Multivariate Multiple Imputation

Utrecht University Winter School: Missing Data in R



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Outline

Flavors of MI

Fully Conditional Specification

Joint Modeling



Joint Modeling vs. Fully Conditional Specification

When imputing with *Joint Modeling* (JM) approaches, the missing data are replaced by samples from the joint posterior predictive distribution.

• To impute *X*, *Y*, and *Z*, we draw:

$$X, Y, Z \sim P(X, Y, Z|\theta)$$

With *Fully Conditional Specification* (FCS), the missing data are replaced with samples from the conditional posterior predictive distribution of each incomplete variable.

• To impute *X*, *Y*, and *Z*, we draw:

$$X \sim P(X|Y, Z, \theta_X)$$

$$Y \sim P(Y|X, Z, \theta_Y)$$

$$Z \sim P(Z|Y, X, \theta_Z)$$



Joint Modeling: Strengths

When correctly implemented, JM approaches are guaranteed to produce *Bayesianly proper* imputations.

- A sufficient condition for properness is that the imputations are randomly sampled from the correctly specified joint posterior predictive distribution of the missing data.
 - This is the defining characteristic of JM methods.

When using the correct distribution, imputations produced by JM methods will be the best possible imputations.

- Unbiased parameter estimates
- Well-calibrated sampling variability

Joint Modeling: Weaknesses

JM approaches don't scale well.

 The computational burden increases with the number of incomplete variables.

JM approaches are only applicable when the joint distribution of all incomplete variables follows a known form.

 Mixes of continuous and categorical variables are difficult to accommodate.

Software Implementations



Fully Conditional Specification: Strengths

FCS scales much better than JM.

• FCS only samples from a series of univariate distributions, not large joint distributions.

FCS approaches can create imputations for variables that don't have a sensible joint distribution.

• FCS can easily treat mixes of continuous and categorical variables.



Fully Conditional Specification: Weaknesses

FCS will usually be slower than JM.

• Each variable gets its own fully parameterized distribution, even if that granularity is unnecessary.

When the incomplete variables don't have a known joint distribution, FCS doesn't have theoretical support.

- There is, however, a large degree of empirical support for the tenability of the FCS approach.
- In practice, we usually choose FCS since real data rarely arise from a known joint distribution.

Software Implementations



Aside: Gibbs Sampling

Up to this point, most of the models we've explored could be approximated by sampling directly from their posterior distributions.

• This won't be true with arbitrary, multivariate missing data.

To make inference regarding a multivariate distribution with multiple, interrelated, unknown parameters, we can use *Gibbs sampling*.

• Sample from the conditional distribution of each parameter, conditioning on the current best guesses of all other parameters.

Aside: Gibbs Sampling

Suppose the following:

- 1. I want to make some inference about the tri-variate mean of $X,Y,Z=\mu_X,\mu_Y,\mu_Z\sim P(\mu|\theta)$
- 2. $P(\mu|\theta)$ is super hairy and difficult to sample
- 3. I can easily sample from the conditional distributions: $P(\mu_X|\hat{\mu}_Y,\hat{\mu}_Z,\theta)$, $P(\mu_Y|\hat{\mu}_X,\hat{\mu}_Z,\theta)$, and $P(\mu_Z|\hat{\mu}_X,\hat{\mu}_Y,\theta)$.

Then, I can approximate the full joint distribution $P(\mu|\theta)$ by sequentially sampling from $P(\mu_X|\hat{\mu}_Y, \hat{\mu}_Z, \theta)$, $P(\mu_Y|\hat{\mu}_X, \hat{\mu}_Z, \theta)$, and $P(\mu_Z|\hat{\mu}_X, \hat{\mu}_Y, \theta)$.

Aside: Gibbs Sampling

Starting with initial guesses of μ_Y , $\hat{\mu}_Y^{(0)}$, and μ_Z , $\hat{\mu}_Z^{(0)}$, and assuming θ is known, Gibbs sampling proceeds as follows:

