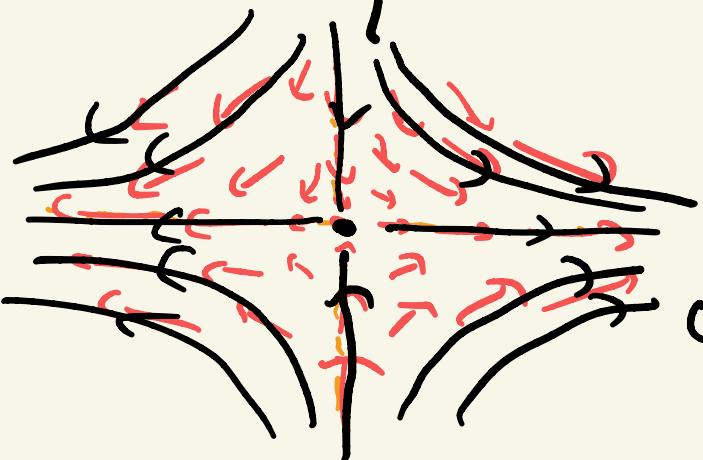


Lecture 23

Ex :

$$\begin{cases} x_1'(t) = 3x_1(t) \\ x_2'(t) = -4x_2(t) \end{cases} \rightarrow \begin{aligned} x_1(t) &= C_1 e^{3t} \\ x_2(t) &= C_2 e^{-4t} \end{aligned}$$



direction field

← at each pt (x, y) draw the vector $(3x, -4y)$

Given $x_1(0), x_2(0)$, soln is
 $(x_1(t), x_2(t)) = (x_1(0) e^{3t}, x_2(0) e^{-4t})$

"phase portrait": draw a sampling of solution curves

$$\underline{\text{Ex}}: \quad \begin{cases} x_1'(t) = -x_1/2 + 7x_2/2 \\ x_2'(t) = 7x_1 - x_2/2 \end{cases} \quad \vec{x} = \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix}$$

$$\vec{x}'(t) = A\vec{x}(t), \quad A = \begin{pmatrix} -1/2 & 7/2 \\ 7 & -1/2 \end{pmatrix}.$$

Ausatz $\vec{x}(t) = e^{rt} \vec{v}$. eval of A ,
evec of A .

char poly $|A - \lambda \mathbb{I}| = \begin{vmatrix} -1/2 - \lambda & 7/2 \\ 7 & -1/2 - \lambda \end{vmatrix} = (4/4 + \lambda)^2 - \frac{49}{4}$

evals: $3, -4$

evecs:

$$\begin{aligned} \lambda = 3: \quad \begin{pmatrix} -1/2 & 7/2 \\ 7 & -1/2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} &= 3 \begin{pmatrix} a \\ b \end{pmatrix} \\ &= \begin{pmatrix} 2 & 7 \\ 7 & 2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} \\ &= (7 + 4)(7 - 3) \end{aligned}$$

$$\rightarrow -1/2 a + 7/2 b = 3a$$

$$\begin{aligned} \Leftrightarrow 7/2 b &= 7/2 a \quad \text{evec } \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ \Leftrightarrow a &= b \end{aligned}$$

$$\lambda = -4 \quad \begin{pmatrix} -11/2 & 7/2 \\ 7/2 & -11/2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = -4 \begin{pmatrix} a \\ b \end{pmatrix} \rightarrow -1/2 a + 7/2 b = -4a$$

