

Spectral Thresholding in Quantum State Estimation for Low Rank States

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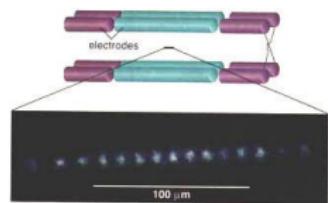
Joint work with:

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Quantum-classical interface is stochastic \Rightarrow Q. Engineering needs Statistics

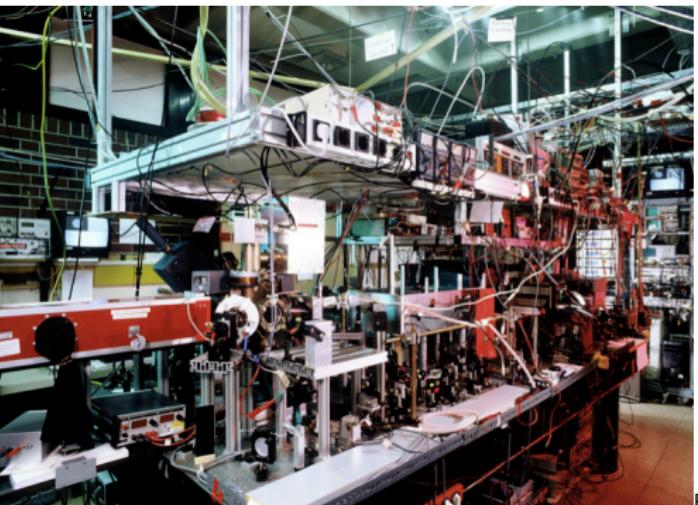
Problem: Quantum state estimation

- **Quantum computation goal:** create specific states of multiple "qubits" (e.g. ions)
- **Validation:** statistical estimation from measurement outcomes



[Häffner et al, Nature 2005]

- ▷ $4^8 - 1 = 65\,535$ parameters
- ▷ $3^8 \times 100 = 656\,100$ measurements
- ▷ 10 hours measurement time
- ▷ days of computer time



Blatt's Lab, Innsbruck

"quantum computer" with 8 qubits (ions)

Outline

- Statistical model for multiple ions tomography
- Least-squares estimator
- Penalised estimator
- Physical estimator
- Cross-validation estimator
- Simulation Results

Quantum states

- Complex Hilbert space of ‘wave functions’ $\mathcal{H} = \mathbb{C}^d, L^2(\mathbb{R})\dots$

- State = preparation: complex density matrix ρ on \mathcal{H}

- $\rho = \rho^*$ (selfadjoint)
- $\rho \geq 0$ (positive)
- $\text{Tr}(\rho) = 1$ (normalised)

$$\rho = \begin{pmatrix} \rho_{11} & \rho_{12} & \cdots & \rho_{1d} \\ \rho_{21} & \rho_{22} & \cdots & \rho_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ \rho_{d1} & \rho_{d2} & \cdots & \rho_{dd} \end{pmatrix}$$

- Convex space of states

- extremals (pure states) : one dimensional projection $P_\psi = |\psi\rangle\langle\psi| = \psi\psi^*$ with $\|\psi\| = 1$
- Mixed state: convex combination of pure states

$$\rho = \sum_i \lambda_i |\psi_i\rangle\langle\psi_i|$$

- Natural distances: $\tau := \rho_1 - \rho_2$

$$\|\tau\| := \lambda_{\max}(|\tau|), \quad \|\tau\|_2^2 := \text{Tr}(|\tau|^2), \quad \|\tau\|_1 := \text{Tr}(|\tau|)$$

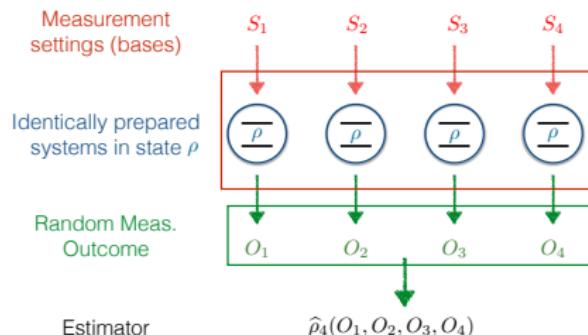
$$h(\rho_1, \rho_2) := 1 - \text{Tr} \left(\sqrt{\rho_1^{1/2} \rho_2 \rho_1^{1/2}} \right) \dots$$

Simple measurements

- Measurement setup given by an orthonormal basis $\mathbf{s} := \{|e_1\rangle, \dots, |e_d\rangle\}$ in \mathbb{C}^d
- Outcome of measurement is a random index of a basis element $O \in \{1, \dots, d\}$
- Probability distribution: if system is prepared state ρ

$$\mathbb{P}[O = i] = \langle e_i | \rho | e_i \rangle$$

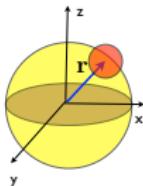
- Quantum state tomography: probe system with sufficient measurements to estimate ρ



Example: spin / two-level ion / qubit tomography

- Any state on \mathbb{C}^2 is parametrized by a 3-D Bloch vector $\mathbf{r} = (r_x, r_y, r_z)$ with $\|\mathbf{r}\| \leq 1$

$$\rho_{\mathbf{r}} = \frac{1}{2} \begin{pmatrix} 1 + r_z & r_x - ir_y \\ r_x + ir_y & 1 - r_z \end{pmatrix}$$



