# **Chapter 3 - Vectors**

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# 3.1 Vectors and Their Components

### key ideas

- Scalars consist of only magnitude and are subject to the ordinary rules of algebra. Vectors consist of magnitude and direction and are subject to the rules of vector algebra.
- Two vectors  $\vec{a}$  and  $\vec{b}$  can be added geometrically by drawing them at common scales and place them head to tail. The vector  $\vec{s}$  that connects the head and the tail is the summed vector. To subtract a vector switch the direction of the one you are subtracting and then proceed as if you were adding them.
- The scalar components,  $(a_x, a_y, a_z, ...)$ , of a vector  $\vec{\mathbf{a}}$  are found by dropping perpendicular lines from the ends of  $\vec{\mathbf{a}}$  onto the coordinate axes. In two dimensions, the components are given by;

$$a_x = a\cos\theta$$
 and  $a_y = a\sin\theta$ 

and the magnitude and orientation by;

$$a = \sqrt{a_x^2 + a_y^2}$$
 and  $\tan(\theta) = \frac{a_y}{a_x}$ 

#### 3.1.1 Vectors and Scalars

**Motion:** A particle moving along a straight line can move in two directions, which can be represented as positive or negative motion. For a particle moving in three dimensions, using just a plus or minus sign is insufficient; vectors are needed to represent both direction and magnitude.

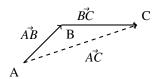
**Vectors:** A vector has both magnitude and direction and follows specific rules for combination. Vector quantities: These are physical quantities that have both magnitude and direction, such as displacement, velocity, and acceleration.

**Scalars:** Physical quantities that do not have a direction, like temperature, pressure, energy, mass, and time. Scalars are handled using regular algebra, and a single value (with a sign) specifies them.

**Displacement:** The simplest vector quantity, which represents a change in position. A vector representing displacement is called a displacement vector. The arrow from point A to B shows displacement, and vectors with the same magnitude and direction (even if shifted) represent the same displacement.

# 3.1.2 Adding Vectors Geometrically

Given a particle that moves from A to B and then B to C. We represent the overall displacement, regardless of the path taken, as two displacement vectors AB and BC. The net displacement is the **vector sum** AC.



The order of the addition does not matter. This is the commutative law;

$$\vec{a} + \vec{b} = \vec{b} + \vec{a}$$

While adding two vectors works the way someone may intuitively guess, subtracting is a little different than scalar subtraction.

$$\vec{\mathbf{d}} = \vec{\mathbf{a}} - \vec{\mathbf{b}} = \vec{\mathbf{a}} + (-\vec{\mathbf{b}})$$

The vector being subtracted is changed to the opposite direction and then added.

# 3.1.3 Component Vectors

#### **Vector Components**

A *component* of a vector is the projection of the vector on an axis. To find the projection of a vector along an axis, we draw perpendicular lines from the two ends of the vector to the axis. The projection of a vector on the x axis is its x component, and similarly the projection on the y axis is the y component. This process of finding the components of a vector is called *resolving* the vector. A component of a vector has the same direction (along an axis) as the vector. If we were to reverse vector  $\vec{a}$ , then both components would be negative, and their arrowheads would point toward the negative x and y directions.

#### **Finding the Components**

We can find the components of  $\vec{a}$  geometrically from the right triangle:

$$a_x = a\cos\theta$$
 and  $a_y = a\sin\theta$ 

where  $\theta$  is the angle that vector  $\vec{a}$  makes with the positive x axis, and a is the magnitude of  $\vec{a}$ . We arrange those components head to tail, and then complete a right triangle with the vector forming the hypotenuse, from the tail of one component to the head of the other.

# Component Notation vs Magnitude-Angle Notation

Once a vector has been resolved into its components along a set of axes, the components themselves can be used in place of the vector. It can also be given by its components  $a_x$  and  $a_y$ . Both pairs of values contain the same information. If we know a vector in component notation  $(a_x \text{ and } a_y)$  and want it in magnitude-angle notation  $(a \text{ and } \theta)$ , we can use the equations:

$$a = \sqrt{a_x^2 + a_y^2}$$
 and  $\tan \theta = \frac{a_y}{a_x}$ 

#### **Three-Dimensional Vectors**

In the more general three-dimensional case, we need a magnitude and two angles (say, a,  $\theta$ , and  $\phi$ ) or three components ( $a_x$ ,  $a_y$ , and  $a_z$ ) to fully specify a vector.

# 3.2 Unit Vectors, Adding Vectors By Components

#### key ideas

- Unit vectors  $\hat{\mathbf{i}}$ ,  $\hat{\mathbf{j}}$ , and  $\hat{\mathbf{k}}$  are the base unit vectors with a magnitude of 1 and directed in the positive direction of the x, y, and z axes respectively.
- We write a vector  $\vec{a}$  as

$$\vec{\mathbf{a}} = a_x \hat{\mathbf{i}} + a_y \hat{\mathbf{j}} + a_z \hat{\mathbf{k}}$$