

Final Presentation-Team ALBOE

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Objectives

- 1.The vehicle shall be controlled wirelessly
- 2.The vehicle shall be able to control and monitor yaw, pitch, and roll
- 3.The vehicle shall dock to a charging interface
- 4.The vehicle shall deliver a 1 lb. payload $\frac{1}{2}$ mile away within 3 ft. of its destination
- 5.The charging station shall utilize clean energy
- 6.The charging station must charge wirelessly

Action Items

- Finalize detailed Mass and Monetary Budget
- Define all 3 axes of flight (Yaw, Pitch and Roll)
- Adjust Gantt Chart Colors
- Remote switch for electromagnet release
- Itemize all Parts in Mass Budget; just don't give a summary

Weekly Emails



Kyle Pedersen

Fri 5/5, 1:24 PM

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Reply all | ▾

Hello, Mentors!

Our group has completed most of the requirements - we just have to fulfill the wireless charging and payload requirements for our drone. We also will be having a final presentation of our project where we will be flying the drone; we will inform you of the presentation date by next week. Next week, we meet Monday from 10:45 AM to 12:25 PM, Wednesday from 10:35 AM to 12:05 PM, and Friday from 1:45 PM to 2:25 PM.

We hope you can make it some time this next week!

- Kyle Pedersen
Da Vinci Senior

Gantt Chart

ERD Gantt Chart

Semester 2 (1/9- 6/5)

Controls and Energy

Solar Panel

Charging Station

Controller

Receiver

Payload Design

Grabber

Arm

Frame

Electromagnet

| | January | | | | February | | | | March | | | | April | | | | May | | | June | | |
|--|---------|------|------|------|----------|------|------|------|-------|------|------|------|-------|------|------|------|-----|-----|------|------|------|-----|
| | 1/9 | 1/16 | 1/23 | 1/30 | 2/6 | 2/13 | 2/20 | 2/27 | 3/6 | 3/13 | 3/20 | 3/27 | 4/3 | 4/10 | 4/17 | 4/24 | 5/1 | 5/8 | 5/15 | 5/22 | 5/29 | 6/5 |

| | | Presentation Date | Actual Presentation Date |
|--------------|-------|-------------------|--------------------------|
| Build Plan | PUP 1 | February | 2/1 |
| Build Actual | PUP 2 | March | 3/1 |
| Build Both | PUP 3 | April | 4/1 |
| Test Plan | | | |
| Test Actual | | | |
| Test Both | | | |

Updated Cost Budget

| Date | Item Category | Item Name/Description | Quantity | Unit Cost | Overall Cost |
|------------|------------------|---|----------|-----------|--------------|
| 11/14/2016 | Supplies | Rosin Core Solder | 1 | \$10.02 | \$10.02 |
| 1/18/2017 | Supplies | uxcell 10 Pcs Molded Plastic Case 1000V 10A Rectifier Diodes 10A10 | 1 | \$3.94 | \$3.94 |
| 1/23/2017 | Tools | 13 pc metric hex key set | 1 | \$11.81 | \$11.81 |
| 1/9/2017 | Renewable Energy | HQST 100 Watt 12 Volt Polycrystalline Solar Panel Kit with 20A PWM Charge Controller with LCD Display | 1 | \$167.99 | \$167.99 |
| 12/14/2016 | Renewable Energy | 12v 10Ah SLA Rechargeable Battery - F2 Terminals | 1 | \$26.99 | \$26.99 |
| 1/18/2017 | Renewable Energy | Uxcell 10 Pcs Molded Plastic Case 1000V 10A Rectifier Diodes 10A10 | 1 | \$3.94 | \$3.94 |
| 3/1/2017 | Renewable Energy | SNAN 300W Car Power Inverter DC 12V to AC 110V with Dual AC Outlet and 4.8A Dual USB Charging Port | 1 | \$24.99 | \$24.99 |
| 11/14/2016 | Vehicle Design | DJI Naza-M Lite | 1 | \$79.00 | \$79.00 |
| 11/14/2016 | Vehicle Design | Drone Body: Wototoy HJ-H4 Reptile | 1 | \$114.98 | \$114.98 |
| 11/14/2016 | Vehicle Design | Drone Motors: Quantum MT Series 4108 700KV | 4 | \$29.03 | \$116.12 |
| 11/30/2016 | Vehicle Design | ESC: Turnigy MultiStar 30A BLHeli-S Rev16 V3 ESC 2~6S (Opto) | 4 | \$17.01 | \$68.04 |
| 11/14/2016 | Vehicle Design | Racers Edge LP4S6400100C 6400mAh 100C 4S LiPo Battery | 1 | \$124.08 | \$124.08 |

