

# Solution to Problem Set 4

October 2017

## Pb 1. 20 pts.

There are many ways of doing this problem but the easiest would be

$$\begin{aligned}\hat{a}^\dagger |\alpha\rangle &= \hat{a}^\dagger \hat{D}(\alpha) |0\rangle = \hat{a}^\dagger \exp(\alpha \hat{a}^\dagger - \alpha^* \hat{a}) |0\rangle = \hat{a}^\dagger e^{-\alpha^* \alpha/2} e^{\alpha \hat{a}^\dagger} |0\rangle \\ &= \left( \frac{\partial}{\partial \alpha} + \frac{\alpha^*}{2} \right) e^{-\alpha^* \alpha/2} e^{\alpha \hat{a}^\dagger} |0\rangle = \left( \frac{\partial}{\partial \alpha} + \frac{\alpha^*}{2} \right) |\alpha\rangle,\end{aligned}\tag{1}$$

where we used the Zassenhaus formula (see full expression in Wikipedia or any advanced quantum textbook), which reduces to

$$e^{\hat{X}+\hat{Y}} = e^{\hat{X}} e^{\hat{Y}} e^{-[\hat{X},\hat{Y}]/2},\tag{2}$$

if  $[X, Y]$  commutes with both  $X$  and  $Y$ . The displacement operator can then be expressed as

$$\hat{D}(\alpha) = e^{-\alpha^* \alpha/2} e^{\alpha \hat{a}^\dagger} e^{-\alpha^* \hat{a}}.\tag{3}$$

## Pb 2. 80 pts.

For this problem, I highly recommended two books for reference.

- Sean Carroll *Geometry and Spacetime, an Introduction to General Relativity*. This may be the standard textbook for GR class next semester. You will find a lot of good examples and exercises about Lorentz Indices in the first two chapters.
- John Baez etc. *Gauge Fields, Knots and Gravity*. A very cute book tells about gauge fields and gravity as an aspect of differential geometry. You can learn a lot about the second problem in first two parts.

In this problem, we use Greek letter  $\alpha, \beta, \gamma, \dots, \mu, \nu, \dots$  for spacetime Lorentzian indices  $0, 1, 2, 3$  and Latin letter  $i, j, k, \dots$  for spatial indices  $1, 2, 3$ . Still we set  $c = 1$ .

### a) Maxwell Equation with Lorentz Indices

In this problem we look at the covariant formulation of classical electromagnetism. As defined in the problem statement, the action  $S$  is

$$S = \int d^4x \mathcal{L} = -\frac{1}{g^2} \int d^4x F_{\mu\nu} F^{\mu\nu} = -\frac{1}{g^2} \int d^4x F_{\mu\nu} g^{\mu\gamma} g^{\nu\kappa} F_{\gamma\kappa},\tag{4}$$

$$F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu = -F_{\nu\mu},\tag{5}$$

and we're interested in finding the equations of motion for the electromagnetic 4-potential  $A^\mu = (\phi, \vec{A})$ , which can be determined from the Euler-Lagrange equations for fields,

$$\begin{aligned}
0 &= \partial_\beta \left( \frac{\partial \mathcal{L}}{\partial (\partial_\beta A_\alpha)} \right) - \frac{\partial \mathcal{L}}{\partial A_\alpha} = -\partial_\beta \left( \frac{g^{\mu\gamma} g^{\nu\kappa}}{g^2} \frac{\partial (F_{\mu\nu} F_{\gamma\kappa})}{\partial (\partial_\beta A_\alpha)} \right) \\
&= -\partial_\beta \left( \frac{g^{\mu\gamma} g^{\nu\kappa}}{g^2} \left[ \frac{\partial F_{\mu\nu}}{\partial (\partial_\beta A_\alpha)} F_{\gamma\kappa} + F_{\mu\nu} \frac{\partial F_{\gamma\kappa}}{\partial (\partial_\beta A_\alpha)} \right] \right) \\
&= -\partial_\beta \left( \frac{g^{\mu\gamma} g^{\nu\kappa}}{g^2} [(\delta_\mu^\beta \delta_\nu^\alpha - \delta_\nu^\beta \delta_\mu^\alpha) F_{\gamma\kappa} + (\delta_\gamma^\beta \delta_\kappa^\alpha - \delta_\kappa^\beta \delta_\gamma^\alpha) F_{\mu\nu}] \right) \\
&= -\frac{1}{g^2} \partial_\beta ((g^{\beta\gamma} g^{\alpha\kappa} - g^{\alpha\gamma} g^{\beta\kappa}) F_{\gamma\kappa} + (g^{\mu\beta} g^{\nu\alpha} - g^{\mu\alpha} g^{\nu\beta}) F_{\mu\nu}) \\
&= -\frac{2}{g^2} \partial_\beta (F^{\beta\alpha} - F^{\alpha\beta}) = -\frac{4}{g^2} \partial_\beta F^{\beta\alpha},
\end{aligned} \tag{6}$$

