## Multivariate Multiple Imputation

Utrecht University Winter School: Missing Data in R



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### Outline

Flavors of MI

**Fully Conditional Specification** 

Joint Modeling

Mixed Data Types



# Joint Modeling vs. Fully Conditional Specification

When imputing with *Joint Modeling* (JM) approaches, the missing data are replaced by samples from the joint posterior predictive distribution.

• To impute X, Y, and Z, we draw:

$$X, Y, Z \sim P(X, Y, Z|\theta)$$

With *Fully Conditional Specification* (FCS), the missing data are replaced with samples from the conditional posterior predictive distribution of each incomplete variable.

• To impute *X*, *Y*, and *Z*, we draw:

$$X \sim P(X|Y, Z, \theta_X)$$

$$Y \sim P(Y|X, Z, \theta_Y)$$

$$Z \sim P(Z|Y, X, \theta_Z)$$



### Joint Modeling: Strengths

When correctly implemented, JM approaches are guaranteed to produce *Bayesianly proper* imputations.

- A sufficient condition for properness is that the imputations are randomly sampled from the correctly specified joint posterior predictive distribution of the missing data.
  - This is the defining characteristic of JM methods.

When using the correct distribution, imputations produced by JM methods will be the best possible imputations.

- Unbiased parameter estimates
- Well-calibrated sampling variability

### Joint Modeling: Weaknesses

JM approaches don't scale well.

• The computational burden increases with the number of incomplete variables.

JM approaches are only applicable when the joint distribution of all incomplete variables follows a known form.

 Mixes of continuous and categorical variables are difficult to accommodate.

### **Software Implementations**

In R, MI via JM is available from several packages.

- Amelia (Honaker, King, & Blackwell, 2011)
  - Bootstrapped EM algorithm
- norm (Schafer, 2013)
  - · Classic data augmentation.
- mice (Van Buuren & Groothuis-Oudshoorn, 2011)
  - Data augmentation for block updating.

JM imputation is also available in SAS, Stata, SPSS, and Mplus.

### Fully Conditional Specification: Strengths

FCS scales much better than JM.

• FCS only samples from a series of univariate distributions, not large joint distributions.

FCS approaches can create imputations for variables that don't have a sensible joint distribution.

• FCS can easily treat mixes of continuous and categorical variables.



### Fully Conditional Specification: Weaknesses

FCS will usually be slower than JM.

• Each variable gets its own fully parameterized distribution, even if that granularity is unnecessary.

When the incomplete variables don't have a known joint distribution, FCS doesn't have theoretical support.

- There is, however, a large degree of empirical support for the tenability of the FCS approach.
- In practice, we usually choose FCS since real data rarely arise from a known joint distribution.

### **Software Implementations**

The **mice** package is the most popular R implementation of FCS. (Van Buuren & Groothuis-Oudshoorn, 2011).

- Mature implementation
- · Well integrated into the larger R ecosystem
- Very active development

The mi package (Su, Yajima, Gelman, & Hill, 2011) offers another option.

- More focus on diagnostics
- Object oriented flavor
- Not very actively developed

FCS imputation is also available in SAS, SPSS, Stata, and Mplus.

### Aside: Gibbs Sampling

Up to this point, most of the models we've explored could be approximated by sampling directly from their posterior distributions.

• This won't be true with arbitrary, multivariate missing data.

To make inference regarding a multivariate distribution with multiple, interrelated, unknown parameters, we can use *Gibbs sampling*.

• Sample from the conditional distribution of each parameter, conditioning on the current best guesses of all other parameters.

### Aside: Gibbs Sampling

#### Suppose the following:

- 1. I want to make some inference about the tri-variate mean of  $X,Y,Z=\mu_X,\mu_Y,\mu_Z\sim P(\mu|\theta)$
- 2.  $P(\mu|\theta)$  is super hairy and difficult to sample
- 3. I can easily sample from the conditional distributions:  $P(\mu_X|\hat{\mu}_Y,\hat{\mu}_Z,\theta)$ ,  $P(\mu_Y|\hat{\mu}_X,\hat{\mu}_Z,\theta)$ , and  $P(\mu_Z|\hat{\mu}_X,\hat{\mu}_Y,\theta)$ .

Then, I can approximate the full joint distribution  $P(\mu|\theta)$  by sequentially sampling from  $P(\mu_X|\hat{\mu}_Y,\hat{\mu}_Z,\theta)$ ,  $P(\mu_Y|\hat{\mu}_X,\hat{\mu}_Z,\theta)$ , and  $P(\mu_Z|\hat{\mu}_X,\hat{\mu}_Y,\theta)$ .