Updated Cost Budget

| | | | | | |
|------------|----------------|--|---|---------|---------|
| 11/14/2016 | Vehicle Design | HJ 12X3.8 Propellers | 4 | \$10.99 | \$43.96 |
| 11/30/2016 | Vehicle Design | 3.5mm Male Female Banana Plug Bullet Connector Replacements 20 Pairs | 1 | \$7.99 | \$7.99 |
| 11/14/2016 | Vehicle Design | Drone Power Distribution Board: Hobby King Quadcopter Power Distribution Board | 1 | \$5.53 | \$5.53 |
| 11/16/2016 | Vehicle Design | Femal Dean Connectors for battery | 4 | \$8.95 | \$35.80 |
| 11/16/2016 | Vehicle Design | Male Dean connectors for battery | 4 | \$8.95 | \$35.80 |
| | Vehicle Design | Bullet Banana Connectors | 1 | \$6.89 | \$27.56 |
| 2/27/2017 | Vehicle Design | Parallel Y-Harness - Deans-type Connector | 1 | \$8.95 | \$8.95 |
| 12/7/2016 | Vehicle Design | Green Body Lights | 1 | \$5.75 | \$5.75 |
| 2/27/2017 | Vehicle Design | Controller and Reciever: FlySky FS-T6 | 1 | \$53.99 | \$53.99 |
| 11/14/2016 | Charging Dock | Wireless Charging PCB Module 5-12V | 2 | \$11.99 | \$27.78 |

Updated Cost Budget

| | | | | | | |
|-------------|---------------|--|---|---------|---------|---------|
| 3/20/2017 | Charging Dock | Booster Converter | 1 | \$7.99 | \$7.99 | Amazon |
| 11/28/2016 | Payload Arm | DC 12V 0.07A 3.5RPM High Torque Gear Box Electric Motor 37mm | 1 | \$16.19 | \$16.19 | Amazon |
| 11/28/2016 | Payload Arm | Motor Shaft coupler | 3 | \$5.89 | \$17.67 | Amazon |
| 1/18/2017 | Payload Arm | Uxcell a13120300ux0142 DC12V 50N 2 Wired Connector Electromagnet Solenoid Lift Holding, 0.33 Amp | 1 | \$8.94 | \$8.94 | Amazon |
| 5/5/2017 | Payload Arm | AGT 12V Waterproof Wireless Remote Control DC Universal 2-Channel Output Works LED Lights | 1 | \$19.99 | \$19.99 | Amazon |
| Total Cost: | | | | | | 1075.79 |

Power Budget

| Item | Rating | 50% | 75% | 100% |
|-----------------|-------------|-------------|-------------|-------------|
| Motors | 30A@22V | 15A@11V | 22.5A@16.5 | 30A@22V |
| V-Sen Regulator | 3A@5V | 1.5A@5V | 2.25A@5V | 3A@5V |
| ESC | 0.001@14.8V | 0.001@14.8V | 0.001@14.8V | 0.001@14.8V |
| Lights | 0.001@1.5V | 0.001@1.5V | 0.001@1.5V | 0.001@1.5V |
| Switch/Magnet | 0.035@12V | 0.035@12V | 0.035@12V | 0.035@12V |
| | | | | |
| | | | | |
| Battery specs | | Full Charge | | |
| amp hours | 6.4 | 6.4 | | |
| Volts | 14.8 | 16.4 | | |
| | | | | |

Testing

(5/3/2017-5/22/17)

Power Budget

- Research Power Consumption of each part
- Establish if the power consumption is constant or variable
- Test lost charge over 5 minutes at hover

| Item | Rating | 50% | 75% | 100% |
|-----------------|-------------|-------------|-------------|-------------|
| Motors | 30A@22V | 15A@11V | 22.5A@16.5 | 30A@22V |
| V-Sen Regulator | 3A@5V | 1.5A@5V | 2.25A@5V | 3A@5V |
| ESC | 0.001@14.8V | 0.001@14.8V | 0.001@14.8V | 0.001@14.8V |
| Lights | 0.001@1.5V | 0.001@1.5V | 0.001@1.5V | 0.001@1.5V |
| Switch/Magnet | 0.035@12V | 0.035@12V | 0.035@12V | 0.035@12V |
| | | | | |
| | | | | |
| Battery specs | | Full Charge | | |
| amp hours | | 6.4 | 6.4 | |
| Volts | | 14.8 | 16.4 | |

