

Note  $\mathcal{X}(M) = \Gamma(TM)$ . in fact,  $C^\infty(M)$ -module:

$$(f\sigma)(p) = f(p)\sigma(p)$$



## Reduction of Structure

17. IV.23

Recall that a vector bundle  $\overset{E}{\underset{\pi}{\downarrow}}_X$  may be specified by  
cocycle data: open cover  $\{V_\alpha | \alpha \in A\}$  of  $X$  + transition fns

$$\tau_{\alpha\beta}: V_\alpha \cap V_\beta \rightarrow GL_k \mathbb{R}$$

satisfying the cocycle condition:  $\forall \alpha, \beta, \gamma \in A$

$$\tau_{\alpha\gamma} = \tau_{\beta\gamma} \tau_{\alpha\beta}$$

Defn Let  $G \leq GL_k \mathbb{R}$ ,  $\pi: E \rightarrow M$  vb of rank  $k$  on  $M$ . A  
reduction of the structure group of  $E$  to  $G$  is a

$GL_k \mathbb{R}$ -cocycle representing the iso class of  $E$ , all of whose transition maps are valued in  $G$ .

E.g. •  $G = GL_k^+ \mathbb{R} = \det^{-1}(\mathbb{R}_{>0}) \leq GL_k \mathbb{R}$

If  $E$  admits a  $GL_k^+ \mathbb{R}$ -cocycle call it orientable.

If  $TM$  is orientable, call  $M$  orientable.

•  $G = O(k) \leq GL_k \mathbb{R}$

If  $E$  admits an  $O(k)$ -cocycle, then we can endow each of its fibers with an inner product and transition data will respect this.

If  $TM$  has structure gp reduced to  $O(n)$ , call

$M$  a Riemannian manifold and say  $M$  has been given a Riemannian structure.

Fact Every smooth mfld admits a Riemannian str.

Twisting Fix a representation (i.e. homomorphism)

$\rho: GL_k(\mathbb{R}) \rightarrow GL_m(\mathbb{R})$ . Composing transition data for  $E \downarrow_M$

with  $\rho$  gives new cocycles

$$\rho \circ \tau_{\alpha\beta}: V_\alpha \cap V_\beta \longrightarrow GL_m(\mathbb{R})$$

$$\begin{matrix} \tau_{\alpha\beta} & \downarrow \\ GL_k(\mathbb{R}) & \nearrow \rho \end{matrix}$$

$$E \xrightarrow{\quad} E^{\rho} \quad \text{fr k on } M \quad \text{fr m on } M$$

$$\uparrow \qquad \qquad \qquad \uparrow$$

$$\{ v_b \text{ on } M \} \quad \{ v_b \text{ on } M \}$$

The associated vb on  $M$  is the  $\rho$ -twisting of  $E$ .

- E.g. •  $\det: GL_n \mathbb{R} \rightarrow GL_1 \mathbb{R} = \mathbb{R}^{\times} \rightsquigarrow \det E$  line bundle on  $M$
- $\wedge^k E$

- $GL_n \mathbb{R} \longrightarrow GL_n \mathbb{R} \rightsquigarrow E^*$  dual of  $E$
- $A \longmapsto (A^{-1})^T$

### Local & Global Frames

$U \subseteq M$  open,  $\overset{E}{\underset{\pi \downarrow}{\sqcup}}$  vb of rank  $k$

$(\sigma_1, \dots, \sigma_k) \in \underbrace{\Gamma(E, U)^k}$  is a local frame if  $\sigma_i(p), \dots, \sigma_k(p)$  is a basis of  $E_p \forall p \in U$ ,

$\sigma_i: U \rightarrow E$

$U \subseteq M$

local sections of  $E$  over  $U$

global frame when  $U = M$ .

Note Frame for  $M$  = frame for  $TM$ .

E.g. • Trivial bundles  $M \times \mathbb{R}^k$  admit the global frame  
 $\downarrow$   
 $M$

$(\tilde{e}_1, \dots, \tilde{e}_k)$  where  $\tilde{e}_i(q) = (p, e_i)$ .

• Local trivializations induce local frames:

$$\pi^{-1}U \xrightarrow{\cong} U \times \mathbb{R}^k \quad \text{so define } v_i = \phi^{-1} \cdot \tilde{e}_i,$$



Prop Every smooth local/global frame for a smooth vb  
is associated with a smooth local/global trivialization.

Pf p. 259  $\square$

Cor A smooth manifold is parallelizable iff  $TM$  is trivial.  $\square$

↑  
defined as  $TM$   
admitting a global  
frame

The Cotangent Bundle

Duals  $V$  an  $\mathbb{R}$ -vector space.

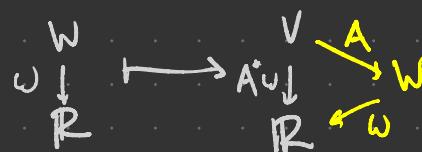
$V^* := \text{Hom}_{\mathbb{R}}(V, \mathbb{R}) = \left\{ \omega: V \rightarrow \mathbb{R} \mid \omega \text{ linear} \right\}$  is the dual space of  $V$ .  
 A covector

Given basis  $v_1, \dots, v_n$  of  $V$  let  $v_1^*, \dots, v_n^* \in V^*$  be the covectors defined by  $v_i^*(v_j) = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$  (then extended linearly).

Then  $v_1^*, \dots, v_n^*$  is the dual basis (to  $(v_i)$ ) of  $V^*$ .

Given  $A: V \rightarrow W$  linear, the dual of  $A$  is

$$A^*: W^* \longrightarrow V^*$$



i.e.  $(A^* \omega)(v) = \omega(Av)$  for  $v \in V$ ,  $\omega \in W^*$ .

