## Question1

Hyperparameters: Learning rate, batch size, and optimizer

Learning rates: [0.0001, 0.001, 0.01, 0.1]

Batch sizes: [512, 256, 128]

Optimizers: [SGD, adam, RMSProp]

Epoch: fixed 5

#### **Regular CNN:**

SGD showed the worst performance out of other optimizers. The best result from using SGD was the combination of learning rate 0.1 and batch size of 128.

Adam showed the good performance. The best performance of the combination is that the learning rate is 0.001, and the batch size is 128.

RMSProp showed the best performance for the regular CNN model. The learning rate is 0.001 and the batch size is 128.

The performance of regular CNN is generally well. RMSProp optimizer with learning rate 0.001, and batch size 128 returned the best accuracy.

#### **Inverted CNN**

The best performance of SGD showed is 0.98 with SGD optimizer, 0.1 learning rate, and 128 batch size.

Adam showed the best performance from the inverted CNN model. The learning rate is 0.001 and the batch size is 128.

RMSProp optimizer shows good performance in inverted CNN. The learning rate is 0.001 and the batch size is 128.

The performance of inverted CNN is generally not well. Adam optimizer with learning rate 0.001, and batch size 128 returned the best accuracy.

#### **Hour-glass shaped CNN**

SGD showed the worst performance out of other optimizers. The best result from using SGD was the combination of learning rate 0.0001 and batch size of 128.

Adam showed the good performance. The best performance of the combination is that the learning rate is 0.001, the batch size is 128.

RMSProp showed the best performance for the hour glass CNN model. The learning rate is 0.001 and the batch size is 128.

```
469/469 [============] - 4s 8ms/step - loss: 0.0654 - accuracy: 0.9804 Epoch 5/5
469/469 [=============] - 4s 8ms/step - loss: 0.0522 - accuracy: 0.9840 313/313 [============] - 1s 3ms/step - loss: 5.9353 - accuracy: 0.9861 Test loss: 5.935269355773926
```

The values of hyperparameters are: Optimizer: SGD, Adam, RMSProp Learning rate: 0.0001, 0.001, 0.01, 0.1

Test accuracy: 0.9861000180244446

Batch size: 128, 256, 512

From the result, we can conclude that regular CNN performed better than other CNNs. The reason I believe the regular CNN performed better is that other CNN has some part of the layer uses less filter size as the training goes on. By decreasing the size of filter while the training is happening, it is failing to condense the features which is returning bad performance. Hyperparameters: The learning rate of 0.001 and batch size of 128 returns the highest accuracy. In addition, I have found that adam and RMSProp optimizer are averagely performs better than SGD.

# Question2

1. What is the effect of learning rate on the training process? Which performed best?

Learning rate: 0.0001

Test loss: 1.3807892799377441 Test accuracy: 0.5338000059127808

Learning rate: 0.0005

Test loss: 2.2831778526306152 Test accuracy: 0.5565999746322632

Learning rate: 0.001

Test loss: 2.6412055492401123 Test accuracy: 0.534600019454956

Learning rate: 0.01

Test loss: 1.6260498762130737 Test accuracy: 0.4242999851703644

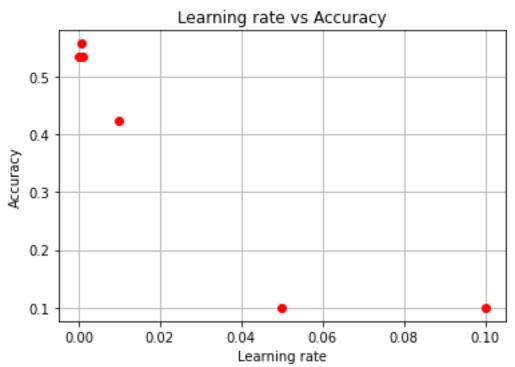
Learning rate: 0.05

Test loss: 2.3036272525787354 Test accuracy: 0.10000000149011612

Learning rate: 0.1

Test loss: 2.304857015609741

Test accuracy: 0.1000000149011612



The best performed learning rate is 0.0005.

From the result we can find that the higher learning rate decrease accuracy for this model. This means that the higher learning rate is causing the model to fail to detect local minima in the middle of training process.

### 2. What is the effect of batch size on the training process? Which performed best?

Batch Size: 32

Test loss: 3.1822121143341064 Test accuracy: 0.5819000005722046

Batch Size: 64

Test loss: 3.661105155944824 Test accuracy: 0.555400013923645

Batch Size: 128

Test loss: 3.225025177001953 Test accuracy: 0.5622000098228455

Batch Size: 256

Test loss: 2.786754608154297

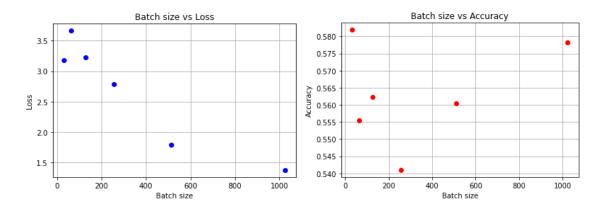
Test accuracy: 0.5410000085830688

Batch Size: 512

Test loss: 1.7933979034423828 Test accuracy: 0.5605000257492065

Batch Size: 1024

Test loss: 1.3790733814239502 Test accuracy: 0.5781999826431274



As the batch size increase, the loss is decreasing, and the accuracy of the model is increasing. Even though the low batch size has good accuracy however, it has high loss score, therefore, high batch size with lower loss score represents the better performance. From this result, we can say that the larger batch size tends to be better.

