

OBJECT DETECTION USING HAAR CASCADE

CS512 Computer Vision
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BACKGROUND

Objective: detection of self-defined object

Traditional object detection:

Background & Foreground segmentation

Geometric properties (size, shape,
position, etc. of the object)

Drawbacks:

Uncontrollable and unexpected interferences from external environment

-Shifted light and shadows

-Interrupt of smoke, rain or the other layers

-...

Research paper: Fares Jalled et al., Object Detection Using Image Processing

HAAR-LIKE FEATURES

Similar to convolution kernels



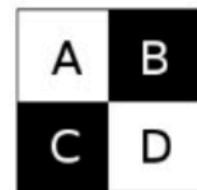
$$f_0(x) = A$$



$$f_3(x) = f_4(x) = B - A - C$$

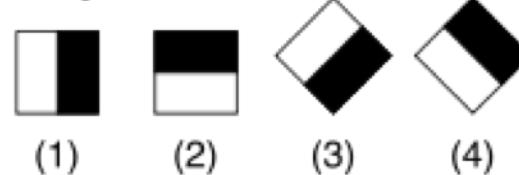


$$f_1(x) = f_2(x) = B - A$$

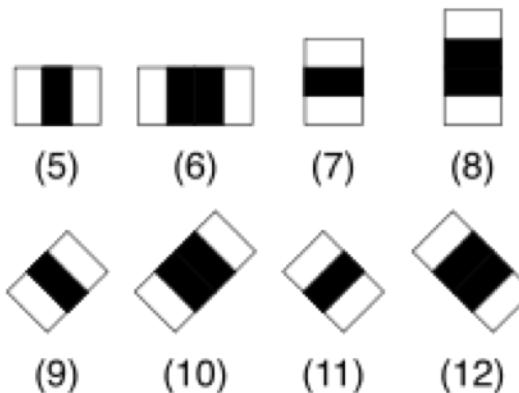


$$f_5(x) = B + C - A - D$$

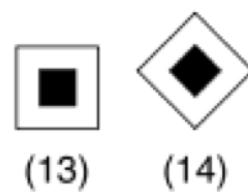
Edge Features



Line Features



Center-surround Features



THE VOILA JONES FRAMEWORK

Problem: huge number of Haar cascade features in the window.

Integral Image

$$ii(x, y) = \sum_{x' \leq x; y' \leq y} i(x', y')$$

$$\sum_{(x,y) \in ABCD} i(x,y) = ii(D) - ii(B) - ii(C) + ii(A)$$

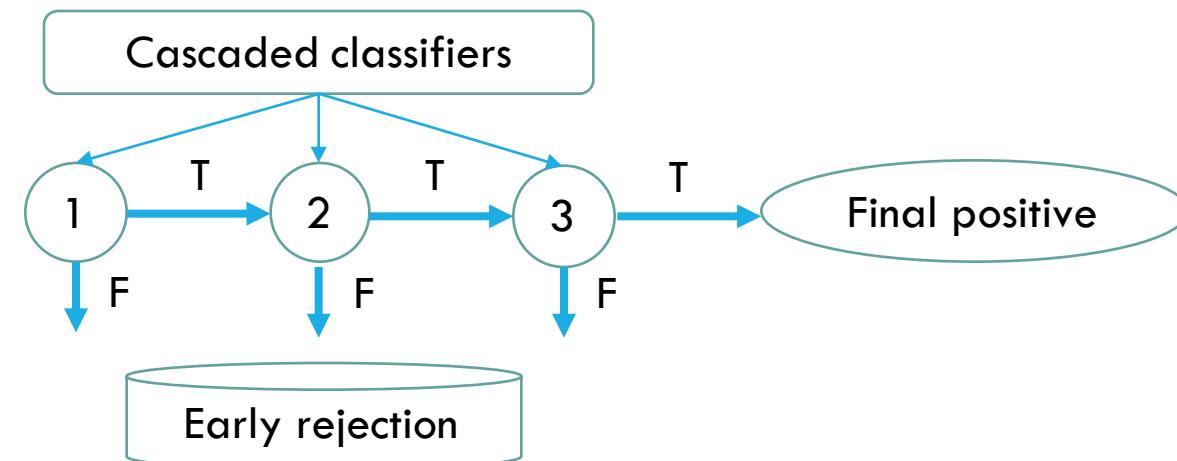
Compute the Haar feature in $O(1)$ time.