### Aside: Gibbs Sampling

Starting with initial guesses of  $\mu_Y$ ,  $\hat{\mu}_Y^{(0)}$ , and  $\mu_Z$ ,  $\hat{\mu}_Z^{(0)}$ , and assuming  $\theta$  is known, Gibbs sampling proceeds as follows:

$$\begin{split} \hat{\mu}_{X}^{(1)} &\sim P(\mu_{X}|\hat{\mu}_{Y}^{(0)},\hat{\mu}_{Z}^{(0)},\theta) \\ \hat{\mu}_{Y}^{(1)} &\sim P(\mu_{Y}|\hat{\mu}_{X}^{(1)},\hat{\mu}_{Z}^{(0)},\theta) \\ \hat{\mu}_{Z}^{(1)} &\sim P(\mu_{Z}|\hat{\mu}_{Y}^{(1)},\hat{\mu}_{X}^{(1)},\theta) \\ \hat{\mu}_{X}^{(2)} &\sim P(\mu_{X}|\hat{\mu}_{Y}^{(1)},\hat{\mu}_{X}^{(1)},\theta) \\ \hat{\mu}_{Y}^{(2)} &\sim P(\mu_{Y}|\hat{\mu}_{X}^{(2)},\hat{\mu}_{Z}^{(1)},\theta) \\ \hat{\mu}_{Y}^{(2)} &\sim P(\mu_{Z}|\hat{\mu}_{Y}^{(2)},\hat{\mu}_{X}^{(2)},\theta) \\ \vdots &\vdots \end{split}$$



### Why do we care?

Multivariate MI employs the same logic as Gibbs sampling.

- The imputations are created by conditioning on the current estimates of the imputation model parameters.
- The imputation model parameters are updated by conditioning on the most recent imputations.
- With FCS, each variable is imputed by conditioning on the most recent imputations of all other variables.

## **Fully Conditional Specification**



### **Procedure: Fully Conditional Specification**

- 1. Fill the missing data with reasonable guesses.
- 2. For each incomplete variable, do a single iteration of univariate Bayesian MI (e.g., as seen in the last set of slides).
  - After each variable on the data set is so treated, we've completed one iteration.
- 3. Repeat Step 2 many times.
- After the imputation model parameters stabilize, save M imputed data sets.

```
## Simulate some data:
simData <-
    simCovData(nObs = 1000, sigma = 0.25, nVars = 4)
head(simData, 10)
           x1
                      x2
                                  x3
                                              x4
    0.06313632 -1.4057704 -0.01709217 1.47929405
  -1.31592547 1.2970920 -0.83500777 -0.44528158
  -0.30997023 0.9782580 0.02731853 0.35507390
4
    0.06927787 0.1836032 0.68794409 0.08049987
  -0.99354894 -0.3038956 0.80918329 -1.72143555
    0.36828016 -0.9423245 1.05155348 -0.11078496
   1.33333163 2.3089780 1.47203000 0.85877495
8
  -0.02759718 0.1714383
                          0.18927909 0.28627771
9
    2.37929433 2.5080935
                          2.18344726
                                     1.56980951
   0.31841502
               0.7886025
                          0.73658136 0.39445970
10
```

```
head(missData, 10)
           x1
                      x^2
                                  x3
                                              ×4
           NA -1.4057704 -0.01709217 1.47929405
  -1.3159255 1.2970920
                                  NA -0.44528158
3
  -0.3099702
                      NA 0.02731853 0.35507390
4
           NA
               0.1836032 0.68794409
                                      0.08049987
  -0.9935489 -0.3038956 0.80918329 -1.72143555
6
    0.3682802 - 0.9423245
                                  NA -0.11078496
   1.3333316
               2.3089780
                                  NA
                                      0.85877495
           NΑ
                      NΑ
                                      0.28627771
                          0.18927909
9
           NA
                      NA
                                  NA
                                      1.56980951
10
           NA
               0.7886025
                          0.73658136 0.39445970
```

```
## Define iteration numbers:
nImps <- 100
nBurn <- 500
nSams <- nBurn + nImps
## Summarize missingness:
rMat <- !is.na(missData)
nObs <- colSums(rMat)
nMis <- colSums(!rMat)
## Fill the missingness with initial (bad) quesses:
mean0 <- colMeans(missData, na.rm = TRUE)
sigma0 <- cov(missData, use = "pairwise")</pre>
draws0 <- rmvnorm(nrow(missData), mean0, sigma0)</pre>
impData
        <- missData
impData[!rMat] <- draws0[!rMat]</pre>
```

