

Lecture 1

Physically Based Modeling Differential Equation Basics

Initial Value Problems

The vector field

Differential equations describe the relationship between an unknown function and its derivatives.

$$x'(t) = f(x, t)$$

$$x'(t) = f(x(t))$$

where x is the state of the system, $x(t)$ and $x'(t)$ is in vector form. The initial value problem gives $x(t_0) = x_0$ and The differential equation above defines a vector field over x .

Initial Value Problems

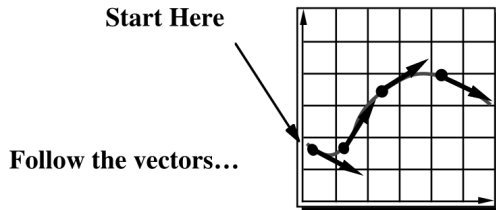


Figure: Starting from a point x_0 , move with the velocity specified by the vector field.

Numerical Solutions

- We take **discrete** time steps starting with the initial value $x(t_0)$.
- Take a step by using the derivative function $f(x, t)$ to **approximate** the change.
- **Derivative evaluations** are performed at each time step.

Euler's Method

Simple derivative

Consider in time step t_0 and time step $t_0 + h$ Let us start writing the simple derivative function:

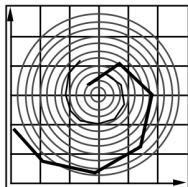
$$x'(t_0) = \frac{x(t_0 + h) - x(t_0)}{h}, h \rightarrow 0$$

Linear approximation

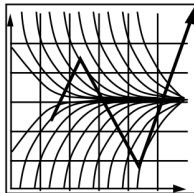
$$x(t_0 + h) \approx x(t_0) + hx'(t_0)$$

Euler's Method

- Linear approximation is bad for simulating curve path



Inaccuracy:
Error turns $x(t)$ from a circle into the spiral of your choice.



Instability: off to Neptune!

Two Problems

Euler's Method

Questions

- Why is a linear approximation bad for spiral/curve path simulation?
- How can we increase the accuracy of simulation?

Euler's Method

The problem

- Increase the accuracy \rightarrow decrease the size step h
- Decrease size step $h \rightarrow$ more step \rightarrow more cost

The solution

- Increase the accuracy \rightarrow improve the derivative evaluation h
- No need to change the size step h , or even increase h .

Taylor expansion series

- Euler is just the "shortened" form of the Taylor expansion series.
- Taylor expansion is used to approximate a function

Taylor general form

$$f(x) = f(a) + \frac{f'(a)}{1!}(x-a)^1 + \frac{f''(a)}{2!}(x-a)^2 + \cdots + \frac{f^{(n)}(a)}{n!}(x-a)^n$$

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!}(x-a)^n$$

Taylor expansion series

- Assuming $x(t)$ is smooth, we can express its value at the end of the step as an infinite sum involving the value and derivatives at the beginning:

Euler is just two terms in the series

$$x(t_0 + h) = x(t_0) + h \cdot x'(t_0) + \frac{h^2}{2!} x''(t_0) + \cdots + \frac{h^n}{n!} \frac{\partial^n x(t_0)}{\partial t^n}$$

- The error term, the difference between the Euler step and the full. In Euler method, it is $O(h^2)$ (read “Order h squared”)

Evaluation

- We chop our stepsize in half $\rightarrow \frac{h}{2}$
- This produces only about one fourth the error because of $O(h^2)$.
- But we have to take twice as many steps over any given interval.

Intuition

So what we have to do is just to keep the same step size h , but improve from $O(h^2)$ to $O(h^3)$

The Midpoint Method

- We could achieve $O(h^3)$ accuracy instead of $O(h^2)$ simply by retaining one additional term in the truncated Taylor series.

Change error term

From $O(h^2)$

$$x(t_0 + h) = x(t_0) + h \cdot x'(t_0) + O(h^2)$$

To $O(h^3)$

$$x(t_0 + h) = x(t_0) + h \cdot x'(t_0) + \frac{h^2}{2!} x''(t_0) + O(h^3)$$

But we do not want to evaluate the second derivative of x since it is costly. Therefore, we do math.

