Multivariate Multiple Imputation Utrecht University Winter School: Missing Data in R

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Outline

Flavors of MI

Fully Conditional Specification

Joint Modeling

Mixed Data Types



Joint Modeling vs. Fully Conditional Specification

When imputing with *Joint Modeling* (JM) approaches, the missing data are replaced by samples from the joint posterior predictive distribution.

• To impute *X*, *Y*, and *Z*, we draw:

$$X, Y, Z \sim P(X, Y, Z|\theta)$$

With *Fully Conditional Specification* (FCS), the missing data are replaced with samples from the conditional posterior predictive distribution of each incomplete variable.

• To impute *X*, *Y*, and *Z*, we draw:

$$X \sim P(X|Y,Z,\theta_X)$$

$$Y \sim P(Y|X, Z, \theta_Y)$$

$$Z \sim P(Z|Y, X, \theta_Z)$$



Joint Modeling: Strengths

When correctly implemented, JM approaches are guaranteed to produce *Bayesianly proper* imputations.

- A sufficient condition for properness is that the imputations are randomly sampled from the correctly specified joint posterior predictive distribution of the missing data.
 - This is the defining characteristic of JM methods.

When using the correct distribution, imputations produced by JM methods will be the best possible imputations.

- Unbiased parameter estimates
- · Well-calibrated sampling variability



Joint Modeling: Weaknesses

JM approaches don't scale well.

 The computational burden increases with the number of incomplete variables.

JM approaches are only applicable when the joint distribution of all incomplete variables follows a known form.

 Mixes of continuous and categorical variables are difficult to accommodate.

Software Implementations

In R, MI via JM is available from several packages.

- Amelia (Honaker, King, & Blackwell, 2011)
 - Bootstrapped EM algorithm
- norm (Schafer, 2013)
 - · Classic data augmentation.
- mice (Van Buuren & Groothuis-Oudshoorn, 2011)
 - Data augmentation for block updating.

JM imputation is also available in SAS, Stata, SPSS, and Mplus.

Fully Conditional Specification: Strengths

FCS scales much better than JM.

• FCS only samples from a series of univariate distributions, not large joint distributions.

FCS approaches can create imputations for variables that don't have a sensible joint distribution.

• FCS can easily treat mixes of continuous and categorical variables.



Fully Conditional Specification: Weaknesses

FCS will usually be slower than JM.

 Each variable gets its own fully parameterized distribution, even if that granularity is unnecessary.

When the incomplete variables don't have a known joint distribution, FCS doesn't have theoretical support.

- There is, however, a large degree of empirical support for the tenability of the FCS approach.
- In practice, we usually choose FCS since real data rarely arise from a known joint distribution.

Software Implementations

The **mice** package is the most popular R implementation of FCS. (Van Buuren & Groothuis-Oudshoorn, 2011).

- Mature implementation
- Well integrated into the larger R ecosystem
- Very active development

The **mi** package (Su, Yajima, Gelman, & Hill, 2011) offers another option.

- More focus on diagnostics
- Object oriented flavor
- Not very actively developed

FCS imputation is also available in SAS, SPSS, Stata, and Mplus.

FULLY CONDITIONAL SPECIFICATION



Procedure: Fully Conditional Specification

- 1. Fill the missing data with reasonable guesses.
- 2. For each incomplete variable, do a single iteration of univariate Bayesian MI (e.g., as seen in the last set of slides).
 - After each variable on the data set is so treated, we've completed one iteration.
- 3. Repeat Step 2 many times.
- 4. After the imputation model parameters stabilize, save M imputed data sets.

Example: Data Generation

First we'll simulate some synthetic data.

```
## Simulate some data:
simData <-
   simCovData(nObs = 1000, sigma = 0.25, nVars = 4)
head(simData, 10)
           x1
                      x2
                             x3
                                             ×4
   0.06313632 -1.4057704 -0.01709217 1.47929405
  -1.31592547 1.2970920 -0.83500777 -0.44528158
  -0.30997023 0.9782580 0.02731853 0.35507390
4
   0.06927787 0.1836032 0.68794409 0.08049987
  -0.99354894 -0.3038956 0.80918329 -1.72143555
6
   0.36828016 -0.9423245 1.05155348 -0.11078496
   1.33333163 2.3089780 1.47203000 0.85877495
 -0.02759718 0.1714383 0.18927909 0.28627771
9
   2.37929433 2.5080935
                          2.18344726 1.56980951
10
   0.31841502
              0.7886025
                          0.73658136 0.39445970
```

Example: Data Generation

Next, we impose some missing values on the simulated data.

