

MATH 7410 Homework 3

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Problem 1

Is the solution set to the system of equations

$$x^3 + y^3 + z^3 = 1, \quad z = xy$$

in \mathbb{R}^3 a smooth manifold? Prove your answer.

Proof. Let $S \subseteq \mathbb{R}^3$ be the solution set to the above system of equations. Define $F : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ by $(u, v) = F(x, y, z) = (x^3 + y^3 + z^3, xy - z)$. Then $S = F^{-1}((1, 0))$. By the regular set theorem, it suffices to show that $F^{-1}((1, 0))$ is a regular set. Hence, we must show that $d_p F$ is surjective for all $p \in S$, or equivalently, that $\text{rank}(J(F)_p) = 2$ for all $p \in S$ where $J(F)$ denotes the Jacobian of F . We initially compute that

$$J(F) = \begin{pmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \end{pmatrix} = \begin{pmatrix} 3x^2 & 3y^2 & 3z^2 \\ y & x & xy \end{pmatrix}$$

Now, suppose $p = (a, b, c) \in S$ is a critical point of F , i.e. $\text{rank}(J(F)_p) < 2$. Then $a^3 + b^3 + c^3 = 1$ and $c = ab$, so

$$J(F)_p = \begin{pmatrix} 3a^2 & 3b^2 & 3c^2 \\ b & a & ab \end{pmatrix} = \begin{pmatrix} 3a^2 & 3b^2 & 3(ab)^2 \\ b & a & ab \end{pmatrix}.$$

If $c = 0$, then either a or b is 0, forcing the other to be 1, whence we obtain one of the following matrices,

$$\begin{pmatrix} 3 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, \quad \begin{pmatrix} 0 & 3 & 0 \\ 1 & 0 & 0 \end{pmatrix},$$

which are both of full rank contradicting the the criticality of p . Thus, $c \neq 0$, so $a, b \neq 0$. Now by standard linear algebra, criticality of p is equivalent to the statement that all 2×2 -minors of $J(F)_p$ vanish. Thus, we have that

$$\det \begin{pmatrix} 3a^2 & 3b^2 \\ b & a \end{pmatrix} = 0, \quad \det \begin{pmatrix} 3a^2 & 3a^2b^2 \\ b & ab \end{pmatrix} = 0, \quad \det \begin{pmatrix} 3b^2 & 3a^2b^2 \\ a & ab \end{pmatrix},$$

whence we obtain the relations,

$$\left. \begin{matrix} 0 = 3a^3 - 3b^3 \\ 0 = 3a^3b - 3a^2b^3 \\ 0 = 3ab^3 - 3a^3b^2 \end{matrix} \right\} \xrightarrow{a, b \neq 0} \left. \begin{matrix} 0 = a^3 - b^3 \\ 0 = b - a^2 \\ 0 = a - b^2 \end{matrix} \right\}.$$

Now, as $b = a^2$, it follows that $0 = a - b^2 = a - a^4$ whence $a \neq 0$ implies that $a^3 = 1$. As $a \in \mathbb{R}$, it follows that $a = 1$ and consequently $b = 1, c = 1$. However, this contradicts the fact that $p \in S$ as $3 = 1 + 1 + 1 = a^3 + b^3 + c^3 \neq 1$. Thus every point in S is regular, so $F^{-1}((1, 0))$ is a regular level set whence by the regular set theorem S is a smooth manifold. \square

Problem 2

A C^∞ map $f : N \rightarrow M$ is said to be *transversal* to a submanifold $S \subseteq M$ if for every $p \in f^{-1}(S)$,

$$f_*(T_p N) + T_{f(p)} S = T_{f(p)} M.$$

The goal of this exercise is to prove the *transversality theorem*: if a C^∞ map $f : N \rightarrow M$ is transversal to a regular submanifold S of codimension k in M , then $f^{-1}(S)$ is a regular submanifold of codimension k in N .

When S consists of a single point c , transversality of f to S simply means that $f^{-1}(c)$ is a regular level set. Thus the transversality theorem is a generalization of the regular level set theorem. It is especially useful in giving conditions under which the intersection of two submanifolds is a submanifold.

Let $p \in f^{-1}(S)$ and (U, x^1, \dots, x^n) be an adapted chart centered at $f(p)$ for M relative to S such that $U \cap S = Z(x^{m-k+1}, \dots, x^m)$, the zero set of the functions x^{m-k+1}, \dots, x^m . Define $g : U \rightarrow \mathbb{R}^k$ to be the map

$$g = (x^{m-k+1}, \dots, x^m).$$

(a): Show that $f^{-1}(U) \cap f^{-1}(S) = (g \circ f)^{-1}(0)$.

