

▼ CNN Applied to EEG Data to classify subject 1 data

▼ Preparation and Loading Data

```
from google.colab import drive
drive.mount('/content/drive')
```

```
Mounted at /content/drive
```

```
%pwd
```

```
'/content'
```

```
% cd 'drive/My Drive/ECE C147'
```

```
% cd 'project'
```

```
% ls
```

```
/content/drive/My Drive/ECE C147
```

```
/content/drive/My Drive/ECE C147/project
```

```
EEG_loading.ipynb  person_train_valid.npy  X_train_valid.npy  y_train_valid.npy
```

```
person_test.npy   X_test.npy             y_test.npy
```

```
def count_parameters(model):
```

```
    """Function for count model's parameters"""
```

```
    return sum(p.numel() for p in model.parameters() if p.requires_grad)
```

```
import numpy as np
```

```
import torch
```

```
import torch.nn as nn
```

```
from torch.utils.data import Dataset, DataLoader, TensorDataset, random_split
```

```
from torchvision import transforms, utils
```

```
import time
```

```
# specific package for visualization
```

```
!pip install livelossplot --quiet
```

```
from livelossplot import PlotLosses
```

```
# get the device type of machine
```

```
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
```

```
# device = 'cpu'
```

```
print(device)
```

```
cuda
```

```
X_test = np.load("X_test.npy")
y_test = np.load("y_test.npy")
person_train_valid = np.load("person_train_valid.npy")
X_train_valid = np.load("X_train_valid.npy")
y_train_valid = np.load("y_train_valid.npy")
person_test = np.load("person_test.npy")
```

```
# adjust labels
y_train_valid -= 769
y_test -= 769
```

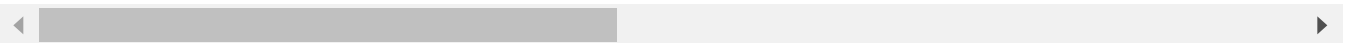
```
print('y_train_valid', y_train_valid[:10])
```

```
y_train_valid [2 3 0 0 0 0 2 1 3 3]
```

```
#filter data for subject 1 only
```

```
train_val_subject1_idx = []
for i, n in enumerate(person_train_valid):
    if n==0:
        train_val_subject1_idx.append(i)
X_train_val_subject1 = X_train_valid[train_val_subject1_idx]
y_train_val_subject1 = y_train_valid[train_val_subject1_idx]
print(len(y_train_val_subject1))
test_subject1_index = []
for i, n in enumerate(person_test):
    if n==0:
        test_subject1_index.append(i)
print(test_subject1_index)
X_test_subject1 = X_test[test_subject1_index]
y_test_subject1 = y_test[test_subject1_index]
print(len(y_test_subject1))
```

```
237
[0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23,
50
```



```
# copy numpy data to tensor
```

```
X_train_valid_tensor = torch.from_numpy(X_train_valid).float().to(device)
X_train_valid_s1_tensor = torch.from_numpy(X_train_val_subject1).float().to(device)
y_train_valid_tensor = torch.from_numpy(y_train_valid).float().long().to(device) # do not for
y_train_valid_s1_tensor = torch.from_numpy(y_train_val_subject1).float().long().to(device)
X_test_tensor = torch.from_numpy(X_test_subject1).float().to(device)
```

```

y_test_tensor = torch.from_numpy(y_test_subject1).float().long().to(device)

# # convert int labels to one hot labels
# y_train_valid_tensor = nn.functional.one_hot(y_train_valid_tensor)
# print('y_train_valid_onehot', y_train_valid_tensor[:10])

print ('Training/Valid data shape: {}'.format(X_train_valid.shape))
print ('Training/Valid for s1 data shape: {}'.format(X_train_val_subject1.shape))
print ('Test data shape: {}'.format(X_test_subject1.shape))
print ('Training/Valid target shape: {}'.format(y_train_valid.shape))
print ('Training/Valid for s1 target shape: {}'.format(y_train_val_subject1.shape))
print ('Test target shape: {}'.format(y_test_subject1.shape))
#print ('Person train/valid shape: {}'.format(person_train_valid.shape))
#print ('Person test shape: {}'.format(person_test.shape))

