

Algorithms for Vehicle Routing

Kyle Davis* and Daniel Hull†

Mentors: Henrik I. Christensen‡ and Prasad Tetali§

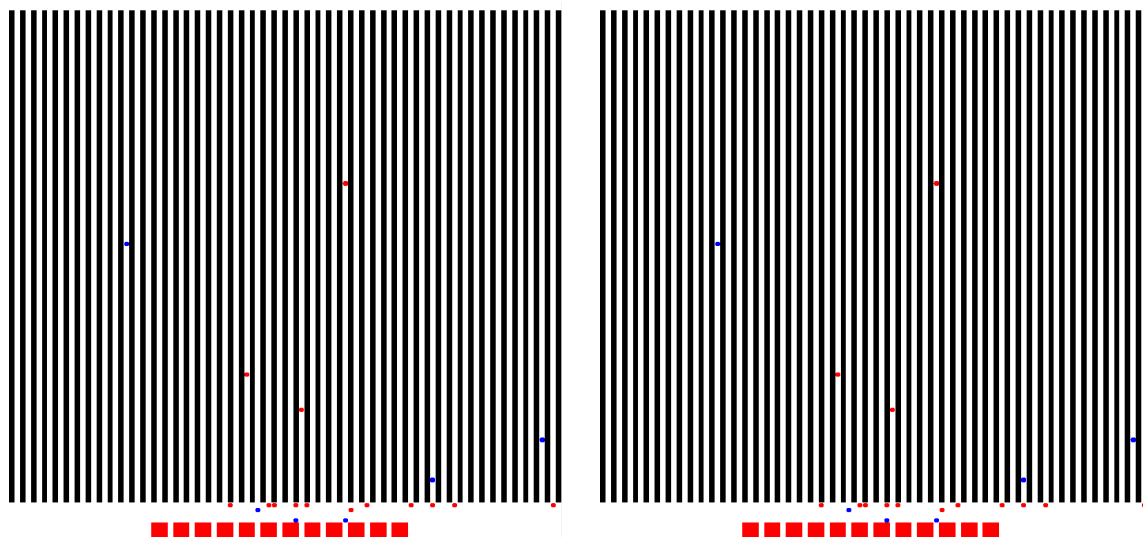
1 Introduction

Vehicle routing has been a challenging problem since the advent of self driving vehicles and robots. This problem is interesting due to its wide range of applications. Vehicle routing algorithms can be used to route packages through large networks, analyze and help improve traffic patterns, and be used to improve the efficiency of shipping warehouses. Working with several shipping companies we have tailored our algorithms to achieve the best performance under the last application. Everything from topology of the warehouse, distribution of the jobs, ordering of the jobs, and the vehicle routes influence the efficiency a warehouse can achieve.

2 Problem Statement

Given a topology and a list of packages, move the packages from their source to destination while minimizing the total duration. A topology is a 2-D grid containing sources, destinations, and vehicles. Vehicles are not allowed to collide with other vehicles, sources or destinations. Sources are black, destinations are red, and vehicles are red or blue circles depending on if they are currently carrying a package. The figures below represent two different topologies with the vehicles in the process of running their respective routes.

*** Use 2 different topologies here ***



The list of packages are given in order and describes the source each package is originally located at, and the destination it must travel to. There is a partial ordering that must be maintained when delivering packages, the packages must arrive in the correct order to each destination. The problem has been relaxed so that vehicles can accelerate to their maximum (unit) velocity and decelerate to zero velocity instantaneously.

*CS Undergraduate Student, College of Computing, Georgia Institute of Technology. Email : kdavis@gatech.edu

†CS Undergraduate Student, College of Computing, Georgia Institute of Technology. Email : dhull6@gatech.edu

‡School of Interactive Computing, Georgia Institute of Technology, Atlanta, GA-30332.

§School of Mathematics and School of Computer Science, Georgia Institute of Technology, Atlanta, GA-30332.

3 Solution Strategies

There were many aspects to this problem. Our initial research was focused on determining which parts of the problem had the greatest impact on overall efficiency. This will pave the way to more focused research related to the most important parts of vehicle routing. With a goal of implementing these solutions and improving the performance of warehouses around the world.

3.1 Topology

When designing a topology there is a tradeoff between space and speed. With more space vehicles have more room and avoiding collisions becomes easier allowing for the faster transporting of packages; however, space is expensive and can not be sacrificed without significant increases in performance. We tested four different topologies that were built with approximately the same space efficiency but the sources and destinations rearranged, number of vehicles was held constant throughout our testing.

The first two topologies are pictures in Fig. 1; the remaining two are pictured below in Fig. 2. When holding other aspects of the problem constant there was a wide variance in performance when changing topologies. Fig. 3 contains statistics about the simulated performance of each topology.

*** Figures 2 and 3 ***

3.2 Job Distribution

A job does not have a specific vehicle it must be assigned to. Distributing the jobs to the vehicles is another part of the problem that must be addressed. If each job's completion time can be estimated then to minimize total time the jobs should be evenly distributed among all robots. This minimizes any given robots total completion time. This can be modeled as a 1-D bin packing problem. Each robot is a bin with a maximum capacity. Pack the bins with jobs using their estimated completion time, adding more robots as necessary.

In order to conform to our original problem some additional work is required. A binary search is performed to find the minimum, maximum capacity that does not require more than the predetermined number of robots. The packing using this maximum capacity is then given as the job distribution.

A simple first-fit solution was used as the bin packing algorithm. It was compared against randomly assigning jobs to robots without attempting to achieve an even distribution. The resulting performance difference is presented in Fig. 4.

*** Figure 4 ***

3.3 Job Ordering

*** Do this ***

3.4 Vehicle Routes

*** Do this ***

4 Results

*** Do this ***

5 Conclusions

*** Do this ***

Specific revisions: -First paragraph, second sentence: What applications? -Second paragraph, first sentence: Why are you addressing this issue? What is the motivation? Why is it important? -Second paragraph, second sentence: Eliminate the word "obvious"

General revisions: 1) The abstract so far needs to flow better. These two paragraphs are essentially an introduction/motivation, which can be concisely condensed into one paragraph. Clearly state the objective of the research, the motivation, and rationale. 2) What are your results??? How did you address the problem. What were your solutions? There is no mention of this. You need to also discuss the results and draw appropriate conclusions. 3) What do these topologies mean? You presented this figure without any explanation. If this figure is representative of your results then keep it, but you need to at least state what it is and show that it is pertinent evidence to the research objective.

Can you make these changes and send them to me by Friday? Note: please use Microsoft Word documents; it will be easier for both of us to edit and revise.

Any questions or concerns, let me know.