- 3 standard measurement bases corresponding to $s = x, y, z$ spin observables

$$\underbrace{|e_x^{\pm}\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm 1 \end{pmatrix}}_{s=x}, \quad \underbrace{|e_y^{\pm}\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm i \end{pmatrix}}_{s=y}, \quad \underbrace{|e_z^+\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad |e_z^-\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}}_{s=z}$$

- Probability distributions: $\mathbb{P}(o = \pm|s) = \frac{1 \pm r_s}{2}, \quad s = x, y, z$
- n measurement repetitions \rightarrow counts $\{N(\pm|x), N(\pm|y), N(\pm|z)\} \rightarrow$ (LS) estimator

$$\hat{\rho}_n := \rho_{\hat{\mathbf{r}}}, \quad \hat{r}_{x,y,z} := \frac{N(+|x,y,z) - N(-|x,y,z)}{n}$$

Boundary/positivity problem: for pure (rank 1) states, estimator may not be physical (positive)

Measuring (correlated) states of multiple ions

- State space of k two-level systems scales exponentially with k !

$$\mathcal{H}_k := \mathbb{C}^2 \otimes \cdots \otimes \mathbb{C}^2 \cong \mathbb{C}^{2^k} = \mathbb{C}^d$$

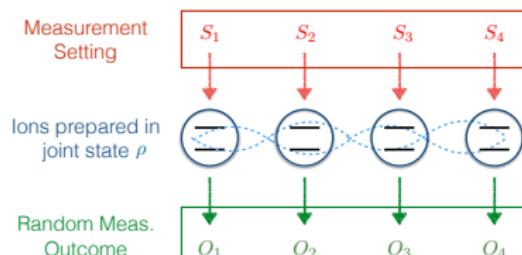
- Joint state of k ions

- Density matrix ρ has $4^k - 1 = d^2 - 1$ parameters (e.g. $4^8 - 1 = 65535$)
- Density matrix of rank r has $r(2 \cdot d - r) - 1$ (e.g. $2^8 - 2 = 254$ for a pure state)

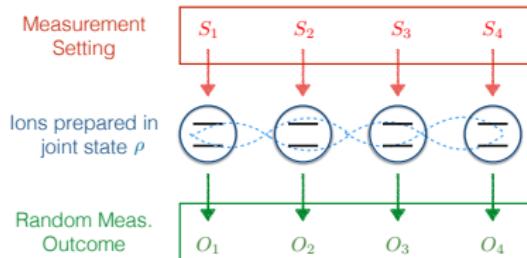
- Simultaneous, separate measurements on each ion:

- 3^k settings $\mathbf{s} = (s_1, \dots, s_k) \in \{x, y, z\}^k$
- 2^k outcomes $\mathbf{o} = (o_1, \dots, o_k) \in \{+, -\}^k$
- probabilities

$$\mathbb{P}_{\rho}(\mathbf{o}|\mathbf{s}) = \langle e_{s_1}^{o_1} \otimes \cdots \otimes e_{s_k}^{o_k} | \rho | e_{s_1}^{o_1} \otimes \cdots \otimes e_{s_k}^{o_k} \rangle$$



Measurement procedure and statistical model



1. For each ion choose a spin direction to measure basis $s \in \{x, y, z\}$
2. measure each ion and obtain outcome $\mathbf{o} := (o_1, \dots, o_k) \in \{1, -1\}^k$
3. Repeat n times and collect counts of outcomes $\{N_{\mathbf{o}, \mathbf{s}} : \mathbf{o} \in \{1, -1\}^k\}$

$$\mathbb{P}_\rho \left(\{N_{\mathbf{o}, \mathbf{s}} : \mathbf{o} \in \{1, -1\}^k\} \right) = \frac{n!}{\prod_o N_{\mathbf{o}, \mathbf{s}}!} \prod_{\mathbf{o}} \mathbb{P}_\rho(\mathbf{o} | \mathbf{s})^{N_{\mathbf{o}, \mathbf{s}}}$$

4. Repeat over all 3^k choices of measurement set-ups

Total set of $3^k \times 2^k \gg 4^k$ projections is highly overcomplete in $M(\mathbb{C}^{2^k})$!

Measurement data

- 3^k columns of length 2^k
- one column for each measurement setting
- each column contains the counts totalling $n = 100$, of the $2^k = 16$ possible outcomes
- frequencies of outcomes are bad estimates of probabilities, but overall info is high

1	2	11	11	11	21	5	16	21	19	11	16	2	26	15	5
2	19	10	6	15	4	22	10	3	12	8	16	18	5	14	16
3	30	12	15	9	10	18	14	3	6	11	4	4	2	1	5
4	0	4	15	10	17	2	4	14	13	0	4	8	5	1	3
5	21	13	12	7	6	5	14	12	8	12	7	19	3	8	3
6	1	12	14	0	1	1	0	6	6	12	8	2	6	2	7
7	1	2	0	19	7	12	14	6	7	14	7	9	23	15	34
8	0	1	1	0	4	8	0	6	6	0	7	12	4	15	5
9	21	17	8	10	7	7	14	9	8	15	6	9	6	3	0
10	2	16	15	0	12	9	0	3	4	1	7	3	0	4	6
11	0	0	1	17	9	2	14	12	7	0	1	0	5	5	2
12	1	1	1	0	2	8	0	4	3	0	1	0	0	3	1
13	1	0	1	1	0	0	0	0	0	14	9	7	6	2	4
14	0	1	0	0	0	1	0	0	1	1	5	6	0	2	2
15	1	0	0	1	0	0	0	0	0	1	2	0	9	6	3
16	0	0	0	0	0	0	1	0	0	0	0	1	0	4	4