3. Try different hyperparameters to obtain the best accuracy on the test set. What is your best performance and what were the hyperparameters?

Epoch: 10

Test loss: 1.341706395149231 Test accuracy: 0.5257999897003174

Epoch: 20

Test loss: 1.3193355798721313 Test accuracy: 0.5698000192642212

Epoch: 30

Test loss: 1.9635429382324219 Test accuracy: 0.5583000183105469

Epoch: 40

Test loss: 2.3796188831329346 Test accuracy: 0.5475000143051147

Epoch: 50

Test loss: 2.734956741333008

Test accuracy: 0.5764999985694885

The other hyperparameter I tried is the epoch. More iteration seems like giving better accuracy but also increases the total loss.

The best combination of hyperparameters is batch size of 1024, learning rate of 0.0005 and epoch of 25.

Test loss: 1.3790733814239502 Test accuracy: 0.5781999826431274

- 4. Implement an equivalent feed forward network for the same task with each hidden layer containing the same number of neurons as the number of filters in each convolution layer. Use the 'Adam' optimizer to train your network on the CIFAR-10 dataset for a fixed set of 25 epochs. Compare its performance with your LeNet implementation based on the following questions:
  - a. What is its performance?

Test loss: 2.303964614868164

Test accuracy: 0.1000000149011612

The performance of the feed forward network is that it stop improves immediately right after the first epoch and defined in loss 2.3025 and accuracy 0.09. The performance of the feed forward network compared with the CNN shows that the CNN has better detection of features to increase the performance.

b. How many parameters are there in this network compared to the LeNet implementation? Are they worth it?

LeNet has 697,046 total parameters.

Layer (type)	Output Shape	Param #
conv2d_1950 (Conv2D)	(128, 32, 32, 6)	456
max_pooling2d_820 (MaxPooli ng2D)	(128, 16, 16, 6)	0
conv2d_1951 (Conv2D)	(128, 16, 16, 16)	2416
max_pooling2d_821 (MaxPooli ng2D)	(128, 8, 8, 16)	0
conv2d_1952 (Conv2D)	(128, 8, 8, 120)	48120
flatten_230 (Flatten)	(128, 7680)	0
dense_280 (Dense)	(128, 84)	645204
dense_281 (Dense)	(128, 10)	850
Total params: 697,046 Trainable params: 697,046 Non-trainable params: 0		

Feed Forward network has 122,854,454 total parameters.

Layer (type)	Output Shape	Param #
flatten_238 (Flatten)	(128, 3072)	0
dense_317 (Dense)	(128, 456)	1401288
dense_318 (Dense)	(128, 2416)	1104112
dense_319 (Dense)	(128, 48120)	116306040
dense_320 (Dense)	(128, 84)	4042164
dense_321 (Dense)	(128, 10)	850
Total params: 122,854,454 Trainable params: 122,854,454 Non-trainable params: 0		

Feed forward network has more parameters than LeNet but show worse performance than LeNet. We can conclude that it was not worth to have more parameters.

## Question3

1. What are the dimensions of the input and the kernel (or filter)? How many parameters are there in the kernel f? [2 points]

```
Dimensions of the input: 6 X 6 X 1
(6, 6)
[[7 5 0 0 3 2]
[6 4 5 1 4 8]
[9 0 2 2 5 4]
[6 3 4 7 9 8]
[5 7 5 6 9 0]
[7 9 0 8 2 3]]

Dimensions of the filter: 3 X 3 X 1
(3, 3)
[[ 1 0 -1]
[ 2 0 -2]
[ 1 0 -1]]
```

The input has volume of 6 \* 6 \* 1 and the filter have volume of 3 \* 3 \* 1. Since the depth of input is 1, filter depth is also 1. Therefore, the dimensions of the input and the kernel are 1.

The parameters for the kernel f can be achieved as ((3 \* 3 \* 1) + 1) \* 1 = 10.

2. What is the output activation map when you apply the convolutional operation using the filter f on the input X without padding? [4 points]

The output activation map can be achieved by calculating the sum of multiplication of two matrices (part of 3\*3 input and filter) for each corresponding element of 4\*4 output matrix. The code to achieve below output is available in the submitted python file.

```
[[ 16. 9. -4. -18.]
[ 17. -5. -10. -12.]
[ 11. -9. -17. 2.]
[ 9. -1. -15. 16.]]
```

3. What is the output when you apply a max-pooling operation on the output from the previous question? [4 points]

The output of applying a max-pooling operation is:

This can be achieved with 2 stride and 2 filter size. It will separate the matrix into 4 parts without any overlapping areas. Each area will determine the max value to be represent the whole area. By decreasing the dimension, we can cut the calculation time. The code to achieve below output is available in the submitted python file.