```

```

Training/Valid data shape: (2115, 22, 1000)
Training/Valid for s1 data shape: (237, 22, 1000)
Test data shape: (50, 22, 1000)
Training/Valid target shape: (2115,)
Training/Valid for s1 target shape: (237,)
Test target shape: (50,)

```

```

class EEGDataset(Dataset):
    """EEG dataset."""
    def __init__(self, subset, transform=None):
        self.subset = subset
        self.transform = transform

    def __getitem__(self, index):
        x, y = self.subset[index]
        if self.transform:
            pass
            # x = self.transform(x)
            # y = self.transform(y)
        return x, y

    def __len__(self):
        return len(self.subset)

init_dataset = TensorDataset(X_train_valid_tensor, y_train_valid_tensor)
init_s1_dataset = TensorDataset(X_train_valid_s1_tensor, y_train_valid_s1_tensor)
test_dataset = TensorDataset(X_test_tensor, y_test_tensor)
# split train and val
lengths = [int(len(init_dataset)*0.8), int(len(init_dataset)*0.2)]
print(lengths)
subset_train, subset_val = random_split(init_dataset, lengths)
lengths_s1 = [int(len(init_s1_dataset)*0.8), 237-int(len(init_s1_dataset)*0.8)]
print(lengths_s1)
subset_train_s1, subset_val_s1 = random_split(init_s1_dataset, lengths_s1)
train_data = EEGDataset(

```

```

subset_train, transform=None)

val_data = EEGDataset(
    subset_val, transform=None)

train_data_s1 = EEGDataset(subset_train_s1,transform=None)
val_data_s1 = EEGDataset(subset_val_s1,transform=None)

test_data=EEGDataset(test_dataset,transform=None)

dataloaders = {
    'train': torch.utils.data.DataLoader(train_data, batch_size=32, shuffle=True, num_workers=4),
    'val': torch.utils.data.DataLoader(val_data, batch_size=32, shuffle=True, num_workers=0),
    'train_s1': torch.utils.data.DataLoader(train_data_s1, batch_size=32, shuffle=True, num_workers=4),
    'val_s1': torch.utils.data.DataLoader(val_data_s1, batch_size=32, shuffle=True, num_workers=0),
    'test':torch.utils.data.DataLoader(test_data, batch_size=64, shuffle=False, num_workers=0)
}

[1692, 423]
[189, 48]

```

▼ Model

```

class ShallowConv(nn.Module):

    # Defining the building blocks of shallow conv net

    def __init__(self, in_channels, num_conv_filters, num_samples_frame, num_eeg_channels, class_num):

        # Defining as a subclass
        super(ShallowConv, self).__init__()

        self.num_samples_frame = num_samples_frame
        self.num_conv_filters = num_conv_filters
        self.num_eeg_channels = num_eeg_channels

        # Define the convolution layer, https://pytorch.org/docs/stable/generated/torch.nn.Conv2d.html
        self.conv1 = nn.Conv2d(in_channels, self.num_conv_filters, (1, 25), stride=1)
        self.conv_output_width = int(self.num_samples_frame - (25-1) - 1 + 1)

        # Define the 2d batchnorm layer
        self.bnorm2d = nn.BatchNorm2d(self.num_conv_filters)

        # Define the 1d batchnorm layer
        self.bnorm1d = nn.BatchNorm1d(self.num_conv_filters)

        # Define the fc layer, https://pytorch.org/docs/stable/generated/torch.nn.Linear.html