Adaboost

$$F(x) = \alpha_1 f_1(x) + \alpha_2 f_2(x) + \dots + \alpha_n f_n(x)$$

Combines the weak classifiers.

Cascading



SAMPLES

2414 negative samples (100 x 100)



1.jpg



4.jpg



5.jpg



6.jpg



7.jpg



10.jpg



12.jpg



13.jpg



16.jpg



17.jpg



22.jpg



23.jpg



24.jpg



27.jpg



29.jpg



33.jpg



34.jpg



36.jpg



37.jpg



38.jpg

1 “real” positive sample (50 x 50)



hand.jpg



phone.jpg



watch.jpg



2414 artificial positive samples



TRAINING

10-15 stages of strong cascade classifiers have been trained.

```
Precalculation time: 7
+-----+-----+
| N | HR | FA |
+-----+-----+
| 1 | 1 | 1 |
+-----+-----+
| 2 | 1 | 1 |
+-----+-----+
| 3 | 1 | 1 |
+-----+-----+
| 4 | 1 | 0.998889 |
+-----+-----+
...
...
...
+-----+-----+
| 96 | 0.995556 | 0.697778 |
+-----+-----+
| 97 | 0.995556 | 0.67 |
+-----+-----+
| 98 | 0.995556 | 0.633333 |
+-----+-----+
| 99 | 0.995556 | 0.652222 |
+-----+-----+
100 | 0.995556 | 0.63 |
```