Power Loss Test

- Tested at hover stabilized with my hand

| Battery Loss Tests | | | |
|--------------------|-----------------|------------------|------|
| Test # | Hover 5 minutes | Charge Used +/-V | |
| 1 | 16.8 | 15.95 | 0.85 |
| 2 | | | |
| 3 | | | |

Renewable Energy Test

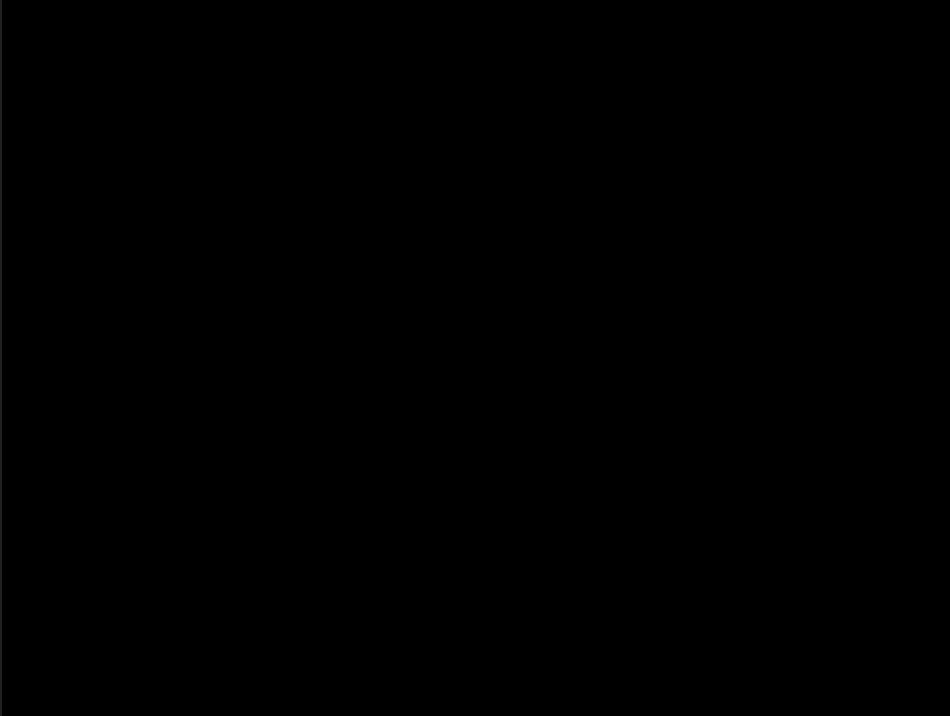


Renewable Energy Test

Testing Procedure:

| Test Number | Observations | Future Steps | Successful? |
|--------------------|---|-----------------------|--------------------|
| 1 | Volts:12.5 Amps:4-5 Bright Weather Energy was easily collected | Attach power to drone | Yes |

Payload Test-5/8/17



Wireless Charging Test-5/10/17



Wireless Charging Test-5/10/17

Wireless Charging Test

Testing Procedure: Wireless Charger can charge Drone Battery within one day

| Test Number | Observations | Successful? |
|-------------|---|--|
| 1 | Volts: 12 V Max. Distance before power loss: 5 mm Magnet was very strong when receiver transmitter were close | Yes, Wireless Transmitter/Receiver worked and could transfer current |

Payload Test (Integration Test)

Payload Test-5/15/17



Drone Flying Test

Testing Procedure: Drone is able to fly $\frac{1}{2}$ mile without any problems.

| Test Number | Observations | Future Steps | Successful? |
|--------------------|--|---------------------|--------------------|
| 1 | Carries 1 lb. well and is able to drop payload with ease | None. | Yes |

Full Integrated test

Full Integration Test

- Obtain and attach voltage regulator
- Attach voltage regulator to battery and magnet and test



Drone Flight and Payload Test # 1 - 5/22/17

Documentation

(5/3/2017-WIP)

