

# Matthew B. Luebbers

PhD Student / Research Assistant  
University of Colorado Boulder  
<http://m-luebbers.github.io>  
[matthew.luebbers@colorado.edu](mailto:matthew.luebbers@colorado.edu)  
Updated Nov 2022

## Education

---

- University of Colorado Boulder**; Boulder, CO Aug 2018 – Present  
Doctor of Philosophy, Computer Science  
Advisor: Prof. Bradley Hayes  
Collaborative AI and Robotics Lab (CAIRO)
- University of Colorado Boulder**; Boulder, CO Aug 2018 – May 2021  
Master of Science, Computer Science
- Cornell University**; Ithaca, NY Aug 2014 – May 2018  
Bachelor of Arts, Computer Science  
Internal Concentration: Artificial Intelligence & Robotics  
External Concentration: Psychology

## Professional Experience

---

- NASA Jet Propulsion Laboratory**; Pasadena, CA Jun 2020 – Aug 2020  
Research Technologist Intern, Robotics (347)  
Created the composite terrain generation pipeline for a Monte-Carlo simulation tool to enable statistical analysis of plans generated by the Perseverance rover's ENav system for autonomous navigation.
- NASA Jet Propulsion Laboratory**; Pasadena, CA Jun 2019 – Aug 2019  
Robotic Systems Engineering Intern, Robotics (347)  
Designed a virtual reality application for stereo image viewing and 3D plan overlay for the Rover Sequencing & Visualization Program (RSVP). Intended for use in rover driving activities for the Mars rovers Curiosity & Perseverance. Also participated in tactical rover driving sessions of Curiosity, learning to sequence and operate the vehicle while helping command its drives to scientific targets.
- NASA Jet Propulsion Laboratory**; Pasadena, CA Jun 2018 – Aug 2018  
Software Systems Engineering Intern, Instrument Data Systems (398)  
Continued work on the Common Workflow Service (CWS), including creation of a web-based BPMN process modeler to contain all CWS functionality within a single webapp.
- NASA Jet Propulsion Laboratory**; Pasadena, CA Jun 2017 – Aug 2017  
Software Systems Engineering Intern, Instrument Data Systems (398)  
Continued work on the Common Workflow Service (CWS), including adaptation work for the Instrument Data Systems pipelines of the Mars 2020 mission.
- NASA Jet Propulsion Laboratory**; Pasadena, CA Jun 2016 – Aug 2016  
Software Systems Engineering Intern, Instrument Data Systems (398)  
Worked on the Common Workflow Service (CWS), a cloud-based workflow-management system for NASA's Advanced Multi-Mission Operations System (AMMOS).

## Teaching & Research Assistantships

---

- Army Research Lab STRONG Program** Aug 2020 – Present  
**University of Colorado Boulder**; Boulder, CO  
Research Assistant, Prof. Bradley Hayes

<b>CSCI 5302 (Advanced Robotics)</b> <b>University of Colorado Boulder</b> ; Boulder, CO Course Manager, Prof. Bradley Hayes	Aug 2021 – Dec 2021
<b>CSCI 5722 (Computer Vision)</b> <b>University of Colorado Boulder</b> ; Boulder, CO Teaching Assistant, Prof. Ioana Fleming	Jan 2020 – May 2020
<b>CSCI 1300 (Introduction to Computer Science)</b> <b>University of Colorado Boulder</b> ; Boulder, CO Teaching Assistant, Prof. Ioana Fleming	Aug 2019 – Dec 2019
<b>Dean's Graduate Fellowship</b> <b>University of Colorado Boulder</b> ; Boulder, CO Research Assistant, Prof. Bradley Hayes	Aug 2018 – May 2019
<b>CS 4700 (Foundations of Artificial Intelligence)</b> <b>Cornell University</b> ; Ithaca, NY Teaching Assistant, Prof. Bart Selman	Aug 2017 – Dec 2017
<b>CS 3410 (Computer System Organization &amp; Programming)</b> <b>Cornell University</b> ; Ithaca, NY Teaching Assistant, Prof. Anne Bracy	Aug 2016 – May 2017
<b>CS 2110 (Object-Oriented Programming &amp; Data Structures)</b> <b>Cornell University</b> ; Ithaca, NY Course Consultant, Profs. David Gries, Nate Foster, & Ross Tate	Aug 2015 – May 2016

## Publications

---

Asterisk (\*) denotes shared first authorship

### Journal Papers

- J1. Aaquib Tabrez, Matthew B. Luebbers, and Bradley Hayes. (2020). **A Survey of Mental Modeling Techniques in Human-Robot Teaming**. In Current Robotics Reports. Springer-Nature.