The Midpoint Method

Proof

We have

$$x'(t) = f(x(t))$$

Then we take derivative of both sides to obtain $x''(t)$

$$\begin{aligned}x''(t) &= f'(x(t))x'(t) \\x''(t) &= f'(x(t))f(x(t)) \\x'' &= f'f\end{aligned}$$

The Midpoint Method

Proof

We have

$$x(t_0 + h) = x(t_0) + h \cdot x'(t_0)$$

The the amount of which x changes from t_0 to $t_0 + h$ is

$$\Delta x = h \cdot x'(t_0) = h \cdot f(x(t_0))$$

The Midpoint Method

Proof

We have the equation need calculating:

$$x(t_0 + h) = x(t_0) + h \cdot x'(t_0) + O(h^2)$$

What if we try to take derivate of both sides:

$$x'(t_0 + h) = x'(t_0) + h \cdot x''(t_0) + O(h^2)$$

$$f(x(t_0 + h)) = f(x(t_0)) + h \cdot f(x(t_0))f'(x(t_0)) + O(h^2)$$

$$f(x(t_0) + h \cdot x'(t_0)) = f(x(t_0)) + h \cdot f(x(t_0))f'(x(t_0)) + O(h^2)$$

$$f(x(t_0) + \Delta x) = f(x(t_0)) + \Delta x f'(x(t_0)) + O(\Delta x^2)$$

$$f(x_0 + \Delta x) = f(x_0) + \Delta x f'(x_0) + O(\Delta x^2)$$

The Midpoint Method

Proof

We already know that we have:

$$\Delta x = h \cdot x'(t_0) = h \cdot f(x(t_0))$$

What if we try to take half the step size. So the new change of position is:

$$\Delta x = \frac{h}{2} \cdot x'(t_0) = \frac{h}{2} \cdot f(x(t_0)) = \frac{h}{2} \cdot f(x_0)$$

But why/how do we think of this? Did you remember the Taylor expansion series?

The Midpoint Method

Proof

Now, try to replace the old Δx with new Δx :

$$\begin{aligned}f(x_0 + \Delta x) &= f(x_0) + \Delta x f'(x_0) + O(h^2) \\f(x_0 + \frac{h}{2} \cdot f(x_0)) &= f(x_0) + \frac{h}{2} \cdot f(x_0) f'(x_0) + O(h^2)\end{aligned}$$

Now we can multiply both side with h , things would get more familiar:

$$hf(x_0 + \frac{h}{2} \cdot f(x_0)) = hf(x_0) + \frac{h^2}{2} \cdot f(x_0) f'(x_0) + O(h^3)$$

We now want to change back to x , not f anymore

The Midpoint Method

Proof

We rearrange the equation:

$$\frac{h^2}{2} \cdot f(x_0)f'(x_0) + O(h^3) = hf(x_0 + \frac{h}{2} \cdot f(x_0)) - h \cdot f(x_0)$$

Notice that $x''(t_0) = f(x_0)f'(x_0)$ and $h \cdot f(x_0) = h \cdot x'(t_0)$

$$\frac{h^2}{2} \cdot x''(t_0) + O(h^3) = hf(x_0 + \frac{h}{2} \cdot f(x_0)) - h \cdot x'(t_0)$$

The Midpoint method

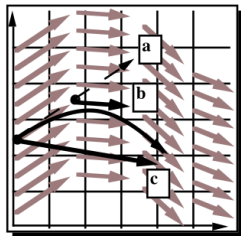
Proof

So that we finally approximate the second order derivative indirectly

$$\begin{aligned}x(t_0 + h) &= x(t_0) + h \cdot x'(t_0) + \frac{h^2}{2!} x''(t_0) + O(h^3) \\&= x(t_0) + h \cdot x'(t_0) + hf(x_0 + \frac{h}{2} \cdot f(x_0)) - h \cdot x'(t_0) \\&= x(t_0) + hf(x_0 + \frac{h}{2} \cdot f(x_0))\end{aligned}$$

Boom! This is the final equation of midpoint method.

The Midpoint Method



a. Compute an Euler step

$$\Delta \mathbf{x} = \Delta t \mathbf{f}(\mathbf{x}, t)$$

b. Evaluate \mathbf{f} at the midpoint

$$\mathbf{f}_{\text{mid}} = \mathbf{f}\left(\frac{\mathbf{x} + \Delta \mathbf{x}}{2}, \frac{t + \Delta t}{2}\right)$$

c. Take a step using the midpoint value

$$\mathbf{x}(t + \Delta t) = \mathbf{x}(t) + \Delta t \mathbf{f}_{\text{mid}}$$

The Midpoint Method