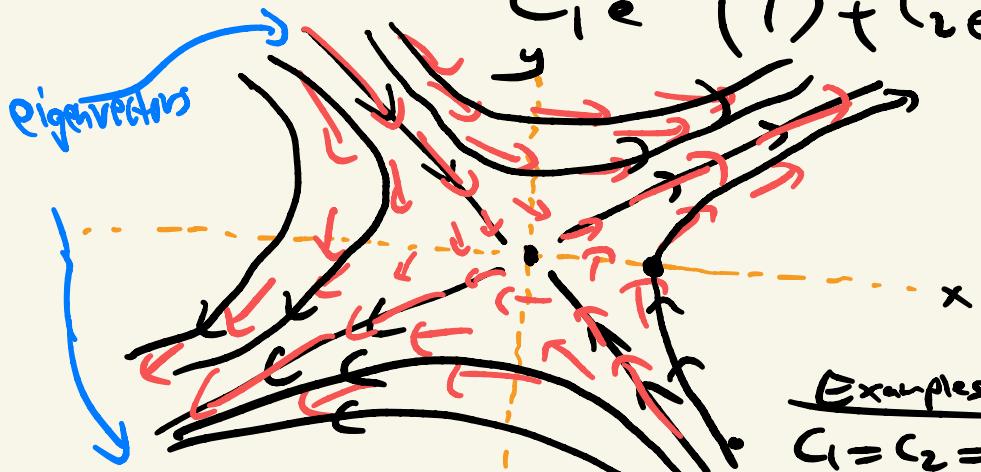
$$-a + 7b = -8a$$

$$7b = -7a$$

$$b = -a$$

vec $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$

General soln:



$$C_1 = C_2 = 1$$

$$(x(t), y(t)) = \left(e^{3t} + e^{-4t}, e^{3t} - e^{-4t} \right)$$

$$\text{at } t=0: (2, 0)$$

direction field: arrow at (x, y) pts in direction $(-11/2x + 7/2y, 7/2x - 11/2y)$

Examples of solutions:

$$C_1 = C_2 = 0 \quad (x(t), y(t)) \equiv (0, 0)$$

$$C_1 = 1, C_2 = 0 \quad (x(t), y(t)) = \left(e^{3t}, e^{3t} \right)$$

$$C_1 = 0, C_2 = 1 \quad (x(t), y(t)) = \left(e^{-4t}, -e^{-4t} \right) \quad \text{lies on line } y=x$$

This picture is called a "saddle point"

(case one pos, one neg eval)

Ex: $\vec{x}'(t) = \underbrace{\begin{pmatrix} -1/2 & 1 \\ -1 & -1/2 \end{pmatrix}}_A \vec{x}(t).$

evals:

$$\begin{vmatrix} -1/2 - \tau & 1 \\ -1 & -1/2 - \tau \end{vmatrix} = (\tau + 1/2)^2 + 1 = \tau^2 + \tau + 5/4$$
$$\tau = \frac{-1 \pm \sqrt{1^2 - 4 \cdot 5/4}}{2}$$

vecs:

$$\tau = -1/2 + i$$

$$\begin{pmatrix} -1/2 & 1 \\ -1 & -1/2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = (-1/2 + i) \begin{pmatrix} a \\ b \end{pmatrix}$$

$$= \frac{-1 \pm \sqrt{-4}}{2} = \frac{-1 \pm 2i}{2}$$
$$= -1/2 \pm i$$

$$\begin{cases} -1/2 a + b = (-1/2 + i) a \\ -a - 1/2 b = (-1/2 + i) b \end{cases} \Rightarrow b = i a$$

can take
evec

$$\begin{pmatrix} 1 \\ i \end{pmatrix}$$

$\tau = -1/2 - i$. Note: if $A \vec{v} = (\alpha + i\beta) \vec{v}$
then $\overline{A} \overline{\vec{v}} = \overline{(\alpha + i\beta)} \overline{\vec{v}}$

take conj
conj of everything

$$\Leftrightarrow A \overline{\vec{v}} = (\alpha - i\beta) \overline{\vec{v}}$$

Upshot:

$$\begin{pmatrix} 1 \\ -i \end{pmatrix}$$

is an eigenvector eval $-1/2 - i$.

So "general solution" $\vec{x}(t) = C_1 e^{(-1/2+i)t} \begin{pmatrix} 1 \\ i \end{pmatrix} + C_2 e^{(-1/2-i)t} \begin{pmatrix} 1 \\ -i \end{pmatrix}$

Not real-valued but can take real and imaginary parts.