Example: Data Visualization

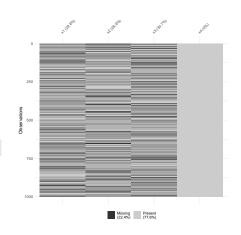
Check the results.

```
head(missData, 10)
           x1
                 x2
                       x3
                                        x4
   0.06313632
                  NA -0.01709217 1.47929405
          NA 1.2970920
                              NA -0.44528158
3
  -0.30997023
             NA 0.02731853 0.35507390
           NΑ
                   NA 0.68794409 0.08049987
5
           NA
                   NA 0.80918329 -1.72143555
6
   0.36828016
                   NΑ
                               NA -0.11078496
   1.33333163 2.3089780
                               NA
                                  0.85877495
8
           NA
                   NA 0.18927909 0.28627771
   2.37929433 2.5080935
                               NA 1.56980951
   0.31841502 0.7886025 0.73658136 0.39445970
```

Example: Data Visualization

Use the naniar::vis_missing() function to visualize the pattern of missing values.

vis_miss(missData)



JOINT MODELING

Aside: Definition of Regression Parameters

So far, we've been using the least-squares estimates of α , β , and σ^2 to parameterize our posterior distributions.

• We can also define the parameters in terms of sufficient statistics.

Given μ and Σ , we can define all of our regression moments as:

$$\beta = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

$$= \mathsf{Cov}(\mathbf{X})^{-1} \mathsf{Cov}(\mathbf{X}, \mathbf{Y})$$

$$\alpha = \mu_{\mathbf{Y}} - \beta^T \mu_{\mathbf{X}}$$

$$\Sigma_{\varepsilon} = \Sigma_{\mathbf{Y}} - \beta^T \Sigma_{\mathbf{X}} \beta$$

These definitions are crucial for JM approaches.

 Within the subset of data define by a given response pattern, the outcome variables will be entirely missing.

Multivariate Bayesian Regression

Previously, we saw examples of univariate Bayesian regression which used the following model:

$$\sigma^2 \sim \text{Inv-}\chi^2 \left(N - P, MSE\right)$$

$$\beta \sim \mathsf{MVN}\left(\hat{\beta}_{ls}, \ \sigma^2(\mathbf{X}^T\mathbf{X})^{-1}\right)$$

We can directly extend the above to the multivariate case:

$$\Sigma^{(i)} \sim \text{Inv-W}\left(N-1, (N-1)\Sigma^{(i-1)}\right)$$

$$\boldsymbol{\mu}^{(i)} \sim \mathsf{MVN}\left(\boldsymbol{\mu}^{(i-1)}, \boldsymbol{N}^{-1}\boldsymbol{\Sigma}^{(i)}\right)$$

We get α , β , and Σ_{ε} via the calculations on the preceding slide

Procedure: Joint Modeling

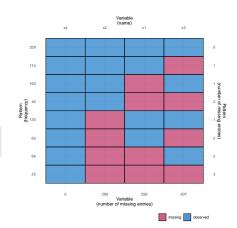
In JM imputation, we estimate the imputation model via the Tanner and Wong (1987) *data augmentation* algorithm.

- 1. Partition the incomplete data by response pattern.
 - \circ Produce S subsets wherein each row shares the same response pattern.
- **2.** Provide initial guesses for μ and Σ .
- 3. Within each subset, use the current guesses of μ and Σ to generate imputations via multivariate Bayesian regression.
- 4. Use the filled-in data matrix to updated the sufficient statistics.
- 5. Repeat Steps 3 and 4 many times.
- 6. After the imputation model parameters have stabilized, save *M* imputed data sets produced in Step 3.

Example: Data Visualization

Use ggmice::plot_pattern() to visualize the response patterns.

library(ggmice)
plot_pattern(missData)



MIXED DATA TYPES

FCS for Mixed Data Types

FCS imputation can easily accommodate incomplete data that contain both continuous and categorical/non-normal variables.

- Replace the normal-theory elementary imputation model described above with an appropriate model for the distribution of each incomplete variable
 - Logistic regression (various flavors)
 - Donor-based methods
 - Tree-based methods

The FCS framework can essentially accommodate any data for which you can define an appropriate supervised model.

• Many useful methods are already implemented in the mice package.

JM for Mixed Data Types

When applying JM to incomplete data with mixed variable types, we have to general options.

- 1. Impute under the multivariate normal model and round, coarsen, or truncate the continuous imputations to "match" the original data.
 - This was the old-school recommendation from the days before FCS (e.g., Allison, 2002; Schafer, 1997).
 - The **Amelia** package implements this approach.
 - This approach tends to perform poorly in methodological evaluations (e.g., Lang & Wu, 2017; Wu, Jia, & Enders, 2015).
- 2. Impute under an appropriate joint model for the data.
 - This approach is only available when a suitable joint model exists.
 - The mix package (Schafer, 2017) implements this approach for the general location model (Little & Schluchter, 1985).
 - This approach also doesn't do very well, in practice (Lang & Wu, 2017).

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