

Good news: \mathbb{X} is functorial in diffeomorphisms!

i.e. $F: M \xrightarrow{\approx} N$ and $X \in \mathbb{X}(M)$ then $\exists! F_* X \in \mathbb{X}(N)$

s.t. $(F_* X)_q = dF_{F^{-1}(q)} X_{F^{-1}(q)}$; moreover, $\text{id}_* X = X$ and

if $G: N \xrightarrow{\approx} P$ then $(G \circ F)_* X = G_* (F_* X)$.

$$\begin{array}{ccc} TM & \xrightarrow[\approx]{dF} & TN \\ X \left(\begin{array}{c} \downarrow \pi_M & & \downarrow \pi_N \\ M & \xrightarrow[\approx]{F} & N \end{array} \right) F_* X = dF \circ X \circ F^{-1} \end{array}$$

Call $F_* X$ the pushforward
of X along F .

Since X and $F_* X$ are F -related,

$$X(f \circ F) = ((F_* X)f) \circ F$$

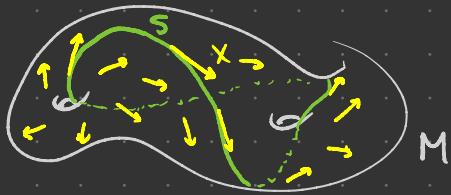
See pp. 183-184 for
detailed comp'n of
 $F_* X$.

Vector fields & submanifolds

$S \subseteq M$ immersed or embedded subfld

For $p \in S$, $X \in \mathcal{X}(M)$ call X tangent to S at p when

$$X_p \in T_p S \subseteq T_p M$$



Note $S \subseteq M$ imm subfld,

$X \in \mathcal{X}(M)$ tangent to S ,

then $\exists! X|_S \in \mathcal{X}(S)$

that is ι -related to X

($\iota : S \hookrightarrow M$)

p. 185

Prop $S \subseteq M$ amb subfld. Then
 $X \in \mathcal{X}(M)$ is tangent to S iff

$$Xf|_S = 0 \quad \forall f \in C^\infty(M) \text{ s.t. } f|_S = 0.$$

{ Directional derivs in directions
tangent to S are 0 or
fns. constant on S .

Lie brackets

Recall $\mathcal{X}(M) \cong \{ \text{derivations } C^\infty(M) \rightarrow C^\infty(M) \}$
 $x \mapsto (f \mapsto Xf)$.

Given $X, Y \in \mathcal{X}(M)$, we may form XY & YX as composites:

$$XY: f \mapsto X(Yf)$$

$$YX: f \mapsto Y(Xf)$$

These are fns $XY, YX : C^\infty(M) \rightarrow C^\infty(M)$ but not derivations.

But the Lie bracket

$$[X, Y] := XY - YX : f \mapsto X(Yf) - Y(Xf)$$

is a derivation $C^\infty(M) \rightarrow C^\infty(M)$ so $[X, Y] \in \mathcal{X}(M)$!

Pf

$$[X, Y](fg) = (XY)(fg) - (YX)(fg)$$

$$= X(fYg + (Yf)g) - Y(fXg + (Xf)g)$$

$$\begin{aligned} &= fXYg + Xf \cdot Yg + Yf \cdot Xg + XYf \cdot g \\ &\quad - (fYXg + Yf \cdot Xg + Xf \cdot Yg + YXf \cdot g) \\ &= f[X, Y]g + [X, Y]f \cdot g \end{aligned}$$

so $[X, Y]$ is a derivation. \square

Later $[X, Y]$ is the "Lie derivative" — directional derivs of Y along X .

Prop $X, Y \in \mathcal{X}(M)$, $X = \sum_i X^i \frac{\partial}{\partial x^i}$, $Y = \sum_j Y^j \frac{\partial}{\partial x^j}$ for some smooth local coords (x^i) for M . Then

$$\begin{aligned}[X, Y] &= \sum_{i,j} \left(X^i \frac{\partial Y^j}{\partial x^i} - Y^i \frac{\partial X^j}{\partial x^i} \right) \frac{\partial}{\partial x^j} \\ &= \sum_j (X^j Y^i - Y^j X^i) \frac{\partial}{\partial x^i}\end{aligned}$$

Pf $\frac{\partial^2}{\partial x^i \partial x^j} = \frac{\partial^2}{\partial x^j \partial x^i}$ on smooth fns. \square

E.g. $\left[\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right] = 0 \quad \forall i, j$

• $X = x \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + x(y+1) \frac{\partial}{\partial z}, Y = \frac{\partial}{\partial x} + y \frac{\partial}{\partial z} \in \mathcal{X}(\mathbb{R}^3)$

Then $[X, Y] = \left(X_1 - Y_x \right) \frac{\partial}{\partial x} + \left(X_0 - Y_1 \right) \frac{\partial}{\partial y} + \left(X_y - Y[x(y+1)] \right) \frac{\partial}{\partial z}$

$$= (0 - 1) \frac{\partial}{\partial x} + 0 \frac{\partial}{\partial y} + (1 - (y+1)) \frac{\partial}{\partial z}$$

$$= -\frac{\partial}{\partial x} - y \frac{\partial}{\partial z}$$

Prop Lie brackets are

- bilinear $[aX + Y, Z] = a[X, Z] + [Y, Z]$

$$[X, aY + Z] = a[X, Y] + [X, Z] \quad \forall a \in \mathbb{R}, X, Y, Z \in \mathfrak{X}(M)$$

- antisymmetric $[X, Y] = -[Y, X] \quad \forall X, Y \in \mathfrak{X}(M)$

They also satisfy the

- Jacobi identity $[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0 \quad \forall X, Y, Z$

and for $f, g \in C^\infty(M)$,

$$[fX, gY] = fg[X, Y] + (fxg)Y - (gyf)X$$

The proof consists of comp's following from defns. \square

A Lie algebra is an \mathbb{R} -vector space \mathfrak{o}_j together with a bilinear transformation $[,] : \mathfrak{o}_j \times \mathfrak{o}_j \rightarrow \mathfrak{o}_j$ which is antisymmetric and satisfies the Jacobi identity.