[Dataset 4 ions (from T. Monz)]

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The least squares estimator

- For large n frequencies are close to the probabilities of the corresponding outcome

$$f_n(\mathbf{o}|\mathbf{s}) = \frac{N(\mathbf{o}|\mathbf{s})}{n} = p(\mathbf{o}|\mathbf{s}) + \epsilon_n(\mathbf{o}|\mathbf{s}) \text{ ("multinomial error")}$$

$$\mathbf{f}_n = \mathbf{p} + \epsilon_n = \mathbf{A}\tilde{\rho} + \epsilon_n$$

- State estimation as a "linear regression" problem: least squares estimator

$$\hat{\rho}_n^{(ls)} = \arg \min_{\tau} \|\mathbf{A}\tilde{\tau} - \mathbf{f}_n\|_2^2 = (\mathbf{A}^t \mathbf{A})^{-1} \cdot \mathbf{A}^t \cdot \mathbf{f}_n$$

- Disadvantages

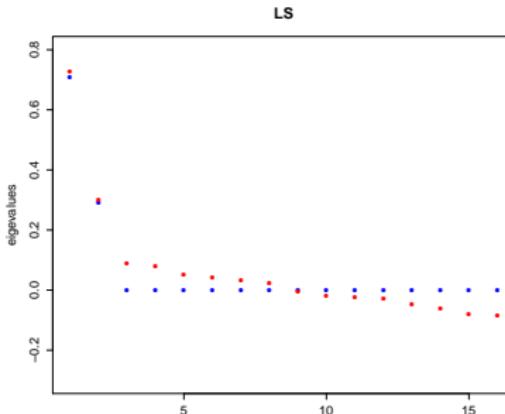
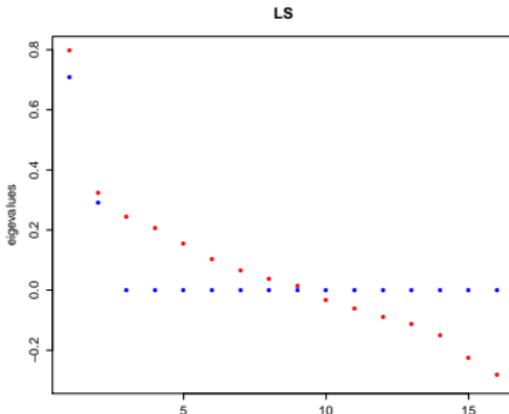
- Least squares estimator is not a density matrix (not positive and trace one)
- Least squares estimator is too "noisy" for low rank states
- Least squares estimator minimises prediction rather than estimation error $\mathbb{E}\|\hat{\rho}_n - \rho\|_2^2$

Eigenvalues distribution for the least squares estimator

- Eigenvalues decomposition for true state and least squares estimator

$$\rho = \sum_{i=1}^r \lambda_i |\psi_i\rangle\langle\psi_i| \quad \hat{\rho}_n^{(ls)} = \sum_{i=1}^d \hat{\lambda}_i |\hat{\psi}_i\rangle\langle\hat{\psi}_i|$$

- If $r \ll d = 2^k$, the $MSE = \mathbb{E}\|\hat{\rho}_n^{(ls)} - \rho\|_2^2$ is large due to variance contributions from many eigenvalues $\hat{\lambda}_i$ which estimated zero eigenvalues of ρ



Eigenvalues of true state of rank 2 (blue) versus least squares estimator (red)

LEFT: $n = 20$ repetitions

RIGHT: $n = 100$ repetitions

Norm-error upper bound for the least squares estimator¹

- operator-norm distance $\|\rho - \tau\| = |\lambda_{max}(\Delta)|$, $\Delta := \rho - \tau$
- norm-two distance $\|\rho - \tau\|_2^2 = \sum_i |\lambda_i(\Delta)|^2 \leq d \cdot \|\rho - \tau\|^2$ (*)

Theorem

For any $\varepsilon > 0$ small enough the following inequality holds with probability larger than $1 - \varepsilon$

$$\left\| \hat{\rho}_n^{(ls)} - \rho \right\| \leq \nu_n(\varepsilon),$$

where the rate $\nu_n(\varepsilon)^2$ is

$$\nu_n(\varepsilon)^2 = \frac{2}{n} \left(\frac{2}{3} \right)^k \log \left(\frac{2^{k+1}}{\varepsilon} \right) = 2 \frac{d}{N} \log \left(\frac{2d}{\varepsilon} \right)$$

with $N := n \cdot 3^k$ the total number of measurements.