$$\begin{split} \hat{\mu}_{X}^{(1)} &\sim P(\mu_{X}|\hat{\mu}_{Y}^{(0)},\hat{\mu}_{Z}^{(0)},\theta) \\ \hat{\mu}_{Y}^{(1)} &\sim P(\mu_{Y}|\hat{\mu}_{X}^{(1)},\hat{\mu}_{Z}^{(0)},\theta) \\ \hat{\mu}_{Z}^{(1)} &\sim P(\mu_{Z}|\hat{\mu}_{Y}^{(1)},\hat{\mu}_{X}^{(1)},\theta) \\ \hat{\mu}_{Z}^{(2)} &\sim P(\mu_{X}|\hat{\mu}_{Y}^{(1)},\hat{\mu}_{Z}^{(1)},\theta) \\ \hat{\mu}_{Y}^{(2)} &\sim P(\mu_{Y}|\hat{\mu}_{X}^{(2)},\hat{\mu}_{Z}^{(1)},\theta) \\ \hat{\mu}_{Y}^{(2)} &\sim P(\mu_{Z}|\hat{\mu}_{Y}^{(2)},\hat{\mu}_{Z}^{(2)},\theta) \\ \vdots &\vdots \end{split}$$



Why do we care?

Multivariate MI employs the same logic as Gibbs sampling.

- The imputations are created by conditioning on the current estimates of the imputation model parameters.
- The imputation model parameters are updated by conditioning on the most recent imputations.
- With FCS, each variable is imputed by conditioning on the most recent imputations of all other variables.

Fully Conditional Specification



Procedure: Fully Conditional Specification

- 1. Fill the missing data with reasonable guesses.
- 2. For each incomplete variable, do a single iteration of univariate Bayesian MI (e.g., as seen in the last set of slides).
 - After each variable on the data set is so treated, we've completed one iteration.
- 3. Repeat Step 2 many times.
- After the imputation model parameters stabilize, save M imputed data sets.

```
## Simulate some data:
simData <-
    simCovData(nObs = 1000, sigma = 0.25, nVars = 4)
head(simData, 10)
           x1
                      x2
                                  x3
                                              x4
    0.06313632 -1.4057704 -0.01709217 1.47929405
  -1.31592547 1.2970920 -0.83500777 -0.44528158
  -0.30997023 0.9782580 0.02731853 0.35507390
4
    0.06927787 0.1836032 0.68794409 0.08049987
  -0.99354894 -0.3038956 0.80918329 -1.72143555
    0.36828016 -0.9423245 1.05155348 -0.11078496
   1.33333163 2.3089780 1.47203000 0.85877495
8
  -0.02759718 0.1714383
                          0.18927909 0.28627771
9
    2.37929433 2.5080935
                          2.18344726
                                     1.56980951
   0.31841502
               0.7886025
                          0.73658136 0.39445970
10
```

```
head(missData, 10)
           x1
                      x^2
                                  x3
                                              ×4
           NA -1.4057704 -0.01709217 1.47929405
  -1.3159255 1.2970920
                                  NA -0.44528158
3
  -0.3099702
                      NA 0.02731853 0.35507390
4
           NA
               0.1836032 0.68794409
                                      0.08049987
  -0.9935489 -0.3038956 0.80918329 -1.72143555
6
    0.3682802 - 0.9423245
                                  NA -0.11078496
   1.3333316
               2.3089780
                                  NA
                                      0.85877495
           NΑ
                      NΑ
                                      0.28627771
                          0.18927909
9
           NA
                      NA
                                  NA
                                      1.56980951
10
           NA
               0.7886025
                          0.73658136 0.39445970
```

```
## Define iteration numbers:
nImps <- 100
nBurn <- 500
nSams <- nBurn + nImps
## Summarize missingness:
rMat <- !is.na(missData)
nObs <- colSums(rMat)
nMis <- colSums(!rMat)
## Fill the missingness with initial (bad) quesses:
mean0 <- colMeans(missData, na.rm = TRUE)
sigma0 <- cov(missData, use = "pairwise")</pre>
draws0 <- rmvnorm(nrow(missData), mean0, sigma0)</pre>
impData
        <- missData
impData[!rMat] <- draws0[!rMat]</pre>
```

Define an elementary imputation function:

```
eif <- function(data, rVec, v) {
   ## Get the expected betas:
   fit <- lm(paste(v, "~ ."), data = data[rVec, ])
   beta <- coef(fit)
   ## Sample sigma:
   sigScale <- (1 / fit$df) * crossprod(resid(fit))</pre>
   sigmaSam <- rinvchisq(1, df = fit$df, scale = sigScale)
   ## Sample beta:
   betaVar <- sigmaSam * solve(crossprod(gr.X(fit$gr)))
   betaSam <- rmvnorm(1, mean = beta, sigma = betaVar)
   ## Return a randomly sampled imputation:
   matrix(cbind(1, data[!rVec, ])) %*% betaSam +
       rnorm(sum(!rVec), 0, sqrt(sigmaSam))
```