and we found two of the Maxwell's equations in vacuum (Gauss electric law & Ampere law),

$$\partial_\beta F^{\beta\alpha} = 0. \tag{7}$$

The electromagnetic tensor also satisfies the Bianchi property

$$\partial_{[\mu} F_{\nu\gamma]} = 0, \tag{8}$$

where  $[\ ]$  is the alternating sum over all permutations. This is because partial derivatives commute (recall the definition of  $F_{\mu\nu}$  contains derivative). This identity leads to the other two Maxwell equations (Faraday law & Gauss magnetic law). The Maxwell equations with sources are

$$\partial_\mu F^{\mu\nu} = J^\nu, \tag{9}$$

and it means that the source terms should come from

$$\frac{\partial \mathcal{L}}{\partial A_\nu} = \frac{4}{g^2} J^\nu, \tag{10}$$

meaning the action should be modified as

$$S_1 \rightarrow -\frac{1}{g^2} \int d^4x F_{\mu\nu} F^{\mu\nu} - \frac{4}{g^2} \int d^4x A_\mu J^\mu. \tag{11}$$

To write Maxwell Equation explicitly, we may take advantages of anti-symmetric tensor  $\epsilon$ . First we want to define  $E$  and  $B$  by  $F^{i0} = E^i$  and  $F^{ij} = -\epsilon^{ijk} B_k$  and inversely we have  $E^i = F^{i0}$  and  $B^i = -\frac{\epsilon^{ijk}}{2} F_{jk}$ .

Starting with (9), first we set  $\nu = 0$  and  $\mu = i = 1, 2, 3$ , (9) becomes

$$\partial_i F^{i0} = \partial_i E^i = \rho \tag{12}$$

which is Gauss's Law for electric field. Then we set  $\nu = j = 1, 2, 3$  and Ampere's Law for magnetic field appears

$$\partial_\mu F^{\mu j} = \partial_t F^{0j} + \partial_i F^{ij} = -\frac{\partial E^j}{\partial t} - \epsilon^{ijk} \partial_i B_k = -\frac{\partial E^j}{\partial t} + (\nabla \times \vec{B})^j = j^j \tag{13}$$

As we mention above, the other two equations are from Bianchi identity. For simplicity, we rewrite Bianchi identity as

$$\epsilon^{\mu\nu\alpha\beta} \partial_\nu F_{\alpha\beta} = \epsilon^{\mu\nu\alpha\beta} \partial_\nu (\partial_\alpha A_\beta - \partial_\beta A_\alpha) = 2\epsilon^{\mu\nu\alpha\beta} \partial_\alpha \partial_\beta A_\nu = 0 \tag{14}$$

Of course from (14) we will get an explicitly impression on why Bianchi identity holds for electromagnetic fields. For  $\mu = 0$ , (14) is the Gauss's Law for magnetic field. Noticing  $\epsilon^{0\nu\alpha\beta} = \epsilon^{ijk}$ , we have

$$0 = \epsilon^{ijk} \partial_i F_{jk} = \epsilon^{ijk} \epsilon_{jkl} \partial_i B^l = 2\delta_i^l \partial_i B^l = 2\nabla \cdot \vec{B} \tag{15}$$

For  $\mu = i = 1, 2, 3$ , calculation is a little bit more complicated but we can still work out

$$0 = \epsilon^{i0jk} \partial_t F_{jk} + \epsilon^{ij0k} \partial_j F_{0k} + \epsilon^{ijk0} \partial_j F_{k0} = -\epsilon^{ijk} \partial_t F_{jk} - 2\epsilon^{ijk} \partial_j F_{k0} = 2\frac{\partial \vec{B}^{(i)}}{\partial t} + 2\nabla \times \vec{E}^{(i)} = 0 \tag{16}$$

Till now we have derived all four Maxwell equations explicitly.