Day 26-5/8/2017

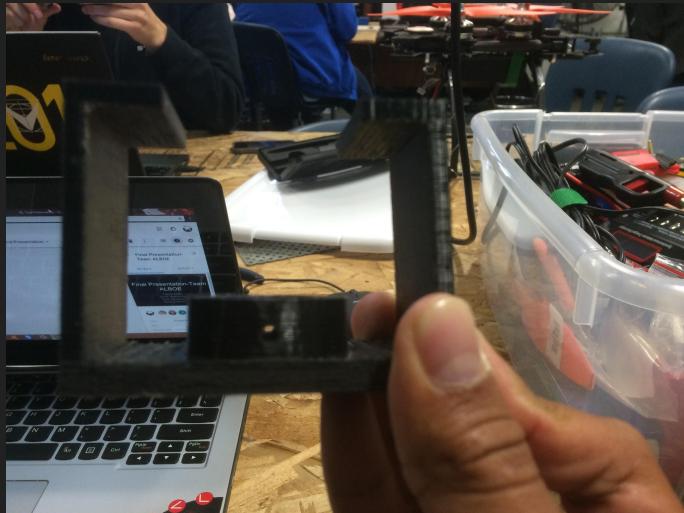


Figure 1.1:3D Printed Electromagnet Holder-Mk 3-Side View

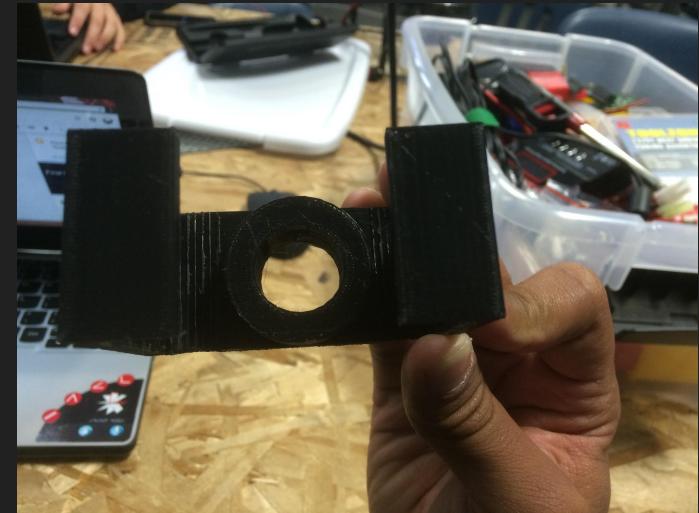


Figure 1.2: 3D-Printed Electromagnet Holder-Mk 3-Top View

Day 26-5/8/2017



Figure 2.1: 3D-Printed Electromagnet Holder-MK 3-Broken

Day 26-5/8/17

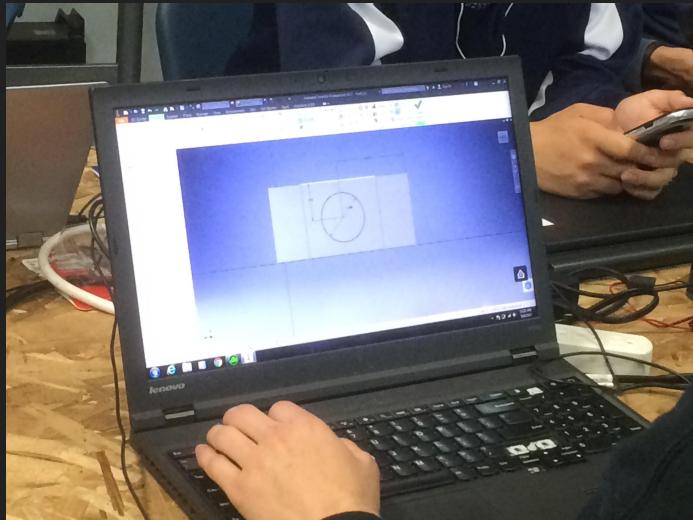


Figure 3.1: Creating new model for Electromagnet carrier-Top View

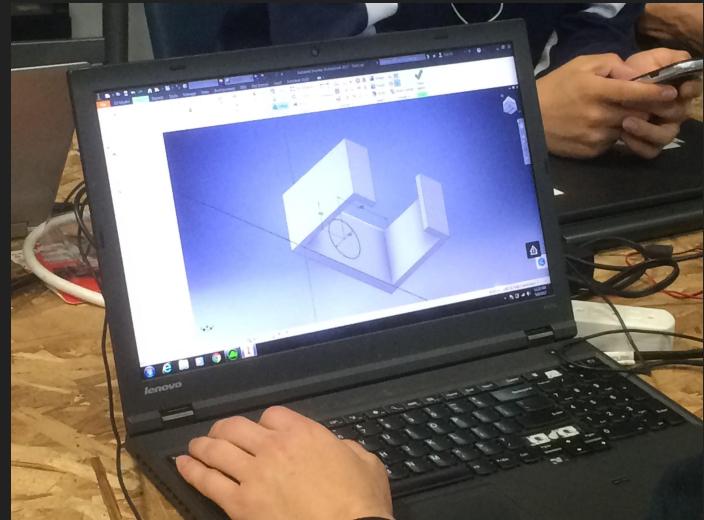


Figure 3.2: New Model for Electromagnet Carrier-Iso View

Day 27-5/10/17



Figure 4.1: Remote Clicker to turn on/ off electromagnet

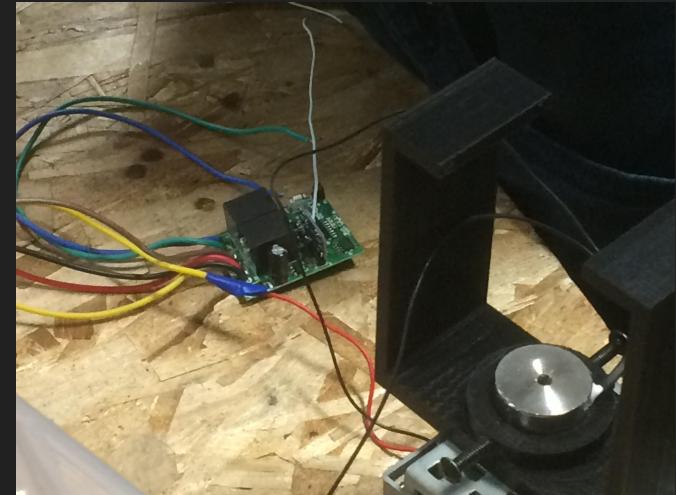


Figure 4.2: Electrical Component to control Electromagnet