Proof. Observe that

$$\begin{aligned} q \in (g \circ f)^{-1}(0) &\iff g(f(q)) = 0 \iff x^i(f(q)) = 0 \text{ for } i = m - k + 1, \dots, m \\ &\iff f(q) \in Z(x^{m-k+1}, \dots, x^m) = U \cap S \iff q \in f^{-1}(U \cap S) = f^{-1}(U) \cap f^{-1}(S). \end{aligned}$$

□

(b): Show that $f^{-1}(U) \cap f^{-1}(S)$ is a regular level set of the function $g \circ f : f^{-1}(U) \rightarrow \mathbb{R}^k$.

Proof. Fix $p \in f^{-1}(S) \cap f^{-1}(U) = (g \circ f)^{-1}(0)$. We wish to show that p is a regular point for $g \circ f$. Suppose that $a \in T_0 \mathbb{R}^k$. Then, noting that $dg_{f(p)}$ is surjective, there exists a $w \in T_{f(p)} M$ such that $dg_{f(p)}(w) = a$. Then, by transversality of f with respect to S , there exist $u \in T_p N$, $v \in T_{f(p)} S$ such that $w = df_p(u) + v$. Now, note that $g(U \cap S) = 0$, so it follows that $dg_{f(p)}(T_{f(p)}(S)) = 0$. Hence, we compute

$$a = dg_{f(p)}(w) = dg_{f(p)}(df_p(u) + v) = dg \circ f_p(u) + dg_{f(p)}(v) = dg \circ f_p(u),$$

so p is a regular point for $g \circ f$ as its differential is surjective.

□

(c): Prove the transversality theorem.

Proof. By the regular level set theorem, $f^{-1}(U) \cap f^{-1}(S)$ is a codimension k submanifold of N . For $q \in S$, choose a chart (V_q, ϕ_q) adapted to q . Then $f^{-1}(V_q \cap S) \subseteq f^{-1}(S)$ and $f^{-1}(S) = \bigcup_{q \in S} f^{-1}(V_q \cap S)$, whence $f^{-1}(S)$ is also a codimension k submanifold of N , as desired.

□

Problem 3

(a): Consider the "height map" $h : S^2 \rightarrow \mathbb{R}$. Here S^2 is the unit sphere in \mathbb{R}^3 and $h(x, y, z) = z$. Find the critical points and critical values for this map.

Proof. First suppose $p = (a, b, c) \in S^2$ with $c > 0$. Consider the chart (U, ϕ) on S^2 given by $U = \{(x, y, z) \in S^2 : z > 0\}$ and $\phi(x, y, z) = (x, y)$. Let $\tilde{h} : \phi(U) \rightarrow \mathbb{R}$ be the coordinate representation of h with respect to this chart. Then $\tilde{h}(x, y) = (h \circ \phi^{-1})(x, y) = h(x, y, \sqrt{1 - x^2 - y^2}) = \sqrt{1 - x^2 - y^2}$, whence

$$d\tilde{h}_p = \begin{pmatrix} \frac{-x}{\sqrt{1-x^2-y^2}} & \frac{-y}{\sqrt{1-x^2-y^2}} \end{pmatrix},$$

which has rank 0 if and only if $x, y = 0$, whence $p = (0, 0, 1)$. Thus $p = (0, 0, 1)$ is the only critical point of h in U and has critical value 1.

If $p = (a, b, c) \in S_2$ with $c < 0$, then we have a similar situation except that $\tilde{h}(x, y) = -\sqrt{1 - x^2 - y^2}$ and our chart is (V, ψ) where $V = \{(x, y, z) \in S^2 : z < 0\}$ and $\psi^{-1}(x, y) = (x, y, -\sqrt{1 - x^2 - y^2})$. Thus, again $d\tilde{h}_p$ has rank 0 if and only if $x, y = 0$. So, in this case $p = \psi^{-1}(0, 0) = (0, 0, -1)$ is the only critical point of h in V and has critical value -1 .

Now must check points on the equator $E = \{(x, y, z) \in S^2 : z = 0\}$. Consider points p in the chart (W, ρ) with $W = \{(x, y, z) \in S^2 : y > 0\}$ and $\rho(x, y, z) = (x, z)$. We compute that the coordinate representation of h is then given by $\tilde{h}(x, z) = z$, whence $dF_p = \begin{pmatrix} 0 & 1 \end{pmatrix}$ for all $p \in W$, so no points in W can be critical. Similarly, no points in $W' = \{(x, y, z) \in S^2 : y < 0\}$ can be critical either (identical calculation).