```

```

self.fc1 = nn.Linear(self.num_eeg_channels*self.num_conv_filters, self.num_conv_filters)

# Define the elu activation
self.elu = nn.ELU(0.2)

# Define the avg pooling layer
self.avgpool = nn.AvgPool1d(75, stride=15)

self.num_features_linear = int(np.floor(((self.conv_output_width - 75)/15)+1))

# Define the fc layer for generating the scores for classes
self.fc2 = nn.Linear(self.num_features_linear*self.num_conv_filters, classes)

# Define the softmax layer for converting the class scores to probabilities
self.softmax = nn.Softmax(dim=1)

# Defining the connections of shallow conv net

def forward(self, x):

    # Reshaping the input for 2-D convolution (B,22,num_samples_frame) -> (B,1,22,num_samples_frame)
    x = x.view(-1, 1, 22, self.num_samples_frame)

    # Performing the 2-D convolution (B,1,22,300) -> (B,40,22,x_shape_4dim)

    x = self.conv1(x)
    x_shape_4dim = x.shape[3]

    # ELU activation

    x = self.elu(x)

    # 2d Batch normalization

    x = self.bnorm2d(x)

    # Reshaping the input to dense layer (B,40,22,x_shape_4dim) -> (B,x_shape_4dim,880)

    x = x.permute(0,3,1,2) # (B,40,22,x_shape_4dim) -> (B,x_shape_4dim,40,22)
    x = x.view(-1,x_shape_4dim,880)

    # Passing through the dense layer (B,x_shape_4dim,880) -> (B,x_shape_4dim,40)

    x = self.fc1(x)

    # ELU activation

    x = self.elu(x)

```

```
.. .. .\..
```

```
# Square activation
```

```
x = torch.square(x)
```

```
# Reshaping the input for average pooling layer (B,x_shape_4dim,40) -> (B,40,x_shape_
```

```
x = x.permute(0,2,1)
```

```
# Passing through the average pooling layer (B,40,x_shape_4dim) -> (B,40,x_pool_3dim)
```

```
x = self.avgpool(x)
```

```
x_pool_3dim = x.shape[2]
```

```
# Log activation
```

```
x = torch.log(x)
```

```
# 1D Batch normalization
```

```
x = self.bnorm1d(x)
```

```
#print(x.shape)
```

```
# Reshaping the input to dense layer (B,40,x_pool_3dim) -> (B,40*x_pool_3dim)
```

```
x = x.reshape(-1, 40*x_pool_3dim)
```

```
# Passing through the dense layer (B,40*x_pool_3dim) -> (B,classes)
```

```
x = self.fc2(x)
```

```
# Passing through the softmax layer
```

```
x = self.softmax(x)
```

```
return x
```

```
## train a model to classify subject1 with data from all subjects
```

```
def train_model_with_alldata(model, optimizer, num_epochs):
```

```
    # for each epoch...
```

```
    liveloss = PlotLosses()
```

```
    for epoch in range(num_epochs):
```

```
        print('Epoch {}'.format(epoch, num_epochs - 1))
```

```
        print('-' * 10)
```

```
        logs = {}
```

```
        # let every epoch go through one training cycle and one validation cycle
```

```

# Let every epoch go through one training cycle and one validation cycle
# TRAINING AND THEN VALIDATION LOOP...
for phase in ['train', 'val']:
    train_loss = 0
    correct = 0
    total = 0
    batch_idx = 0

    start_time = time.time()
    # first loop is training, second loop through is validation
    # this conditional section picks out either a train mode or validation mode
    # depending on where we are in the overall training process
    # SELECT PROPER MODE- train or val
    if phase == 'train':
        for param_group in optimizer.param_groups:
            print("LR", param_group['lr']) # print out the learning rate
        model.train() # Set model to training mode
    else:
        model.eval() # Set model to evaluate mode

    for inputs, labels in dataloaders[phase]:
        inputs = inputs.to(device)
        labels = labels.to(device)
        batch_idx += 1

        optimizer.zero_grad()

        with torch.set_grad_enabled(phase == 'train'):
            # the above line says to disable gradient tracking for validation
            # which makes sense since the model is in evaluation mode and we
            # don't want to track gradients for validation)
            outputs = model(inputs)
            # compute loss where the loss function will be defined later

            loss = loss_fn(outputs, labels)
            # backward + optimize only if in training phase
            if phase == 'train':
                loss.backward()
                optimizer.step()
            train_loss += loss
            _, predicted = outputs.max(1)

            total += labels.size(0)
            correct += predicted.eq(labels).sum().item()

    # if phase == 'train':
    #     if epoch%5 == 0:
    #         # prints for training and then validation (since the network will be in either tr
    #         print(" Training Epoch %d, Total loss %0.6f, iteration time %0.6f" % (epoch, tr

    # if phase == 'val' and epoch%5 == 0:
    #     print(" Validation Epoch %d, Total loss %0.6f, iteration time %0.6f" % (epoch, tr

