Multivariate Multiple Imputation Stats Camp 2018: Missing Data Analysis



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Outline

- Discuss the two frameworks for multivariate MI
 - Fully conditional specification
 - Joint Modeling
- Show a manual R example of each approach

Joint Modeling vs. Fully Conditional Specification

When imputing with *Joint Modeling* approaches, the missing data are replaced by samples from the joint posterior predictive distribution.

• To impute X, Y, and Z, we draw:

$$X, Y, Z \sim P(X, Y, Z|\theta)$$

With Fully Conditional Specification, the missing data are replaced with samples from the conditional posterior predictive distribution of each incomplete variable.

• To impute X, Y, and Z, we draw:

$$X \sim P(X|Y,Z,\theta_X)$$

$$Y \sim P(Y|X, Z, \theta_Y)$$

$$Z \sim P(Z|Y, X, \theta_Z)$$

Joint Modeling: Strengths

When correctly implemented, joint modeling approaches are guaranteed to produce *Bayesianly proper* imputations.

- The sufficient condition for properness is that the imputations are randomly sampled from the correctly specified joint posterior predictive distribution of missing data.
 - This is the defining characteristic of joint modeling methods.

When using the correct distribution imputations produced by joint modeling methods will be the best possible imputations.

- Unbiased parameter estimates
- · Well-calibrated sampling variability

Joint Modeling: Weaknesses

Joint modeling approaches are very computationally demanding.

 The computational burden increases with the number of incomplete variables.

Joint modeling approaches are only applicable when the joint distribution of all incomplete variables follows a known form.

 Mixes of continuous and categorical variables are very difficult to accommodate.

Fully Conditional Specification: Strengths

FCS is computationally simpler than JM approaches.

• FCS only samples from a series of univariate distributions, not large joint distributions.

FCS approaches can create imputations for variables that don't have a sensible joint distribution.

 Mixes of continuous and categorical variables are easily treated with FCS.

Fully Conditional Specification: Weaknesses

FCS will usually be slower than JM.

• Each variable is given its own fully parameterized distribution, even if that granularity is unnecessary.

When the incomplete variables don't have a known joint distribution, we don't have theoretical support for the validity of FCS.

- There is, however, a large degree of empirical support for the tenability of the FCS approach.
- In practice, we will usually use FCS since real data rarely arise from a known joint distribution.

Aside: Gibbs Sampling

Up to this point, most of the models we've explored could be approximated by sampling directly from their posterior distributions.

This won't be true with arbitrary, multivariate missing data

To make inference regarding a multivariate distribution with multiple, interrelated, unknown parameters, we can use *Gibbs sampling*.

 Sample from the conditional distribution of each parameter, conditioning on the current best guesses of all other parameters.

Aside: Gibbs Sampling

Suppose the following:

- 1. I want to make some inference about the tri-variate mean of $X, Y, Z = \mu_X, \mu_Y, \mu_Z \sim P(\mu|\theta)$
- 2. $P(\mu|\theta)$ is super hairy and difficult to sample
- 3. The conditional distributions: $P(\mu_X|\hat{\mu}_Y, \hat{\mu}_Z, \theta)$, $P(\mu_Y|\hat{\mu}_X, \hat{\mu}_Z, \theta)$, and $P(\mu_Z|\hat{\mu}_X, \hat{\mu}_Y, \theta)$ are easily sampled.

Then I can approximate the full joint distribution $P(\mu|\theta)$ by repeatedly and sequentially sampling from $P(\mu_X|\hat{\mu}_Y,\hat{\mu}_Z,\theta)$, $P(\mu_Y|\hat{\mu}_X,\hat{\mu}_Z,\theta)$, and $P(\mu_Z|\hat{\mu}_X,\hat{\mu}_Y,\theta)$.