► Concentration inequality and (*) give upper bound for the MSE

$$\mathbb{E} \left\| \hat{\rho}_n^{(ls)} - \rho \right\|_2^2 \leq C \frac{k}{n} \left(\frac{4}{3} \right)^k \approx C \log(d) \cdot \frac{\text{#parameters}}{\text{\#samples}}$$

¹Butucea, Guta & K (2015), arXiv:1504.08295; this improves on the $(4/3)^k$ factor in the upper bound of P. Alquier, C. Butucea, et al, Phys. Rev. A (2013)

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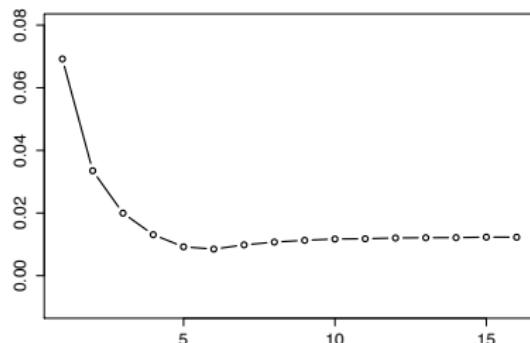
Penalising small eigenvalues

- Assume true state ρ of low rank: $\rho = \sum_{i=1}^r \lambda_i |\psi_i\rangle\langle\psi_i|$ with $r \ll d$
- Idea: $\|\hat{\rho}_n^{(ls)} - \rho\| \approx \nu_n \Rightarrow$ eigenvalues of $\hat{\rho}_n^{(ls)}$ s.t. $|\hat{\lambda}_i| \leq \nu_n$ may be "statistical noise"
- Truncated versions of the LS estimator: order $|\hat{\lambda}_1| \geq \dots \geq |\hat{\lambda}_d|$ and for each $k \leq d$

$$\hat{\rho}_n^{(ls)} = \sum_{i=1}^d \hat{\lambda}_i |\hat{\psi}_i\rangle\langle\hat{\psi}_i| \longrightarrow \hat{\rho}_n(k) = \sum_{i=1}^k \hat{\lambda}_i |\hat{\psi}_i\rangle\langle\hat{\psi}_i|$$

Question: how to choose the truncation rank ?

- Oracle estimator has rank which minimises the norm-two error $E(k) := \|\hat{\rho}_n(k) - \rho\|_2^2$



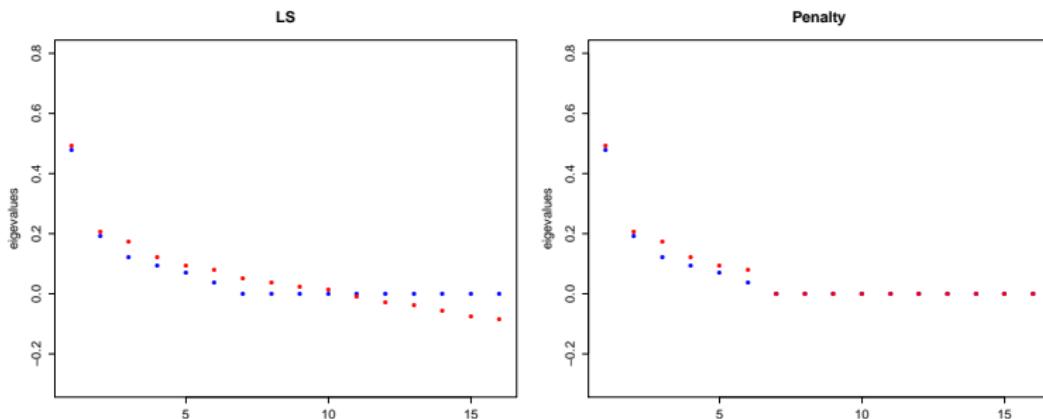
$E(k)$ for a state of rank $r = 6$, as function of truncation rank k

Penalised least squares estimator

- Choose rank $\hat{k} := \max\{k : \hat{\lambda}_k^2 \geq \nu_n^2\}$ with $|\hat{\lambda}_1| \geq |\hat{\lambda}_2| \geq \dots \geq |\hat{\lambda}_d|$
- Equivalently, \hat{k} minimises the **rank-penalised** distance to the least squares

$$\hat{k} = \arg \min_k [\|\hat{\rho}_n(k) - \hat{\rho}_n\|_2^2 + k \cdot \nu_n^2] = \arg \min_k \left[\sum_{i=k+1}^d |\hat{\lambda}_i|^2 + \nu_n^2 \cdot k \right]$$

- Penalised estimator: $\hat{\rho}_n^{(pen)} := \hat{\rho}_n(\hat{k})$



Eigenvalues of true state ρ (blue) versus: LS (red) on LEFT and penalised estimator (red) RIGHT
for a rank 6 state with $n = 100$ repetitions

MSE upper bound for the penalised estimator²

- Penalised estimator: with $\hat{k} := \max\{k : \hat{\lambda}_k^2 \geq \nu_n^2\}$

$$\hat{\rho}_n^{(ls)} = \sum_{i=1}^d \hat{\lambda}_i |\hat{\psi}_i\rangle\langle\hat{\psi}_i| \longrightarrow \hat{\rho}_n^{(pen)} = \sum_{i=1}^{\hat{k}} \hat{\lambda}_i |\hat{\psi}_i\rangle\langle\hat{\psi}_i|$$

Theorem

Let ρ be a state of (unknown) rank r .