```

```

    prefix = ''
    if phase == 'val':
        prefix = 'val_'

    logs[prefix + 'loss'] = train_loss.item()/(batch_idx)
    logs[prefix + 'acc'] = correct/total*100.

    liveloss.update(logs)
    liveloss.send()

# end of single epoch iteration... repeat of n epochs
return model

# train a model to classify subject 1 data with only subject 1 data

def train_model_with_s1data(model, optimizer, num_epochs):
    # for each epoch...
    liveloss = PlotLosses()

    for epoch in range(num_epochs):
        print('Epoch {}/{}'.format(epoch, num_epochs - 1))
        print('-' * 10)
        logs = {}

        # let every epoch go through one training cycle and one validation cycle
        # TRAINING AND THEN VALIDATION LOOP...
        for phase in ['train_s1', 'val_s1']:
            train_loss = 0
            correct = 0
            total = 0
            batch_idx = 0

            start_time = time.time()
            # first loop is training, second loop through is validation
            # this conditional section picks out either a train mode or validation mode
            # depending on where we are in the overall training process
            # SELECT PROPER MODE- train or val
            if phase == 'train_s1':
                for param_group in optimizer.param_groups:
                    print("LR", param_group['lr']) # print out the learning rate
                model.train() # Set model to training mode
            else:
                model.eval() # Set model to evaluate mode

            for inputs, labels in dataloaders[phase]:
                #print(inputs.size())
                #print(labels.size())
                inputs = inputs.to(device)
                labels = labels.to(device)

```



```

batch_idx += 1

optimizer.zero_grad()

with torch.set_grad_enabled(phase == 'train_s1'):
    # the above line says to disable gradient tracking for validation
    # which makes sense since the model is in evaluation mode and we
    # don't want to track gradients for validation)
    outputs = model(inputs)
    # compute loss where the loss function will be defined later
    #print(outputs.size())

    loss = loss_fn(outputs, labels)
    # backward + optimize only if in training phase
    if phase == 'train_s1':
        loss.backward()
        optimizer.step()
    train_loss += loss
    _, predicted = outputs.max(1)

    total += labels.size(0)
    correct += predicted.eq(labels).sum().item()

# if phase == 'train':
#     if epoch%5 == 0:
#         # prints for training and then validation (since the network will be in either tr
#         print(" Training Epoch %d, Total loss %0.6f, iteration time %0.6f" % (epoch, tr

# if phase == 'val' and epoch%5 == 0:
#     print(" Validation Epoch %d, Total loss %0.6f, iteration time %0.6f" % (epoch, tr

prefix = ''
if phase == 'val_s1':
    prefix = 'val_'

logs[prefix + 'loss'] = train_loss.item()/(batch_idx)
logs[prefix + 'acc'] = correct/total*100.

liveloss.update(logs)
liveloss.send()

# end of single epoch iteration... repeat of n epochs
return model

def test(model):
    dataloader = dataloaders['test']
    size = len(dataloader.dataset)

```

```

model.eval()
test_loss, correct = 0, 0
with torch.no_grad():
    for X, y in dataloader:
        X, y = X.to(device), y.to(device)
        pred = model(X)
        test_loss += loss_fn(pred, y).item()
        correct += (pred.argmax(1) == y).type(torch.float).sum().item()
test_loss /= size
correct /= size
print(f"Test Error: \n Accuracy: {(100*correct):>0.1f}%, Avg loss: {test_loss:>8f} \n")

