switchValue = XGpio DiscreteRead(&swb, 1) & 0xF0;
                               xil printf("You moved a switch! Switch Value: %d\n", switchValue >>
4);
                       XGpio DiscreteWrite(&leds, 1, switchValue >> 4);
                       //display leds with switch values
                       if ((XGpio DiscreteRead(&swb, 1) & 0x01) == 0x01) { /*button2 is pressed
AND button0 is pressed*/
                               if (!b0) { b0 = true; xil printf("Button[0] has been pressed!\n"); }
                               count++;
                               count masked = count & 0xF;
                               xil printf("Value of LEDs = 0x\%x\n\r", count masked);
                               delay();
                       }
                       else if ((XGpio DiscreteRead(&swb, 1) & 0x02) == 0x02) { /*button2 is pressed
AND button1 is pressed*/
                               if (!b1) { b2 = true; xil printf("Button[1] has been pressed!\n"); }
                               count--;
                               count masked = count & 0xF;
                               xil printf("Value of LEDs = 0x\%x\n\r", count masked);
                               delay();
                       }
               else if (button3) {
                       //same check
                       if (b1) { b1 = false; xil printf("Button[1] has been released!\n"); }
                       if (b0) { b0 = false; xil printf("Button[0] has been released!\n"); }
                       if (b2) { b2 = false; xil printf("Button[2] has been released!\n");}
                       if (!b3) { b3 = true; xil printf("Button[3] has been pressed!\n"); }
                       if ((XGpio DiscreteRead(&swb, 1) & 0x01) == 0x01) { //if button 3 AND button
0
                               count++;
                               count masked = count & 0xF;
                               XGpio DiscreteWrite(&leds, 1, count masked);
                               xil printf("Value of LEDs = 0x\%x\n\r", count masked);
                               delay();
                       else if ((XGpio DiscreteRead(&swb, 1) & 0x02) == 0x02) { //if button 3 AND
button 1
                               if (!b1) { b1 = true; xil printf("Button[1] has been pressed!\n"); }
                               count--;
                               count masked = count & 0xF;
                               XGpio DiscreteWrite(&leds, 1, count masked);
                               xil printf("Value of LEDs = 0x\%x\n\r", count masked);
                               delay();
                       else { //just button 3 is pressed; we simply display the current count value
                               XGpio DiscreteWrite(&leds, 1, count masked);
```

```
#clock_100MHz
set_property PACKAGE_PIN K17 [get_ports clk_100MHz]
set_property IOSTANDARD LVCMOS33 [get_ports clk_100MHz]
create_clock -add -name sys_clk_pin -period 10.00 -waveform {0.5} [get_ports clk_100MHz]
#led tri o
set_property PACKAGE_PIN M14 [get_ports {led_tri_o[0]}]
set property IOSTANDARD LVCMOS33 [get_ports {led_tri_o[0]}]
set_property PACKAGE_PIN M15 [get_ports {led_tri_o[1]}]
set property IOSTANDARD LVCMOS33 [get_ports {led_tri_o[1]}]
set_property PACKAGE_PIN G14 [get_ports {led_tri_o[2]}]
set_property IOSTANDARD LVCMOS33 [get_ports {led_tri_o[2]}]
set_property PACKAGE_PIN D18 [get_ports {led_tri_o[3]}]
set_property IOSTANDARD LVCMOS33 [get_ports {led_tri_o[3]}]
#sw
set_property PACKAGE_PIN G15 [get_ports {btn_sw_tri_i[0]}]
set_property IOSTANDARD LVCMOS33 [get_ports {btn_sw_tri_i[0]}]
set_property PACKAGE_PIN P15 [get_ports {btn_sw_tri_i[1]}]
set_property IOSTANDARD LVCMOS33 [get_ports {btn_sw_tri_i[1]}]
set_property PACKAGE_PIN W13 [get_ports {btn_sw_tri_i[2]}]
set_property IOSTANDARD LVCMOS33 [get_ports {btn_sw_tri_i[2]}]
set_property PACKAGE_PIN T16 [get_ports {btn_sw_tri_i[3]}]
set_property IOSTANDARD LVCMOS33 [get_ports {btn_sw_tri_i[3]}]
#btn
set_property PACKAGE_PIN K18 [get_ports {btn_sw_tri_i[4]}]
set_property IOSTANDARD LVCMOS33 [get_ports {btn_sw_tri_i[4]}]
set_property PACKAGE_PIN P16 [get_ports {btn_sw_tri_i[5]}]
set_property IOSTANDARD LVCMOS33 [get_ports {btn_sw_tri_i[5]}]
```

}

}

}

set_property PACKAGE_PIN K19 [get_ports {btn_sw_tri_i[6]}] set_property IOSTANDARD LVCMOS33 [get_ports {btn_sw_tri_i[6]}]

set_property PACKAGE_PIN Y16 [get_ports {btn_sw_tri_i[7]}] set_property IOSTANDARD LVCMOS33 [get_ports {btn_sw_tri_i[7]}]