Aside: Gibbs Sampling

Starting with initial guesses of μ_Y , $\hat{\mu}_Y^{(0)}$, and μ_Z , $\hat{\mu}_Z^{(0)}$, and assuming θ is known, Gibbs sampling proceeds as follows:

$$\begin{split} \hat{\mu}_{X}^{(1)} &\sim P(\mu_{X}|\hat{\mu}_{Y}^{(0)}, \hat{\mu}_{Z}^{(0)}, \theta) \\ \hat{\mu}_{Y}^{(1)} &\sim P(\mu_{Y}|\hat{\mu}_{X}^{(1)}, \hat{\mu}_{Z}^{(0)}, \theta) \\ \hat{\mu}_{Z}^{(1)} &\sim P(\mu_{Z}|\hat{\mu}_{Y}^{(1)}, \hat{\mu}_{X}^{(1)}, \theta) \\ \\ \hat{\mu}_{X}^{(2)} &\sim P(\mu_{X}|\hat{\mu}_{Y}^{(1)}, \hat{\mu}_{Z}^{(1)}, \theta) \\ \hat{\mu}_{Y}^{(2)} &\sim P(\mu_{Y}|\hat{\mu}_{X}^{(2)}, \hat{\mu}_{Z}^{(1)}, \theta) \\ \hat{\mu}_{Z}^{(2)} &\sim P(\mu_{Z}|\hat{\mu}_{Y}^{(2)}, \hat{\mu}_{X}^{(2)}, \theta) \\ \vdots &\vdots \end{split}$$

Why do we care?

Multivariate MI employs the same logic as Gibbs sampling.

- The imputations are created by conditioning on the current estimates of the imputation model parameters.
- The imputation model parameters are updated by conditioning on the most recent imputations.
- With FCS, each variable is imputed by conditioning on the most recent imputations of all other variables.

Procedure: Fully Conditional Specification

- 1. Fill the missing data with reasonable guesses.
- 2. For each incomplete variable, do a single iteration of univariate Bayesian MI (e.g., as seen in the last set of slides).
 - After each variable on the data set is so treated, we've completed one iteration.
- 3. Repeat Step 2 many times.
- 4. After the imputation model parameters stabilize, save *M* imputed data sets.

```
## Simulate some data:
simData <-
   simCovData(nObs = 1000, sigma = 0.25, nVars = 4)
head(simData, 10)
##
              x1
                        x2.
                                    x3
                                                x4
## 1 0.06313632 -1.4057704 -0.01709217 1.47929405
## 2 -1.31592547 1.2970920 -0.83500777 -0.44528158
## 3 -0.30997023 0.9782580 0.02731853 0.35507390
## 4 0.06927787 0.1836032 0.68794409 0.08049987
## 5 -0.99354894 -0.3038956
                            0.80918329 - 1.72143555
## 6 0.36828016 -0.9423245 1.05155348 -0.11078496
    1.33333163 2.3089780
                            1.47203000 0.85877495
## 8 -0.02759718 0.1714383
                            0.18927909 0.28627771
## 9 2.37929433 2.5080935
                            2.18344726 1.56980951
## 10 0.31841502 0.7886025
                            0.73658136 0.39445970
```

```
head (missData, 10)
##
              x1
                        x2
                                   x3
                                               ×4
    0.06313632 -1.4057704
                                    NA 1.47929405
## 2
              NA 1.2970920 -0.83500777 -0.44528158
    -0.30997023 0.9782580 0.02731853 0.35507390
    0.06927787
                            0.68794409 0.08049987
                        NA
## 5
              NA -0.3038956 0.80918329 -1.72143555
    0.36828016
                        NA
                            1.05155348 - 0.11078496
    1.33333163 2.3089780
                                    NA 0.85877495
## 8 -0.02759718 0.1714383
                            0.18927909 0.28627771
## 9 2.37929433 2.5080935
                                    NA 1.56980951
## 10 0.31841502
                            0.73658136 0.39445970
                        NA
```

```
## Define iteration numbers:
nImps <- 100
nBurn <- 500
nSams <- nBurn + nImps
## Summarize missingness:
rMat <- !is.na(missData)
nObs <- colSums(rMat)
nMis <- colSums(!rMat)
## Fill the missingness with initial (bad) guesses:
mean0 <- colMeans(missData, na.rm = TRUE)</pre>
sigma0 <- cov(missData, use = "pairwise")</pre>
draws0 <- rmvnorm(nrow(missData), mean0, sigma0)</pre>
impData <- missData
impData[!rMat] <- draws0[!rMat]</pre>
```