```

▼ Train the Model with only subject 1 data and then classify subject 1 data

```

# define the hyperparameters
weight_decay = 0.15 # weight decay to alleviate overfitting

model = ShallowConv(in_channels=1, num_conv_filters=40, num_samples_frame=1000, num_eeg_channel

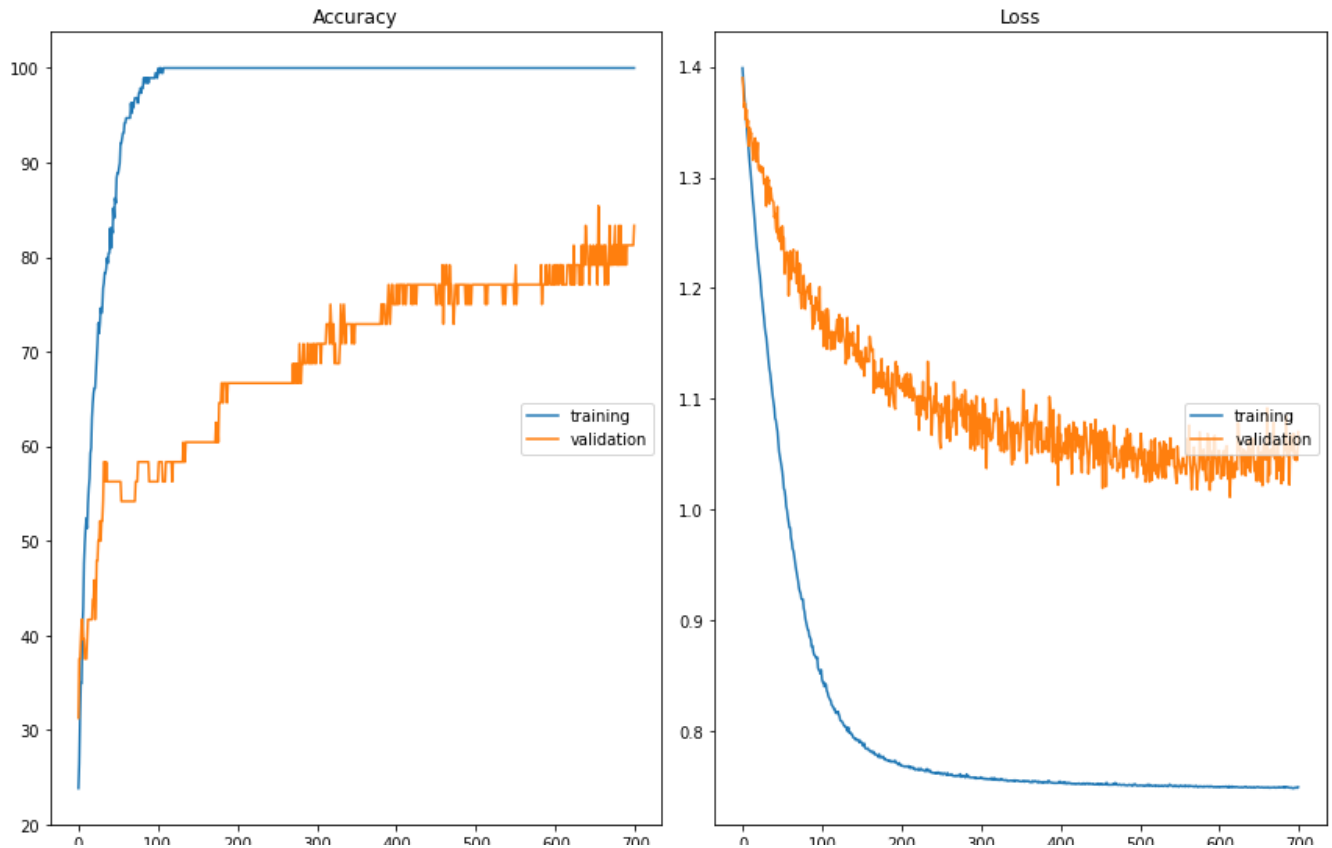
count = count_parameters(model)
print ('model parameters amount {}'.format(count))

loss_fn = nn.CrossEntropyLoss()
optimizer = torch.optim.Adam(model.parameters(), lr = 2e-5, weight_decay=weight_decay)

    model parameters amount 46204

model=train_model_with_s1data(model, optimizer, num_epochs=700)
test(model)