Thus $\mathfrak{X}(M)$ is a Lie algebra!

The Lie algebra of a Lie group

G a Lie group. $X \in \mathfrak{X}(G)$ is left invariant when $(L_g)_* X = X \forall g \in G$.

Write $\text{Lie}(G) = \mathfrak{o}_j \subseteq \mathfrak{X}(G)$ for the \mathbb{R} -vector subspace of left-invariant vector fields on G .

Prop If $X, Y \in \mathfrak{o}_j$, then $[X, Y] \in \mathfrak{o}_j$ so \mathfrak{o}_j is a Lie algebra.

$$\underline{\text{Pf}} \quad (L_g)_*[x, y] = [(L_g)_*x, (L_g)_*y] = [x, y] \quad \square$$

↑
Naturality of $[,]$: If $F: M \rightarrow N$ smooth, $X_1, X_2 \in \mathcal{X}(M)$,
 $Y_1, Y_2 \in \mathcal{X}(N)$ s.t. X_i is F -related to Y_i , $i=1, 2$,

then $[X_1, X_2]$ is F -related to $[Y_1, Y_2]$. (Applying to

$$F = L_g \cdot)$$

$$\underline{\text{Pf}} \quad X_1 X_2 (f \circ F) = X_1 ((Y_2 f) \circ F) = (Y_1 Y_2 f) \circ F$$

$$X_2 X_1 (f \circ F) = X_2 ((Y_1 f) \circ F) = (Y_2 Y_1 f) \circ F$$

$$\Rightarrow [X_1, X_2] (f \circ F) = X_1 X_2 (f \circ F) - X_2 X_1 (f \circ F)$$

$$= (Y_1 Y_2 f) \circ F - (Y_2 Y_1 f) \circ F$$

$$= ([Y_1, Y_2] f) \circ F. \quad \square$$

A Lie algebra homomorphism is a linear map $A: \mathfrak{g} \rightarrow \mathfrak{h}$ s.t.

$$A[X, Y] = [AX, AY] \quad \forall X, Y \in \mathfrak{g}.$$

E.g. • $\mathfrak{gl}_n \mathbb{R} := \mathbb{R}^{n \times n}$ with $[A, B] := AB - BA$

• $\mathfrak{gl}_n \mathbb{C} := \mathbb{C}^{n \times n}$ as $2n^2$ -dim- \mathbb{C} -vs with $[A, B] := AB - BA$

(Later we'll see these are $\cong \text{Lie}(GL_n F)$ for $F = \mathbb{R}, \mathbb{C}$ resp.)

Thm Let G be a Lie group. The evaluation map

$$\varepsilon: \text{Lie}(G) \longrightarrow T_e G$$

$$X \longmapsto X_e$$

is a vector space isomorphism. Thus $\dim_{\mathbb{R}} \text{Lie}(G) = \dim G$.

Pf ε is linear and if $\varepsilon(X) = X_e = 0$ then $X = 0$ b/c (by left-invariance) $X_g = d(L_g)_e(X_e) = 0 \quad \forall g$.

For surjectivity, let $v \in T_e G$ be arbitrary and define

$$v^L|_g := d(L_g)_e(v)$$

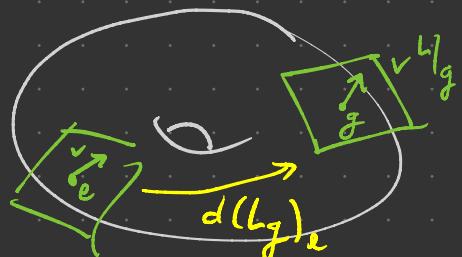
v^L is smooth: Suffices to show $v^L f$

smooth $\forall f \in C^\infty(G)$. Take $\gamma: (-\delta, \delta) \rightarrow G$ smooth with

$\gamma(0) = e$, $\gamma'(0) = v$. Then for $g \in G$,

$$(v^L f)(g) = v^L|_g f = d(L_g)_e(v) f = v(f \circ L_g)$$

$$= \gamma'(0) (f \circ L_g) = \frac{d}{dt} \Big|_{t=0} (f \circ L_g \circ \gamma)(t)$$



Define $\varphi: (-\delta, \delta) \times G \rightarrow \mathbb{R}$

$$(t, g) \mapsto f \cdot L_g \circ \gamma(t) = f(g\gamma(t))$$

Then $(v^L f)(g) = \frac{\partial \varphi}{\partial t}(0, g)$. Since φ is smooth, $v^L f$ is smooth. ✓

v^L is left-invariant: WTS $d(L_h)_g(v^L|_g) = v^L|_{hg} \quad \forall g, h \in G$.

$$\begin{aligned} \text{By defn, } d(L_h)_g(v^L|_g) &= d(L_h)_g(d(L_g)_e v) \\ &= d(L_h \circ L_g)_e v \\ &= d(L_{hg})_e v \\ &= v^L|_{hg}. \end{aligned}$$

Finally, $\varepsilon(v^L) = v^L|_e = v$ so ε is surjective. □