Let $\varepsilon > 0$ be a small parameter. Then with probability larger than $1 - \varepsilon$, we have

$$\|\hat{\rho}_n^{(pen)} - \rho\|_2^2 \leq C \frac{r}{n} \left(\frac{2}{3}\right)^k \log\left(\frac{2^{k+1}}{\varepsilon}\right)$$

- Concentration inequality gives upper bound for the MSE

$$\mathbb{E} \left\| \hat{\rho}_n^{(pen)} - \rho \right\|_2^2 \leq C \frac{k \cdot r}{n} \left(\frac{2}{3}\right)^k \approx C \log(d) \cdot \frac{\text{#parameters(rank = r)}}{\text{\#samples}}$$

²Butucea, Guta & K (2015), arXiv:1504.08295

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Physical estimator

- Disadvantage of penalised estimator: $\hat{\rho}_n^{(pen)}$ may not be a state (positive, trace-one matrix)
- Physical estimator $\hat{\rho}_n^{(phys)}$ exploits the positivity properties of ρ :

$$\hat{\rho}_n^{(phys)} = \arg \min_{\sigma \in \mathcal{S}(\nu_n)} \left\| \sigma - \hat{\rho}_n^{(ls)} \right\|_2^2,$$

- $\hat{\rho}_n^{(ls)}$ is the "normalised LS estimator" s.t. $\text{Tr} \hat{\rho}_n^{(ls)} = 1$

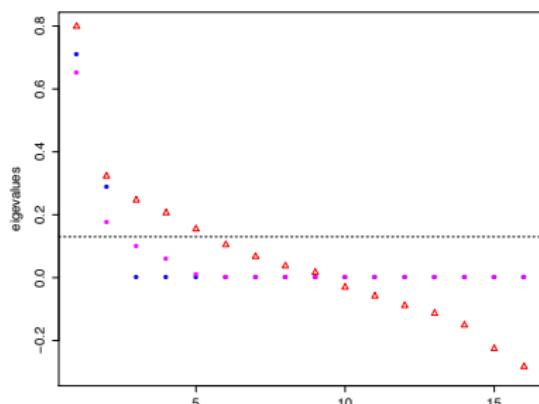
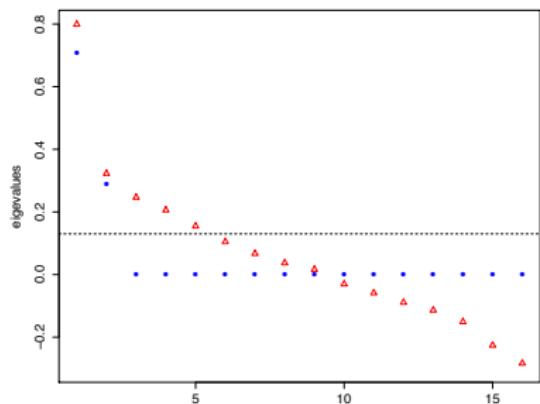
- $\mathcal{S}(\nu_n)$ denotes the set of states at noise level ν_n

$$\mathcal{S}(\nu_n) = \{ \sigma : \text{ density matrix with eigenvalues } \lambda_j \in \{0\} \cup (4\nu_n, 1], j = 1, \dots, d \}.$$

Questions: can it be computed efficiently, and what is its MSE?

Physical estimator: implementation

- Optimisation: solution is a truncated LS matrix $\hat{\rho}_n(\hat{k}) = \sum_{i=1}^{\hat{k}} \hat{\lambda}_i |\hat{\psi}_i\rangle\langle\hat{\psi}_i|$
- Truncation rank: simple iterative algorithm on eigenvalues arranged as $\hat{\lambda}_1 \geq \dots \geq \hat{\lambda}_d$ selects maximum k for which all eigenvalues of $\hat{\rho}_n(\hat{k})$ are larger than threshold after being normalised by shifting with constant



Eigenvalues of true state ρ (blue circles) versus LS (red triangles) on LEFT vs. eigenvalues of physical estimator (rose) on RIGHT
for a rank 2 state with $n = 20$ repetitions

Physical estimator: upper bound

Theorem

Let ρ be a state of (unknown) rank r .

Let $\varepsilon > 0$ be a small parameter, and assume that $\lambda_r > 8\nu_n(\varepsilon)$. Then, with probability larger than $1 - \varepsilon$ we have

$$\left\| \widehat{\rho}_n^{(phys)} - \rho \right\|_2^2 \leq C \frac{r}{n} \left(\frac{2}{3} \right)^k \log \left(\frac{2^{k+1}}{\varepsilon} \right)$$

► Concentration inequality gives upper bound for the MSE

$$\mathbb{E} \left\| \widehat{\rho}_n^{(ls)} - \rho \right\|_2^2 \leq C \frac{r \cdot k}{n} \left(\frac{2}{3} \right)^k \approx C \log(d) \cdot \frac{\#\text{parameters}(\text{rank} = r)}{\#\text{samples}}$$

Outline

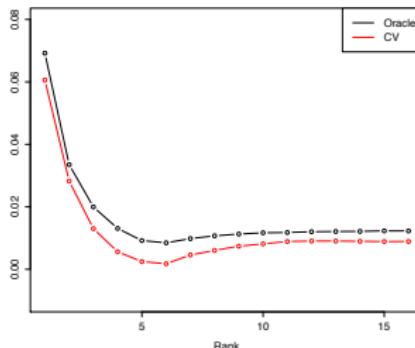
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Choosing truncation rank by cross-validation

- Norm-two error $E(k) := \|\hat{\rho}_n(k) - \rho\|_2^2$ minimised by oracle estimator
- Cross-validation:
 - Split dataset in 5 independent batches and compute $\hat{\rho}_{n;j}^{(ls)}$ and $\hat{\rho}_{n;-j}^{(ls)}$ on batch j and respectively all-but- j batches, for $j = 1, \dots, 5$.
 - Replace $E(k)$ by unbiased estimator (up to constant independent of k)

$$CV(k) = \frac{1}{5} \sum_{i=1}^5 \left\| \hat{\rho}_{n;-j}(k) - \hat{\rho}_{n;j}^{(ls)} \right\|_2^2.$$

- Cross-validation estimator: $\hat{\rho}_n^{(cv)} := \hat{\rho}_n(\hat{k})$ where \hat{k} is the minimiser of $CV(k)$.