Apply the elementary imputation function to each incomplete variable:

```
## Iterate through the FCS algorithm:
impList <- list()</pre>
for(s in 1 : nSams) {
    for(v in targets) {
        rVec
                          <- rMat[ , v]
        impData[!rVec, v] <- eif(impData, rVec, v)</pre>
    ## If the chains are burnt-in, save imputed datasets:
    if(s > nBurn) impList[[s - nBurn]] <- impData</pre>
Error in matrix(cbind(1, data[!rVec, ])) %*% betaSam: requires
numeric/complex matrix/vector arguments
```

Analyze the multiply imputed datasets:

```
## First, our manual version:
fits1 <- lapply(impList,
                function(x) lm(x1 \sim x2 + x3, data = x)
pool1 <- MIcombine(fits1)</pre>
Error in variances[[1]]: subscript out of bounds
## Do the same analysis with mice():
miceOut <- mice(data = missData,
                m = 100,
                method = "norm".
                printFlag = FALSE)
fits2 <- with(miceOut, lm(x1 \sim x2 + x3))
pool2 <- pool(fits2)</pre>
```

Compare approaches:

```
Error in coef(pool1): object 'pool1' not found
Error in vcov(pool1): object 'pool1' not found
Error in eval(expr, envir, enclos): object 'cf1' not found
Error in eval(expr, envir, enclos): object 'pool1' not found
Error in pt(t1, df1, lower.tail = FALSE): object 't1' not
found
Error in eval(expr, envir, enclos): object 'pool1' not found
Error in cbind(cf1, se1, t1, p1, fmi1): object 'cf1' not
found
Error in colnames(res1) <- c("Est", "SE", "t", "p", "FMI"):</pre>
object 'res1' not found
Error in eval(expr, envir, enclos): object 'res1' not found
Error in res1[flag, "p"] <- "<0.001": object 'res1' not</pre>
found
Error in rownames(res1): object 'res1' not found
Error in xtable(res1, caption = "Manual Version"): object
23 of 35
```

Joint Modeling



Aside: Definition of Regression Parameters

So far, we've been using the least-squares estimates of α , β , and σ^2 to parameterize our posterior distributions.

• We can also define the parameters in terms of sufficient statistics.

Given μ and Σ , we can define all of our regression moments as:

$$\beta = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

$$= \mathsf{Cov}(\mathbf{X})^{-1} \mathsf{Cov}(\mathbf{X}, \mathbf{Y})$$

$$\alpha = \mu_{\mathbf{Y}} - \beta^T \mu_{\mathbf{X}}$$

$$\Sigma_{\varepsilon} = \Sigma_{\mathbf{Y}} - \beta^T \Sigma_{\mathbf{X}} \beta$$

These definitions are crucial for JM approaches.

 Within the subset of data define by a given response pattern, the outcome variables will be entirely missing.

Multivariate Bayesian Regression

Previously, we saw examples of univariate Bayesian regression which used the following model:

$$\begin{split} \beta &\sim \text{MVN}\left(\hat{\beta}_{ls}, \ \sigma^2 (\mathbf{X}^T\mathbf{X})^{-1}\right) \\ \sigma^2 &\sim \text{Inv-}\chi^2 \left(N-P, MSE\right) \end{split}$$

We can directly extend the above to the multivariate case:

$$\begin{split} & \boldsymbol{\Sigma^{(i)}} \sim \text{Inv-W}\left(N-\mathbf{1}, (N-\mathbf{1})\boldsymbol{\Sigma^{(i-1)}}\right) \\ & \boldsymbol{\mu^{(i)}} \sim \text{MVN}\left(\boldsymbol{\mu^{(i-1)}}, N^{-1}\boldsymbol{\Sigma^{(i)}}\right) \end{split}$$