Start w/ $e^{(-1/2+i)t} \begin{pmatrix} 1 \\ i \end{pmatrix} = e^{-t/2} e^{it} \begin{pmatrix} 1 \\ i \end{pmatrix}$

(vector valued function)

$$= e^{-t/2} \begin{pmatrix} \cos(t) + i\sin(t) \\ i \end{pmatrix} \begin{pmatrix} 1 \\ i \end{pmatrix}$$

$$= e^{-t/2} \begin{pmatrix} \cos(t) + i\sin(t) \\ i\cos(t) - \sin(t) \end{pmatrix}$$

real part: $e^{-t/2} \begin{pmatrix} \cos(t) \\ -\sin(t) \end{pmatrix}$

imag part: $e^{-t/2} \begin{pmatrix} \sin(t) \\ \cos(t) \end{pmatrix}$

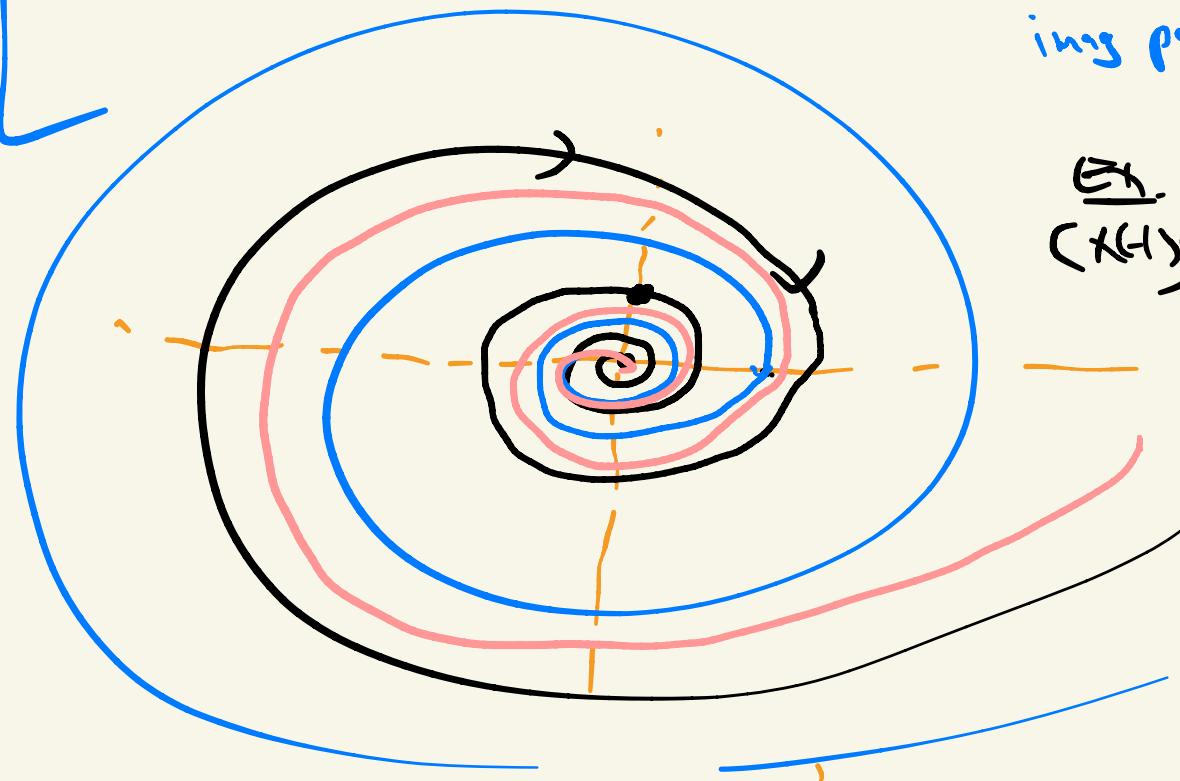
Real-valued general solution:

$$C_1 e^{-t/2} \begin{pmatrix} \cos(t) \\ -\sin(t) \end{pmatrix} + C_2 e^{-t/2} \begin{pmatrix} \sin(t) \\ \cos(t) \end{pmatrix}$$

think: starting $e^{(-\lambda_2 - i)t} \begin{pmatrix} 1 \\ -i \end{pmatrix}$

real part img part

$$e^{-t/2} \begin{pmatrix} \cos(t) \\ \sin(t) \end{pmatrix} - e^{-t/2} \begin{pmatrix} \sin(t) \\ \cos(t) \end{pmatrix}$$