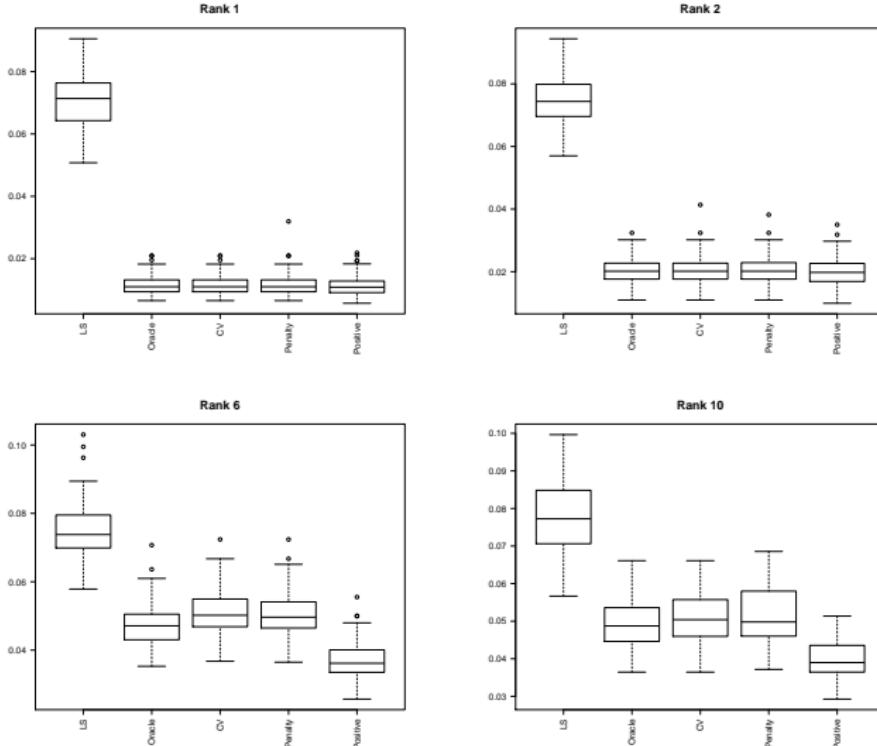


$E(k)$ (black) and $CV(k)$ (red) for one dataset from a rank 6 state with $n = 500$ repetitions

Outline

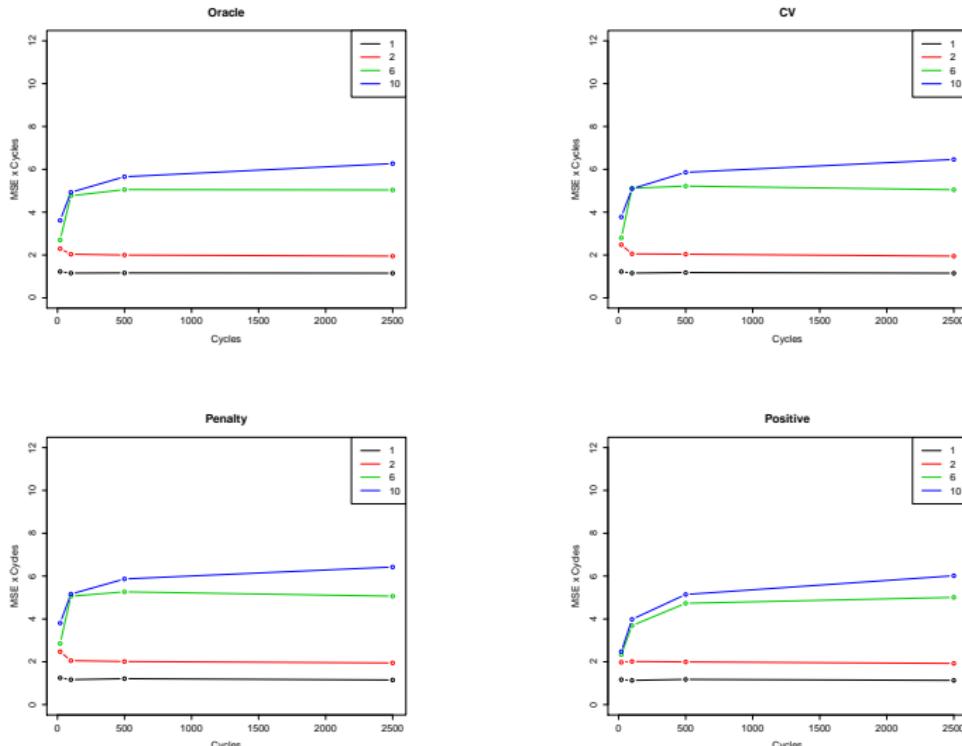
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Comparison of estimators: SEs for different states, with $n = 100$