Hit ratio

Each stage must validate all objects

False alarm ratio

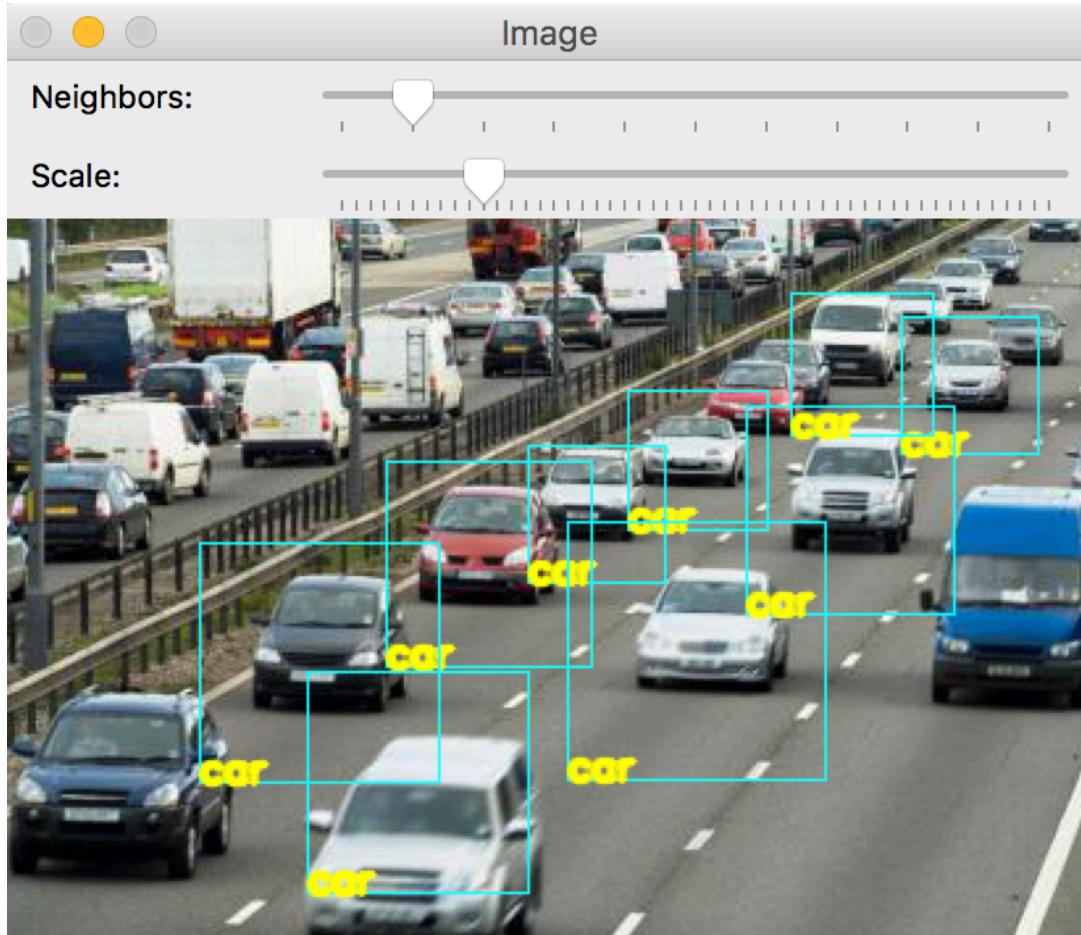
Also produces many false positives



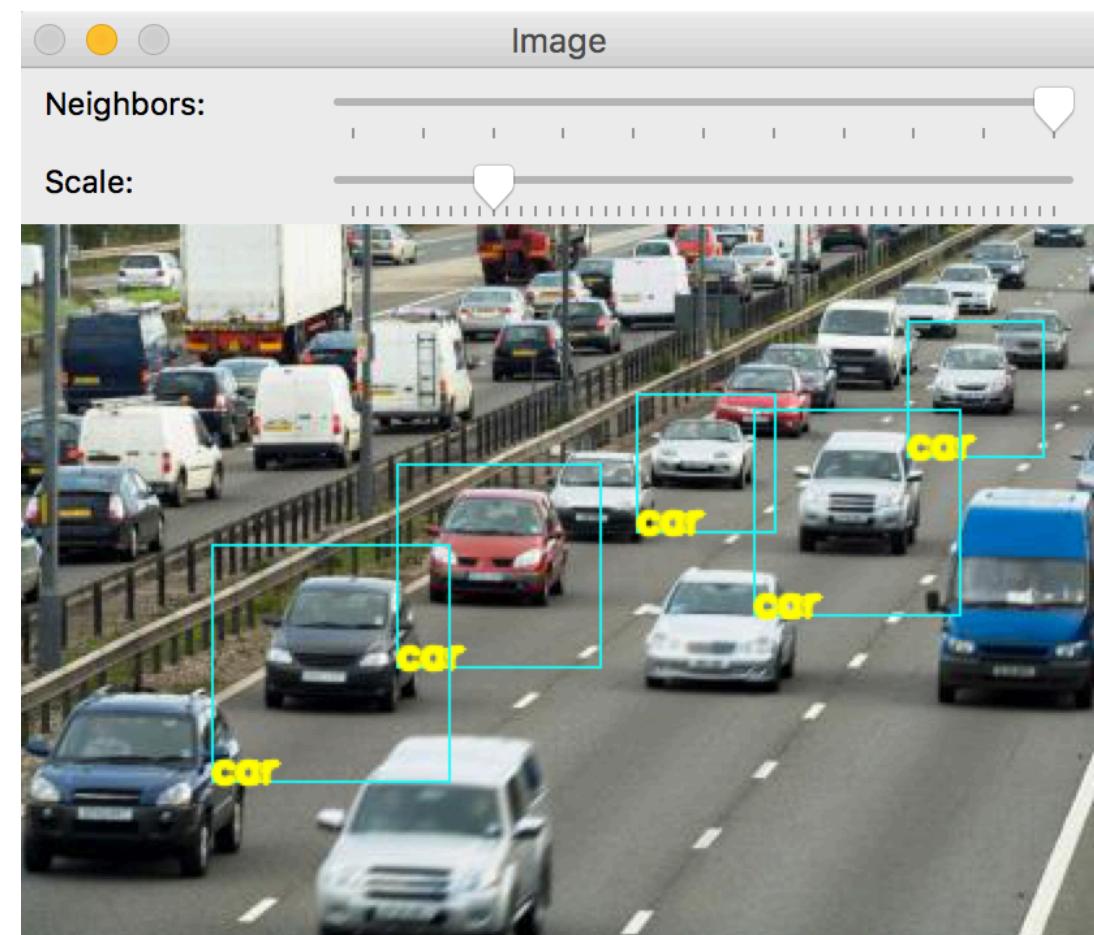
		cascade.xml
▶		stage0.xml
▶		stage1.xml
▶		stage2.xml
		stage3.xml
▶		stage4.xml
▶		stage5.xml
▶		stage6.xml
▶		stage7.xml
▶		stage8.xml
		stage9.xml

