

## Senses

What's Inside?

## Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

## Haptic Exploration

What's Inside?

Exploratory Procedures

Types of Sensing

## Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

Workspace vs Force

Haptic Wearables?

## Readings

Thursday

# Wearable Technologies and Applications (Wearable Informatics)

Winfree

## Lecture 3

# What's Inside?

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## Senses

[What's Inside?](#)

## Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

## Haptic Exploration

[What's Inside?](#)

[Exploratory Procedures](#)

[Types of Sensing](#)

## Haptic Devices

[Tactile and Proprioceptive Devices](#)

[Tactile Device Challenges](#)

[Kinesthetic Device Challenges](#)

[Workspace vs Force](#)

[Haptic Wearables?](#)

## Readings

Thursday

# Five Senses, Which is Most Important to You?

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(EE499/EE599)

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## Senses

[What's Inside?](#)

### Define

[Defined: Haptic](#)

[Defined: \(Opt\)ics](#)

[Defined: Haptics](#)

### Haptic Exploration

[What's Inside?](#)

[Exploratory Procedures](#)

[Types of Sensing](#)

### Haptic Devices

[Tactile and Proprioceptive Devices](#)

[Tactile Device Challenges](#)

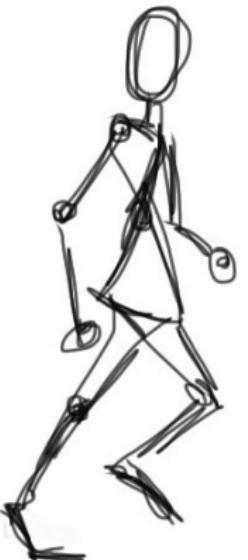
[Kinesthetic Device Challenges](#)

[Workspace vs Force](#)

[Haptic Wearables?](#)

### Readings

[Thursday](#)



- ▶ Hearing?
  - ▶ Sight?
  - ▶ Smell?
  - ▶ Taste?
  - ▶ Touch?
- 
- ▶ Which of these seems the most valuable to you?
  - ▶ Which would you relinquish last?

# Five Senses, Which is Most Important to You?

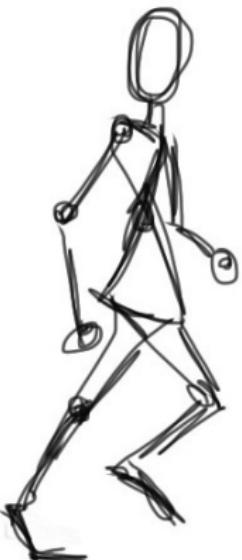
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(EE499/EE599)

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## Sight



- ▶ Centralized
- ▶ Broad
- ▶ Passive
- ▶ Cognitive



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[What's Inside?](#)

### Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

### Haptic Exploration

[What's Inside?](#)

[Exploratory Procedures](#)

[Types of Sensing](#)

### Haptic Devices

[Tactile and Proprioceptive Devices](#)

[Tactile Device Challenges](#)

[Kinesthetic Device Challenges](#)

[Workspace vs Force](#)

[Haptic Wearables?](#)

### Readings

[Thursday](#)

# Five Senses, Which is Most Important to You?

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(EE499/EE599)

Winfree

## Sight

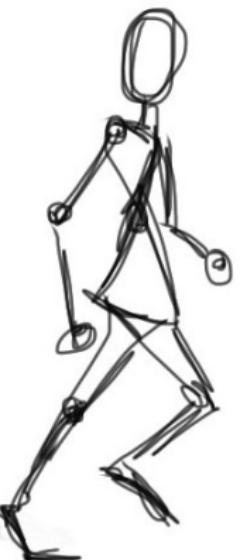


- ▶ Centralized
- ▶ Broad
- ▶ Passive
- ▶ Cognitive

## Touch



- ▶ Distributed
- ▶ Narrow
- ▶ Interactive
- ▶ Fundamental



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What's Inside?

### Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

### Haptic Exploration

What's Inside?