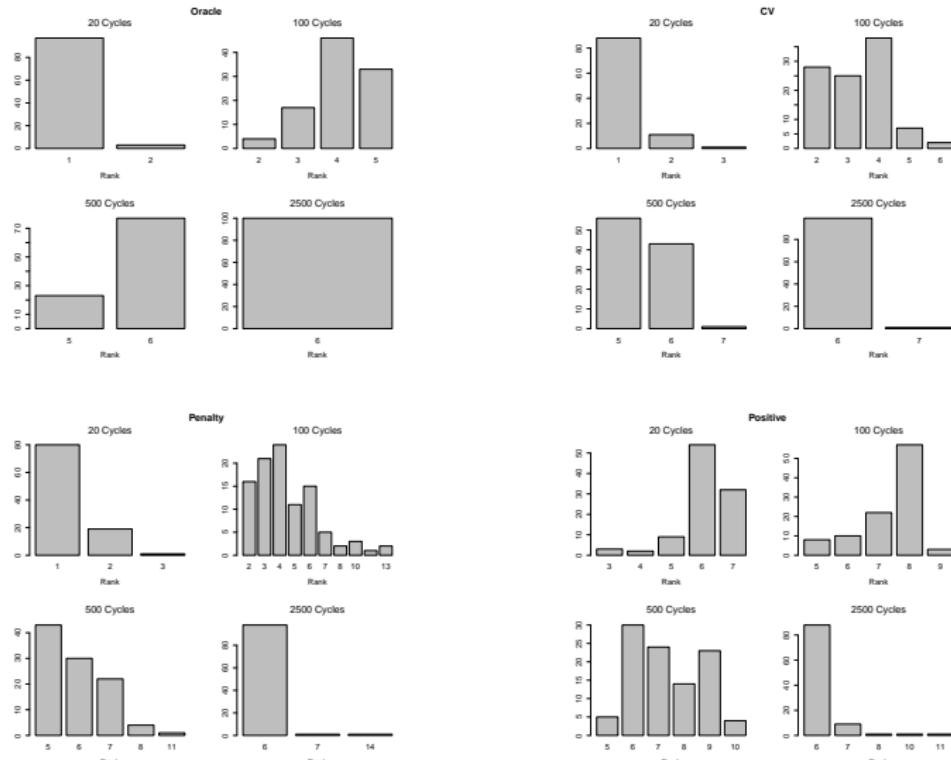
Boxplots of norm-two errors $\|\hat{\rho}_n - \rho\|_2^2$ of different estimators for states of ranks 1, 2, 6, 10 with $n = 100$ repetitions
(computed from 100 datasets)

Comparison of estimators: MSE for different states and repetitions n



Renormalised MSEs = $n \cdot \mathbb{E}\|\hat{\rho}_n - \rho\|_2^2$ as a function of number of repetitions n
 for states with different ranks: 1(black), 2 (red), 6 (green), 10 (blue) .

Comparison of estimators: Empirical distribution of chosen rank

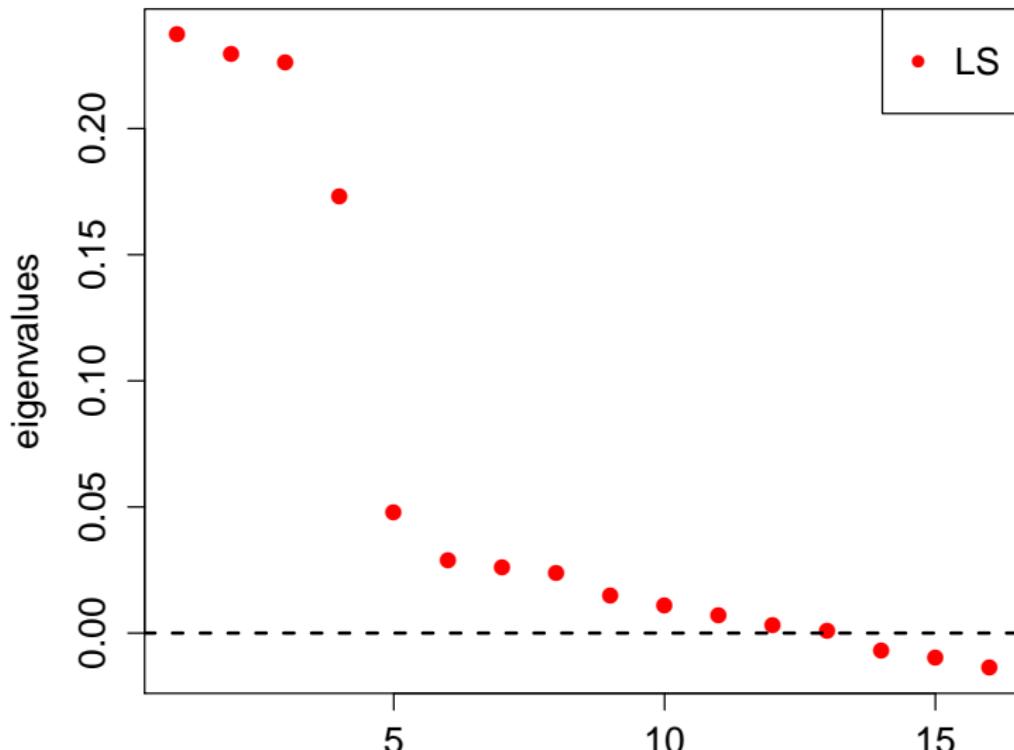


Histograms of the probabilities of the chosen rank for different estimators, as function of the number of repetitions n
for a state of rank $r = 6$

Real Data: 4 ions (thanks to Thomas Monz, Innsbruck)

