Kyle DeProw

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EDUCATION

Saint Louis University

St. Louis, MO

Master of Science in Engineering; GPA: 3.85

Jan. 2017 - Dec. 2022

Southern Illinois University of Edwardsville

Edwardsville, IL

Bachelor of Science in Mechanical Engineering; GPA: 3.89

Aug. 2012 - May 2016

EXPERIENCE

Boeing Research & Technology

Hazelwood, MO

AI/ML Principal Investigator

Dec 2021. - Present

- **DNN Anomaly Detection**: Pursued research efforts aimed at bolstering platform cybersecurity by detecting operational deviations from expected behavioral patterns encoded in DNN structures such as VAE, GAN, Transformers/LLM, and GNN.
- Research and Development: Expanded a limited scope research effort executed solely by myself to an enterprise-wide ML initiative supporting multiple efforts while leading a team of five engineers with skills varying from Data Science to Software Engineering.
- Proposal Writing and Funding Capture: Utilized AI/ML subject matter expertise to identify opportunities for designing and authoring competitive business discriminators in response to customer, primarily DARPA, proposal requests to a total of over \$20M in potential capture events.

Boeing Defense, Space, & Security

Hazelwood, MO

Software Engineer

Feb. 2019 - Dec 2021.

- Autonomy/AI: Designed and developed Monte Carlo Tree Search and A* algorithms for AI Agents operating inside of a custom simulation gym to solve optimal path-planning problems given real-world mission context.
- Machine Learning: Architected and Implemented DQN and A2C Reinforcement Learning algorithms to solve path-planning and refueling missions and encode this learning into a general solution.
- Constructive Simulation: Development lead for incorporating maritime simulation capabilities into AFSIM.
- Real-time Simulation: Developed IFF, ILS, and Radar simulation capabilities for real-time, RHEL OS.
- DevSecOps and CI/CD: Implemented containerized solutions for a variety of enterprise use-cases.

Saint Louis University

St. Louis, MO

Graduate Research Associate

Jan. 2017 - Feb. 2019

- Academic Research and Publications: Research grant funded position to lead research relevant to NSF Cyber-Human Systems programs which included fields such as Robotics, AI, and Machine Learning.
- **Perception Systems**: Computer vision system using Xbox Kinect to implement inverse kinematic solutions that solved operator arm pose angles transposed on a telerobotic arm.
- Supervised Learning: Designed LSTM structures to predict robot payload contents from time-series data.

Dynamic Controls

Maryland Heights, MO

Controls Engineer

Jan. 2016 - Sep. 2017

Emerson - White Rodgers

Ferguson, MO

Mechanical and Electrical Engineer – Co-op

Dec. 2014 - Sep. 2015

PUBLICATIONS

- A Curved Port Delivery System for Laser Interstitial Thermal Therapy of Brain Tumors: 2019
- Design of a Lightweight, Ergonomic Manipulator for Enabling Expressive Gesturing in Telepresence Robots: 2018
- Motion and Deformation of a Water Droplet Under the Influence of an Electric Field: 2014

CERTIFICATIONS

- DevSecOps for Developers: Saint Louis University
- Software Engineering and Architecture: Saint Louis University

PROGRAMMING SKILLS

• Languages: Python, C++, C, Matlab Technologies: Tensorflow/Pytorch, Docker, K8s, CMake, Git