Haar cascade classifiers

PROGRAM

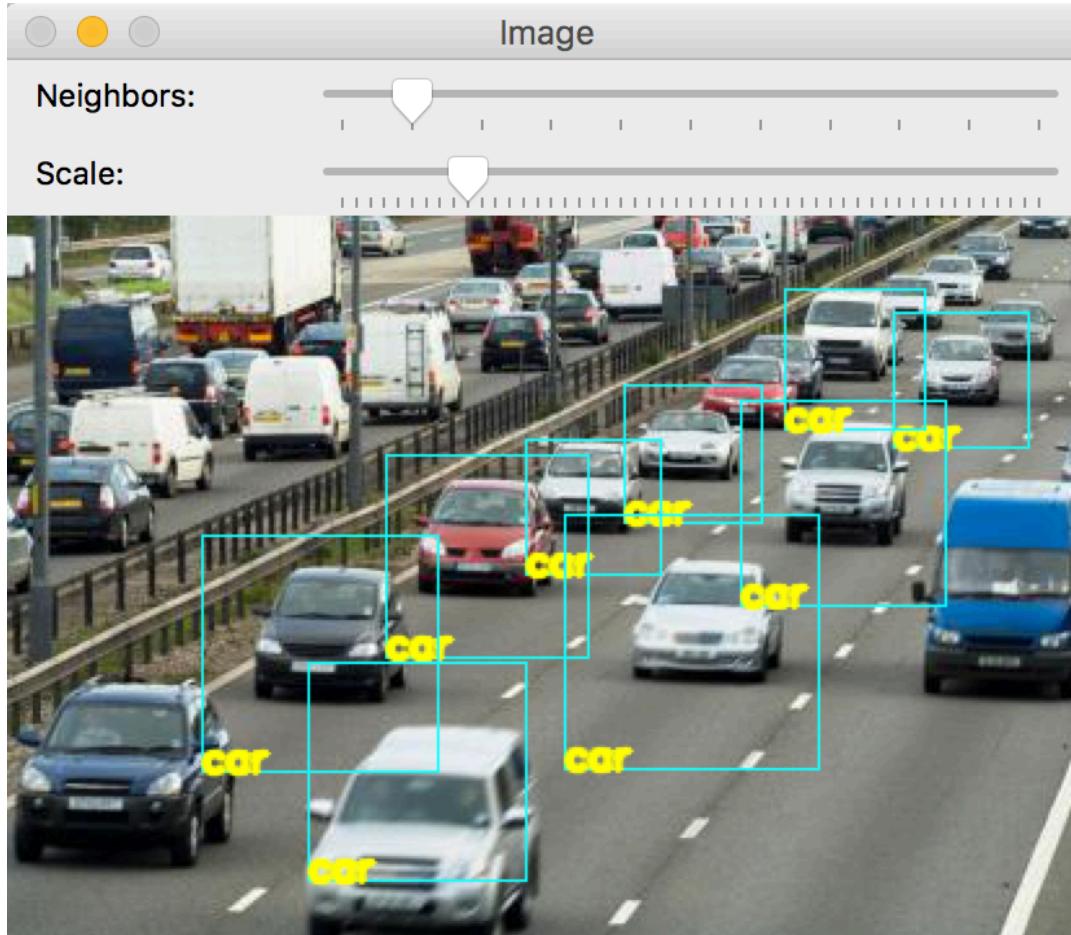


minNeighbors = 1, scale = 1.1

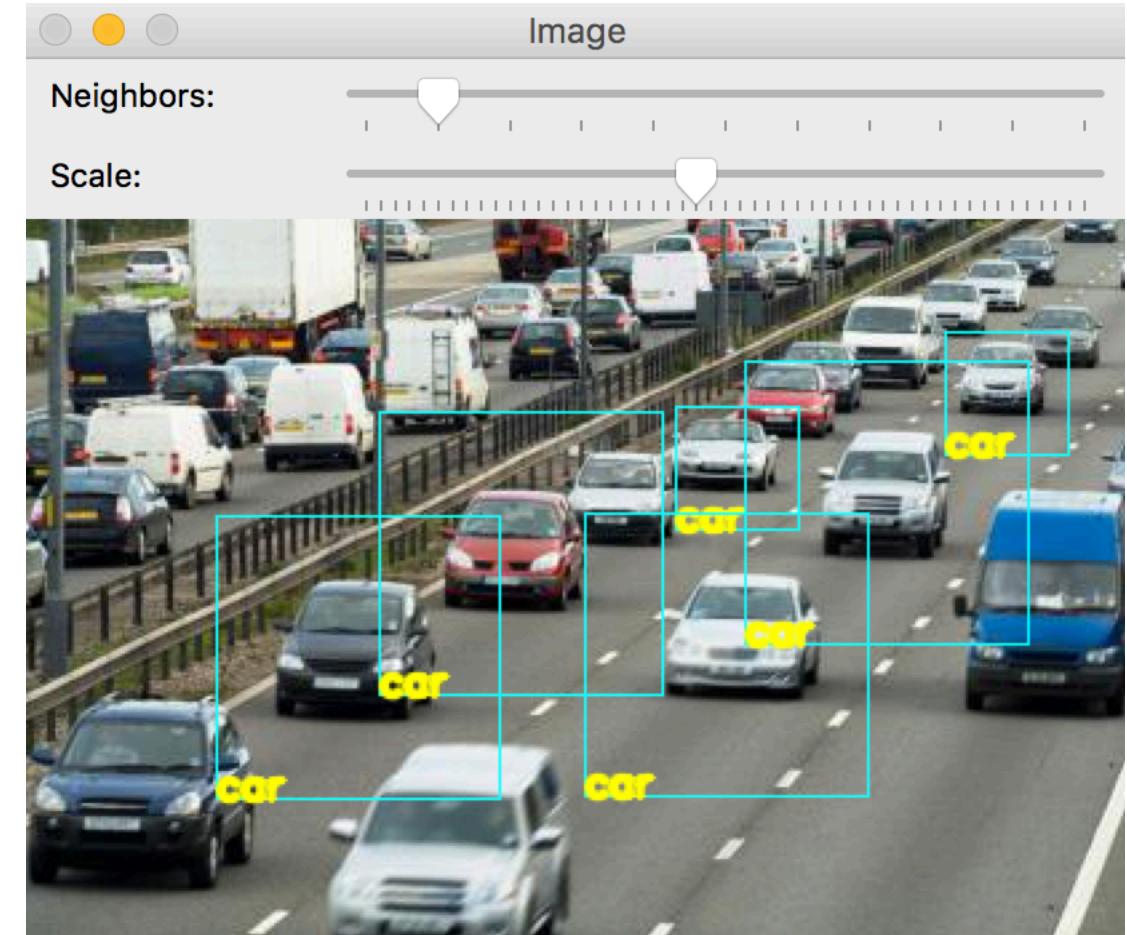


minNeighbors = 1, scale = 3.0