We get α , β , and Σ_{ε} via the calculations on the preceding slide

Procedure: Joint Modeling

- 1. Partition the incomplete data by response pattern.
 - Produce *S* subsets wherein each row shares the same response pattern.
- **2.** Provide initial guesses for μ and Σ .
- 3. Within each subset, use the current guesses of μ and Σ to generate imputations via multivariate Bayesian regression.
- 4. Use the filled-in data matrix to updated the sufficient statistics.
- 5. Repeat Steps 3 and 4 many times.
- 6. After the imputation model parameters have stabilized, save *M* imputed data sets produced in Step 3.

```
iStep <- function(data, pats, ind, p0, pars) {
    ## Loop over non-trivial response patterns:
   for(i in c(1 : nrow(pats))[-p0]) {
        ## Define the current response pattern:
       p1 <- pats[i, ]
       ## Subset the data:
       dat1 <- data[ind == i. ]
        ## Replace missing data with imputations:
        data[ind == i, !p1] <- getImps(data = dat1,
                                             = pars$mu,
                                       mu
                                       sigma = pars$sigma,
                                       р1
                                             = p1)
   ## Return the imputed data:
   data
```

```
getImps <- function(data, mu, sigma, p1) {</pre>
    ## Partition the parameter matrices:
    mY <- matrix(mu[!p1])
   mX <- matrix(mu[p1])
    sY <- sigma[!p1, !p1]
    sX <- sigma[p1, p1]
    cXY <- sigma[p1, !p1]
    ## Compute the imputation model parameters:
    beta <- solve(sX) %*% cXY
    alpha <- mY - t(beta) %*% mX
    sE <- sY - t(beta) %*% sX %*% beta
    ## Pull out predictors:
    X <- as.matrix(data[ , p1])</pre>
    ## Generate and return the imputations:
    n \leftarrow nrow(X)
    matrix(1, n) %*% t(alpha) + X %*% beta + rmvnorm(n, sigma = sE)
```

Now that we've defined the necessary functions, do the imputation:

```
## Some preliminaries:
impData <- missData</pre>
nIter < -50
nImps <- 100
## Summarize response patterns:
rMat <- !is.na(impData)</pre>
pats <- uniquecombs(rMat)</pre>
Error in uniquecombs(rMat): could not find function "uniquecombs"
ind <- attr(pats, "index")</pre>
Error in eval(expr, envir, enclos): object 'pats' not found
p0 <- which(apply(pats, 1, all))
Error in apply(pats, 1, all): object 'pats' not found
## Get starting values for the parameters:
pars <- list(mu = colMeans(impData, na.rm = TRUE),</pre>
             sigma = cov(impData, use = "pairwise")
 31 of 35
```

```
## Iterate over I- and P-Steps to generate imputations:
impList3 <- list()</pre>
for(m in 1 : nImps) {
    for(rp in 1 : nIter) {
        impData <- iStep(data = impData,</pre>
                          pats = pats,
                           ind = ind,
                          p0 = p0,
                          pars = pars)
        pars <- pStep(impData)</pre>
        if(rp == nIter) impList3[[m]] <- impData</pre>
Error in iStep(data = impData, pats = pats, ind = ind, p0 = p0, pars =
pars): object 'pats' not found
```

Do the same type of imputation with norm:

```
missData <- as.matrix(missData)
meta <- prelim.norm(missData)</pre>
Error in prelim.norm(missData): could not find function "prelim.norm"
theta0 <- em.norm(meta, showits = FALSE)
Error in em.norm(meta, showits = FALSE): could not find function "em.norm"
rngseed(235711)
Error in rngseed(235711): could not find function "rngseed"
impList4 <- list()</pre>
for(m in 1 : nImps) {
    theta1 <- da.norm(s = meta,
                       start = theta0.
                       steps = nIter)
    impList4[[m]] <- imp.norm(s = meta,</pre>
                               theta = theta1.
                                     = missData)
33 of 35
```

Analyze the multiply imputed data:

```
## Manual implementation:
fits3 <- lapply(impList3,
                function(x) lm(x1 ~x2 + x3, data = x)
pool3 <- MIcombine(fits3)</pre>
Error in variances[[1]]: subscript out of bounds
## Imputation using norm():
fits4 <- lapply(impList4,
                function(x) lm(x1 ~ x2 + x3,
                                data = as.data.frame(x)
pool4 <- MIcombine(fits4)</pre>
Error in variances[[1]]: subscript out of bounds
```

Compare approaches:

```
Error in coef(pool3): object 'pool3' not found
Error in vcov(pool3): object 'pool3' not found
Error in eval(expr, envir, enclos): object 'cf3' not found
Error in eval(expr, envir, enclos): object 'pool3' not found
Error in pt(t3, df3, lower.tail = FALSE): object 't3' not
found
Error in eval(expr, envir, enclos): object 'pool3' not found
Error in cbind(cf3, se3, t3, p3, fmi3): object 'cf3' not
found
Error in colnames(res3) <- c("Est", "SE", "t", "p", "FMI"):</pre>
object 'res3' not found
Error in eval(expr, envir, enclos): object 'res3' not found
Error in res3[flag, "p"] <- "<0.001": object 'res3' not
found
Error in coef(pool4): object 'pool4' not found
Error in vcov(pool4): object 'pool4' not found
```