

Kyle Wang

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EDUCATION

Northwestern University

Evanston, IL

M.S in Robotics, 2024

Case Western Reserve University

Cleveland, OH

B.S.E in Electrical Engineering, 2023

SKILLS

Robotics: Embedded Systems; Gazebo; OpenCV; Machine Learning; MoveIt; Robot Kinematics; ROS/ROS2; SLAM;

Programming: AWS; CSS; C; C++; Django; GitHub; HTML; Java; Javascript; MATLAB; Python; Unit Testing;

EMPLOYMENT AND PROFESSIONAL EXPERIENCES

Cleanr - Innovation Engineer

Mar - Aug 2023

- Developed a data logger system and website to allow efficient real-time and historical data access
- Prototyped an RFID-based tracker for disposable washing machine pods
- Assisted in designing a washing machine buffer tank to adapt to international pump standards
- Designed a custom microprocessor board for electrical systems, optimizing design, prototyping, and production

Viscofan Collagen USA - Electrical Engineer Intern

May - Aug 2021, Jun - Aug 2022

- Designed a new Programmable Logic Controller and Display system for monitoring and controlling an assembly line
- Designed a Dual-Tank HCl Filling system with multiple control panels for efficient control and operation
- Created power diagrams for one of the buildings and updated old charts to include building renovations
- Created networking diagrams for various components including network switches, PLCs, and computers

Eagle Scout, Boy Scouts of America

Oct 2019

PROJECTS

Light Painting with Drone Swarm (In Progress)

Jan - Mar 2024

- Developed a ROS2 package to control 3 Crazyflie drones to fly specified trajectories for long-exposure photography
- Utilized multi-robot trajectory planning to fly 3 drones in a swarm

Simultaneous Localization and Mapping (SLAM) (In Progress)

Jan - Mar 2024

- Developed an Extended Kalman Filter SLAM algorithm from scratch to use with a Turtlebot 3
- Programmed a C++ Library for calculating the kinematics of the robot along with a simulation environment in RVIZ

Robot Coffee Maker

Nov - Dec 2023

- Worked with a team of 5 to program a 7 DoF Franka Emika Panda robot arm to brew a cup of pour-over coffee
- Built a Python wrapper for the MoveIt 2 package to guide the robot to specified positions, or follow a defined path
- Utilized ROS2, OpenCV, AprilTags, and various features of MoveIt including path constraints and inverse kinematics

KUKA youBot Mobile Manipulation Simulation

Nov - Dec 2023

- Simulated a mobile robot with mecanum wheels and a 5 DoF robotic arm in CoppeliaSim
- Generated a trajectory to manipulate a block, using feed-forward control and a PI controller

CWRUBOTIX Robotics Team, Combat Team Co-Lead

Aug 2021 - May 2023

- Designed a chassis, weapon, and electronics system for a 3 pound combat robot with a full-body spinner type weapon
- Programmed an algorithm to convert a 2-axis control system into instructions for a 3-axis triangular drivetrain

Custom Smart Lamp

January 2022 — May 2022

- Developed an IoT Smart-Lamp using AWS, Raspberry Pi, iOS Apps, MQTT, and Web Frameworks
- Integrated dynamic websites, remote update, analytics, load testing, Bluetooth Low Energy, and security certificates