

# Variational Autoencoder

Ref: [Altosaar blog](#), [Rocca blog](#), [CMU ppt](#), [EM](#), [rose yu slides](#) [Code sample](#)

Post: [Patacchiola](#)

## 0 Bayesian Basics

**likelihood**  
probability distribution of the observed data given a parameter value  
*(how probable are the observed data for this parameter value?)*

**prior**  
probability distribution of the parameter independantly from any observation  
*(prior knowledge: how probable are each value of the parameter before any observation?)*

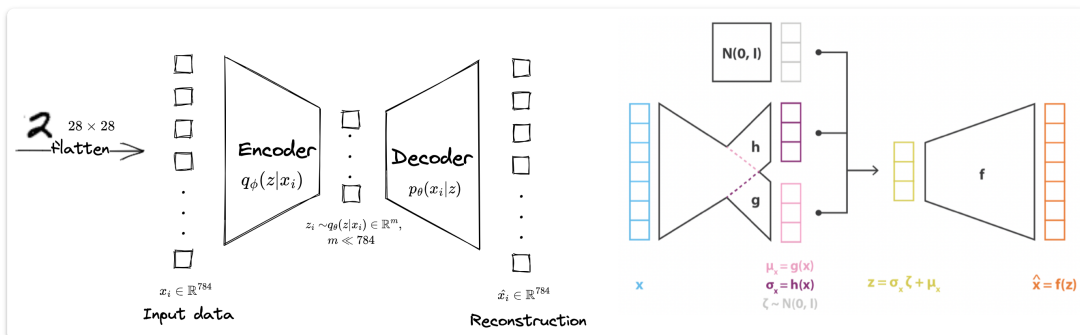
$$p(\theta | x) = \frac{p(x | \theta) p(\theta)}{p(x)}$$

**posterior**  
probability distribution of the parameter given the observed data  
*(updated knowledge: how probable are each value of the parameter given the observed data?)*

**evidence**  
probability distribution of the observed data independantly from any parameter value  
*(how probable is it to observe these particular data?)*

## 1 Architecture & Loss Function

### 1.1 Architecture



### 1.2 Loss

The loss  $L_i$  generated by one training sample  $x_i$  is defined as

$$L_i(\theta, \phi) = - \underbrace{\mathbb{E}_{z \sim q_\theta(z|x_i)} \log p_\phi(x_i|z)}_{\text{term1: Recon. loss}} + \underbrace{KL(q_\theta(z|x_i), p(z))}_{\text{term2: Disentanglement}}$$

- $p_\phi(x_i|z)$ : **Likelihood** of decoder regenerating the i-th input data  $x_i$ , given latent variable  $z_i$
- $q_\theta(z_i)$ : **Posterior** probability distribution of latent variable  $z_i$ , given i-th input data  $x_i$
- $p(z) = N(0, 1)$ : **Prior**. We assume the ground-truth distribution of latent variable  $z_i$  to be a standard normal distribution.
- Term1 - Reconstruction loss**: Expected neg-log-likelihood of i-the input data  $x_i$ . (Given an input data  $x_i$  and encoder output  $z_i$ , we want to maximize the likelihood of decoder regenerating  $x_i$ ). This can be effectively replaced by MSE loss when actually implementing the loss:

```
x_hat = model.decoder.forward(model.encoder.forward(x))
loss_recon = nn.functional.mse_loss(x_hat, x)
```

language-python

- **Term2 - KL divergence:** We want to regularize the latent variable distribution such that it's close to a standard normal distribution.

$$KL(q_{\theta}(z|x_i), p(z)) = KL(N(\mu, \sigma), N(0, 1))$$

$$= \frac{1}{2} \sum_{i=1}^d \left( 1 + \log \sigma_j^2 - \mu_j^2 - \sigma_j \right)$$

```
def loss_function(self, *args, **kwargs) -> dict:

    recons = args[0]
    input = args[1]
    mu = args[2]
    log_var = args[3] # sigma

    kld_weight = kwargs['M_N'] # Account for the minibatch samples from
the dataset
    recons_loss =F.mse_loss(recons, input)
    kld_loss = torch.mean(-0.5 * torch.sum(1 + log_var - mu ** 2 -
log_var.exp(), dim = 1), dim = 0)

    loss = recons_loss + kld_weight * kld_loss

    return {'loss': loss, 'Reconstruction_Loss':recons_loss.detach(),
'KLD':-kld_loss.detach()}
```

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## 1.3 Re-parameterization Trick

(TODO)

## 2 ELBO - Evidence Lower Bound

Recall the [encoder-decoder view](#) of dimensionality reduction. We'll use the following notation:

- $x$ : Input data (e.g. an image);  $z$ : Encoded data
- $\theta$ : Decoder model parameters;  $\phi$ : Encoder model parameters