Define an elementary imputation function:

```
eif <- function(data, rVec, v) {
    ## Get the expected betas:
    fit <- lm(paste(v, "~ ."), data = data[rVec, ])
    beta <- coef(fit)
    ## Sample sigma:
    sigScale <- (1 / fit$df) * crossprod(resid(fit))</pre>
    sigmaSam <- rinvchisq(1, df = fit$df, scale = sigScale)
    ## Sample beta:
    betaVar <- sigmaSam * solve(crossprod(gr.X(fit$gr)))</pre>
    betaSam <- rmvnorm(1, mean = beta, sigma = betaVar)
    ## Return a randomly sampled imputation:
    matrix(cbind(1, data[!rVec, ])) %*% betaSam +
        rnorm(sum(!rVec), 0, sqrt(sigmaSam))
```

Apply the elementary imputation function to each incomplete variable:

Analyze the multiply imputed datasets:

```
## First, our manual version:
fits1 <- lapply(impList,
                function (x) lm(x1 \sim x2 + x3, data = x)
pool1 <- MIcombine(fits1)</pre>
## Do the same analysis with mice():
miceOut <- mice(data = missData,
                m = 100,
                method = "norm",
                printFlag = FALSE)
fits2 <- with (miceOut, lm(x1 \sim x2 + x3))
pool2 <- pool(fits2)
```

Compare approaches:

	Est	SE	t	р	FMI
(Intercept)	0.023	0.034	0.675	0.5	0.253
x2	0.172	0.04	4.35	< 0.001	0.473
x 3	0.211	0.042	5.032	< 0.001	0.502

Manual Version

	Est	SE	t	p	FMI
(Intercept)	0.019	0.044	0.44	0.66	0.568
x2	0.169	0.044	3.791	< 0.001	0.584
x 3	0.212	0.05	4.217	< 0.001	0.656

Aside: Definition of Regression Parameters

So far, we've been using the least-squares estimates of α , β , and σ^2 to parameterize our posterior distributions.

We can also define the parameters in terms of sufficient statistics.

Given μ and Σ , we can define all of our regression moments as:

$$\beta = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

$$= \operatorname{Cov}(\mathbf{X})^{-1} \operatorname{Cov}(\mathbf{X}, \mathbf{Y})$$

$$\alpha = \mu_Y - \beta^T \mu_X$$

$$\Sigma_{\varepsilon} = \Sigma_Y - \beta^T \Sigma_X \beta$$

These definitions are crucial for JM approaches.

 Within the subset of data define by a given response pattern, the outcome variables will be entirely missing.

Multivariate Bayesian Regression

Previously, we saw examples of univariate Bayesian regression which used the following model:

$$\beta \sim \text{MVN}\left(\hat{\beta}_{ls}, \ \sigma^2(\mathbf{X}^T\mathbf{X})^{-1}\right)$$

$$\sigma^2 \sim \text{Inv-}\chi^2\left(N - P, MSE\right)$$

We can directly extend the above to the multivariate case:

$$\begin{split} & \boldsymbol{\Sigma}^{(i)} \sim \text{Inv-W}\left(N-1, (N-1)\boldsymbol{\Sigma}^{(i-1)}\right) \\ & \boldsymbol{\mu}^{(i)} \sim \text{MVN}\left(\boldsymbol{\mu}^{(i-1)}, N^{-1}\boldsymbol{\Sigma}^{(i)}\right) \end{split}$$