PROGRAM

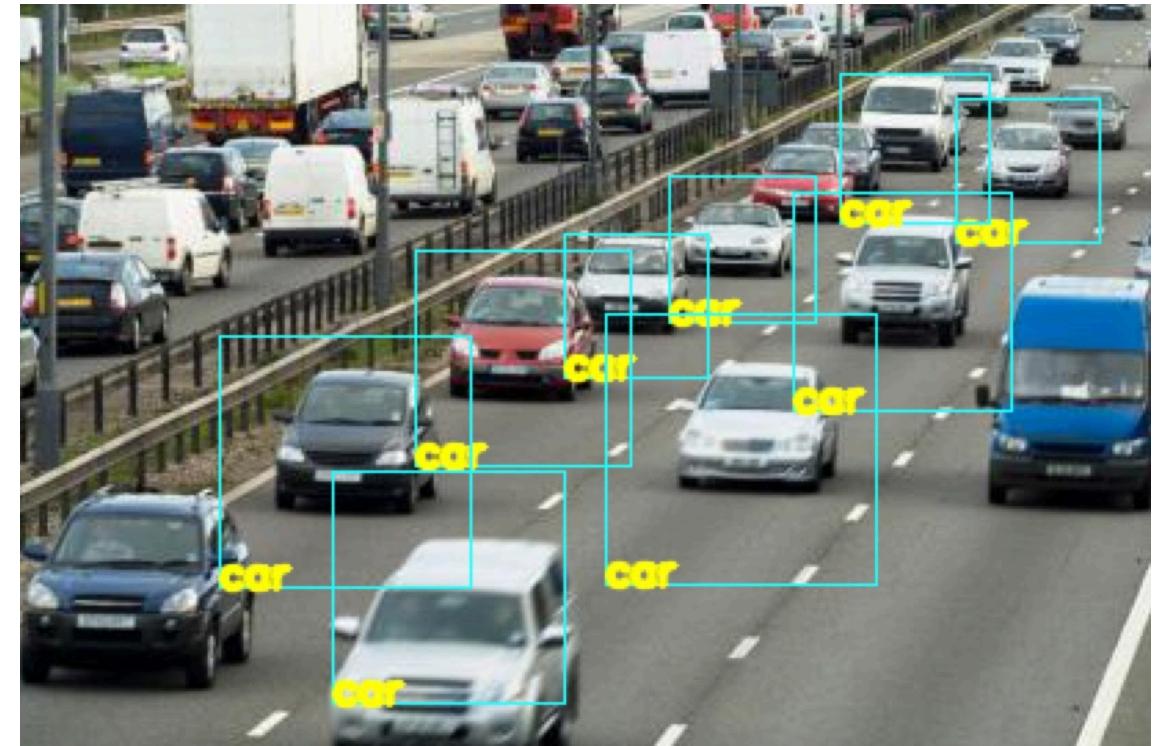
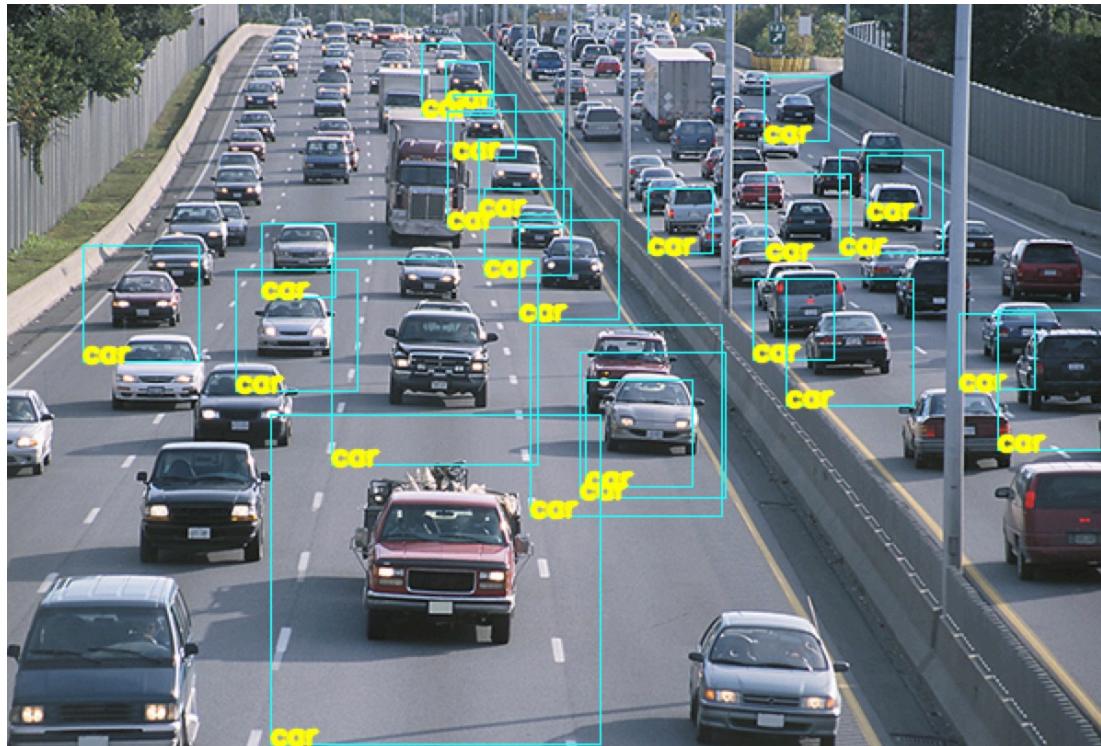