Define an elementary imputation function:

```
eif <- function(data, rVec, v) {
    ## Get the expected model parameters:
    fit <- lm(paste(v, "~ ."), data = data[rVec, ])
    beta <- coef(fit)
    s2 <- summarv(fit)$sigma^2</pre>
    ## Partition data:
    vars <- setdiff(colnames(data), v)</pre>
    data <- as.matrix(data)
    xObs <- cbind(1, data[rVec, vars])
    xMis <- cbind(1, data[!rVec, vars])
    ## Sample sigma:
    sigmaSam <- rinvchisq(1, df = fit$df, scale = s2)
    ## Sample beta:
    betaVar <- sigmaSam * solve(crossprod(xObs))</pre>
    betaSam <- rmvnorm(1, mean = beta, sigma = betaVar)
    ## Return a randomly sampled imputation:
    xMis %*% t(betaSam) + rnorm(nrow(xMis), 0, sgrt(sigmaSam))
```

Apply the elementary imputation function to each incomplete variable:

Analyze the multiply imputed datasets:

#### Compare approaches:

	Est	SE	t	р	FMI
(Intercept)	0.019	0.037	0.499	0.618	0.383
x2	0.211	0.042	5.03	< 0.001	0.463
x3	0.156	0.042	3.709	< 0.001	0.484

#### Manual Version

	Est	SE	t	p	FMI
(Intercept)	0.019	0.036	0.521	0.603	0.332
x2	0.21	0.042	5.02	< 0.001	0.469
x3	0.163	0.043	3.774	< 0.001	0.52

MICE Version

## Joint Modeling



### Aside: Definition of Regression Parameters

So far, we've been using the least-squares estimates of  $\alpha$ ,  $\beta$ , and  $\sigma^2$  to parameterize our posterior distributions.

• We can also define the parameters in terms of sufficient statistics.

Given  $\mu$  and  $\Sigma$ , we can define all of our regression moments as:

$$\beta = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

$$= \mathsf{Cov}(\mathbf{X})^{-1} \mathsf{Cov}(\mathbf{X}, \mathbf{Y})$$

$$\alpha = \mu_{\mathbf{Y}} - \beta^T \mu_{\mathbf{X}}$$

$$\Sigma_{\varepsilon} = \Sigma_{\mathbf{Y}} - \beta^T \Sigma_{\mathbf{X}} \beta$$

These definitions are crucial for JM approaches.

 Within the subset of data define by a given response pattern, the outcome variables will be entirely missing.

### Multivariate Bayesian Regression

Previously, we saw examples of univariate Bayesian regression which used the following model:

$$\begin{split} \beta &\sim \text{MVN}\left(\hat{\beta}_{ls}, \ \sigma^2(\mathbf{X}^T\mathbf{X})^{-1}\right) \\ \sigma^2 &\sim \text{Inv-}\chi^2\left(N-P, MSE\right) \end{split}$$

We can directly extend the above to the multivariate case:

$$\begin{split} & \boldsymbol{\Sigma^{(i)}} \sim \text{Inv-W}\left(N-\mathbf{1}, (N-\mathbf{1})\boldsymbol{\Sigma^{(i-1)}}\right) \\ & \boldsymbol{\mu^{(i)}} \sim \text{MVN}\left(\boldsymbol{\mu^{(i-1)}}, N^{-1}\boldsymbol{\Sigma^{(i)}}\right) \end{split}$$

We get  $\alpha$ ,  $\beta$ , and  $\Sigma_{\varepsilon}$  via the calculations on the preceding slide

### Procedure: Joint Modeling

In JM imputation, we estimate the imputation model via the Tanner and Wong (1987) *data augmentation* algorithm.

- 1. Partition the incomplete data by response pattern.
  - Produce *S* subsets wherein each row shares the same response pattern.
- **2.** Provide initial guesses for  $\mu$  and  $\Sigma$ .
- 3. Within each subset, use the current guesses of  $\mu$  and  $\Sigma$  to generate imputations via multivariate Bayesian regression.
- 4. Use the filled-in data matrix to updated the sufficient statistics.
- 5. Repeat Steps 3 and 4 many times.
- After the imputation model parameters have stabilized, save M imputed data sets produced in Step 3.

```
iStep <- function(data, pats, ind, pars) {
    ## Loop over non-trivial response patterns:
    for(i in 1:nrow(pats)) {
        ## Define the current response pattern:
       p1 <- pats[i, ]
        ## Replace missing data with imputations:
        data[ind == i, !p1] <- getImps(data = data[ind == i, ],</pre>
                                              = pars$mu,
                                        mıı
                                        sigma = pars$sigma,
                                              = p1)
                                        p1
    ## Return the imputed data:
    data
```

```
getImps <- function(data, mu, sigma, p1) {</pre>
    ## Partition the parameter matrices:
   mY <- matrix(mu[!p1])
   mX <- matrix(mu[p1])</pre>
    sY <- sigma[!p1, !p1]
    sX <- sigma[p1, p1]
    cXY <- sigma[p1, !p1]
    ## Compute the imputation model parameters:
    beta <- solve(sX) %*% cXY
    alpha <- mY - t(beta) %*% mX
    sE <- sY - t(beta) %*% sX %*% beta
    ## Pull out predictors:
    X <- as.matrix(data[ , p1])</pre>
    ## Generate and return the imputations:
    n \leftarrow nrow(X)
   matrix(1, n) %*% t(alpha) + X %*% beta + rmvnorm(n, sigma = sE)
```

```
pStep <- function(data) {
    ## Update the complete-data sufficient statistics:
    n <- nrow(data)
    m <- colMeans(data)
    s <- (n - 1) * cov(data)

## Sample the covariance matrix and mean vector:
    sigma <- riwish((n - 1), s)
    mu <- rmvnorm(1, m, (sigma / n))

## Return the updated parameters:
    list(mu = mu, sigma = sigma)
}</pre>
```