Exploratory Procedures

Types of Sensing

### Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

Workspace vs Force

Haptic Wearables?

### Readings

Thursday

# What is Haptics?

INF632  
(EE499/EE599)

Winfree

## Senses

What's Inside?

## Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

## Haptic Exploration

What's Inside?

Exploratory Procedures

Types of Sensing

## Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

Workspace vs Force

Haptic Wearables?

## Readings

Thursday

## Definition

haptic

**adjective**

1. of or relating to the sense of touch, in particular relating to the perception and manipulation of objects using the senses of touch and proprioception.

## origin

1. late 19th century: from Greek *haptikos* ‘able to touch or grasp,’ from *haptein* ‘fasten.’

# What is (Opt / Informat)ics?

## Definition

optics

**plural noun**

1. the scientific study of sight and the behavior of light, or the properties of transmission and deflection of other forms of radiation.

## Definition

in•for•mat•ics

**plural noun**

1. the science of processing data for storage and retrieval; informatics science

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What's Inside?

## Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

## Haptic Exploration

What's Inside?

Exploratory Procedures

Types of Sensing

## Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

Workspace vs Force

Haptic Wearables?

## Readings

Thursday

## What's Inside?

### Senses

What's Inside?

### Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

### Haptic Exploration

What's Inside?

Exploratory Procedures

Types of Sensing

### Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

Workspace vs Force

Haptic Wearables?

### Readings

Thursday

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INF632  
(EE499/EE599)

Winfree

## Senses

What's Inside?

## Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics



## Haptic Exploration

What's Inside?

Exploratory Procedures

Types of Sensing

## Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

Workspace vs Force

Haptic Wearables?

## Readings

Thursday

# What's Inside?

INF632  
(EE499/EE599)

Winfree



## Senses

What's Inside?

## Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

## Haptic Exploration

What's Inside?

Exploratory Procedures

Types of Sensing

## Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

Workspace vs Force

Haptic Wearables?

## Readings

Thursday

# Exploratory Procedures

INF632  
(EE499/EE599)

Winfree

## Senses

What's Inside?

## Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

## Haptic Exploration

What's Inside?

### Exploratory Procedures

Types of Sensing

## Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

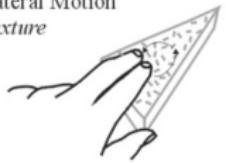
Workspace vs Force

Haptic Wearables?

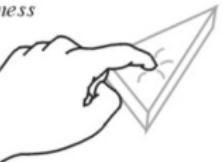
## Readings

Thursday

Lateral Motion  
Texture



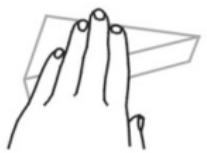
Pressure  
Hardness



Enclosure  
Global shape/Volume



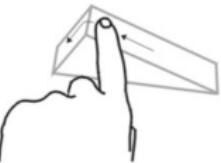
Static Contact  
Temperature



Unsupported Holding  
Weight



Contour Following  
Shape



# Types of Sensing

Cutaneous / Tactile  
Stems from skin contact



Kinesthetic / Proprioceptive  
Stems from body movement

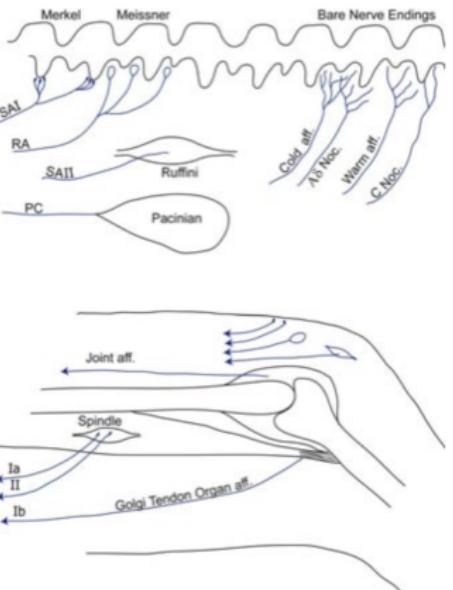


Illustration by A. M. Okamura.