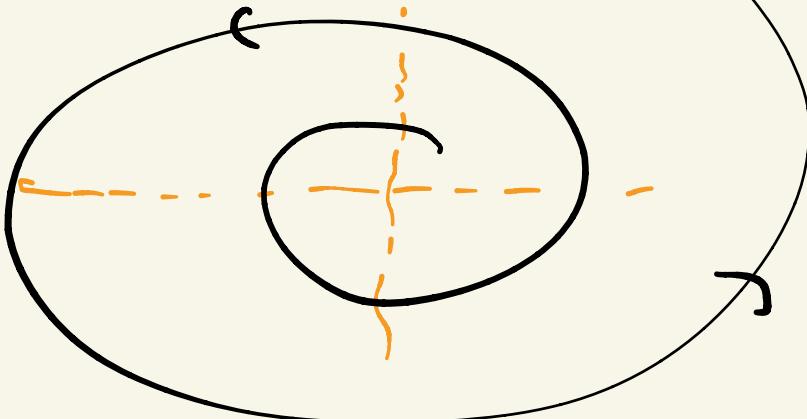


Ex. $C_1 = 0, C_2 = 1$

$$(x(t), y(t)) = \begin{pmatrix} e^{-t/2} \cos(t) \\ e^{-t/2} \sin(t) \end{pmatrix}$$

"spiral point"

Q: Is there a system $\vec{x}'(t) = A\vec{x}(t)$ w/ solution



If A has evals
 $\alpha \pm i\beta$ $\alpha > 0$,
get two-nd picture.

Ex: $\vec{x}'(t) = \begin{pmatrix} -3 & \sqrt{2} \\ \sqrt{2} & -2 \end{pmatrix} \vec{x}(t)$

evals: $\begin{vmatrix} -3-\lambda & \sqrt{2} \\ \sqrt{2} & -2-\lambda \end{vmatrix} = (\lambda+3)(\lambda+2) - 2$
 $= \lambda^2 + 5\lambda + 4$
 $= (\lambda+1)(\lambda+4)$