Thus, it remains to check the points $(1, 0, 0)$ and $(-1, 0, 0)$. Consider the chart (K, γ) given by $K = \{x > 0\}$ and $\gamma(x, y, z) = (y, z)$. Then again, $\tilde{h}(y, z) = z$, whence no points in K can be critical. Similarly, no points in $K' = \{(x, y, z) \in S^2 : x < 0\}$ can be critical either (by the same calculation). \square

(b): Show that any map $f : S^2 \rightarrow \mathbb{R}$ has at least two critical points. Generalize this proof from S^2 to any n -dimensional compact manifold.

Proof. Since f is continuous and S^2 is compact, it follows that there exist $p, q \in S^2$ such that $f(p) \leq f(x) \leq f(q)$ for all $x \in S^2$ and $p \neq q$. Thus p, q are global minima/maxima of the function f . Choose a chart (U, ϕ) on S^2 such that $p, q \in U$. Then the function $\tilde{f} : \phi(U) \rightarrow \mathbb{R}$ given by $\tilde{f} = f \circ \phi^{-1}$ is smooth as a function from $\mathbb{R}^2 \rightarrow \mathbb{R}$ and has global minima/maxima p, q . Thus, by calculus 3,

$$\frac{\partial \tilde{f}}{\partial x} = \frac{\partial \tilde{f}}{\partial y} = \frac{\partial \tilde{f}}{\partial x} = \frac{\partial \tilde{f}}{\partial y} = 0,$$

whence df_p has rank 0 at both p and q , so p and q are critical points of f .

Now suppose that $F : M \rightarrow \mathbb{R}$ is a smooth map from an n -dimensional compact manifold M . Again, by continuity, there exist $p, q \in M$ such that $f(p) \leq f(x) \leq f(q)$ for all $x \in M$ and $p \neq q$. Again, choose a chart (U, ϕ) containing both p and q . Then $\tilde{F} = F \circ \phi^{-1}$ is a smooth function from $\phi(U) \subseteq \mathbb{R}^n$ to \mathbb{R} with global minima/maxima p, q . Again, for $i = 1, \dots, n$, it follows that

$$\frac{\partial \tilde{F}}{\partial x_i} = \frac{\partial \tilde{F}}{\partial x_i} = 0,$$

whence the jacobian of \tilde{F} at p and at q has rank 0, making p, q critical points of F . \square

Problem 4

Consider a submanifold $M^n \subseteq \mathbb{R}^k$ and let $TM \subseteq \mathbb{R}^k \times \mathbb{R}^k$ be the set of all pairs (x, v) where x is a point in M and $v \in T_x M$. Show that TM is a smooth $2n$ -dimensional submanifold of \mathbb{R}^{2k} .

Proof. Fix $(x, v) \in TM$ and let (U, ϕ) be a chart on \mathbb{R}^k adapted to M about p . Set $V = U \cap M$, $\tilde{U} = U \times \mathbb{R}^k$, and $\tilde{V} = \bigsqcup_{y \in V} (\{y\} \times T_y M) \subseteq TM$. Let $\tilde{\phi} : \tilde{U} \rightarrow \mathbb{R}^k \times \mathbb{R}^k$ be given by $\tilde{\phi}(y, w) = (\phi(y), d\phi_y(w))$. Note that, after identifying $T_y M \cong \mathbb{R}^n \subseteq \mathbb{R}^k$ for each $y \in U$, we have that $\tilde{V} = \tilde{U} \cap TM$. As (U, ϕ) is adapted to M , by definition $\phi(U) = \phi(U \cap M) \times \{0\} \subseteq \mathbb{R}^n \times \mathbb{R}^{k-n}$. Now compute that

$$\begin{aligned} \tilde{\phi}(\tilde{U}) &= \{(\phi(p), d\phi_p(v)) : p \in V, v \in \mathbb{R}^n\} \\ &= \{(\phi|_V, 0, \dots, 0, d\phi|_V(v), 0, \dots, 0) \in \mathbb{R}^k \times \mathbb{R}^k : p \in V, v \in T_p M\} \\ &= \tilde{\phi}(\tilde{U} \cap TM) \times \mathbb{R}^{2(k-n)}. \end{aligned}$$

Hence, it suffices to show that if $(U, \phi), (V, \psi)$ are two charts on \mathbb{R}^k adapted to M , that the transition maps $\tilde{\phi} \circ \tilde{\psi}^{-1}$ is smooth (the other direction would follow since the charts chosen are arbitrary). Let $p \in \psi(U \cap V), v \in \mathbb{R}^k$. Then

$$\tilde{\phi} \circ \tilde{\psi}^{-1}(p, v) = (\phi \circ \psi^{-1}(p), d\phi_{\psi^{-1}(p)} \circ d\psi_p^{-1}(v)) = (\phi \circ \psi^{-1}(p), d(\phi \circ \psi^{-1})_p(v)),$$

which is smooth as the jacobian smoothly depends upon p, v . □