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What's Inside?

## Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

## Haptic Exploration

What's Inside?

Exploratory Procedures

### Types of Sensing

## Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

Workspace vs Force

Haptic Wearables?

## Readings

Thursday

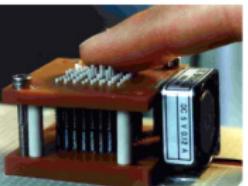
# Tactile and Proprioceptive Devices

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## Haptic Interfaces

### Tactile Devices



Stimulate skin to create contact sensations



## Hybrid Devices

Attempt to combine tactile and kinesthetic feedback



### Kinesthetic Devices

Apply forces to guide or inhibit body movement

## Senses

[What's Inside?](#)

## Define

[Defined: Haptic](#)

[Defined: \(Opt\)ics](#)

[Defined: Haptics](#)

## Haptic Exploration

[What's Inside?](#)

[Exploratory Procedures](#)

[Types of Sensing](#)

## Haptic Devices

[Tactile and Proprioceptive Devices](#)

[Tactile Device Challenges](#)

[Kinesthetic Device Challenges](#)

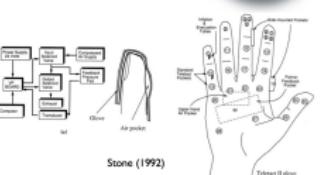
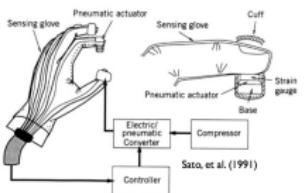
[Workspace vs Force](#)

[Haptic Wearables?](#)

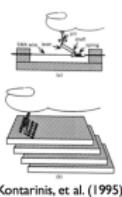
## Readings

[Thursday](#)

# Tactile Device Challenges



Wagner &amp; Howe (2002)



Kontarinis, et al. (1995)

- ▶ Stimulation density needs to be high.
- ▶ Multimodal sensations are very hard to overlay.
- ▶ High complexity and weight diminish portability.
- ▶ Passive touch does not feel real.
- ▶ Tactile device design is difficult!

## Senses

[What's Inside?](#)

## Define

[Defined: Haptic](#)

[Defined: \(Opt\)ics](#)

[Defined: Haptics](#)

## Haptic Exploration

[What's Inside?](#)

[Exploratory Procedures](#)

[Types of Sensing](#)

## Haptic Devices

[Tactile and Proprioceptive Devices](#)

### Tactile Device Challenges

[Kinesthetic Device Challenges](#)

[Workspace vs Force](#)

[Haptic Wearables?](#)

## Readings

[Thursday](#)

# Kinesthetic Device Challenges

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- ▶ Competing goals of high stiffness and low mass.
- ▶ Force feedback feels soft - “Nerfworld”.
- ▶ Point based interactions are overly simple.
- ▶ High quality devices are expensive.
- ▶ Limited workspace.
- ▶ Constrained to a desk!

Senses

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Haptic Exploration

What's Inside?