Our goal is to maximize the likelihood of the decoder regenerating  $x$ . Which, expressed in terms of log-likelihood, is:

$$\operatorname{argmax}_{\theta} \log p_{\theta}(x)$$

To find  $q_{\phi}(\cdot)$  that best approximates  $p_{\theta}(\cdot)$ , we can just minimize their [KL divergence](#), which essentially evaluates how closely two probability distribution functions (PDFs) resembles each other. Therefore we attempt to derive  $KL(q_{\phi}(\cdot), p_{\theta}(\cdot))$ . From the definition of KL divergence:

$$KL(q_{\phi}(z|x), p_{\theta}(z|x)) = \mathbb{E}_{q_{\phi}} \log \frac{q_{\phi}(z|x)}{p_{\theta}(z|x)}$$

Now our goal is to approximate the intractable  $p_\theta(z|x)$ . We start by evaluating the  $KL$  divergence, using [expectation of a function of RV](#) along the way:

$$\begin{aligned}
 KL(q_\phi(z|x), p_\theta(z|x)) &= \mathbb{E}_{q_\phi} \log \frac{q_\phi(z|x)}{p_\theta(z|x)} \\
 &= \mathbb{E}_{q_\phi} \log q_\phi(z|x) - \mathbb{E}_{q_\phi} \log p_\theta(z|x) && (\text{log property}) \\
 &= \mathbb{E}_{q_\phi} \log q_\phi(z|x) - \mathbb{E}_{q_\phi} \log \frac{p_{\theta_1}(z, x)}{p_{\theta_2}(x)} && (\text{Bayes rule}) \\
 &= \mathbb{E}_{q_\phi} \log q_\phi(z|x) - \mathbb{E}_{q_\phi} \log p_{\theta_1}(z, x) + \underbrace{\mathbb{E}_{z \sim q_\phi} \log p_{\theta_2}(x)}_{g(z)} \\
 &= \mathbb{E}_{q_\phi} \log q_\phi(z|x) - \mathbb{E}_{q_\phi} \log p_{\theta_1}(z, x) + \int \log(p_{\theta_2}(x)) q_\phi(z|x) dz && (\mathbb{E} \text{ of } g(z)) \\
 &= \mathbb{E}_{q_\phi} \log q_\phi(z|x) - \mathbb{E}_{q_\phi} \log p_{\theta_1}(z, x) + \log p_{\theta_2}(x) \int q_\phi(z|x) dz \quad \nearrow^1
 \end{aligned}$$

Rearranging, we can express  $\log p_{\theta_2}(x)$  as:

$$\log p_{\theta_2}(x_i) = KL(q_\phi(z|x_i), p_\theta(z|x_i)) + \underbrace{\mathbb{E}_{q_\phi} \log \frac{p_\theta(z, x_i)}{q_\phi(z|x_i)}}_{\text{ELBO}}$$

Which is intractable since we need exponential time to evaluate  $p_{\theta_2}(x) = \int p(x|z)p(z)dz$  (over all configuration of the latent variable  $z$ ). But, since  $KL(q_\phi, p_\theta) \geq 0$  (can prove using [Jensen's inequality](#)), we've found a lower bound of  $\log p_{\theta_2}(x)$ :

$$\log p_{\theta_2}(x_i) \geq \underbrace{\mathbb{E}_{q_\phi} \log \frac{p_\theta(z, x_i)}{q_\phi(z|x_i)}}_{\text{ELBO}}$$

The ELBO is short for "**evidence lower bound**", i.e. the lower bound of the approximated posterior  $p_\theta(x)$ . Therefore we can **maximize** ELBO in order to maximize  $\log p_\theta(x)$ :

$$\begin{aligned}
 \text{ELBO} &= \mathbb{E}_{q_\phi} \log \frac{p_\theta(z, x_i)}{q_\phi(z|x_i)} \\
 &= \mathbb{E}_{q_\phi} \log \frac{p_\theta(x_i|z)p(z)}{q_\phi(z|x_i)} = \mathbb{E}_{q_\phi} \log p_\theta(x_i|z) - \mathbb{E}_{q_\phi} \frac{q_\phi(z|x_i)}{p(z)} \\
 &= \mathbb{E}_{q_\phi} \log p_\theta(x_i|z) - KL(q_\phi(z|x_i)|p(z))
 \end{aligned}$$

$$L(\theta, \phi; x_i) = -\text{ELBO} = -\mathbb{E}_{q_\phi} \log p_\theta(x_i|z) + KL(q_\phi(z|x_i)|p(z))$$

### 3 Question

Since  $p_\theta(x|z)$  is the decoder output, it makes sense by definition, but what is  $p_\theta(z|x)$ ?

- We can see it as the "ground truth" posterior