

Project Requirements: Automated Warehouse Management

1 Project Overview

The goal of this project is to create a multi-threaded, concurrent simulation of an automated warehouse. The simulation will manage autonomous robots, charging stations, a parts inventory, and a queue of part requests, all running in parallel. The system must be resilient, manage shared resources in a thread-safe manner, handle errors gracefully using specific Java exception handling patterns, and provide a live-monitoring GUI.

2 Functional Requirements

2.1 FR-1: Core Simulation & System Components

- The simulation must be **multi-threaded**, with a central `ExecutorService` managing the lifecycle of all active components.
- A central `Warehouse` class shall contain and manage all other components and shared resources.
- **Storage Management System:** An `Inventory` class must manage a collection of `Part` objects and their quantities. It must support fast part lookups by `partID` string.
- **Task Management System:** A `PartRequestManager` must manage a thread-safe queue of incoming tasks (`PartRequest`).

2.2 FR-2: Entities & State Models

- **Robot (Runnable):** Must run on its own thread.
 - Must have a `batteryLevel` (0-100).
 - Must have a `RobotStatus` state machine (IDLE, WORKING, LOW_BATTERY, WAITING_FOR_CHARGE, CHARGING).
 - Battery must drain after WORKING and recharge during CHARGING.
 - Must independently pull tasks from the `PartRequestManager`.
- **ChargingStation (Runnable):** Must run on its own thread.
 - Must pull Robots from a shared, thread-safe `BlockingQueue`.
 - Must hold a Robot and call its `charge()` method until `isFullyCharged()` returns true.

- **PartRequest (Record):**
 - Must be an immutable `record`.
 - Must have a `RequestStatus` (PENDING, IN_PROGRESS, COMPLETED, FAILED).
 - Must provide a `withStatus()` method to create a new, updated copy.

2.3 FR-3: Data Exchange (I/O Streams)

- **Character Streams (Read):** The `PartRequestManager` must use `BufferedReader` to read and parse the `pending_requests.txt` file.
- **Character Streams (Write):** The `LoggerUtil` must use `BufferedWriter` to write all text-based log files.
- **Byte Streams (Write):** The `Warehouse` must use `DataOutputStream` to write a final binary report file (`completed_report.dat`) upon shutdown.

2.4 FR-4: Logging & Reporting

- **Event Logging:** A `LoggerUtil` class must be used to log timestamped events for all major components.
- **Granular Logs:** Logs must be generated for each individual robot (e.g., `Robot-R-001.txt`), charging station (e.g., `ChargingStation-CS-A.txt`), and system component (e.g., `Warehouse-WH-01.txt`).
- **Log Metadata Management:** The `LoggerUtil` must, upon initialization, find all previous logs of its type in the `Logs/` directory and move them to an `Logs/Archive/` directory.

2.5 FR-5: Graphical User Interface (GUI)

- The system must provide a **Swing-based GUI** (`WarehouseSystemGUI`) for control and monitoring.
- The GUI must allow the user to **configure** (robot/station count) and **Start/Stop** the simulation.
- The GUI must allow users to **manually add new tasks** to the `PartRequestManager` queue at runtime.
- The GUI must display **live-updating JTables** for:
 - All Robots (ID, Status, Task, Battery).
 - All ChargingStations (ID, Status, Charging Robot).
 - All Inventory items (ID, Name, Stock).
 - The active `PartRequest` queue (both PENDING and IN_PROGRESS tasks).
- All file I/O operations for the GUI's log viewer must be performed on a **background thread** (e.g., `SwingWorker`) to prevent freezing the UI.

3 Non-Functional Requirements

3.1 NFR-1: Concurrency & Thread Safety

- The system must use an `ExecutorService` to manage a thread pool for all `Runnable` components.
- Shared collections must be thread-safe:
 - **Inventory:** The main stock map must use `ConcurrentHashMap`.
 - **Task Queue:** The request queue must use `ConcurrentLinkedQueue`.
 - **Charging Queue:** The queue for robots awaiting a charge must be a `BlockingQueue` (e.g., `LinkedBlockingQueue`) to handle producer-consumer logic between robots and stations.
- **Atomicity:** Critical operations on shared resources (e.g., checking for and taking a task, checking and removing stock) must be atomic, using `synchronized` blocks.
- **Inter-thread Communication:**
 - The `PartRequestManager` must use `wait()` and `notifyAll()` to efficiently pause and resume `Robot` threads when the task queue is empty.
 - Fields read by the GUI thread but written by component threads (e.g., `Robot.status`, `Robot.batteryLevel`, `ChargingStation.currentRobot`) must be marked as `volatile` to ensure visibility.

3.2 NFR-2: Exception Handling

The project must correctly implement four specific exception handling patterns:

- a. **Handling Multiple Exceptions:** A single `catch` block must be used to handle at least two distinct exception types.
 - **Implementation:** `PartRequestManager.loadRequestsFromFile` uses `catch (IOException | NumberFormatException e)` to handle file-reading and parsing errors in one block.
- b. **Re-throwing Exceptions (Business Error):** A method must throw a custom, checked exception to signal a specific business rule failure.
 - **Implementation:** `Inventory.removeStock` throws `InsufficientStockException` if the requested quantity is not available. This is caught by the `Robot`'s `findAndSecureTask` method, which then fails the task.
- c. **Resource Management (try-with-resources):** All file and I/O streams must be managed using the `try-with-resources` statement to prevent resource leaks.
 - **Implementation:** Used in `LoggerUtil` (for `BufferedWriter`), `PartRequestManager` (for `BufferedReader`), and `Warehouse` (for `DataOutputStream`).
- d. **Chaining Exceptions:** Low-level exceptions (e.g., `IOException`) must be caught and wrapped in a custom, high-level exception, preserving the original `cause`.
 - **Implementation:** `PartRequestManager.loadRequestsFromFile` catches `(IOException | NumberFormatException e)` and throws `new RequestProcessingException("Error reading request file...", e)`.

3.3 NFR-3: Unit Testing

(No unit test files were provided, but this would be the requirement)

- **Test Coverage:** Unit tests should be created for each major class (e.g., Robot, Inventory, PartRequestManager, ChargingStation).
- **Test Suite:** All unit tests should be combined into a single test suite for regression testing.
- **Test Execution:** Tests must be run and results captured as proof of completion.