We get α , β , and Σ_{ε} via the calculations on the preceding slide

Procedure: Joint Modeling

- 1. Partition the incomplete data by response pattern.
 - Produce *S* subsets wherein each row shares the same response pattern.
- 2. Provide initial guesses for μ and Σ .
- 3. Within each subset, use the current guesses of μ and Σ to generate imputations via multivariate Bayesian regression.
- 4. Use the filled-in data matrix to updated the sufficient statistics.
- 5. Repeat Steps 3 and 4 many times.
- After the imputation model parameters have stabilized, save M imputed data sets produced in Step 3.

```
iStep <- function(data, pats, ind, p0, pars) {</pre>
    ## Loop over non-trivial response patterns:
    for(i in c(1 : nrow(pats))[-p0]) {
        ## Define the current response pattern:
        p1 <- pats[i, ]
        ## Subset the data:
        dat1 <- data[ind == i, ]</pre>
        ## Replace missing data with imputations:
        data[ind == i, !p1] <- getImps(data = dat1,</pre>
                                        mu = pars$mu,
                                        sigma = pars$sigma,
                                        p1 = p1
    ## Return the imputed data:
    data
```

```
qetImps <- function(data, mu, sigma, p1) {</pre>
    ## Partition the parameter matrices:
    mY <- matrix(mu[!p1])
    mX <- matrix(mu[p1])</pre>
    sY <- sigma[!pl, !pl]
    sX <- sigma[p1, p1]
    cXY <- sigma[p1, !p1]
    ## Compute the imputation model parameters:
    beta <- solve(sX) %*% cXY
    alpha <- mY - t(beta) %*% mX
    sE <- sY - t(beta) %*% sX %*% beta
    ## Pull out predictors:
    X <- as.matrix(data[ , p1])</pre>
    ## Generate and return the imputations:
    n < - nrow(X)
    matrix(1, n) % * % t(alpha) + X % * % beta + rmvnorm(n, sigma = sE)
```

```
pStep <- function(data) {
    ## Update the complete-data sufficient statistics:
    n <- nrow(data)</pre>
    m <- colMeans(data)
    s \leftarrow (n - 1) * cov(data)
    ## Sample sigma and mu:
    sigma < - riwish((n - 1), s)
    mu <- rmvnorm(1, m, (sigma / n))</pre>
    ## Return the updated parameters:
    list (mu = mu, sigma = sigma)
```

Now that we've defined the necessary functions, do the imputation:

```
## Some preliminaries:
impData <- missData
nIter <- 50
nImps <- 100
## Summarize response patterns:
rMat <- !is.na(impData)</pre>
pats <- uniquecombs(rMat)</pre>
ind <- attr(pats, "index")</pre>
p0 <- which (apply (pats, 1, all))
## Get starting values for the parameters:
pars <- list(mu = colMeans(impData, na.rm = TRUE),</pre>
              sigma = cov(impData, use = "pairwise")
```

```
## Iterate over I- and P-Steps to generate imputations:
impList3 <- list()</pre>
for(m in 1 : nImps) {
    for(rp in 1 : nIter) {
        impData <- iStep (data = impData,
                          pats = pats,
                           ind = ind,
                           0q = 0q
                          pars = pars)
        pars <- pStep(impData)</pre>
        if(rp == nIter) impList3[[m]] <- impData</pre>
```

Do the same type of imputation with norm:

```
missData <- as.matrix(missData)</pre>
meta <- prelim.norm(missData)</pre>
theta0 <- em.norm(meta, showits = FALSE)
rngseed (235711)
impList4 <- list()</pre>
for(m in 1 : nImps) {
    theta1 <- da.norm(s = meta,
                       start = theta0,
                       steps = nIter)
    impList4[[m]] <- imp.norm(s = meta,</pre>
                                theta = theta1,
                                x = missData)
```

Analyze the multiply imputed data:

```
## Manual implementation:
fits3 <- lapply(impList3,
                 function (x) lm(x1 \sim x2 + x3, data = x)
pool3 <- MIcombine(fits3)</pre>
## Imputation using norm():
fits4 <- lapply(impList4,
                 function (x) lm (x1 ~ x2 + x3,
                                  data = as.data.frame(x)
pool4 <- MIcombine(fits4)</pre>
```

Compare approaches:

	Est	SE	t	р	FMI
(Intercept)	0.023	0.043	0.529	0.597	0.545
x2	0.169	0.045	3.729	< 0.001	0.597
x 3	0.212	0.05	4.228	< 0.001	0.651

Manual Version

	Est	SE	t	p	FMI
(Intercept)	0.019	0.047	0.398	0.691	0.611
x2	0.164	0.044	3.755	< 0.001	0.569
x3	0.215	0.05	4.28	< 0.001	0.656