Have  $(A \circ B)^* = B^* \circ A^*$  and  $\text{id}_V^* = \text{id}_{V^*}$  so duality is a functor  $\text{Vect}_{\mathbb{R}}^{\text{op}} \rightarrow \text{Vect}_{\mathbb{R}}$ .

Double dual  $V^{**} = (V^*)^*$ . Have

$$\begin{array}{ccc} \xi = \xi_V : V & \longrightarrow & V^{**} \\ v \longmapsto & V^* & \omega : V \rightarrow \mathbb{R} \\ & \xi(v) \downarrow & \downarrow \\ & \mathbb{R} & \omega(v) \end{array}.$$

Then  $\xi : \text{id}_{\text{Vect}_{\mathbb{R}}} \Rightarrow (\cdot)^*$  is a natural transformation:

for  $A : V \rightarrow W$  linear,

$$V \xrightarrow{A} W$$

$\xi_V \downarrow \qquad \qquad \downarrow \xi_W$

$$V^{**} \xrightarrow{A^{**}} W^{**}$$

Prop If  $\dim V < \infty$ , then  $\xi: V \xrightarrow{\cong} V^{**}$  is a natural isomorphism.



- $V \neq V^{**}$  for infinite dim'l vector spaces
- $V \cong V^*$  for  $V$  finite dim'l, but the iso is not natural

## Tangent covectors on manifolds

$p \in M$  smooth mfld, the cotangent space at  $p$  is

$$T_p^* M := (T_p M)^*$$

The transition fns for  $T^*M$  are inverse-transpose of those for  $TM$ .

Write  $\mathcal{X}^*(M) = \Gamma(T^*M)$  for smooth covector fields on  $M$ .

The differential

$$\Gamma(T^*M, M)$$

For  $f \in C^\infty(U)$ , write  $df \in \mathcal{X}^*(U)$  defined by

open in  $M$

$$\begin{array}{c} T^*M \\ \downarrow \omega \\ M \\ \omega_p : T_p M \rightarrow \mathbb{R} \\ \text{linear} \end{array}$$

$$df : U \longrightarrow T^*M$$

$$p \longmapsto T_p M \xrightarrow{\quad v \quad} \mathbb{R}$$

$$df_p \downarrow \quad \downarrow \quad df_p(v) = vf$$

$$\text{using } T_p M = \text{Der}_p(C^\infty(U))$$

Call  $df$  the differential covector field of  $f$ .

Take  $(x^i)$  smooth coords on  $U \subseteq M$  open.

Get a frame  $\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}$  of  $TM|_U$  with dual frame

$\lambda^1, \dots, \lambda^n$  of  $T^*M|_U$ . ( $\lambda_i|_p = (\frac{\partial}{\partial x^i}|_p)^*$ )

Have  $df_p = \sum A_i(p) \lambda^i|_p$  for some fns  $A_i: U \rightarrow \mathbb{R}$ .

By defn of  $df$ ,

$$A_i(p) = df_p \left( \frac{\partial}{\partial x^i} \Big|_p \right) = \frac{\partial}{\partial x^i} \Big|_p f = \frac{\partial f}{\partial x^i} \Big|_p.$$

Thus  $df_p = \sum \frac{\partial f}{\partial x^i}(p) \lambda^i|_p$   $\underbrace{\quad}_{\nabla f_p}$  in  $x^i$  coord system

In particular, applied to  $x^i: U \rightarrow \mathbb{R}$  coord fn, get

$$dx^j|_p = \left[ \sum_i \frac{\partial x^j}{\partial x^i}(p) \lambda^i \right]_p = \lambda^j|_p$$

I.e.,  $dx^1, \dots, dx^n$  is the dual frame of  $\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}$ .

Thus  $df_p = \left[ \sum_i \frac{\partial f}{\partial x^i}(p) dx^i \right]_p \in T_p^* M$

$$\int f(x) \underline{dx}$$

and  $df = \sum_i \frac{\partial f}{\partial x^i} dx^i \in \mathbb{X}^*(U)$ .

Why covectors? They give us coordinate-free versions of gradients!

$$TM \xrightarrow{dF} TN$$

$$\downarrow \quad \quad \downarrow$$

$$M \xrightarrow{F} N$$

$$TM \xrightarrow{df} T\mathbb{R} = \mathbb{R} \times \mathbb{R}$$

$$\downarrow \quad \quad \downarrow$$

$$M \xrightarrow{f} \mathbb{R}$$

$$\Leftrightarrow df \in \mathcal{X}^*(M)$$

$$T^*M$$

$$\begin{matrix} & \downarrow \\ M & \xrightarrow{\quad df \quad} \end{matrix}$$

$$T_p M \longrightarrow \{p\} \times \mathbb{R}$$

$$v \longmapsto (p, vf)$$

E.g.  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$   
 $(x, y) \mapsto x^2 y \cos x$

$$df = \frac{\partial(x^2 y \cos x)}{\partial x} dx + \frac{\partial(x^2 y \cos x)}{\partial y} dy$$

$$= (2xy \cos x - x^2 y \sin x) dx + (x^2 \cos x) dy$$

while  $\nabla f = ( \quad, \quad )$

Prop  $f, g \in C^\infty(M)$ ,  $a, b \in \mathbb{R}$

$$(a) d(af + bg) = adf + bdg$$

$$(b) d(fg) = f dg + g df$$

$$(c) d(f/g) = \frac{1}{g^2} (g df - f dg) \text{ on } g \neq 0$$

(d)  $\exists f \in J \subseteq \mathbb{R}$ ,  $h: J \rightarrow M$   
 $\Rightarrow d(h \circ f) = (h' \circ f) df$

(e)  $f \text{ const} \Rightarrow df = 0$ . □