## b) A glance at differential Geometry, Hodge Operator, and other properties on differential forms.

Now we turn to differential geometry. In that formalism the action  $S_1$  takes the simpler form

$$S_2 = -\frac{1}{g^2} \int F \wedge (\star F) \equiv S_1, \quad (17)$$

$$A \equiv A_\mu dx^\mu \quad (18)$$

$$F \equiv F_{\mu\nu} dx^\mu \wedge dx^\nu \quad (19)$$

$$d \equiv dx^\mu \partial_\mu \quad (20)$$

where the wedge product satisfies  $dx^\mu \wedge dx^\nu = -dx^\nu \wedge dx^\mu$  as stated in the problem.

Now we can find the equations of motion using  $S_2$ . We define the exterior derivative of p-form  $X$  as

$$dX = (dX_{k_1 \dots k_p}) \wedge dx^{k_1} \wedge \dots \wedge dx^{k_p} = \frac{1}{p!} \partial_{[k_1} X_{k_2 \dots k_{p+1}]} dx^{k_1} \wedge \dots \wedge dx^{k_{p+1}}, \quad (21)$$

which can be found from the definition of  $d$  given in the problem.

- Some Useful Properties of Differential Form

Suppose we have a p-form  $X \equiv X_I dx^I$ , where  $I$  represent multiple indices.

–  $d^2 X = 0$ , this is because

$$d(dX) = \partial_\mu \partial_\nu X_I dx^\mu \wedge dx^\nu \wedge dx^I = 0 \quad (22)$$

–  $d(X \wedge Y) = dX \wedge Y + (-1)^p X \wedge dY$ , we can proof it as

$$\begin{aligned} d(X \wedge Y) &= (\partial_\mu X_I Y_J + X_I \partial_\mu Y_J) dx^\mu \wedge dx^I \wedge dy^J \\ &= (\partial_\mu X_I Y_J) dx^\mu \wedge dx^I \wedge dy^J + (-1)^p (X_I \partial_\mu Y_J) dx^I \wedge dx^\mu \wedge dy^J \\ &= dX \wedge Y + (-1)^p X \wedge dY \end{aligned} \quad (23)$$

- Some Useful Properties of Hodge Operator. At first we will figure out  $\star\star$  is a kind of self dual.

$$X = X_{k_1 \dots k_p} dx^{k_1} \wedge \dots \wedge dx^{k_p} \equiv X_I dx^I, \quad (24)$$

$$\star X = \frac{\sqrt{|\det g_{\mu\nu}|}}{p!} \epsilon_{k_{p+1} \dots k_{d+1}}^{k_1 \dots k_p} X_{k_1 \dots k_p} dx^{k_{p+1}} \wedge \dots \wedge dx^{k_{d+1}}, \quad (25)$$

$$\star(\star X) = \frac{\sqrt{|\det g_{\mu\nu}|}}{(d+1-p)!} \epsilon_{q_1 \dots q_p}^{k_{p+1} \dots k_{d+1}} \frac{\sqrt{|\det g_{\mu\nu}|}}{p!} \epsilon_{k_{p+1} \dots k_{d+1}}^{k_1 \dots k_p} X_{k_1 \dots k_p} dx^{q_1} \wedge \dots \wedge dx^{q_p}, \quad (26)$$

where applying the Hodge star operator twice gives back a p-form,  $d+1-(d+1-p)=p$ . We will need the following identity

$$\epsilon^{k_{p+1} \dots k_{d+1} q_1 \dots q_p} \epsilon_{k_{p+1} \dots k_{d+1} k_1 \dots k_p} = -(d+1-p)! \delta_{k_1}^{q_1} \dots \delta_{k_p}^{q_p}, \quad (27)$$