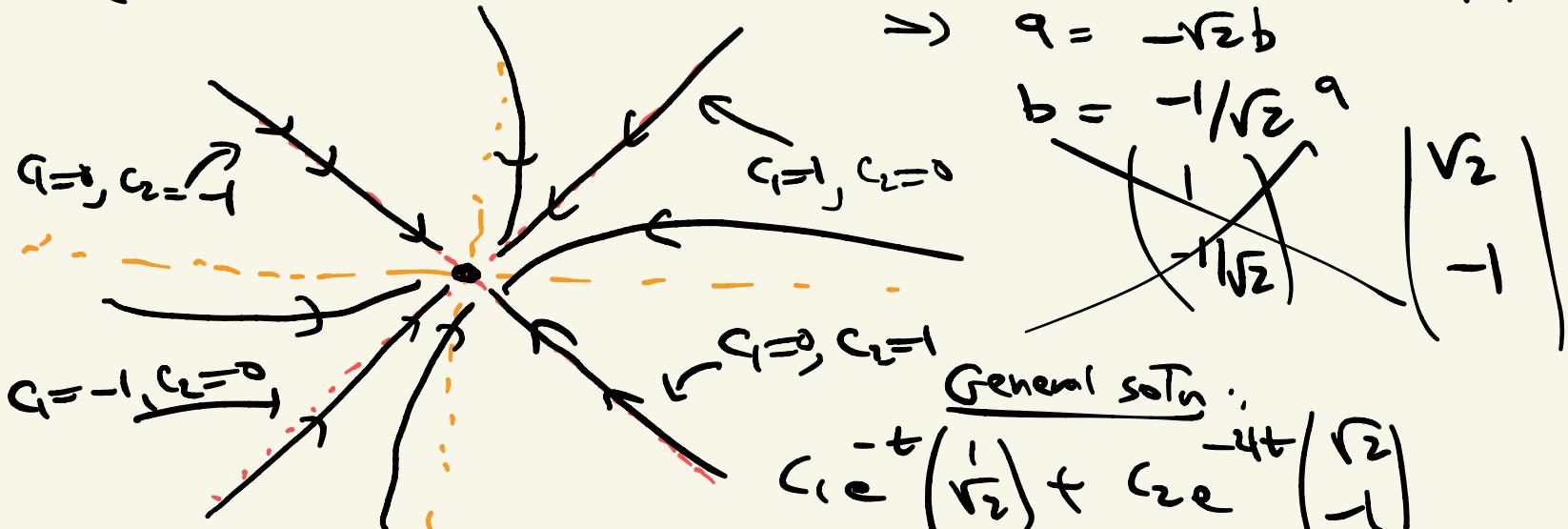
$$\lambda = -1, -4$$

evecs: $\lambda = -1$

$$\begin{pmatrix} -3 & \sqrt{2} \\ \sqrt{2} & -2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = - \begin{pmatrix} a \\ b \end{pmatrix} \rightarrow -3a + \sqrt{2}b = -a \\ -2a = -\sqrt{2}b \\ b = \sqrt{2}a$$

$$\pi = -4$$

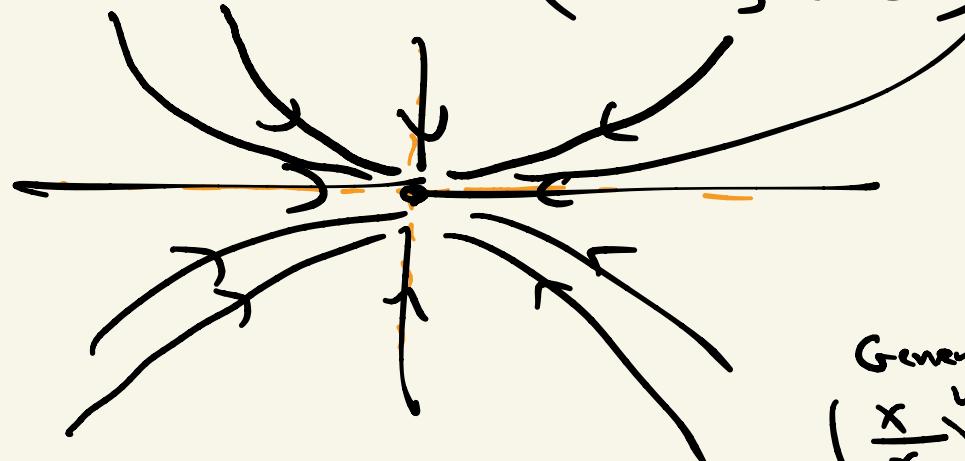
$$\begin{pmatrix} -3 & \sqrt{2} \\ \sqrt{2} & -2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = -4 \begin{pmatrix} a \\ b \end{pmatrix} \rightarrow -3a + \sqrt{2}b = -4a \\ \Rightarrow a = -\sqrt{2}b \\ b = -1/\sqrt{2}a$$



Fact: If A is a symmetric matrix, its eigenvectors are orthogonal.

Analogous system: $\begin{cases} x'(t) = -x(t) \\ y'(t) = -4y(t) \end{cases}$

$$\Rightarrow (x(t), y(t)) = (x_0 e^{-t}, y_0 e^{-4t})$$



"nodal sink"

Ex. - $x_0 = y_0 = 1$

$$(x(t), y(t)) = (e^{-t}, e^{-4t})$$

$$y = x^4$$

General

$$\left(\frac{x}{x_0}\right)^4 = \frac{y}{y_0} \Rightarrow y = \frac{y_0}{x_0^4} x^4$$