4 atoms, 4800 total cycles

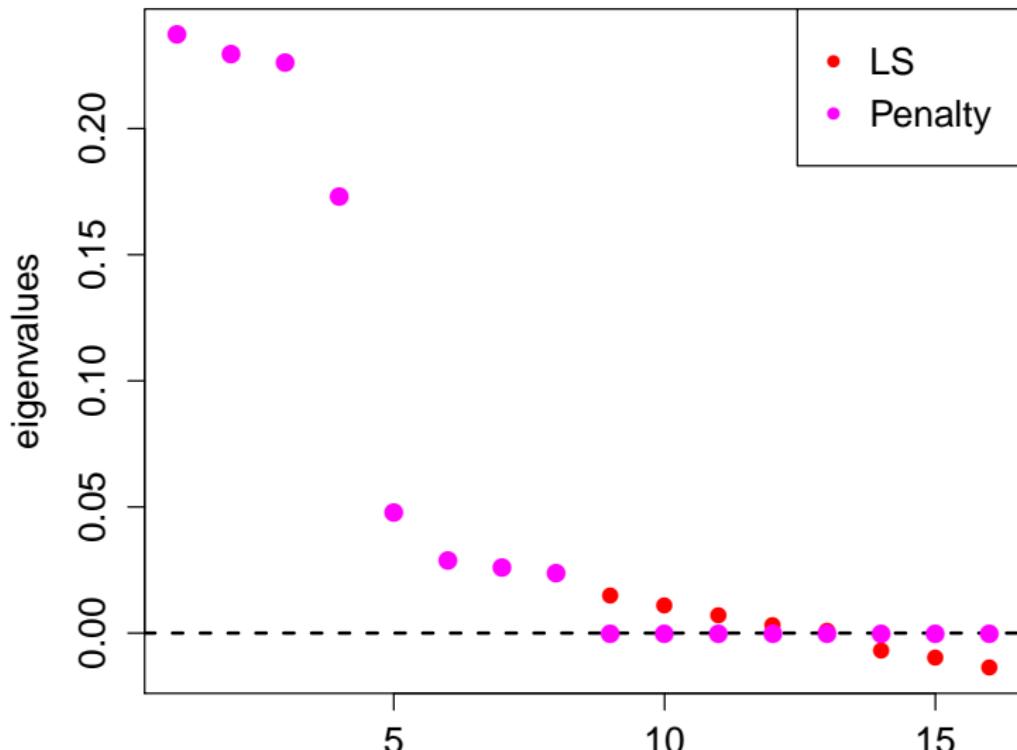
Eigen values



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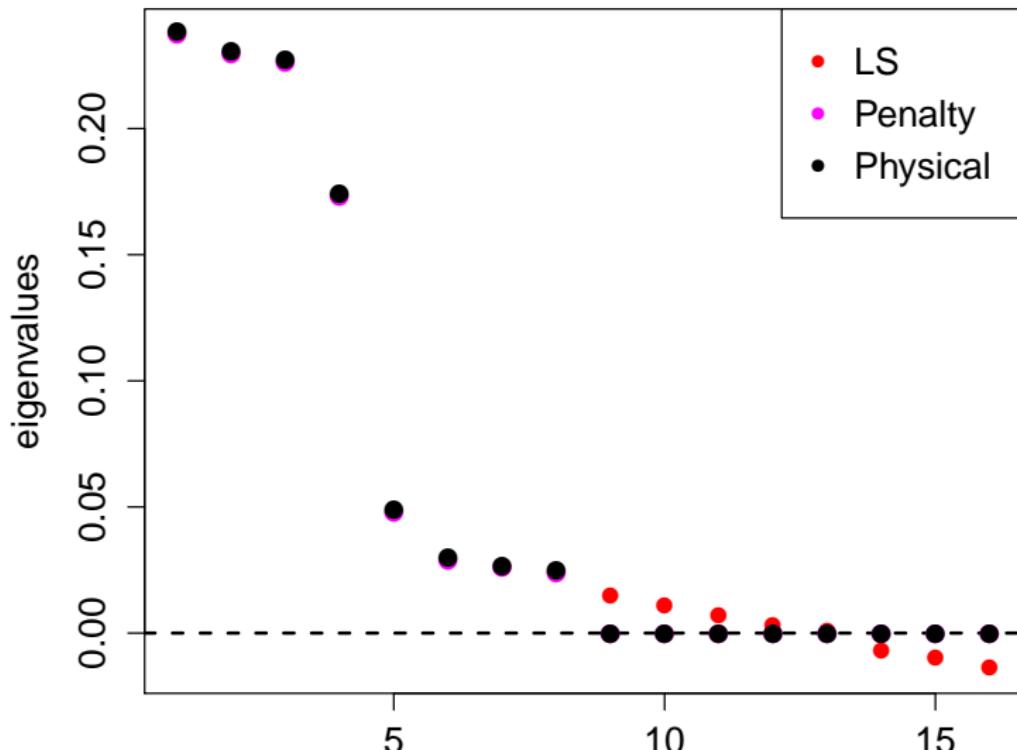
Eigen values



Real Data: 4 ions (thanks to Thomas Monz, Innsbruck)

4 atoms, 4800 total cycles

Eigen values



The results (ie chosen ranks) are comparable to the ones obtained by more traditional rank (model) selection methods in Guta, K & Dryden (2012):

- Akaike Information Criterion: rank = 9
- Bayesian Information Criterion: rank = 6

Outlook

- New class of estimators based on spectral truncation of the LS estimator
- Can LS be replaced by a better linear estimators as starting point ?
- Better understanding of the role of positivity (e.g. LS with positivity constraints)
- Confidence intervals / regions
- Measurement design with reduced measurement settings:
 - new threshold estimators
 - Behaviour of MSE with number of settings