... Using the identity above we have the following result

$$\begin{aligned} \epsilon_{q_1 \dots q_p}^{k_{p+1} \dots k_{d+1}} \epsilon_{k_{p+1} \dots k_{d+1}}^{k_1 \dots k_p} &= (-1)^{d+1-p} \epsilon_{q_1 \dots q_p}^{k_{p+1} \dots k_{d+1}} \epsilon_{k_{p+1} \dots k_{d+1}}^{k_1 \dots k_p} \\ &= (-1)^{p(d+1-p)} \epsilon_{q_1 \dots q_p}^{k_{p+1} \dots k_{d+1}} \epsilon_{k_{p+1} \dots k_{d+1}}^{k_1 \dots k_p} \\ &= (-1)^{p(d+1-p)} g_{q_1 \alpha_1} \dots g_{q_p \alpha_p} \epsilon_{k_{p+1} \dots k_{d+1} \alpha_1 \dots \alpha_p} g^{k_1 \beta_1} \dots g^{k_p \beta_p} \epsilon_{k_{p+1} \dots k_{d+1} \beta_1 \dots \beta_p} \\ &= -(-1)^{p(d+1-p)} (d+1-p)! g_{q_1 \alpha_1} \dots g_{q_p \alpha_p} g^{k_1 \beta_1} \dots g^{k_p \beta_p} \delta_{\beta_1}^{\alpha_1} \dots \delta_{\beta_p}^{\alpha_p} \\ &= -(-1)^{p(d+1-p)} (d+1-p)! \delta_{q_1}^{k_1} \dots \delta_{q_p}^{k_p}, \end{aligned} \quad (28)$$

which allows us to simplify

$$\begin{aligned}
\star(\star X) &= -(-1)^{p(d+1-p)} \frac{|\det g_{\mu\nu}|}{p!} \delta_{q_1}^{k_1} \cdots \delta_{q_p}^{k_p} X_{k_1 \dots k_p} dx^{q_1} \wedge \cdots \wedge dx^{q_p} \\
&= -(-1)^{p(d+1-p)} \frac{|\det g_{\mu\nu}|}{p!} X_{k_1 \dots k_p} dx^{k_1} \wedge \cdots \wedge dx^{k_p} \\
&= -(-1)^{p(d+1-p)} \sqrt{|\det g_{\mu\nu}|} X = -(-1)^{p(d+1-p)} X,
\end{aligned} \tag{29}$$

where  $\det g_{\mu\nu} = -1$  in our case. Now we focus on the special case

$$\star(\star F) = -(-1)^4 F = -F. \tag{30}$$

Let's look at the Hodge operator more carefully. The Hodge star operator ( $\star$ ) maps the  $p$ -form  $X$  to a  $(d+1-p)$ -form  $\star X$  as follows. Therefore, it is easy for us to construct a  $n$ -form from two  $p$ -forms  $A$  and  $B$  as  $A \wedge \star B$ . And we have some such identity

$$\int A \wedge \star B = \int \star A \wedge B \tag{31}$$

### c) Maxwell equation in differential form

It is useful to realize that  $F = dA$  and this is very easy to verify  $F = F_{\mu\nu} dx^\mu \wedge dx^\nu = \frac{1}{2!} (\partial_\mu A_\nu - \partial_\nu A_\mu) dx^\mu \wedge dx^\nu = dA$ . From (22), we can derive second pair of Maxwell equations.

$$dF = d(dA) = 0 \tag{32}$$

By action principle, we can extremize the action  $S_2$  to get the first pair of Maxwell equation.

$$\begin{aligned}
0 = \delta_A S_2 &= -\frac{1}{g^2} \int [d(\delta A) \wedge (\star dA) + dA \wedge (\star d(\delta A))] \\
&= -\frac{2}{g^2} \int d(\delta A) \wedge (\star dA) \\
&= -\frac{2}{g^2} \int [d(\delta A \wedge (\star F)) + \delta A \wedge d(\star F)] \\
&= -\frac{2}{g^2} \int \delta A \wedge d(\star F),
\end{aligned} \tag{33}$$

where we used the identity, for a  $p$ -form  $X$  and a  $q$ -form  $Y$ ,  
which is easy to show with what's given in the problem. We just found

$$d(\star F) = 0. \tag{34}$$

Note that in the presence of sources you would find

$$dF = 0, \tag{35}$$

$$d(\star F) = \star J. \tag{36}$$

Now we consider the action

$$S_3 = -\frac{1}{g^2} \int F \wedge (\star F) + \theta \int F \wedge F, \tag{37}$$

and extremize the action

$$0 = \delta_A S_3 = -\frac{2}{g^2} \int d(\delta A) \wedge (\star F) + 2\theta \int d(\delta A) \wedge F = -\frac{2}{g^2} \int \delta A \wedge d(\star F) + 2\theta \int \delta A \wedge dF, \tag{38}$$

but since  $dF = d(dA) = 0$ , the equations of motion are unchanged:  $d(\star F) = 0$ .