Now that we've defined the necessary functions, do the imputation:

```
## Some preliminaries:
impData <- missData
nIter <- 50
nImps <- 100
## Summarize response patterns:
rMat <- !is.na(impData)</pre>
pats <- uniquecombs(rMat, ordered = TRUE)</pre>
ind <- attr(pats, "index")</pre>
## Exclude the fully observed pattern:
if(tail(pats, 1) %>% all())
    pats <- pats[-nrow(pats), ]</pre>
## Get starting values for the parameters:
theta0 <- list(mu = colMeans(impData, na.rm = TRUE),
                sigma = cov(impData, use = "pairwise")
```

```
## Iterate over I- and P-Steps to generate imputations:
impList1 <- list()</pre>
for(m in 1:nImps) {
    ## Initialize the parameter vector:
    theta1 <- theta0
    for(rp in 1:nIter) {
        ## Do one I-Step:
        impData <- iStep(data = impData,</pre>
                           pats = pats,
                           ind = ind,
                           pars = theta1)
        ## Do one P-Step:
        theta1 <- pStep(impData)</pre>
    ## Save the final imputed dataset:
    impList1[[m]] <- impData</pre>
```

Do the same type of imputation with norm:

```
missData <- as.matrix(missData)</pre>
## Pre-process the data and get starting values via EM:
meta <- prelim.norm(missData)</pre>
theta0 <- em.norm(meta, showits = FALSE)
rngseed(235711)
impList2 <- list()</pre>
for(m in 1 : nImps) {
    ## Estimate the imputation model via data augmentation:
    theta1 <- da.norm(s = meta, start = theta0, steps = nIter)
    ## Impute missing values via a final I-Step of DA:
    impList2[[m]] <- imp.norm(s = meta, theta = theta1, x = missData)</pre>
```

Analyze the multiply imputed data:

#### Compare approaches:

	Est	SE	t	p	FMI
(Intercept)	0.022	0.036	0.593	0.554	0.347
x2	0.21	0.042	5.033	< 0.001	0.456
x3	0.153	0.044	3.478	0.001	0.527

#### **Manual Version**

	Est	SE	t	р	FMI
(Intercept)	0.021	0.038	0.558	0.577	0.386
x2	0.213	0.042	5.134	< 0.001	0.452
x3	0.151	0.042	3.625	< 0.001	0.471

**NORM Version** 

## Mixed Data Types



### FCS for Mixed Data Types

FCS imputation can easily accommodate incomplete data that contain both continuous and categorical/non-normal variables.

- Replace the normal-theory elementary imputation model described above with an appropriate model for the distribution of each incomplete variable
  - Logistic regression (various flavors)
  - Donor-based methods
  - Tree-based methods

The FCS framework can essentially accommodate any data for which you can define an appropriate supervised model.

• Many useful methods are already implemented in the mice package.

### JM for Mixed Data Types

When applying JM to incomplete data with mixed variable types, we have to general options.

- Impute under the multivariate normal model and round, coarsen, or truncate the continuous imputations to "match" the original data.
  - This was the old-school recommendation from the days before FCS (e.g., Allison, 2002; Schafer, 1997).
  - The **Amelia** package implements this approach.
  - This approach tends to perform poorly in methodological evaluations (e.g., Lang & Wu, 2017; Wu, Jia, & Enders, 2015).
- 2. Impute under an appropriate joint model for the data.
  - This approach is only available when a suitable joint model exists.
  - The mix package (Schafer, 2017) implements this approach for the general location model (Little & Schluchter, 1985).
  - This approach also doesn't do very well, in practice (Lang & Wu, 2017).

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