Exploratory Procedures

Types of Sensing

Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

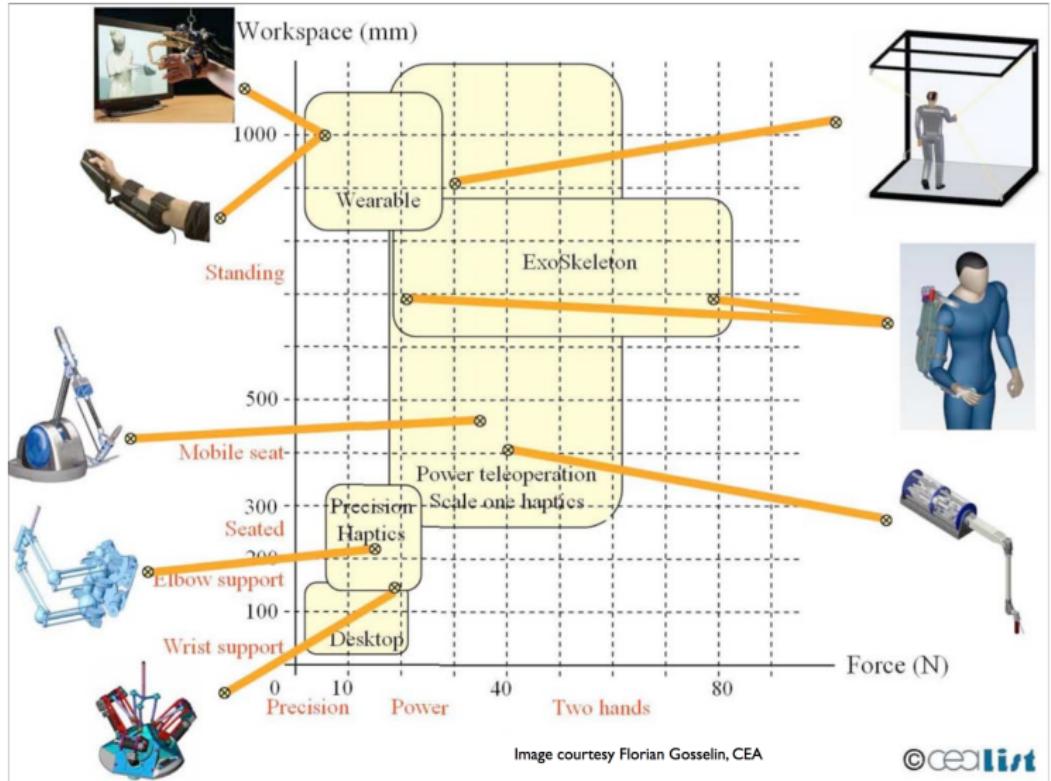
Workspace vs Force

Haptic Wearables?

Readings

Thursday

# Workspace vs Force



## Senses

[What's Inside?](#)

## Define

[Defined: Haptic](#)

[Defined: \(Opt\)ics](#)

[Defined: Haptics](#)

## Haptic Exploration

[What's Inside?](#)

[Exploratory Procedures](#)

[Types of Sensing](#)

## Haptic Devices

[Tactile and Proprioceptive Devices](#)

[Tactile Device Challenges](#)

[Kinesthetic Device Challenges](#)

[Workspace vs Force](#)

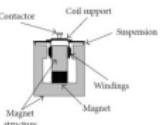
[Haptic Wearables?](#)

## Readings

[Thursday](#)

# But what can you do with haptic wearables?

- ▶ Vibration (eccentric mass motor or tactor)
- ▶ Skin stretch
- ▶ Kinesthetic force
- ▶ Inertial changes



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Defined: Haptics

## Haptic Exploration

What's Inside?

Exploratory Procedures

Types of Sensing

## Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

Workspace vs Force

Haptic Wearables?

## Readings

Thursday

## Senses

[What's Inside?](#)

## Define

[Defined: Haptic](#)

[Defined: \(Opt\)ics](#)

[Defined: Haptics](#)

## Haptic Exploration

[What's Inside?](#)

[Exploratory Procedures](#)

[Types of Sensing](#)

## Haptic Devices

[Tactile and Proprioceptive Devices](#)

[Tactile Device Challenges](#)

[Kinesthetic Device Challenges](#)

[Workspace vs Force](#)

[Haptic Wearables?](#)

## Readings

[Thursday](#)

## Senses

What's Inside?

## Define

Defined: Haptic

Defined: (Opt)ics

Defined: Haptics

## Haptic Exploration

What's Inside?

Exploratory Procedures

Types of Sensing

## Haptic Devices

Tactile and Proprioceptive Devices

Tactile Device Challenges

Kinesthetic Device Challenges

Workspace vs Force

Haptic Wearables?

## Readings

Thursday