```



- ▼ Train the model with all data and then then classify subject 1 data

```
validation (min.: 01.250, max.: 03.417, cat.: 03.555,
weight_decay = 0.15 # weight decay to alleviate overfitting

model = ShallowConv(in_channels=1, num_conv_filters=40,num_samples_frame=1000,num_eeg_channel

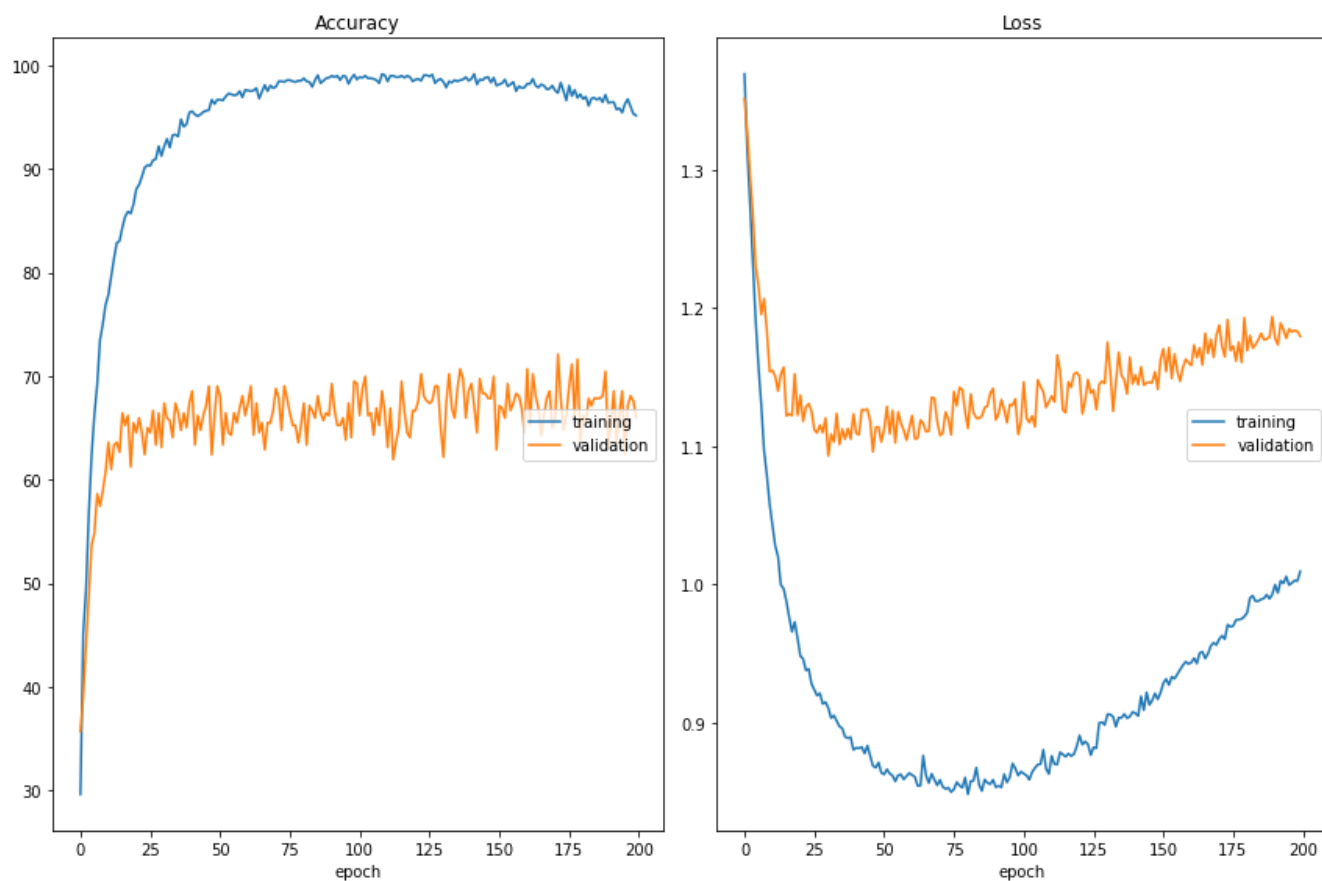
count = count_parameters(model)
print ('model parameters amount {}'.format(count))

loss_fn = nn.CrossEntropyLoss()
optimizer = torch.optim.Adam(model.parameters(), lr = 1e-4, weight_decay=weight_decay)

    model parameters amount 46204

model=train_model_with_alldata(model, optimizer, num_epochs=200)
test(model)
```





Accuracy

training	(min: 29.610, max: 99.173, cur: 95.154)
validation	(min: 35.697, max: 72.104, cur: 65.957)

Loss

training	(min: 0.848, max: 1.369, cur: 1.009)
validation	(min: 1.093, max: 1.351, cur: 1.179)

Test Error:

Accuracy: 78.0%, Avg loss: 0.023357