### Conference Papers

- C1. Matthew B. Luebbers\*, Aaquib Tabrez\*, and Bradley Hayes. (2022). **Descriptive and Prescriptive Visual Guidance to Improve Shared Situational Awareness in Human-Robot Teaming**. In Proceedings of the International Conference on Autonomous Agents and Multiagent Systems (AAMAS 2022). Auckland, New Zealand. *Best Student Paper Runner-Up (Top 2 of 629 submissions). Acceptance Rate: 26%.*
- C2. Matthew B. Luebbers, Connor Brooks, Carl L. Mueller, Daniel Szafir, and Bradley Hayes. (2021). **ARC-LfD: Using Augmented Reality for Interactive Long-Term Robot Skill Maintenance via Constrained Learning from Demonstration**. In Proceedings of the IEEE International Conference on Robotics and Automation (ICRA 2021). Xi'an, China. *Acceptance Rate: 48%.*

### Workshops, Symposia, & Posters

- W1. Matthew B. Luebbers\*, Aaquib Tabrez\*, and Bradley Hayes. (2022). **Augmented Reality-Based Explainable AI Strategies for Establishing Appropriate Reliance and Trust in Human-Robot Teaming**. In Proceedings of the Workshop on Virtual, Augmented and Mixed Reality for Human-Robot Interaction (VAM-HRI 2022). Sapporo, Japan.
- W2. Matthew B. Luebbers\*, Christine T. Chang\*, Aaquib Tabrez\*, Jordan Dixon\*, and Bradley Hayes. (2021). **Emerging Autonomy Solutions for Human and Robotic Deep Space Exploration**. In Proceedings of SpaceCHI: Human-Computer Interaction for Space Exploration (SpaceCHI 2021). Yokohama, Japan.

- W3. Matthew B. Luebbbers\*, Aaquib Tabrez\*, and Bradley Hayes. (2020). **Automated Failure-Mode Clustering and Labeling for Informed Car-To-Driver Handover in Autonomous Vehicles**. In Proceedings of the Workshop on Assessing, Explaining, and Conveying Robot Proficiency for Human-Robot Teaming. Cambridge, UK.
- W4. Matthew B. Luebbbers, Connor Brooks, Minjae John Kim, Daniel Szafir, and Bradley Hayes. (2019). **Augmented Reality Interface for Constrained Learning from Demonstration**. In Proceedings of the Workshop on Virtual, Augmented and Mixed Reality for Human-Robot Interaction (VAM-HRI 2019). Daegu, South Korea.
- W5. Matthew B. Luebbbers, Ramchandran Muthukumar, Madeleine Udell, and Ross A. Knepper. (2017). **Planning Aerial Survey Missions using Low Rank Approximation**. Presented: Northeast Robotics Colloquium (NERC 2017). Boston, Massachusetts, USA.

## Further Experience

---

### Workshop Leadership

- Organizing Committee, “Virtual, Augmented and Mixed Reality for Human-Robot Interaction (VAM-HRI)”, HRI 2023.
- Organizing Committee, “Exploring Applications for Autonomous Non-Verbal Human-Robot Interactions (nHRI)”, HRI 2021.

### Conference & Journal Review

- Robotics and Automation Letters (RA-L)
- IEEE/RSJ International Conference on Intelligent Robotics and Systems (IROS)
- IEEE International Conference on Robotics and Automation (ICRA)
- ACM/IEEE International Conference on Human-Robot Interaction (HRI)
- IEEE International Conference on Robot and Human Interactive Communication (RO-MAN)

### Additional Projects of Interest

- Self-Driving RC Car** Aug 2019 – Dec 2019  
 Designed and built a self-driving RC car capable of racing around indoor tracks. Created in a team of five as a semester-long project for CSCI 5302 – Advanced Robotics.
- Multiple Asteroid Flyby Mission Formulation** Jan 2019 – May 2019  
 Formulated a NASA Discovery-class mission concept for a robotic spacecraft to perform multispectral remote sensing of three main-belt asteroids to gain valuable understanding of planetary migration and solar system formation. Delivered a formal, cost-constrained proposal, and presented a PDR (Preliminary Design Review). Created in a team of ten as a semester-long project for ASEN 5148 – Spacecraft Design. I was responsible for the CDH (Command & Data Handling), and FSW (Flight Software) subsystems.
- Autonomous Solar-Powered Airship** Sep 2016 – May 2018  
 Group project within Cornell’s Robotic Personal Assistants Lab (RPAL) to design and build an airship capable of flying autonomously. A lightweight solar power system and robust autonomy extend the range of the airship, enabling it to perform long-duration aerial survey missions for ecological monitoring.