### d) A particle moving in fields

Now we consider the action

$$S_4 = -\frac{1}{g^2} \int F \wedge (\star F) + \theta \int F \wedge F + \frac{m}{2} \int dt \dot{X}^2 + q \int A = \int dt L, \quad (39)$$

The 4-current due to the point particle is  $I^\mu = q(1, \dot{\vec{X}}) = q(1, \vec{V})$  (note: this is not a density), and thus  $qA = qA_\mu dX^\mu = A_\mu(qdX^\mu/dt)dt = A_\mu I^\mu dt = q\phi dt - q\vec{A} \cdot \vec{V}$ . First the canonical momentum of the point particle is

$$P^j = \frac{dL}{d\dot{X}^j} = m\dot{X}^j - qA^j \Rightarrow \vec{P} = m\vec{\dot{X}} - q\vec{A}, \quad (40)$$

where  $j$  stands for spatial coordinates. The momentum of the particle is shifted by  $q\vec{A}$ . Secondly we find the equations of motion of the point particle

$$\begin{aligned} \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{X}^j} \right) - \frac{\partial L}{\partial X^j} &= m\ddot{X}^j - q \frac{dA^j}{dt} - q \frac{d\phi}{dX^j} + q \frac{d}{dX^j} (\vec{A} \cdot \vec{V}) \\ &= m\ddot{X}^j - q \frac{\partial A^j}{\partial t} - q \frac{d\phi}{dX^j} + q \frac{d}{dX^j} (\vec{A} \cdot \vec{V}) - q \frac{dX^i}{dt} \frac{dA^j}{dX^i} \\ &= m\ddot{X}^j - q \frac{\partial A^j}{\partial t} - q \frac{d\phi}{dX^j} + q \frac{d}{dX^j} (\vec{A} \cdot \vec{V}) - qV_i \frac{dA^j}{dX^i}. \end{aligned} \quad (41)$$

We find that

$$m\ddot{\vec{X}} = q \frac{\partial \vec{A}}{\partial t} + q\nabla\phi - q\nabla(\vec{A} \cdot \vec{V}) + q(\vec{V} \cdot \nabla)\vec{A} = -q \left[ -\frac{\partial \vec{A}}{\partial t} - \nabla\phi + \vec{V} \times (\nabla \times \vec{A}) \right] = -q [\vec{E} + \vec{V} \times \vec{B}] \quad (42)$$

It shouldn't be surprising that we found the Lorentz force. Then we extremize the action for the EM fields

$$0 = \delta_A S_4 = -\frac{1}{g^2} \int d(\delta A) \wedge (\star F) + \int \delta A \wedge (\star J) = -\frac{1}{g^2} \int \delta A \wedge d(\star F) + \int \delta A \wedge (\star J), \quad (43)$$

and we found

$$d(\star F) = \star J, \quad (44)$$

(where  $J$  is a 1-form). Now define the current density use Dira delta functions,

$$J^\mu = q \left( \delta(\vec{x} - \vec{X}), \vec{V} \delta(\vec{x} - \vec{X}) \right) \quad (45)$$

where  $\vec{X}(t)$  is the path of the particle (such that  $\int d\vec{x} A_\mu J^\mu = A_\mu I^\mu|_{x=X}$  which we used before). Then do the Hodge star operation and you get the Maxwell equations with sources.

### e) Chern-Simons term

Now we consider the action

$$S_5 = c_1 \int A \wedge dA + c_2 \int A \wedge A \wedge A \quad (46)$$

and extremize the action

$$\begin{aligned} 0 = \delta_A S_5 &= c_1 \int \delta A \wedge dA + c_1 \int A \wedge d(\delta A) + 3c_2 \int \delta A \wedge A \wedge A \\ &= 2c_1 \int \delta A \wedge dA + 3c_2 \int \delta A \wedge A \wedge A \end{aligned} \quad (47)$$

$$F := dA + \frac{3c_2}{2c_1} A \wedge A = 0 \quad (48)$$

Here the cubic term is related to the structure constant of gauge group. Notice that in general we have non-Abelian gauge theory (Yang -Mills Theory). For instance, usually we  $c_2 = \frac{2}{3}c_1$  and we define field strength (in explicit form)

$$F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu + [A_\mu, A_\nu] \quad (49)$$