Day 28-10/12/2017

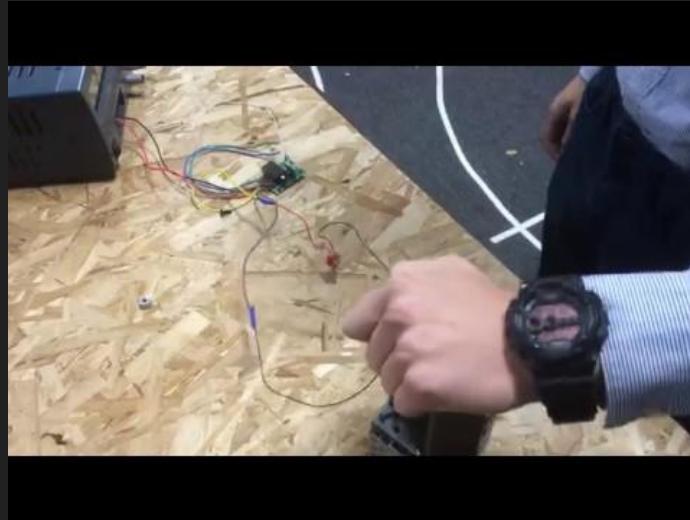


Figure 5.1: Test of Lifting Ability of the Electromagnet

Day 29-5/15/17

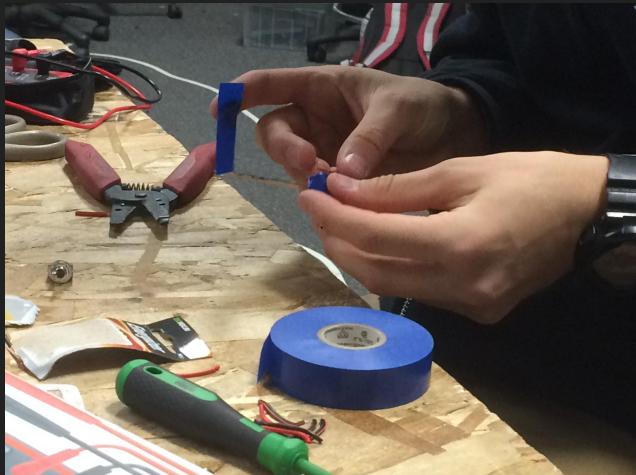


Figure 3.1: Jacob attaching
electrical tape to Drone
Components

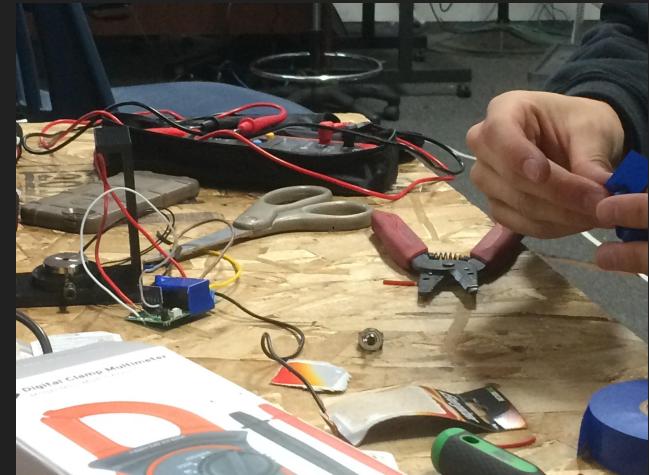


Figure 3.2: Jacob finishing up work
on Drone Component

Day 30-5/17/2017

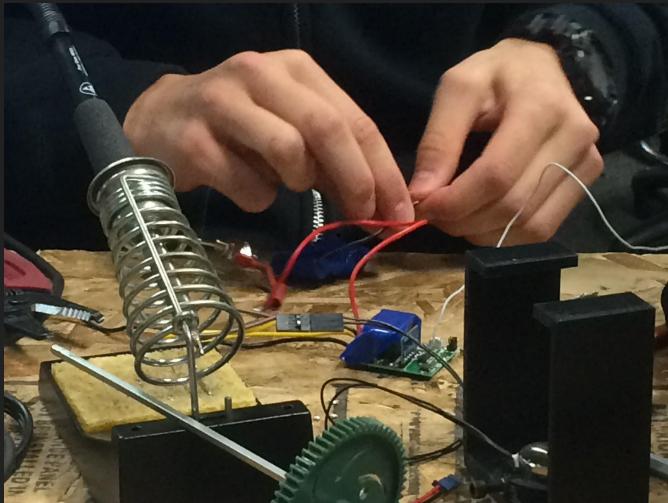


Figure 4.1: Jacob soldering on stronger gauge wires to boost Converter

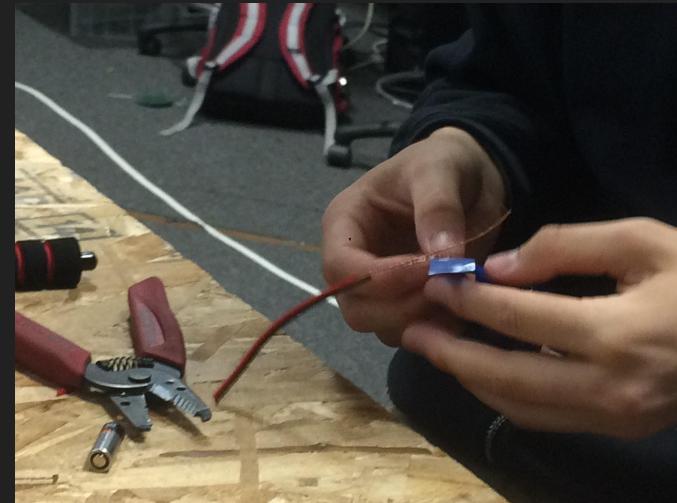


Figure 6.2: More soldering for the wires

Day 31-5/19/17

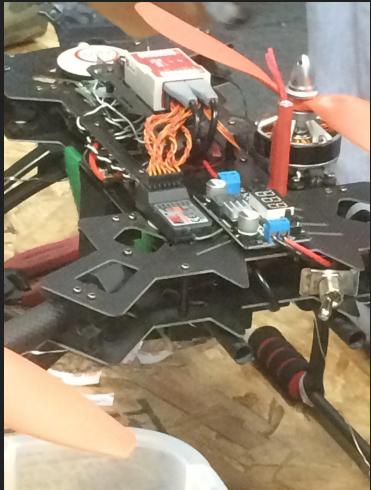


Figure 8.1: Frontal View of Final Drone Build



Figure 8.2: Top Frontal View of the Drone Build

Day 32-5/22/17



Figure 9.1: Side View of Drone Build



Figure 9.2: Side Top View of Drone Build

Day 33-5/24/17



Figure 10.1: New Electromagnet holder-Front View



Figure 10.2: New Electromagnet Holder-Bottom View

Requirements Completed

- 1.The vehicle shall be controlled wirelessly 😊
- 2.The vehicle shall be able to control and monitor yaw, pitch, and roll 😊
- 3.The vehicle shall dock to a charging interface 😊
- 4.The vehicle shall deliver a 1 lb. payload ½ mile away within 3 ft. of its destination 😊
- 5.The charging station shall utilize clean energy 😊
- 6.The charging station must charge wirelessly 😞

Thank You