minNeighbors = 1, scale = 1.1

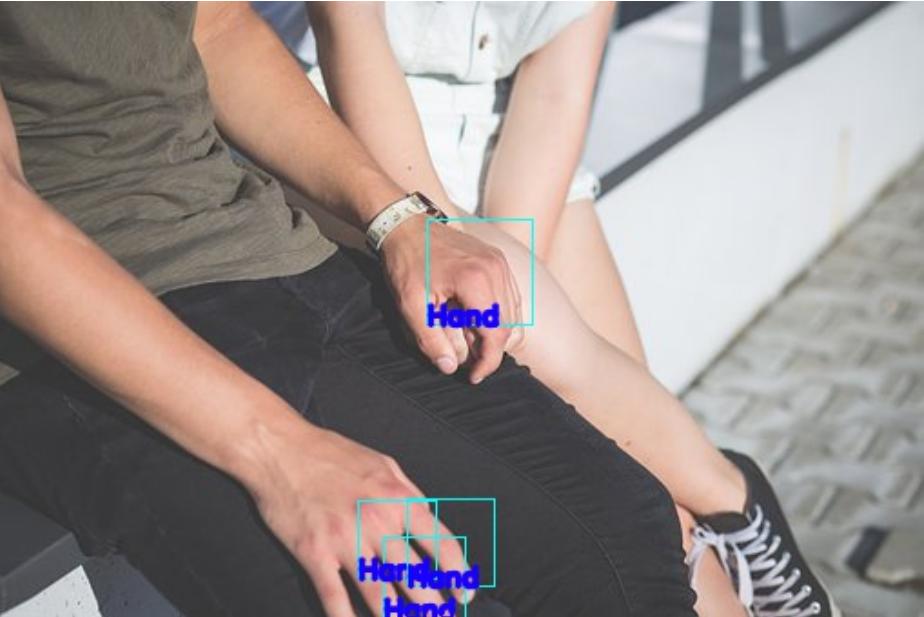


minNeighbors = 10, scale = 1.1

RESULTS



RESULTS



CONCLUSION

Pros

- Can generalize to any kind of object
- Efficient (eliminate false region quickly)

Cons

- High false positive rate (when the parameters not well tuned)
- Lowering bias while increasing variance

REFERENCE

- [1] Fares Jalled et al., Object Detection Using Image Processing
- [2]https://docs.opencv.org/2.4.13.2/modules/objdetect/doc/cascade_classification.html
- [3] ir.library.louisville.edu/cgi/viewcontent.cgi?article = 2731&context = etd



Thank you.